



Introduction

- Ultrasound Imaging is diagnostic Imaging technique using ultrasound waves
- It is used to visualise body structures like muscles, joints, vessels and internal organs such as heart, kidney etc.
- Structures like muscles, joints etc are imaged at a frequency around
 7-18 MHz
- Deeper structures such as liver and kidney are imaged at lower frequencies: 1-6 MHz

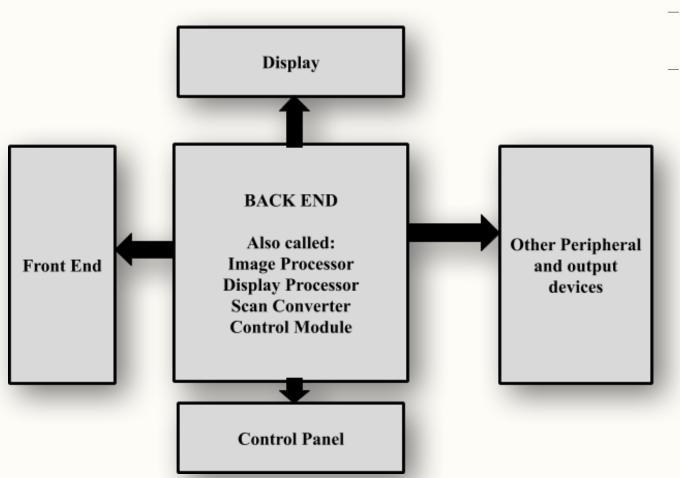
Principle



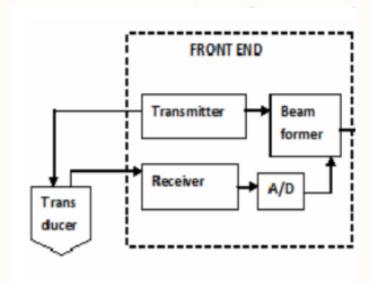
Ultrasound Image

- The Ultrasound wave travels into the body
- Some of the energy in the wave generates an echo due to reflection process
- Wave is reflected anywhere there are density changes in the body.
 Some of the reflections return to the transducer
- The return wave vibrates the transducer, which turns the vibrations into electrical pulses that travel to the ultrasonic scanner where they are processed and transformed into a digital image.
- The ultrasound image consists of a 2D representation of the echo pattern in a cross-section of tissue with the transducer position at the top of the image. The locations of echo-producing tissue interfaces are represented by bright pixels on a dark background.

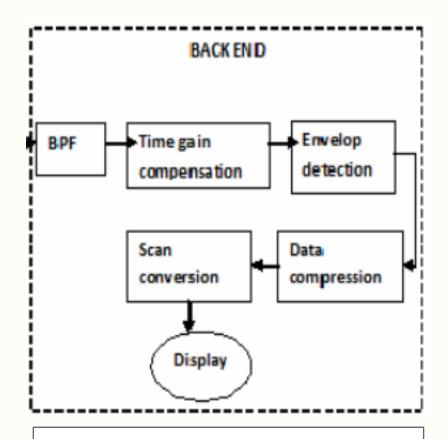
Block Diagram



- Front End System: It synchronises the generation of ultrasound waves
- Front End System consists of transducer, pulser i.e voltage generator for transducer, transmitter and receiver, A/D convertor etc.



Block Diagram



Components of Back End System

- Output of front end system is provided to Backend System
- Backend System: This part performs some signal processing to make the data fit the human eye perception.

