

AUTO TAKEOFF AND LANDING

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1 Tutorial Name

AUTO TAKEOFF AND AUTO LANDING

2 Theory and Description

we have connected R pi and Apm through UART. and we have written a code in python. so after running this code on r pi.drone will take off autonomously without any control. it will go up to hight of 2 m. then after 10 seconds it will go in LAND mode.
you can see video on youtube.

<https://www.youtube.com/watch?v=GHcQYoiWwgk>

code is here:

<https://github.com/eYSIP-2016/Autonomous-Drone>