

# SymPy (Mr. P Solver)

Video Link: <https://youtu.be/1yBPEPhq54M> (<https://youtu.be/1yBPEPhq54M>).

Codes: [https://www.youtube.com/redirect?event=video\\_description&redir\\_token=QUFFLUhqbfPpXWXFuczlGOVZ4RFlbHV0eko2T29jUEw1UXxBQ%3F&url=https%3A%2F%2Fwww.youtube.com%2Fredirect%3F&w=1280&h=720](https://www.youtube.com/redirect?event=video_description&redir_token=QUFFLUhqbfPpXWXFuczlGOVZ4RFlbHV0eko2T29jUEw1UXxBQ%3F&url=https%3A%2F%2Fwww.youtube.com%2Fredirect%3F&w=1280&h=720)  
[https://www.youtube.com/redirect?event=video\\_description&redir\\_token=QUFFLUhqbfPpXWXFuczlGOVZ4RFlbHV0eko2T29jUEw1UXxBQ%3F&url=https%3A%2F%2Fwww.youtube.com%2Fredirect%3F&w=1280&h=720](https://www.youtube.com/redirect?event=video_description&redir_token=QUFFLUhqbfPpXWXFuczlGOVZ4RFlbHV0eko2T29jUEw1UXxBQ%3F&url=https%3A%2F%2Fwww.youtube.com%2Fredirect%3F&w=1280&h=720)

SymPy means SYMBOLIC PYTHON.

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import sympy as smp
```

## Introduction

Symbols can be defined as follows

```
In [2]: x = smp.symbols('x')
```

```
In [3]: x**2 - 5*x + 6
```

Out[3]:  $x^2 - 5x + 6$

```
In [4]: y = smp.sin(x)
y**2 + (smp.cos(x))**2
```

Out[4]:  $\sin^2(x) + \cos^2(x)$

```
In [5]: y1 = smp.log(x,10) # input the base
y1
```

Out[5]:  $\frac{\log(x)}{\log(10)}$

type '**smp.**' and press '**Tab**' to see all the SymPy functions

```
In [6]: z = (x**2 - 5*x + 6)**2
display(z.factor(), z.expand())
display(smp.solve(z,x))
```

$(x - 3)^2(x - 2)^2$

$x^4 - 10x^3 + 37x^2 - 60x + 36$

[2, 3]

```
In [7]: z.as_poly()
```

```
Out[7]: Poly(x4 - 10x3 + 37x2 - 60x + 36, x, domain = ZZ)
```

type 'z.' and press 'Tab' to see all the operations that can be done on z

```
In [8]: z.fourier_series([-smp.pi, smp.pi])
```

```
Out[8]: -20π2 sin(x) +  $\frac{(45\pi + 10\pi^3) \sin(2x)}{\pi} + \frac{(-100\pi - 8\pi^3) \cos(x)}{\pi} + \frac{(2\pi^3 + 34\pi) \cos(2x)}{\pi}$ 
```

```
In [9]: z1 = smp.exp(x) + smp.exp(-x)
display(z1)
display(smp.solve(z1))
```

$e^x + e^{-x}$

$[-I\pi/2, I\pi/2]$

```
In [10]: x = smp.symbols('x', real=True, positive=True)
smp.solve(x**4 - 16, x)
```

```
Out[10]: [2]
```

Can define many variables at once

```
In [11]: x, y, z = smp.symbols('x y z')
f = x**3*smp.sin(z) - y**2*smp.exp(z)
f
```

```
Out[11]: x3 sin(z) - y2 ez
```

```
In [12]: y_soln = smp.solve(f, y)
y_soln
```

```
Out[12]: [-sqrt(x**3*exp(-z)*sin(z)), sqrt(x**3*exp(-z)*sin(z))]
```

```
In [13]: smp.solve(f, x)
```

```
Out[13]: [(y**2*exp(z)/sin(z))**(1/3),
-(y**2*exp(z)/sin(z))**(1/3)/2 - sqrt(3)*I*(y**2*exp(z)/sin(z))**(1/3)/2,
-(y**2*exp(z)/sin(z))**(1/3)/2 + sqrt(3)*I*(y**2*exp(z)/sin(z))**(1/3)/2]
```

For multivariable expressions, can also substitute values in

