

## \*> Introduction to Process Scheduling [FCFS] Convoy effect

### if Process Scheduling →

- \* Basis of Multi-Programming o.s

- \* By switching CPU among Processes, os can make Computer more Productive

- \* Many Processes are kept in memory at a time, when a Process must wait @ time quantum Expires, the o.s takes the CPU away from that Process & give the CPU to another Process if this Pattern Continues.

## 2] CPU Scheduler :-

- \* Whenever the CPU become idle, OS must select one process from the ready queue to be executed.
- \* Done by STS

## 3] Non-Preemptive Scheduling :-

- \* once CPU has been allocated to a process, the process keeps the CPU until it releases CPU either by terminating / by switching to wait state.
- Demerit \* Starvation, as a process with long burst time may starve less burst time process.
- \* Low CPU utilization.

## 4] Preemptive Scheduling :-

- \* CPU is taken away from a process after time quantum expires along with terminating @ switching to wait state.
- \* Less Starvation \* High CPU utilization.

@ More overhead

## 5] Goals of CPU Scheduling :-

- \* Max CPU utilization \* Minimum Turnaround time (TAT)
- \* Min wait time \* Min response time
- \* Max throughput of the system.

6] Throughput : No. of processes completed per unit time.

7] Arrival Time [AT] : Time when process is arrived at ready queue.

8] Burst Time [BT] : The time required by the process for its execution.

9] Turnaround Time [TAT] : Time taken from 1<sup>st</sup> time process enters ready state till it terminates.  
[CT - AT].

10] Wait Time (WT): Time Process spends waiting for CPU.  
 $[WT = TAT - BT]$

11] Response Time: Time duration b/w Process getting into ready q & Process getting CPU for the 1<sup>st</sup> time

12] Completion Time (CT): Time taken till Process gets terminated.

1\*\*> FCTS { First Come First Serve }:

\* Whichever Process comes 1<sup>st</sup> in R.Q will get CPU first.

\* In this, if one Process has longer BT. It will have major effect on average W.T of diff Processes, Called "Convoy effect".

↓  
 "It is a situation where many Processes, who needs to use a resource for a short time, are blocked by one Process holding that resource for a long time"

↳ This Cause for resource Management.

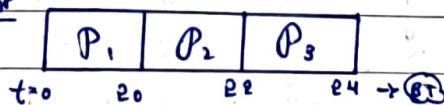
(Imp)

1] 

Process	AT	BT	CT	CT-AT TAT	CT-BT WT
P <sub>1</sub>	0	20	20	20	0
P <sub>2</sub>	1	2	22	21	19
P <sub>3</sub>	2	2	24	22	20

→ Avg: 13

② Gantt Chart



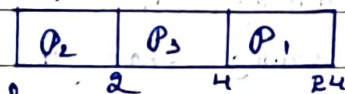
\* More avg W.T because P<sub>1</sub> has huge BT

2] 

Process	AT	BT	CT	TAT	WT
P <sub>2</sub>	0	2	2	2	0
P <sub>3</sub>	1	2	4	3	1
P <sub>1</sub>	2	20	24	22	2

→ Avg = 1

③ Gantt Chart



\* least avg time since P<sub>2</sub> is at last



## 2) Shortest Job First [SJF] :-

C>i) Non - Preemptive:

- \* Process with least B.T will be dispatched to CPU.
- \* Must do estimation of BT for each process in RQ beforehand, correct estimation of BT is an impossible task (ideally).
- \* Process Starvation may happen if 1<sup>st</sup> P has large BT

It will be 1<sup>st</sup> ←

P	AT	BT	CT	TAT	WT
P <sub>1</sub>	0	8	8	8	0
P <sub>2</sub>	1	4	12	11	7
P <sub>3</sub>	2	9	26	24	15
P <sub>4</sub>	3	5	17	14	9

→ Avg = 7.75

\* Gantt :-

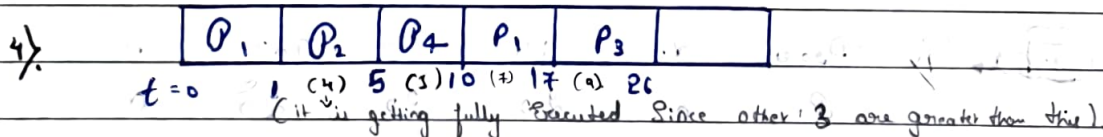


t=0 8 (4) 12 (8) 17 (9) 26

(all A, P, P<sub>4</sub> are scheduled)

Criteria for Selection: AT + BT.

