

## Sumesh Thakur

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<b>PRINCIPAL INTERESTS</b>	Mesh Processing, Pointcloud Processing, 3D Computer Vision, Graph Neural Networks, Convolutions Neural Networks, Applied Machine Learning, Scientific Software Development, Computer Graphics, Research Management, Technical Writing.
<b>ACADEMIC BACKGROUND</b>	<div><div><i>M.Sc. Computer Science</i>2021</div><div><a href="#">Saint Mary's University</a>, Halifax, N<ul style="list-style-type: none"><li>M.Sc. thesis in machine learning under direction of Dr. <a href="#">Jiju Poovvancheri</a>. Dissertation title: Graph Attention Network for Point Cloud Processing.</li></ul></div></div> <div><div><i>B.Tech. Computer Science Engineering</i>2018</div><div><a href="#">Chandigarh Engineering College</a>, Mohali, PB<ul style="list-style-type: none"><li>Focus areas: Software Development, Computer Graphics</li></ul></div></div>
<b>EMPLOYMENT HISTORY</b>	<div><div><i>Machine Learning Developer</i>Jan, 2022 - Present</div><div><a href="#">Falkbuilt Inc.</a>, Calgary, AB<ul style="list-style-type: none"><li>Part of AI Research team</li><li>Working on developing a novel Graph Neural network for Indoor Mesh Processing.</li><li>Developed Mesh reconstruction tools using Trimesh and MongoDB library.</li><li>Developed data visualization tools for a huge indoor mesh dataset for exploratory data analysis.</li><li><b>Skills:</b> PyTorch, Autoencoder, CUDA, GNN, Mesh, C++, Deep Learning, Python</li></ul></div></div> <div><div><i>Perception Software Engineer (Intermediate-I)</i>July, 2021 - Jan, 2022</div><div><a href="#">JCA Technologies</a>, Winnipeg, MB<ul style="list-style-type: none"><li>Part of Perception team</li><li>Researched and developed perception based solutions for precision farming.</li><li>Developed Deep learning and Computer Vision algorithms for Point cloud processing and Image processing.</li><li>Deployed Machine learning models on Nvidia Jetson and JCA's Eagle platform.</li><li>Familiarized with Agile software development in Python, Modern C++, ROS 2 Foxy, Ubuntu 20.04</li><li>Developed software cycle composed of High-Level Design, Detailed Design, Implementation, Unit Test, Integration test.</li><li>Developing algorithms for Lidar and Camera based mapping, sensor fusion, simultaneous localization and mapping ( SLAM ), Computer Vision based visual Odometry.</li><li>Experienced software release process and testing procedures.</li></ul></div></div>

- **Skills:** Modern C++ , Sensor Fusion, Tensorflow, MLOps, TensorRT, OpenCV, Computer Vision, ROS/ROS, SLAM, PCL, Linux-Ubuntu (Bash), Git, Jira, Docker, Agile Software Release ( Scrum, Sprints, Demo ), Software Release Process

*Research Associate*

Dec, 2017 - April, 2019

[Barrierbreak Solutions](#), Mumbai, MH

- Part of R&D Team
- Lead the development of "6 by 6" android application, India's first currency detection application for visually impaired.
- Maintained and annotated a dataset of Indian currency dataset, consisting of 1,00,000 examples and 9 classes.
- Deployed InceptionNet based ML model on android mobile devices.
- Developed light detection and magnifier tools for "6by6" android application.
- Developed testing tools for accessibility testing.
- **Skills:** Android Development, Tensorflow, MLOps, JAVA, Computer Vision

## INTERNSHIP

*Research Scientist*

Sep, 2020 - Dec, 2020

[Nuance Communications](#), Montreal, QC

- Part of Central Research Team
- Researched and developed Sequence to Sequence model for automatic video subtitle generation.
- Developed Sequence-2-Sequence (CNN-LSTM) model for automatic video description for medical assistant and enhance patient-doctor interaction for DRAGON virtual assistant platform.
- Train and tested Seq2Seq model on TACOS Video data set corpus.
- Managed to get a benchmark score of 0.71 on BLEU and 0.47 on METEOR.

## PUBLICATIONS

- Thakur, Sumesh, Pandey, B. and Jiju Peethambran. "A GRAPH ATTENTION NETWORK FOR OBJECT DETECTION FROM RAW LIDAR DATA". **IEEE-IGARSS 2022**.
- Thakur, Sumesh, and Jiju Peethambran. "DYNAMIC EDGE WEIGHTS IN GRAPH NEURAL NETWORKS FOR 3D OBJECT DETECTION." **arXiv preprint** (2020).
- Pandey, B., S. Thakur, H. Joshi, A. Pradhanga, Y. Akiyama, and J. Peethambran. "TOWARDS VIDEO BASED COLLECTIVE MOTION ANALYSIS THROUGH SHAPE TRACKING AND MATCHING." **IET Electronics Letter** (2020).

## SCHOLARSHIPS AND AWARDS

- *MITACS Accelerate Funding* , MITACS & MODEST TREE, Jan. 2021 - Jul. 2021, **Valued at \$ 10,000 per semester**
- *FGSR Fellowship*, SAINT MARY'S UNIVERSITY, Apr. 2019 - Jul. 2021, **Valued at \$ 17,500 per year**
- *First Position, 3 Minute Thesis Competition*, SAINT MARY'S UNIVERSITY, Mar. 2020, **Won \$750 as winning prize, competing with 19 participants from master's and PhD program.**

## **SKILLS**

- **Programming:** Python, C++, C, JavaScript
- **DevOps:** Docker, CI/CD, Jenkins
- **MLOps:** MLFlow, Weights & Biases, Tensorflow Extended
- **Machine learning:** Tensorflow, Pytorch, Keras
- **Tools:** OpenCV, NumPy, Pandas, Flask, PyTest, Docker, Jenkins, Tensorflow Extended, ROS2, PCL, Open3D

## **EXTRA-CURRICULAR ACTIVITIES**

- Head Coordinator, E-Games, CGC Landran, 2019
- Volunteer, Blind School, Sector 26, Chandigarh
- Volunteer, Asha Kiran School for Disabled Kids, Hoshiarpur
- Member, TORCA, Mountain Biking Club