

view\_frames Result

Recorded at time: 2057.415

map

Broadcaster: /map\_odom\_broadcaster  
Average rate: 10.255 Hz  
Most recent transform: 2057.468 ( -0.053 sec old)  
Buffer length: 3.413 sec

odom

Broadcaster: /gazebo  
Average rate: 10.294 Hz  
Most recent transform: 2057.357 ( 0.058 sec old)  
Buffer length: 3.400 sec

chassis

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 2057.415 sec old)  
Buffer length: 0.000 sec

camera

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 2057.415 sec old)  
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot\_state\_publisher  
Average rate: 10.294 Hz  
Most recent transform: 2057.365 ( 0.050 sec old)  
Buffer length: 3.400 sec

left\_wheel

Broadcaster: /robot\_state\_publisher  
Average rate: 10.294 Hz  
Most recent transform: 2057.365 ( 0.050 sec old)  
Buffer length: 3.400 sec

right\_wheel