C>ii) Preemptive SJF:-



				TAT	WT
P <sub>1</sub>	0	8	17	17	9
P <sub>2</sub>	1	4	5	4	0
P <sub>3</sub>	2	9	26	24	15
P <sub>4</sub>	3	5	10	27	2

→ Avg = 6.5

\* No Convex effect → Less Starvation.

\* Since even though P<sub>2</sub> is with more B.T; it is preempted.

\* Gives average W.T less for a given set of process as scheduling short job before a long one in W.T.

3 \*\*

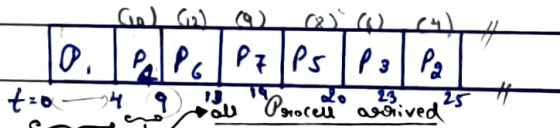
# Priority Scheduling: Assign Priority to each Job.

↳ Non-Preemptive.

- \* Priority is assigned to a Process when it is Created
- \* SJF is a Special Case of general Priority Scheduling with Priority Inversely Proportional to B.T.

5)

P	Priority	AT	BT	CT	TAT	WT	10 → high Priority
P <sub>1</sub>	2	0	4	4	4	0	
P <sub>2</sub>	4	1	2	25	24	22	
P <sub>3</sub>	6	2	3	23	22	19	
P <sub>4</sub>	10	3	5	9	06	1	
P <sub>5</sub>	8	4	1	20	16	15	
P <sub>6</sub>	12	5	4	13	8	4	
P <sub>7</sub>	9	6	6	19	13	7	→ 9.714



For Next Process, Since  $t=4$ ; All Process with AT 0-4 Come into action. → Select high Priority among them.

↳ Preemptive.

- \* Current Run State job will be Preempted if next job has higher Priority.

↳ drawback ∴ \* Huge Convoy effect.

\* Indefinite Waiting @ Extreme Starvation.

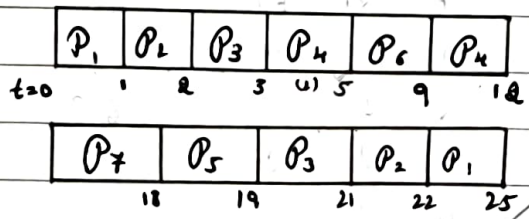
↳ Sol<sup>n</sup>: - Ageing → We gradually Inc the Priority of Lowest Job.

↳ Eg: Every 15 min → lowest Priority Job → Priority + 1 Inc.

6)