```
In [14]: f.subs([(y, smp.sqrt(x)), (z, smp.pi/2)])
```

```
Out[14]: x3 - x e $\frac{\pi}{2}$ 
```

**SymPy to NumPy conversion so that the function can be plotted.**

```
In [15]: f1sym = y_soln[1]
f1sym
```

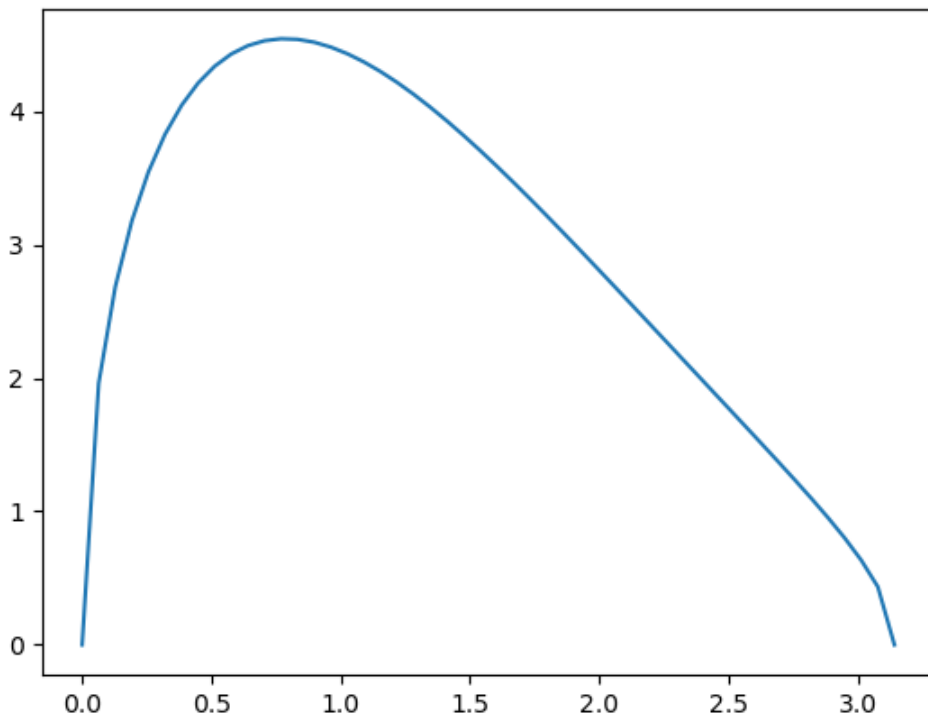
```
Out[15]:  $\sqrt{x^3 e^{-z} \sin(z)}$ 
```

```
In [16]: f1num = smp.lambdify([x,z], f1sym)
f1num(4,np.pi/2)
```

```
Out[16]: 3.64750502212797
```

```
In [17]: xnum = 4
ynum = np.linspace(0,np.pi,50)
plt.plot(ynum, f1num(xnum, ynum))
```

```
Out[17]: [<matplotlib.lines.Line2D at 0x19fc34ea250>]
```



## Example

A falling object encounters a moving platform accelerating upwards:

1. Object  $h_o(t) = h_0 - v_o t - \frac{1}{2} g t^2$
2. Platform  $h_p(t) = v_p t + \frac{1}{2} q t^2$

Find the initial velocity  $v_0$  such that when the object and platform collide, they are moving at the same speed.

**Soln:** We need to solve for  $v_0$  and  $t$  in the 2 eqns:

1.  $h_0(t) = h_p(t)$  and
2.  $\frac{dh_o}{dt}(t) = -\frac{dh_p}{dt}(t)$

from these 2 equations we can define 2 functions eq1 and eq2