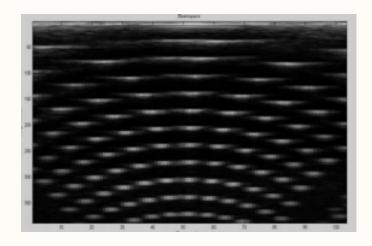


Image before Scan Conversion

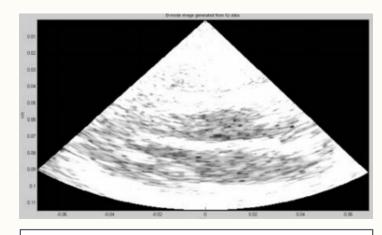
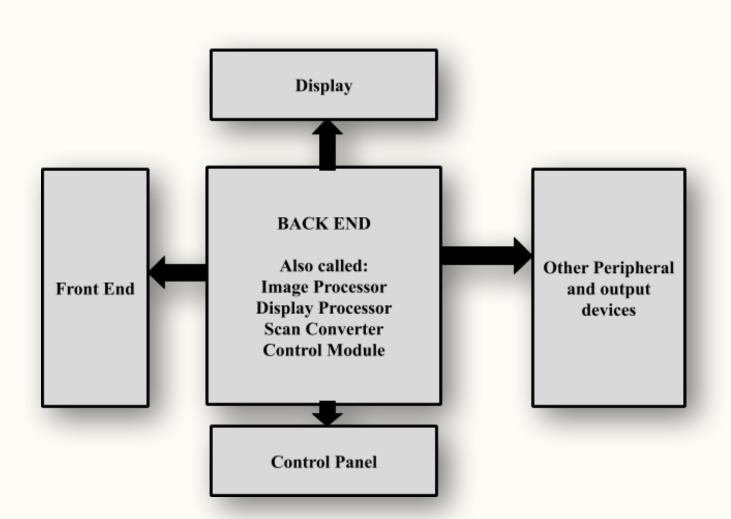
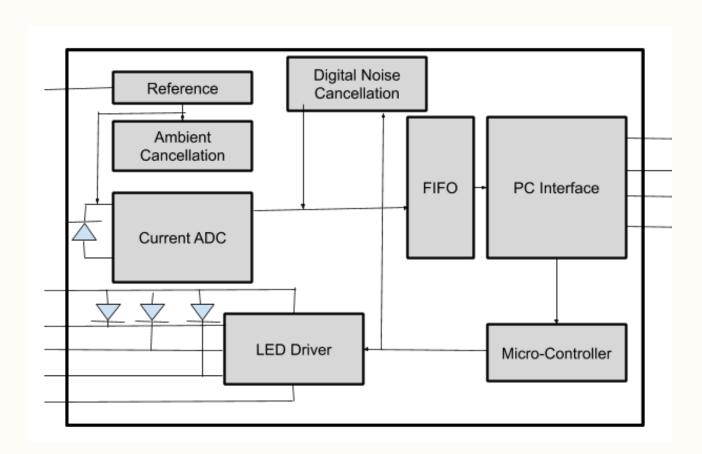


Image after Scan Conversion

Block Diagram



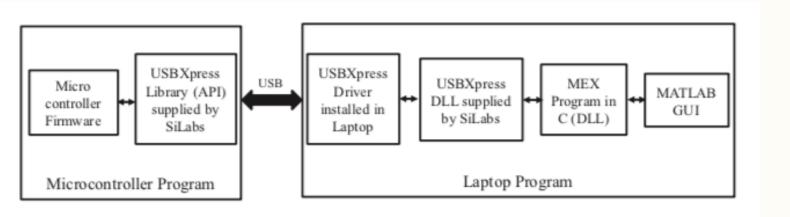
- Display (System monitoring): This system monitor is an RGB display monitor with an integrated microphone.
- Control Panel: It mainly consists of user input peripheral devices such as keyboard, trackball, microphone, foot switch, touch panels.
- Other Peripherals and Output devices: It includes printers, speakers networks and other ports.



Microcontroller:

- Many micro-controllers such as silicon lab's C8051F340 or STM32 can be used for ultrasound imaging applications.
- The image and video processing algorithms like smoothening, sharpening etc. are performed by interfacing MATLAB and the microcontroller.

Interfacing C8051F340 micro-controller:

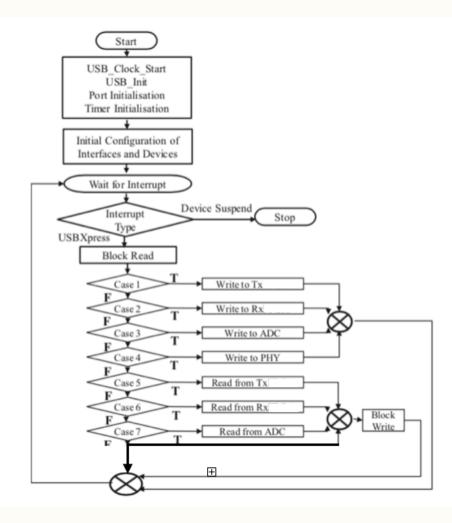


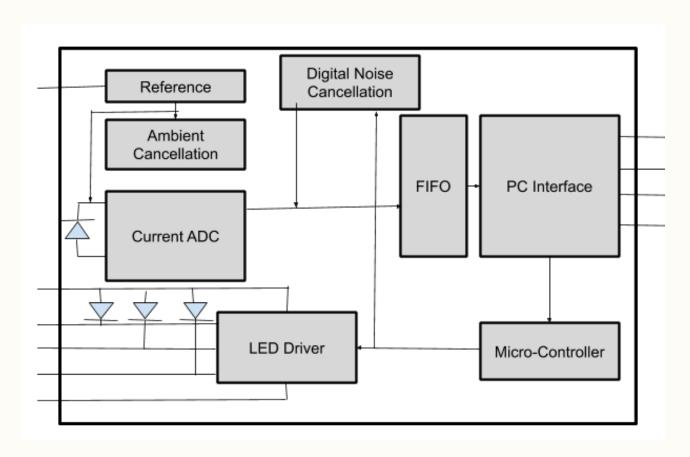
USB DLL interface functions.

Function name	Function
SI_GetNumDevices	Returns the number of devices connected
SI_GetProductString	Returns a descriptor for a device
SI_Open	Opens a device and returns a handle
SI_Close	Cancels pending IO and closes the device
SI_Read	Reads a block of data from the device
SI_Write	Writes a block of data to the device
SI_SetTimeouts	Sets read and write block timeout
SI_CheckRXQue ue	Gets the number of bytes in the device Rx Queue

USB API device interface functions.

