DSP

Recap: -> Connection between LTI system's proporties & impulse response

-> Case-study.

"eigen"

Linear transformation System.

(defined by a matrix Anxn.

Eigen vector.

Eigen vector.

Eigen vector.

Eigen vector.

This eigen vector.

 $A = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$

 $\frac{1}{2} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ V, = / 1 7

 $A\bar{v_i} = \begin{bmatrix} 2\\0 \end{bmatrix} = 2\begin{bmatrix} 1\\0 \end{bmatrix}$

 $A\overline{v_2} = \left(\begin{array}{c} 1 \\ 1 \end{array} \right)$

The concept of Eigenvector com be extended to analyze the Eigen Segnence of discrete-time. LTI systems

$$\mathcal{X}(n) = a^n \qquad \qquad \mathcal{Y}(n)$$
Complex exponential

function.

$$y(n) = h(n) * x(n)$$

$$= \sum_{k=0}^{\infty} h(k) x(n-k)$$

$$= \sum_{k=1}^{\infty} h(k) a^{h-k}$$

$$= \left[\sum_{k=-\infty}^{\infty} h(k) a^{-k} \right] a^{n}$$

an: Eigen Segnence of LTI System

$$a^n \longrightarrow \lambda_{a'a}^n$$

$$a_i^n \longrightarrow \lambda_{a_i} \cdot a_i^n$$

$$a_2^n \rightarrow \lambda_{a_2} \cdot a_2^n$$

$$\begin{bmatrix} C_1 & a_1^n + C_2 a_2^n \end{bmatrix} \xrightarrow{T.} C_1 T \begin{bmatrix} a_1^n \end{bmatrix} + c_2 T \begin{bmatrix} a_2^n \end{bmatrix}$$

$$= C_1 \lambda a_1 a_1^n + C_2 \lambda a_2 a_2^n.$$

Now, let's consider • x(n) = an W-> rad (angle). => a = ejw. 1 2 plane ejwn unit-circle. $\rightarrow y(n) = ?$ h(n) $f(n) = \int_{-\infty}^{\infty} h(\kappa) e^{-j\omega \kappa} d\kappa$ / eigen value of e jiwn This is a polynomial in ela (power-series) Let's Considery define, H(eiw) = \(\sum_h(k)e^{-j\omega_k}\) By definition it would be called as Discrete-time Fourier Transform (DTFT). of h(n). h(n) $\stackrel{\text{DTFT}}{\longleftrightarrow} \stackrel{\times}{>} h \text{ (nre-jwn)}$ $h(t) \stackrel{CTFT}{\longleftrightarrow} \int h(t) e^{-j\Omega t} dt = H(e^{j\Omega}).$) Analog Signal SL ⇒ Andog freq Counterpast (rad/sec) W= 52 Theory W => Digital freq. (rad)