```
In [18]: t, h0, v0, g, vp, q = smp.symbols('t h_0 v_0 g v_p q',
                                             real=True, positive=True)

h0t = h0 - v0*t - smp.Rational(1,2)*g*t**2
hpt = vp*t + smp.Rational(1,2)*q*t**2
dh0dt = -v0 + g*t
dhpdt = vp + q*t

eq1 = h0t - hpt
eq2 = dh0dt + dhpdt

sol = smp.solve([eq1,eq2], [v0,t])
display(sol)
```

$$\left[ \left( v_p + (g + q) \cdot \left( -2 \cdot v_p / (3 \cdot (g + q)) + \sqrt{2} \cdot \sqrt{3 \cdot g \cdot h_0 + 3 \cdot h_0 \cdot q + 2 \cdot v_p^2} / (3 \cdot (g + q)) \right), \right. \right. \\ \left. \left. -2 \cdot v_p / (3 \cdot (g + q)) + \sqrt{2} \cdot \sqrt{3 \cdot g \cdot h_0 + 3 \cdot h_0 \cdot q + 2 \cdot v_p^2} / (3 \cdot (g + q)) \right) \right]$$

```
In [19]: v_initial, t_collision = sol[0]
v_initial
```

Out[19]:

$$v_p + (g + q) \left( -\frac{2v_p}{3(g + q)} + \frac{\sqrt{2}\sqrt{3gh_0 + 3h_0q + 2v_p^2}}{3(g + q)} \right)$$

velocities at the time of collision

```
In [20]: dh0dt.subs([(v0, v_initial), (t,t_collision)]).simplify()
```

Out[20]:

$$\frac{-gv_p - \frac{qv_p}{3} - \frac{q\sqrt{6gh_0 + 6h_0q + 4v_p^2}}{3}}{g + q}$$

```
In [21]: dhpdt.subs([(v0, v_initial), (t,t_collision)]).simplify()
```

Out[21]:

$$\frac{gv_p + \frac{qv_p}{3} + \frac{q\sqrt{6gh_0 + 6h_0q + 4v_p^2}}{3}}{g + q}$$

## Calculus (1st year)

More depth discussion here: <https://www.youtube.com/watch?v=-SdIZHPuW9o>  
<https://www.youtube.com/watch?v=-SdIZHPuW9o>

```
In [22]: x = smp.symbols('x')
```

## Limits

$$\lim_{x \rightarrow \pi} \sin(x/2 + \sin(x))$$

```
In [23]: smp.limit(smp.sin(x/2 + smp.sin(x)), x, smp.pi)
```

Out[23]: 1

## Derivatives

$$\frac{d}{dx} \left( \frac{1 + \sin x}{1 - \cos x} \right)^2$$

```
In [24]: smp.diff(((1+smp.sin(x))/(1-smp.cos(x)))**2, x)
```

Out[24]:  $\frac{2(\sin(x) + 1)\cos(x)}{(1 - \cos(x))^2} - \frac{2(\sin(x) + 1)^2 \sin(x)}{(1 - \cos(x))^3}$

$$\frac{d}{dx} f(x + g(x))$$

```
In [25]: f,g = smp.symbols('f g', cls=smp.Function)

g = g(x)
f = f(x+g)
display(f)

dfdx = smp.diff(f,x)
dfdx
```

$$f(x + g(x))$$

Out[25]:  $\left( \frac{d}{dx} g(x) + 1 \right) \frac{d}{d\xi_1} f(\xi_1) \Big|_{\xi_1=x+g(x)}$

```
In [26]: dfdx.subs(g, smp.sin(x)).doit() # doit() performs the derivative
```

Out[26]:  $(\cos(x) + 1) \frac{d}{d\xi_1} f(\xi_1) \Big|_{\xi_1=x+\sin(x)}$

## Integrations

**Indefinite Integrals** (Integration constant is not added)

$$\int \csc(x) \cot(x) dx$$

```
In [27]: smp.integrate(smp.csc(x)*smp.cot(x), x)
```

Out[27]:  $-\frac{1}{\sin(x)}$

**Definite Integrals**

$$\int_0^{\ln(4)} \frac{e^x dt}{\sqrt{e^{2x} + 9}}$$

