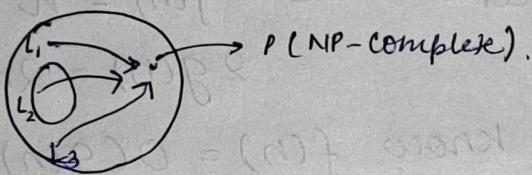


Q1

i) if a decision problem in P is NP-complete then $P = NP$. Recall that P denotes a decision problem which can be solved in polynomial time. (YES).

As we know NP-complete problems^(P) are those problem

- i) which lies in NP.
- ii) All problems \leq_p L of NP $L \leq_p$ problem (P)



Claim: if p can be solved in polynomial time then $P = NP$.

$\Rightarrow p \in P$ (given).

$\forall L_{in\ NP} \leq_p L \leq_p P$ (from defn above).

\Rightarrow all problems in NP are polynomial time reducible to p, Also as p can be solved in polynomial time L can be solved in polynomial time too.

\Rightarrow there will be no problem in NP which can not be solved in polynomial time ($NP - P = \text{Null}$)

$\Rightarrow P = NP$. (as $P \subseteq NP$ & $NP - P = \emptyset$).

ii) safe vertex is removal of v does not disconnect G.
(NO).

Let's take following example

G has DFS Tree as.

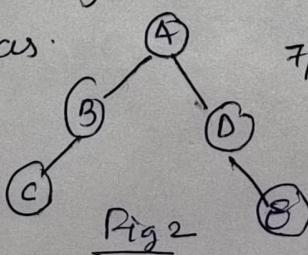


Fig 2

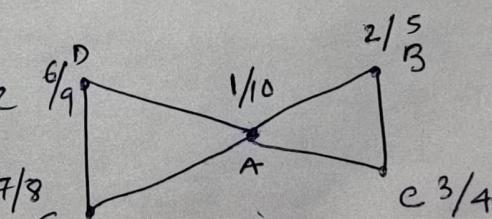


Fig 1

As from Fig 1 we can say that removal of A disconnects the graph. But in Fig 2 DFS has more than 2 child.

iii). if $f(n) = O(g(n))$ then $2^{f(n)}$ is $2^{O(g(n))}$ (NO)
 $f(n) = O(g(n)) \Rightarrow \exists c > 0$ such that $f(n) < c g(n)$ for all $n > n_0$

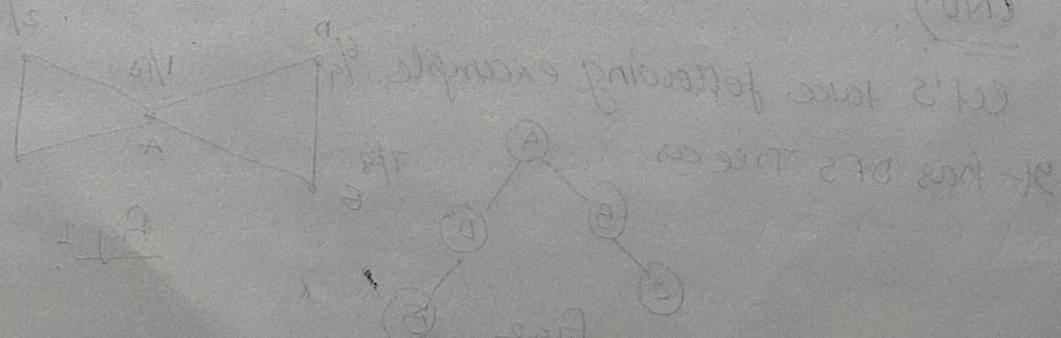
$\Rightarrow f(n) \leq c g(n)$ let's take $f(n) = n$]
 $2^{g(n)} = 2^n$] A

We know $f(n) = O(g(n))$.

now if we take power on both sides it will be:

$$\frac{2^{f(n)}}{2^{g(n)}} = \frac{2^n}{2^{2n}} \quad] B.$$

- In case A ratio between two is constant which can be used to set C.
 - but in case B ratio between these two is ∞ which can't be written using C.
- \Rightarrow above given statement is false -



2) Given
S: $n+1$ numbers (distinct) (unsorted)
A: n numbers from S (unsorted)

$O(n)$ time ^{DC} algorithm to find the number which is not in S.

- As we know $T(n) = T(n_1) + T(n_2) + O(n)$, where $n_1 + n_2 \leq 2n$

then the solⁿ of this recurrence is $O(n)$

- So we need to divide & conquer using throwing sum some part of the array.

- We need to find out the median for both arrays A & S and based on the position of median we can say that which part has missing element.

- If we refine the solution more we can use the partitioning algorithm to set the position of an element in S and A and for next iteration select the size of sides of S & A which has unbalance sizes.

