

## Applied Mechanics-I BEG\_\_CI

Year: I

Semester: I

Teaching						Examination	Scheme			Total Marks
	Iours/v			Int	ernal		Fina	al	G. H. VIEW	
				Theory	Practical	Theor	у -	Practi	cal	
Cr	L	T	P		ILANGE DE REFERE	Duration	Marks	Duration	Marks	
3	3	3	-	40		3	60			100

Course Objective:

This course has been developed to provide the basic knowledge of engineering mechanics where in laws of physics are applied to solve engineering problems. This course will helps the students to understand structural engineering theory in later courses.

## **Detailed Course Contents:**

Ch.	Tonio		Subtopic				De	pth				Hour	Remarks
No.	Topic		Subtopic	SD	D	DR	I	E	A	EX	N	Hour	Remarks
		1.1	Definition & scope of mechanics, engineering mechanics and static	1					1				
1	Introduction	1.2	Concepts of particle, rigid body, deformed & fluid bodies	1						1		5	
		1.3	Equation of static equilibrium in 2D & 3D		1								
		1.4	Free body diagram	1	1	A I	1			46		Pray	
		1.5	System of units							1			



		2.1	Definition & principles of forces	1				T				
		2.2	Types of forces (coplanar, collinear, concurrent, parallel, external & internal forces)	1			1		1			
		2.3	Principle of transmissibility & its limitations	1	1	179	1		1			
		2.4	Resolution & composition of forces				1-	1	10 10 10			
2	Forces	2.5	Lami's theorem, Varignon's theorem, triangle, parallelogram & polygon law of forces	1		1	1			1	7	
		2.6	Moment of forces about a point & axis (in scalar & vector form)	1		1				1		
		2.7	Definition of couple & proof of it as a free vector	1		1		-				
		2.8	Resolution of force into force & a couple & vice versa				1			1		
		2.9	Resultant of a system of forces (wrench, parallel, coplanar, concurrent & general)	1	1		1		1	1		
		3.1	Definition & derivation of center of gravity & centroid (composite figure & direct integration method)	1		1	1					
		3.2	Centroid of lines, areas and volumes	1		1	1			1		
3	Distributed Force	3.3	Definition of second moment of area (moment of Inertia) and radius of gyration	1	1		1			1	6	
		3.4	Parallel and perpendicular axis theorem, MOI of common figures (e.g. rectangle, triangle, circle and ellipse) and uniform thin rod	1		1	1			1		
		3.5	MOI of built up section.							1		
		3.6	MOI by direct integration method.	20						1	BYE	



		4.1	Introduction	1							3	
		4.2	Laws of dry friction	1								
4	Friction	4.3	Static friction, co-efficient of friction & angle friction	1			1				4	
		4.4	Condition of sliding or tipping		1							
		4.5	Application to static problems					1		1-		
120		5.1	Structural components (beam, frame, truss, 2-D plate, cable, arch, grid)	1			1					
		5.2	Difference between plane and space structures.	1			1				<b>.</b>	
5	Introduction to Structures	5.3	Difference between mechanism & structures	1			1				. 3	
		5.4	Types of loading & supports		1		1		1			
		5.5	Determinacy (internal & external) and stability (statical & geometrical)		1			1		1	a l	
		6.1	Definition and types of beam	1			1					
		6.2	External and internal forces in beam	1			1					
6	Introduction to	6.3	Definition and sign convection of axial forces, shear forces and bending moment	1			1			1 1/2	8	Any types of determinant beam with any types of static loading
	Analysis of Beam	6.4	Relationship between load, shear force & bending moment			1		1				loaung
-		6.5	Axial force, shear force & bending moment diagram							1		Portal frame and cantilever
		7.1	Definition & type of frame (rigid, deficient, redundant)	1			1					frame (without internal hinge, inclined and
7	Introduction to Analysis of Frame	7.2	Determinacy & stability						111	1	6	overhanging member) with
	Alialysis of Flame	7.3	Axial force, shear force & bending moment diagram							1		combination of point load, moment and UDL.



	Landadiant	8.1	Definition & types of plane (according to support condition purpose of utilization, degree of complexity)	1	1	-		
8	Introduction to Analysis of Truss	8.2	Determinacy & Stability pf plane			1	6	
	7 may sis of 17 ass	8,3	Analysis of plane truss (method of joints & method of section)			-		
		8.4	Introduction of space truss	1	1	III Y. III	1100	

Note: Define(SD), Description (D), Derive (D), Illustration (I), Explanation (E), Application (A), Explanation (Ex), Numerical (N)

## Final Examination Scheme:

Chapters	Marks	Remarks
1,4,5	10	Th+ N
2	10	Th+N
3	10	Th+N
6	10	Th + N
7	10	N
8	10	Th + N
Total	60	

Note: There might be minor deviation in mark distribution.

Mandatory: Marks should be evaluated based on solving steps.

## References:

- 1. Beer F.P., & Johnston, E.R. (1987). Mechanics for Engineers-Statics and Dynamics. 4th edition, Mcgraw-Hill.
- 2. Hibbeler, R.C., & Gupta, A. (2009). Engineering Mechanics-Statics and Dynamics. 11th edition. Pearson Education.
- 3. Shames, I.H. (1990). Engineering Mechanics-Statics and Dynamics. 3rd edition. Prentice Hall of India.