```
In [28]: smp.integrate(smp.exp(x)/smp.sqrt(smp.exp(2*x) + 9), (x, 0, smp.log(4)))
```

Out[28]:  $-\operatorname{asinh}\left(\frac{1}{3}\right) + \operatorname{asinh}\left(\frac{4}{3}\right)$

$$\int_1^t x^{10} e^x dx$$

```
In [29]: t = smp.symbols('t')
smp.integrate(x**10*smp.exp(x), (x,1,t))
```

```
Out[29]: (t10 - 10t9 + 90t8 - 720t7 + 5040t6 - 30240t5 + 151200t4 - 604800t3 + 1814400t2 - 3628800
```

## Examples

The hydrogen wave function is given by

$$\psi_{nlm} = R_{nl}(r)Y_l^m(\theta, \phi)$$

where

$$R_{nl}(r) = \sqrt{\left(\frac{2}{na}\right)^3 \frac{(n-l-1)!}{2n[(n+l)!]}} e^{-r/na} \left(\frac{2r}{na}\right)^l [L_{n-l-1}^{2l+1}(2r/na)]$$

Calculate:

The mean distance from the nucleus of the electron:

$$\langle r \rangle = \int R_{nl}^2 r^3 dr$$

The standard deviation in the distance from the nucleus of the electron:

$$\sigma = \sqrt{\langle r^2 \rangle - \langle r \rangle^2} = \sqrt{\left(\int_0^\infty R_{nl}^2 r^4 dr\right) - \left(\int_0^\infty R_{nl}^2 r^3 dr\right)^2}$$

## Solution:

```
In [30]: from sympy import assoc_laguerre
```

Define variables

```
In [31]: r, a = smp.symbols('r a', real=True, positive=True)
n, l = smp.symbols('n l', integer=True, positive=True)
```

define  $R_{nl}(r)$

```
In [32]: R = smp.sqrt((2/(n*a))**3 * smp.factorial(n-l-1) / (2*n*smp.factorial(n+l))) * smp.exp(
*(2*r/(n*a))**1 * assoc_laguerre((n-l-1), (2*l+1), (2*r/(n*a))))
R
```

```
Out[32]: (2*(2r/an)l e-r/an L-l+n-1(2l+1) (2r/an) √(-l+n-1)!)/
a3/2 n2 √(l+n)!
```

ground state function

```
In [33]: R_10 = R.subs([(n,1),(1,0)])
R_10
```

Out[33]: 
$$\frac{2e^{-\frac{r}{a}}}{a^{\frac{3}{2}}}$$

Function to compute  $\int_0^\infty R_{nl}^2 r^k dr$  for particular values of  $n, l$  and  $k$ ,

```
In [34]: def comp_int(n1,l1,k):
    Rn1l1 = R.subs([(n,n1),(1,l1)])
    return smp.integrate(Rn1l1**2 * r**k, (r,0, smp.oo))
```

Average r

```
In [35]: r10avg = comp_int(1,0,3) # ground state
r10avg
```

Out[35]: 
$$\frac{3a}{2}$$

```
In [36]: r53avg = comp_int(n1=5,l1=3,k=3)
r53avg
```

Out[36]: 
$$\frac{63a}{2}$$

```
In [37]: sigma10 = smp.sqrt(comp_int(1,0,4) - (comp_int(1,0,3))**2)
sigma10 # ground state
```

Out[37]: 
$$\frac{\sqrt{3}a}{2}$$

```
In [38]: sigma64 = smp.sqrt(comp_int(6,4,4) - (comp_int(6,4,3))**2)
sigma64
```

Out[38]: 
$$11\sqrt{2}a$$

Graphs