Priority AT BT CT

1	2	0	4	25
2	4	1	2	22
3	6	2	3	21
4	10	3	5	12
5	8	4	1	19
6	12	5	4	9
7	9	6	6	18

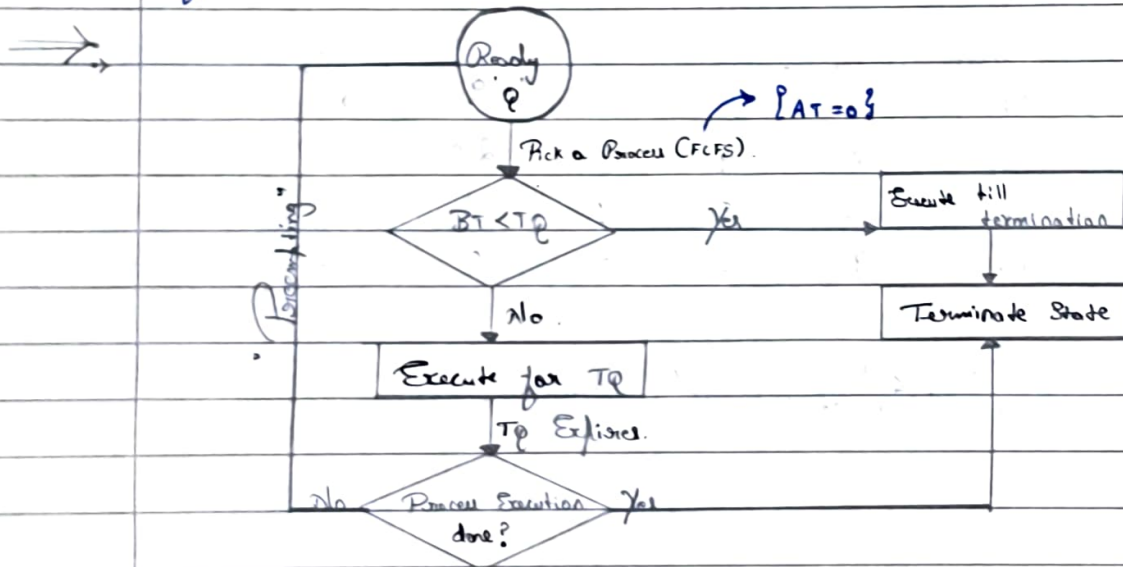


Avg = 11.4

- \* Round Robin → IBM 7094 at MIT → 1967 → 1973 (may Job of lower Priority didn't get CPU yet),

## 4★★> Round Robin Scheduling (RR)

- \* Most Popular & Like FCFS but Preemptive & Easy to implement.
- \* Designed for Time Sharing Systems
- \* Criteria:  $AT + \text{time Quantum } (T_q)$ , does not depend on BT.
- \* No Process is going to wait forever, hence very low starvation 'No Convey Effect'.
- \* If  $T_q$  is Small, more will be Context Switch (more overhead).



- \*> It is a CPU Scheduling algorithm where each Process is cyclically assigned a fixed time slot.
- \*> The Period of time for which a Process @ job is allowed to run in a Pre-emptive method is called "Time Quantum".

→  $T_q = 2s$

P	AT	BT	
1	0	4 <sup>2s</sup> end	
2	1	5 <sup>3s</sup> end	
3	2	2 <sup>0s</sup>	
4	3	1 <sup>0s</sup> end	
5	4	6 <sup>4s</sup> 2 end	
6	5	3 <sup>1s</sup> end	

$t=0$	$P_1$	$P_1$	$P_3$	$P_1$	$P_4$	$P_5$	$P_2$	$P_6$
2								
4								
6								
8								
9								
11								
13								
15								

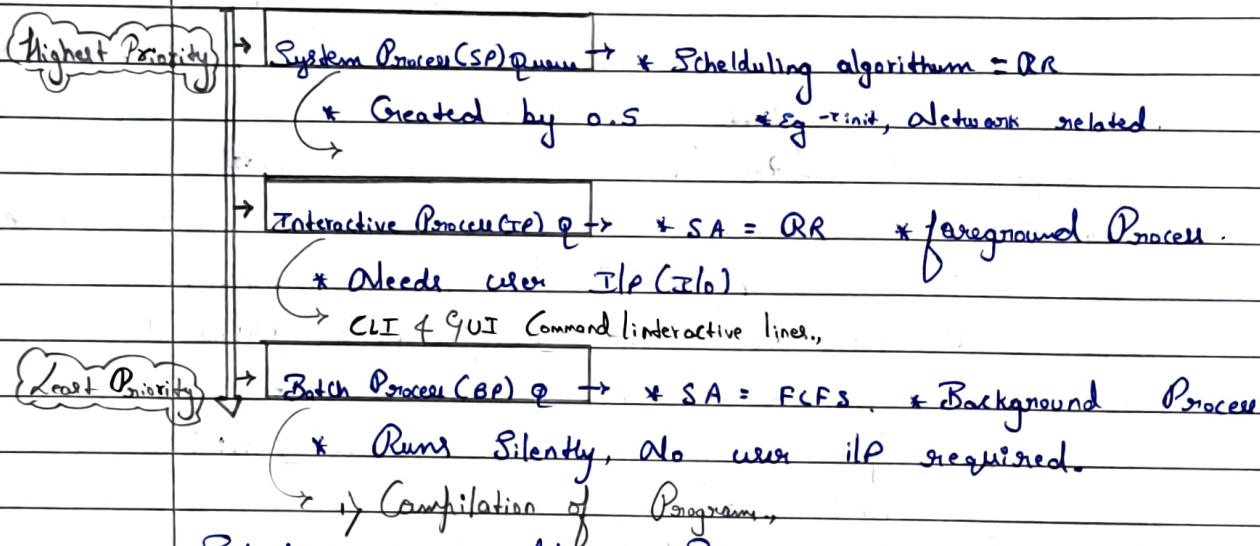
17	$P_5$	$P_2$	$P_6$	$P_5$				
18								
19								