Algorithm : find-missing (A, S)

$O(1)$ - // Check base condⁿ here (defined next)

$O(1)$ - Select random number e from A

$O(n)$ - find the position of e in S

$O(n)$ - set e as pivot in both A & S and do partitioning as discussed in class this gives us A_1, e, A_2 and S_1, e, S_2

if $|A_1| \neq |S_1|$

call find_missing (A_1, S_1).

else

Call find_missing (A_2, S_2)

} // END of algorithm.

base condition [if $\text{size } |S_1| = 1 \text{ and } |A_2| = 0$]

(Should be at constant of recursion) return the element of S_1 as answer.

Complexity: as discussed in class. we are calling only one subarray. so as it has complexity of selection algorithm where one part of the array is thrown off and work done in each iteration is $O(n)$.

our recurrence eqn is also like

$$T(n) = T(n_1) + O(n)$$

(where $n_1 < n$)

Since P_i is chosen randomly we can say that it has decreasing the size of problem as a factor

$$\Rightarrow T(n) = O(n).$$

Proof of correctness:

As we are selecting e in $A \Rightarrow e$ will be in S

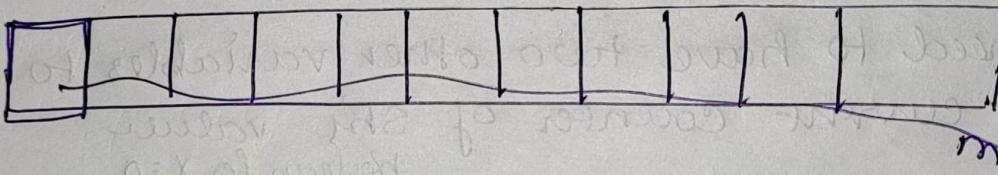
too, now if we do partition elements less than e are in first part & greater than are in second part of arrays S & T

Since all elements are distinct we can simply compare the size of first & second part to find out which part has missing number (which is causing imbalance) //

3) Shuffle of two strings

a) given 3 string $A[1..n]$, $B[1..m]$, $C[1..m+n]$
 we give a DP that to check that C is a shuffle
 of $A \oplus B$.

this problem is same as ~~graph~~ edit-distance
 where at each point we should check if
 i^{th} element of C is in order elements of
 either A or B .



Shuffle (A, B) \in A_i, B_j, C_k) $\xrightarrow{\text{Value}}$
 base cond.

if $(C_k = A_i)$

~~value shuffle = shuffle~~

~~value~~ $\not\equiv$ ~~value~~ $1 + \text{shuffle}(A_{i+1}, B_j, C_{k+1})$. $\xrightarrow{\text{Value}}$

if $(C_k = B_j)$

$\text{value} = 1 + \text{shuffle}(A_i, B_{j+1}, C_{k+1}, \text{value})$

if $C_k = A_i \wedge C_k = B_j$ then

return no valid shuffle

if $\text{value} = m+n$

return C is valid shuffle.

base condⁿ

Idea is to count valid matches using A, B to C and incrementing pointer appropriately.

Complexity

Time $\Rightarrow O(m+n)$

Space $\Rightarrow O(1)$ only one variable
Value is used.

- 5) smooth shuffling no more than two shuffles are done

X Y Z.

We need to have two other variables to store current counter of S_{ij} value

boolean for $X = 0$

$Y = 0$

S-shuffle ($X_i, Y_j, Z_k, (S_{ij}), \text{coenl, value}$).

{

if value = $m+n$.

return valid shuffle

if $Z_k \neq X_i$ and $Z_k \neq Y_j$

return invalid shuffle.

if coenl > 2

return invalid shuffle.

if $Z_k = X_i$

value = 1 + S shuffle ($X_{i+1}, Y_i, Z_{k+1}, 0, \frac{\text{count}}{2}$)

if $Z_k = Y_j$

value = 1 + S shuffle ($X_i, Y_{j+1}, Z_{k+1}, 1, \frac{\text{count}}{2}$)

4) f_i : families

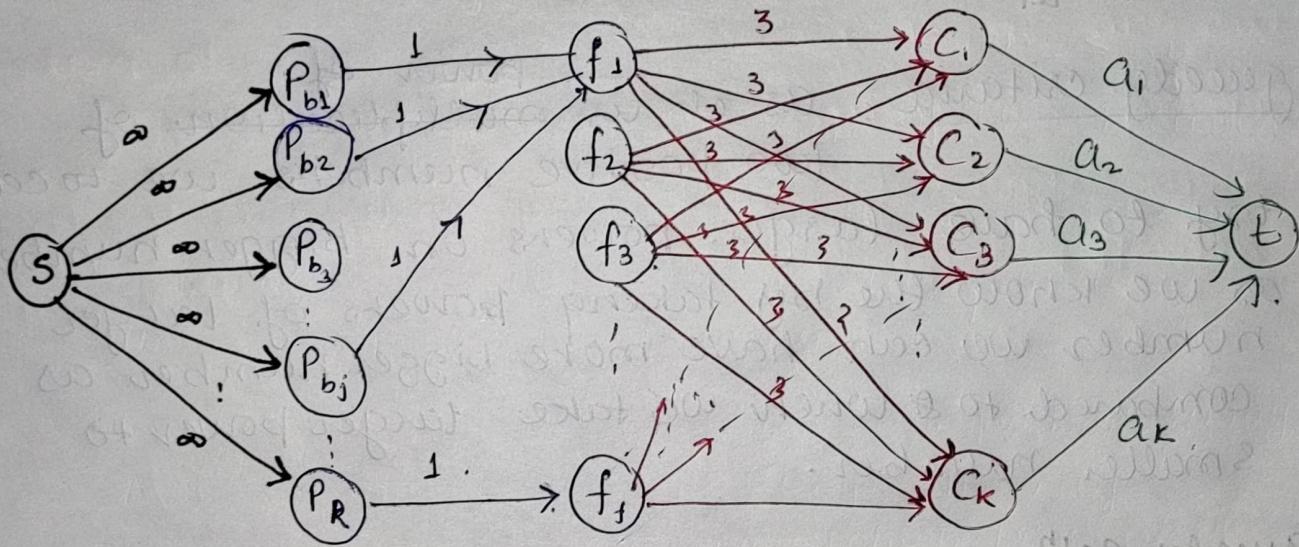
R : clubs.