```
In [39]: def meandist(n1,l1=0):
    expr = comp_int(n1,l1,k=3)
    expr_f = smp.lambdify([a], expr)
    return expr_f(1) # taking a=1
```

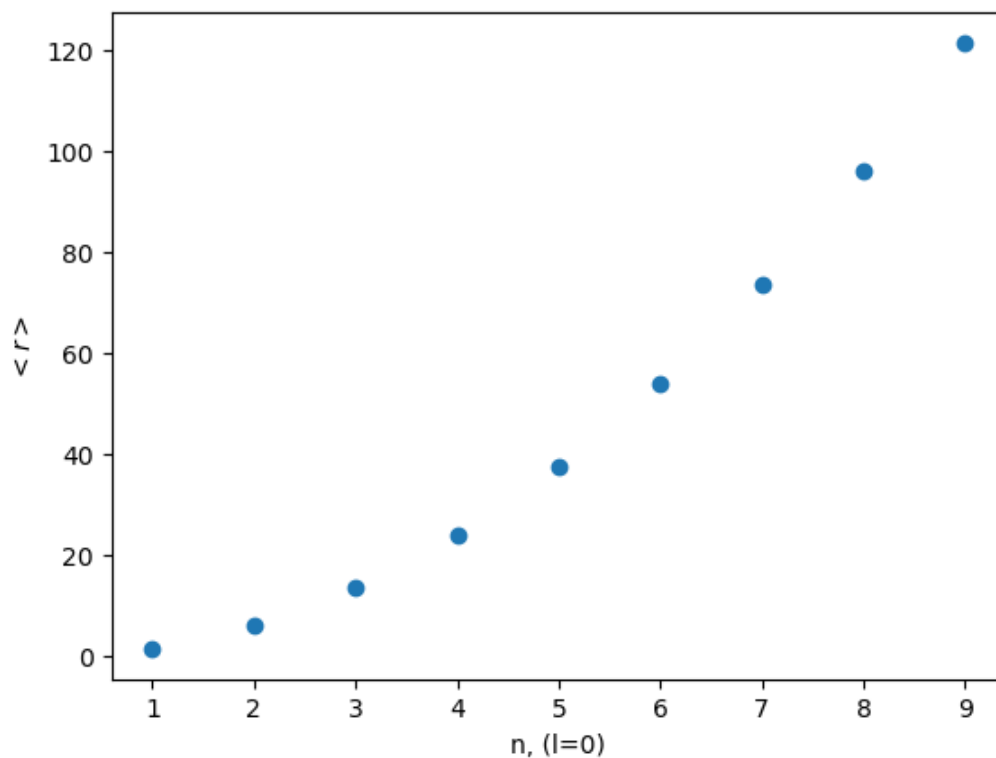
```
In [40]: meandist(1)
```

Out[40]: 1.5

```
In [41]: n2 = np.arange(1,10)
dist = [meandist(ni) for ni in n2]
```

```
In [42]: plt.scatter(n2,dist)
plt.xlabel('n, (l=0)')
plt.ylabel('$\langle r \rangle$')
```

```
Out[42]: Text(0, 0.5, '$\langle r \rangle$')
```



## Multivariable Calculus

```
In [43]: x,y,z,t,u1,u2,u3,v1,v2,v3 = smp.symbols('x y z t u_1 u_2 u_3 v_1 v_2 v_3')
```

## Vectors and Geometry

```
In [44]: u = smp.Matrix([u1,u2,u3])
v = smp.Matrix([v1,v2,v3])
```

### Matrix Operations

```
In [45]: 5*u - 2*v
```

```
Out[45]: 
$$\begin{bmatrix} 5u_1 - 2v_1 \\ 5u_2 - 2v_2 \\ 5u_3 - 2v_3 \end{bmatrix}$$

```

```
In [46]: u.dot(v)
```

```
Out[46]:  $u_1v_1 + u_2v_2 + u_3v_3$ 
```



```
In [47]: u.cross(v)
```

```
Out[47]: 
$$\begin{bmatrix} u_2 v_3 - u_3 v_2 \\ -u_1 v_3 + u_3 v_1 \\ u_1 v_2 - u_2 v_1 \end{bmatrix}$$

```

```
In [48]: u.norm()
```

```
Out[48]: 
$$\sqrt{|u_1|^2 + |u_2|^2 + |u_3|^2}$$

```

Projection - (See the 2nd year calculus notes)

Lines:  $\vec{r}(t) = \vec{r}_0 + t\vec{v}$