Queue:  $P_1, P_2, P_3, P_4, P_5, P_6$



## \* Multi-Level Queue Scheduling [MLQ]:

- \* Ready  $q$  is divided into multiple queues depending upon Priority.
- \* A Process is Permanently assigned to one of the queues (inflexible) based on Some Property of Process, memory, Size, Process Priority or Process type.

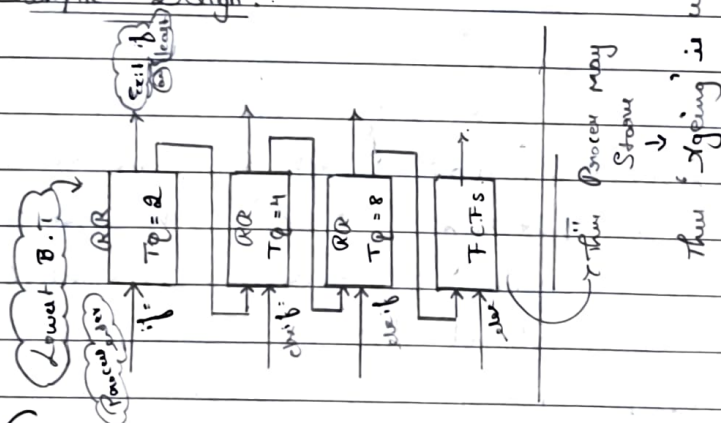


- \* Scheduling among different sub-queues is implemented as "fixed Priority Preemptive Scheduling" Eg  $\rightarrow$  F.P high Priority than B.P.
- \* If F.P comes & B.P is currently Executing  $\rightarrow$  then B.P will be Preempted.
- \* Problem: only after Completion of all the Processes from the top-level ready  $q$ , the further level Ready  $q$  will be Scheduled.
- \* This results in Starvation of lower Priority Process.
- \* Convoy effect is Present.

## \* Multi-level feedback queue Scheduling (MLFQ) :-

- \* Multiple Sub-queue are present (Inter q movement allowed).
- \* Allow the Process to move b/w queue. The idea is to Separate Processes according to the Characteristics of their BT. If a Process uses too much CPU time, it will be moved to lower Priority Queue. This Scheme leaves I/O bound and interactive Processes in the higher-Priority q.
- \* In addition, a Process that waits much in lower-priority queue may be moved to a higher Priority q. This form of 'ageing' Prevents Starvation.
- \* Less Starvation than MLQ.
- \* It is flexible
- \* Can be Configured to match a Specific System design requirement

### \* Sample Design:



- i) No. of q
- ii) Scheduling algorithm in each q
- iii) Method to upgrade process to higher q
- iv) Demote a Process to Lower Priority

### \* Comparison:

	<u>FCFS</u>	<u>SJF</u>	<u>PSJF</u>	<u>Priority</u>	<u>P Priority</u>	<u>RR</u>	<u>MLQ</u>	<u>MLFQ</u>
1) <u>Design</u> →	Simple	Complex	Complex	Complex	Complex	Simple	Complex	Complex
2) <u>Preemption</u> →	No	No	Yes	No	Yes	Yes	Yes	Yes
3) <u>Convey Effect</u> →	Yes	Yes	No	Yes	Yes	No	Yes	Yes
4) <u>overhead</u> →	No	No	Yes	No	Yes	Yes	Yes	Yes