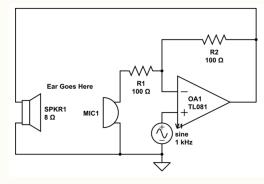
Function name	Function
USB_Clock_Start	Initializes the USB clock
USB_Init	Enables the USB interface
Block_Write	Writes a buffer of data to the host via USB
Block_Read	Reads a buffer of data from the host via USB
USB_Int_Enable	Enables API interrupts
USB_Disable	Disables USB interface
USB_Suspend	Suspends the USB interface

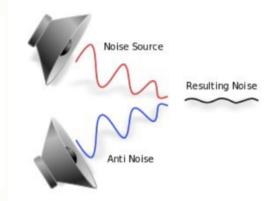


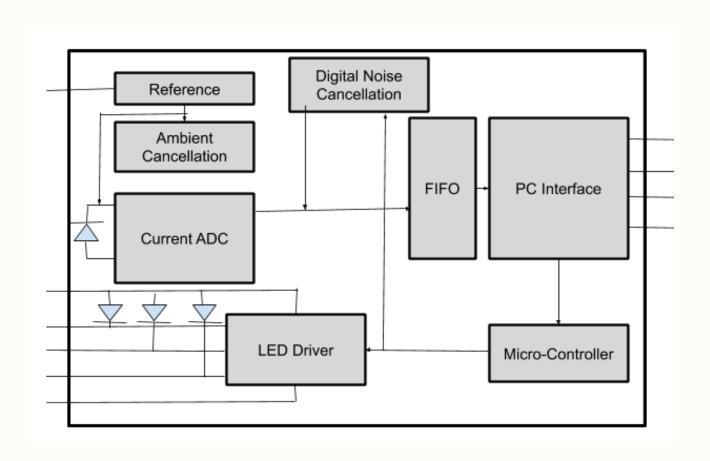


Ambient Cancellation:

- Cancels background noise
- It emits a sound wave with the same amplitude but with inverted phase to the original sound leading to destructive interference.
- It consists of various op-amps, resistors etc.







Digital Noise Cancellation:

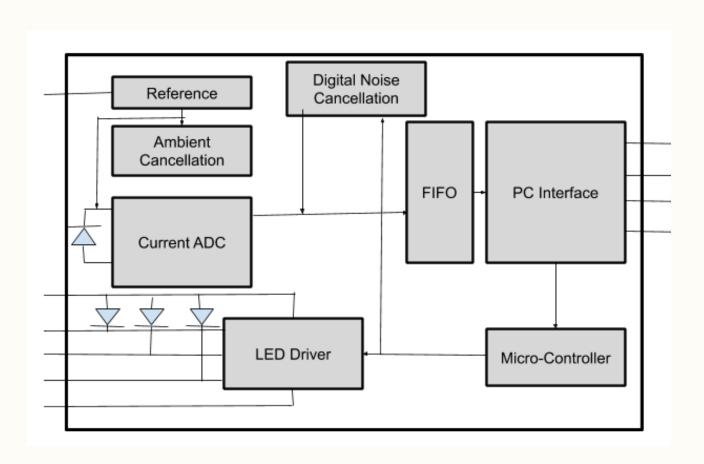
- Digital Noise: visual distortion
- It can be removed by convolving the original image with a mask that represents a low-pass filter.

Current ADC:

 It converts an input analog current to a digital number representing the magnitude of that current.

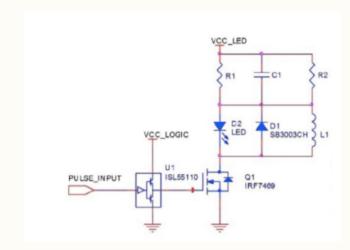
FIFO (First In First Out):

 It acts as intermediate storage when data arrives at the receiving subsystem at a high rate but can then only be processed slowly. The first data written into a FIFO is also the first to leave it at readout.



LED Driver:

 required to convert the alternating current from the power supply to the regulated voltage direct current used by the LEDs



PC Interface:

It acts as a central processing unit. It performs processing of image data



Diagnostic Applications

- In the field of obstetrics and gynaecology:
- Monitoring the baby for various procedures
- Measuring the size of the foetus
- In the field of Urology:
- Measuring blood flow through the kidney
- Locating kidney stones
- In the field of cardiology
- Seeing the inside of the heart to identify abnormal function
- Measuring blood flow through the heart and major blood vessels



Risks involved

The two major risks involved with Ultrasound are:

- Development of heat: Sometimes tissues or water absorb the ultrasound energy which increases their temperature locally, leading to development of heat.
- Formation of bubbles (cavitation): When dissolved gases come out of solution due to local heat caused by Ultrasound, bubbles are formed.

Benefits

- It images muscles and soft tissues very well.
- Ultrasound systems render live images where the most desirable section is selected.
- It shows the structure of organs.
- It has no long-term side-effects.
- It is widely available, comparatively flexible, relatively inexpensive and highly portable
- It's spatial resolution is better in high frequency ultrasound scanners.



Limitations

- Is Ultrasound Imaging devices have trouble penetrating bone.
- It performs very poorly when there is a gas between the transducer and organ of interest.
- Body habitus has a large influence on image quality.
- This method is operator-dependent.