```
In [49]: r0 = smp.Matrix([1,1,1])
v = smp.Matrix([4,3,4])
r = r0 + t*v
r
```

```
Out[49]: 
$$\begin{bmatrix} 4t + 1 \\ 3t + 1 \\ 4t + 1 \end{bmatrix}$$

```

Planes:  $\vec{n} \cdot (P_0 - \langle x, y, z \rangle) = 0$

```
In [50]: n = smp.Matrix([3,2,3])
P0 = smp.Matrix([2,2,3,2])
r = smp.Matrix([x,y,z])
n.dot(P0 - r)
```

```
Out[50]:  $-3x - 2y - 3z + 18.6$ 
```

## Vector Calculus

### Vector derivatives

```
In [51]: r = smp.Matrix([4*t, 6*smp.cos(5*t), t**3])
smp.diff(r, t)
```

```
Out[51]: 
$$\begin{bmatrix} 4 \\ -30 \sin(5t) \\ 3t^2 \end{bmatrix}$$

```

**Example:** Find the angle between the velocity and acceleration as a function of time  $\theta(t)$  and also find the angle at  $t = 8s$ .

```
In [52]: v = smp.diff(r,t)
a = smp.diff(v,t)
theta = smp.acos(v.dot(a)/(v.norm()*a.norm()))
theta.simplify()
```

```
Out[52]:
```

$$\operatorname{acos}\left(\frac{3(t^3 + 125 \sin(10t))}{\sqrt{|t|^2 + 625|\cos(5t)|^2} \sqrt{9|t^2|^2 + 900|\sin(5t)|^2 + 16}}\right)$$

```
In [53]: theta.subs(t,8).evalf() # eval() evaluates a float value
```

```
Out[53]: 1.23941092042577
```

## Vector Integrals

```
In [54]: r = smp.Matrix([smp.exp(-t**3), smp.sin(t), 5*t**3 + 4*t])
I = smp.Integral(r,t)
I
```

```
Out[54]:
```

$$\int \begin{bmatrix} e^{-t^3} \\ \sin(t) \\ 5t^3 + 4t \end{bmatrix} dt$$

```
In [55]: I.doit() # performs the integration
```

```
Out[55]:
```

$$\begin{bmatrix} \frac{\Gamma(\frac{1}{3})\gamma(\frac{1}{3},t^3)}{9\Gamma(\frac{4}{3})} \\ -\cos(t) \\ \frac{5t^4}{4} + 2t^2 \end{bmatrix}$$

Some cases integrals can't be solved analytically. So we need to solve them numerically.

```
In [56]: from scipy.integrate import quad_vec
```

```
In [57]: r1 = smp.Matrix([smp.exp(-t**2)*smp.cos(t)**3, smp.exp(-t**4), 1/(3+t**2)])
I1 = smp.Integral(r1, (t,0,1))
I1
```

```
Out[57]:
```

$$\int_0^1 \begin{bmatrix} e^{-t^2} \cos^3(t) \\ e^{-t^4} \\ \frac{1}{t^2+3} \end{bmatrix} dt$$

```
In [58]: rf = smp.lambdify([t],r1)
rf(1)
```

```
Out[58]: array([[0.05802511],
               [0.36787944],
               [0.25      ]])
```

```
In [59]: quad_vec(rf, 0,1) # integration and error
```

```
Out[59]: (array([[0.53525785],
                [0.84483859],
                [0.30229989]]),
          3.5151979041265046e-14)
```

```
smp.integrate(r1, (t,0,1))
```

Result: (high processing time)

$$\begin{bmatrix} \int e^{-t^2} \cos^3(t) dt \\ \frac{\Gamma(\frac{1}{4})\gamma(\frac{1}{4}, t^4)}{16\Gamma(\frac{5}{4})} \\ \frac{\sqrt{3} \operatorname{atan}\left(\frac{\sqrt{3}t}{3}\right)}{3} \end{bmatrix}$$

## Arclength

$$L = \int_a^b \sqrt{dx^2 + dy^2 + dz^2} = \int_a^b \sqrt{(dx/dt)^2 + (dy/dt)^2 + (dz/dt)^2} dt$$

Find arclength of  $\langle 0, 3t, 2t^2 \rangle$  from  $t = 0$  to  $t = 1$ .