i th club needs - a_i number of memb.
can take at most 3
from a family

each person can belong to at most 1 club.

each family has b_j members.

1- each member has to be in a family (atmost 1).



source can be connected to each person with capacity ∞ or any other capacity $C > 1$

constraint
that is satisfied

None

each P_i is connected to f_j if $P_i \in f_j$ by a directed edge of capacity 1.

each person can be atmost in one family

each f_i is connected to each c_j with a directed edge of capacity 3.

each club can have atmost 3 members from a family

each club is connected by f with capacity a_i

Club has to take atleast a_i members in total

Q.5.

Near Clique \leq_p k_{C_2} or $k_{C_2} - 1$ edges

To prove clique \leq_p Near Clique.

Clique $\xrightarrow[\text{time reducible}]{\text{polynomial}} \text{Near Clique}$
 $G(V, E)$ to $G'(V, E')$.

We can simply remove ^{exactly} one edge in G to make it G' at a time and ask if it has a near clique of size k . If answer is yes to all $|E|$ graphs G' then we can say that clique of size k existed in graph G .

Proof :- If G has a clique of size k then all $G'_i(V, E)$ will ~~answer~~ have near clique $i \in [0, |E|]$

This is easy to prove that if G has a clique of size k then G' can have only have a clique or near clique of same size (k). As our algorithm for finding clique is called $O(|E|)$ times which is polynomial we can say clique is polynomial time reducible to near clique.

- If all $G'_i(V, E)$ st $i \in [0, |E|]$ has near cliques then G has a clique.

As similar to above G' only has one edge missing at a time \Rightarrow if near clique is not present then the clique of size k will no longer be present in G . Conversely if for all G' if near clique present $\Rightarrow G$ will have a clique.

6) given X : n +ve int

drawn for y : iD - been done by
S. I want to add nos. "

soln of: fo

(+)

soln: y

arrange the elements in X & Y in some order

x_i ith element: y_i ith element in this order
arrange such that-

$$\prod_{i=1}^n x_i^{y_i} = x_1^{y_1} \times x_2^{y_2} \times x_3^{y_3} \times \dots \times x_n^{y_n}$$

Greedy criteria: as it is multiplication of power of two positive numbers we can try to have larger powers on bigger numbers as we know the by taking powers of larger number we can have more bigger number as compared to when we take larger power to smaller number.

Greedy soln:

x' = Sort X in decreasing order

y' = Sort Y in decreasing order

calculate the $\prod_{i=1}^n x_i^{y_i}$

Proof of correctness:

in first step greedy select the first two elements of x' & y' . & optimal takes any other 2, e.g., for $y' < x'$

Base step:

greedy $x'[1]^{y'[1]}$

optimal $x'[k]^{y'[k]}$

as we can say.

$x'[1]^{r'[1]}$ is the max^m possible product
⇒ greedy is ahead of optimal in first step.

Also, let's assume greedy matches $x'[k]$ to $y'[k]$
~~and $x'[j]$ to $y'[j]$~~
⇒ $x'[1]^{r'[1]} \times x'[k]^{r'[k]}$ ~~$\times x'[j]^{r'[j]}$~~ is the (g)
partial product envolve in greedy

on the other hand optimal taken:

$$x'[k]^{[i]} \times x'[i]^{[t]} \quad \text{---} \quad \textcircled{O1}$$

the multiplication of (O1) will be less than (g)
always. as the values here are increasing for
taking larger power of larger elements.

Induction:

Claim: if greedy solution agrees to optimal
in $n-1$ step then we should prove
the it will agrees for n steps too

Proof: let

Greedy	O_1	O_2	O_3	---	O_n
Optimal	G_1	G_2	G_3	---	G_n

then by combining prove in above case for $n=1$
we can say that-

Greedy	O_1	O_2	O_3	---	O_n
Optimal	G_1	G_2	G_3	---	G_n

agrees with each other.