```
In [60]: r2= smp.Matrix([0, 3*t, 2*t**2])
display(r2)

f1 = smp.diff(r2,t).norm()
L= smp.integrate(f1, (t,0,1))
display(L)
```

$$\begin{bmatrix} 0 \\ 3t \\ 2t^2 \end{bmatrix}$$

$$\frac{9 \operatorname{asinh}\left(\frac{4}{3}\right)}{8} + \frac{5}{2}$$

## Biot-Savart Law

The magnetic field at a point  $\vec{r}$  of a current configuration is

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int_t \frac{I \frac{d\vec{\ell}}{dt} \times (\vec{r} - \vec{\ell})}{|\vec{r} - \vec{\ell}|^3} dt$$

Where  $\vec{r} = (x, y, z)$  and  $\vec{\ell} = (f(t), g(t), h(t))$  is a 1D curve in space that gives location of the wire. (Here,  $t$  is a parameter, not time.)

## Writing General Formulae

```
In [61]: x,y,z,t,I, mu0 = smp.symbols('x y z t I \mu_0', real= True)
f,g,h = smp.symbols('f g h', cls= smp.Function)
f = f(t)
g = g(t)
h = h(t)
```

```
In [62]: r = smp.Matrix([x, y, z])
l = smp.Matrix([f, g, h])
dldt = smp.diff(l)
```

```
In [63]: l
```

```
Out[63]: 
$$\begin{bmatrix} f(t) \\ g(t) \\ h(t) \end{bmatrix}$$

```

```
In [64]: dBdt = (mu0* I/(4*smp.pi))* dldt.cross(r-l)/ ((r-l).norm())**3
dBdt
```

```
Out[64]: 
$$\begin{bmatrix} \frac{I\mu_0\left(-(y-g(t))\frac{d}{dt}h(t)+(z-h(t))\frac{d}{dt}g(t)\right)}{4\pi\left(|x-f(t)|^2+|y-g(t)|^2+|z-h(t)|^2\right)^{\frac{3}{2}}} \\ \frac{I\mu_0\left((x-f(t))\frac{d}{dt}h(t)-(z-h(t))\frac{d}{dt}f(t)\right)}{4\pi\left(|x-f(t)|^2+|y-g(t)|^2+|z-h(t)|^2\right)^{\frac{3}{2}}} \\ \frac{I\mu_0\left(-(x-f(t))\frac{d}{dt}g(t)+(y-g(t))\frac{d}{dt}f(t)\right)}{4\pi\left(|x-f(t)|^2+|y-g(t)|^2+|z-h(t)|^2\right)^{\frac{3}{2}}} \end{bmatrix}$$

```

**Question:** Find magnetic field at a distance  $H$  above a ring of radius  $R$  flowing clockwise.

```
In [65]: H, R = smp.symbols('H R', real = True)
```

```
In [66]: dBdt1 = dBdt.subs([(f, R*smp.cos(t)), (g, R*smp.sin(t)), (h, 0),
(x,0), (y,0), (z,H)]).doit()
dBdt1.simplify()
dBdt1
```

```
Out[66]: 
$$\begin{bmatrix} \frac{HIR\mu_0 \cos(t)}{4\pi(H^2+R^2)^{\frac{3}{2}}} \\ \frac{HIR\mu_0 \sin(t)}{4\pi(H^2+R^2)^{\frac{3}{2}}} \\ \frac{IR^2\mu_0}{4\pi(H^2+R^2)^{\frac{3}{2}}} \end{bmatrix}$$

```

```
In [67]: B1 = smp.integrate(dBdt1, [t, 0, 2*smp.pi])
B1
```

```
Out[67]: 
$$\begin{bmatrix} 0 \\ 0 \\ \frac{IR^2\mu_0}{2(H^2+R^2)^{\frac{3}{2}}} \end{bmatrix}$$

```

**Question:** Find magnetic field at a distance  $\rho$  from a wire of length  $L$  kept at the  $z$  axis.

```
In [68]: L, rho, th = smp.symbols('L \\rho \\theta', real = True)
```

```
In [69]: dBdt2 = dBdt.subs([(f, 0), (g, 0), (h, t),
                           (x, rho* smp.cos(th)), (y, rho* smp.sin(th)), (z,0)]).doit()
dBdt2.simplify()
dBdt2
```

```
Out[69]:
```

$$\begin{bmatrix} -\frac{I\mu_0\rho\sin(\theta)}{4\pi(\rho^2+t^2)^{\frac{3}{2}}} \\ \frac{I\mu_0\rho\cos(\theta)}{4\pi(\rho^2+t^2)^{\frac{3}{2}}} \\ 0 \end{bmatrix}$$

```
In [70]: B2 = smp.integrate(dBdt2, [t, -L/2, L/2])
B2
```

```
Out[70]:
```

$$\begin{bmatrix} -\frac{IL\mu_0\sin(\theta)}{4\pi\rho^2\sqrt{\frac{L^2}{4\rho^2}+1}} \\ \frac{IL\mu_0\cos(\theta)}{4\pi\rho^2\sqrt{\frac{L^2}{4\rho^2}+1}} \\ 0 \end{bmatrix}$$

## Partial/Directional Derivatives

```
In [71]: x, y, z = smp.symbols('x y z')
```

Partial derivatives  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial f}{\partial y}$  and  $\frac{\partial^3 f}{\partial x y^2}$  of  $f(x, y) = y^2 \sin(x + y)$

```
In [72]: fxy = y**2 * smp.sin(x+y)
```

```
In [73]: smp.diff(fxy, x)
```

```
Out[73]: y2 cos (x + y)
```

```
In [74]: smp.diff(fxy, y)
```

```
Out[74]: y2 cos (x + y) + 2y sin (x + y)
```

```
In [75]: smp.diff(fxy, y, y, x)
```

```
Out[75]: -y2 cos (x + y) - 4y sin (x + y) + 2 cos (x + y)
```

### The Chain Rule

Suppose  $x, y$  and  $z$  are functions of  $t$  and  $w = w(x, y, z)$ . Find  $dw/dt$ .

```
In [76]: t = smp.symbols('t')
x, y, z, w = smp.symbols('x y z w', cls = smp.Function)
x = x(t)
y = y(t)
z = z(t)
w = w(x,y,z)
w
```

Out[76]:  $w(x(t), y(t), z(t))$

```
In [77]: smp.diff(w,t)
```

Out[77]:  $\frac{d}{dx(t)}w(x(t), y(t), z(t))\frac{d}{dt}x(t) + \frac{d}{dy(t)}w(x(t), y(t), z(t))\frac{d}{dt}y(t) + \frac{d}{dz(t)}w(x(t), y(t), z(t))\frac{d}{dt}z(t)$

```
In [78]: w1 = x* smp.sin(y)* smp.exp(-z**2)
smp.diff(w1,t)
```

Out[78]:  $-2x(t)z(t)e^{-z^2(t)} \sin(y(t))\frac{d}{dt}z(t) + x(t)e^{-z^2(t)} \cos(y(t))\frac{d}{dt}y(t) + e^{-z^2(t)} \sin(y(t))\frac{d}{dt}x(t)$

```
In [79]: smp.diff(w1,t).subs([(x, 1/t**2), (y, 14*t), (z, 2*t)]).doit()
```

Out[79]:  $-\frac{8e^{-4t^2} \sin(14t)}{t} + \frac{14e^{-4t^2} \cos(14t)}{t^2} - \frac{2e^{-4t^2} \sin(14t)}{t^3}$

## Multiple Integrals

In rare cases it can be solved symbolically.

$$\int_0^1 \int_0^{1-x^2} \int_3^{4-x^2-y^2} x^3 dz dy dx$$

```
In [80]: x, y, z = smp.symbols('x y z')
f1 = x**3
smp.integrate(f1, (z,3, 4-x**2-y**2), (y,0,1-x**2), (x,0,1))
```

Out[80]:  $\frac{1}{30}$

## Lagrangian Mechanics

In [ ]: