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Soln:- 1:- (a) Transformation functions for generating the individual bit-planes of a 4-bit monochromatic image:

for bit plane 1 :

$$f_1(x) = \begin{cases} 0 & \text{if } x \mod 2 == 0 \text{ (ie; } x \text{ is even)} \\ 1 & \text{otherwise} \end{cases}$$

for bit plane 2 :

$$f_2(x) = \begin{cases} 0 & \text{if } x \mod 4 == 1 \text{ or } x \mod 4 == 0 \\ 1 & \text{otherwise} \end{cases}$$

for bit plane 3 :

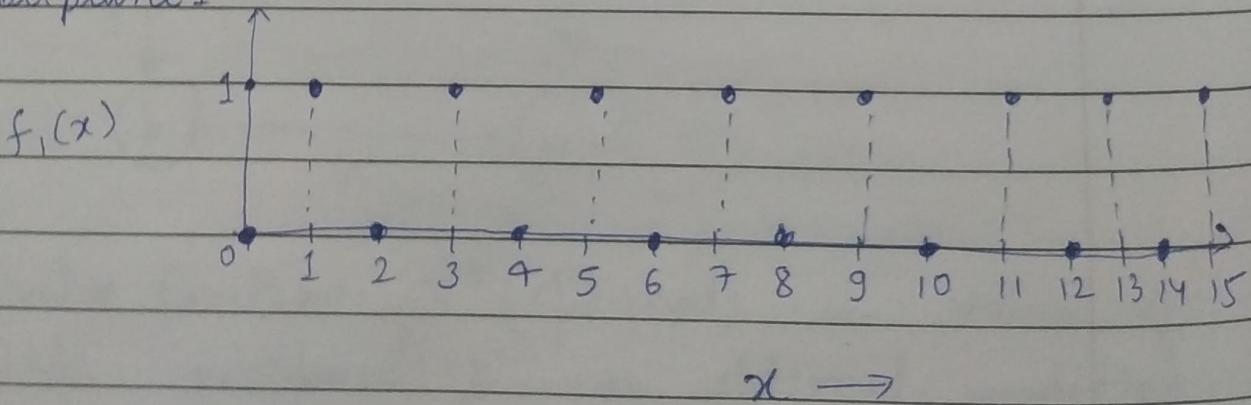
$$f_3(x) = \begin{cases} 0 & \text{if } x \mod 8 \leq 3 \\ 1 & \text{otherwise} \end{cases}$$

for bit plane 4 :

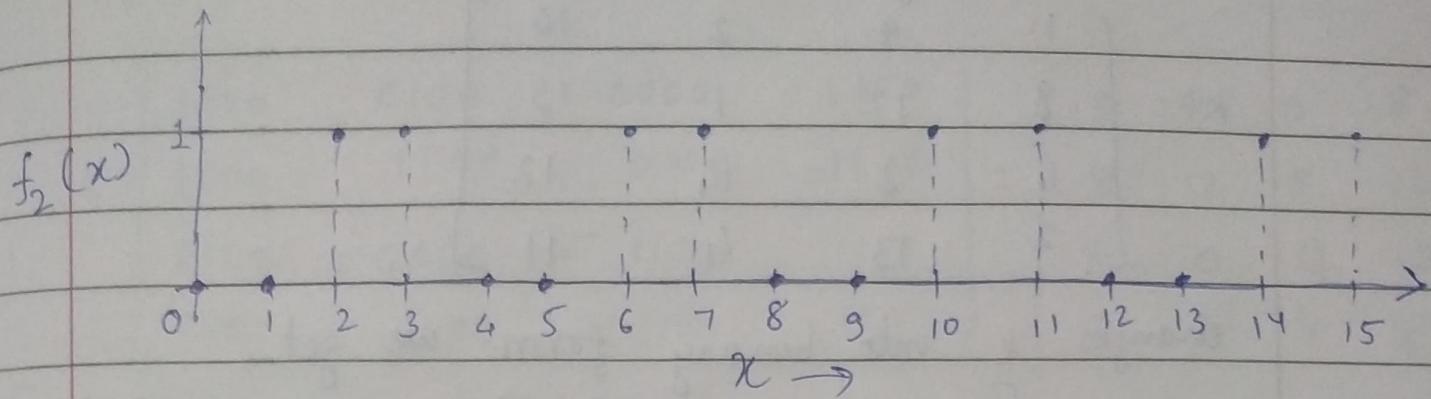
$$f_4(x) = \begin{cases} 1 & \text{if } x \geq 8 \\ 0 & \text{otherwise} \end{cases}$$

Plots for each bit-plane :-

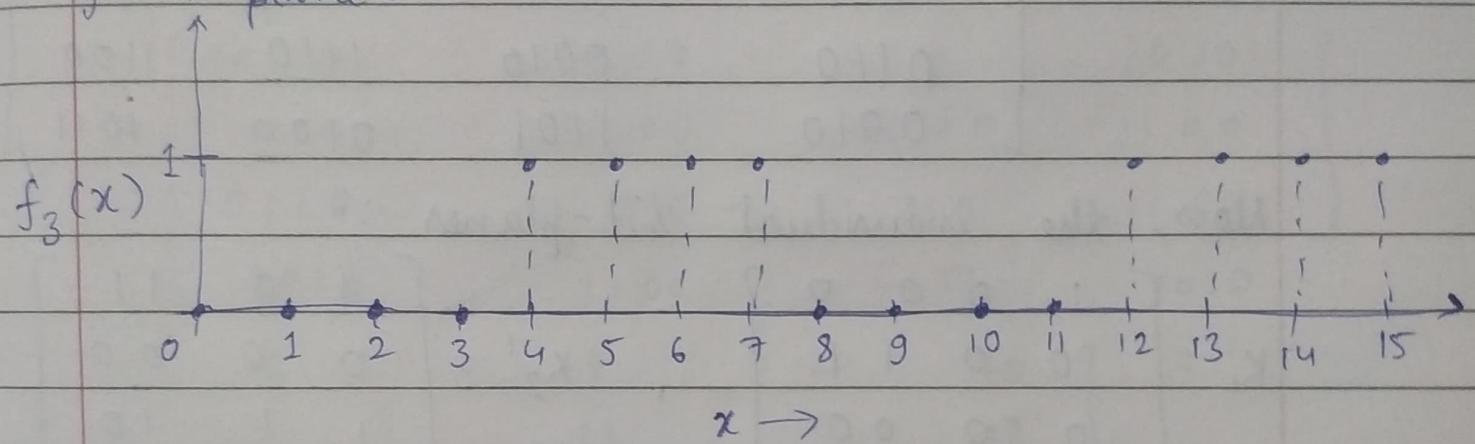
for bit plane 1 :



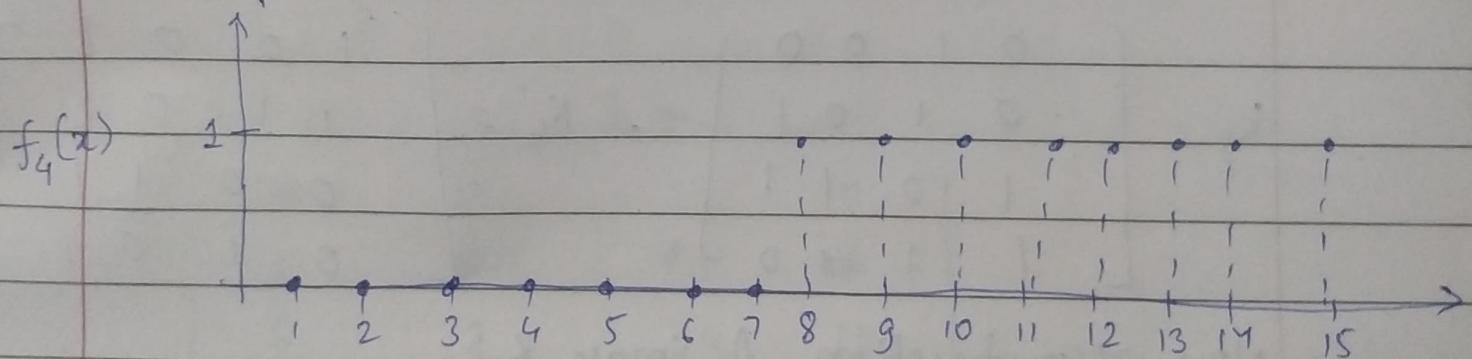
for bitplane 2 :-



for bitplane 3 :-



for bitplane 4 :-



(b) 4-bit gray level image K:

$$K = \begin{bmatrix} 11 & 4 & 2 & 10 \\ 8 & 12 & 1 & 13 \\ 6 & 2 & 14 & 12 \\ 2 & 13 & 4 & 11 \end{bmatrix}$$

changes K into binary form we get,

$$K' = \begin{bmatrix} 1011 & 0100 & 0010 & 1010 \\ 1000 & 1100 & 0001 & 1101 \\ 0110 & 0010 & 1110 & 1100 \\ 0010 & 1101 & 0100 & 1011 \end{bmatrix}$$

Now, the individual bit-planes :-

$$K'_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}, \quad K'_2 = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix}$$

$$K'_3 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}, \quad K'_4 = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$

Now, reconstruction of image K:

(i) bit-plane 4

$$K = \begin{bmatrix} 1000 & 0000 & 0000 & 1000 \\ 1000 & 1000 & 0000 & 1000 \\ 0000 & 0000 & 1000 & 1000 \\ 0000 & 1000 & 0000 & 1000 \end{bmatrix}$$

$$= \begin{bmatrix} 8 & 0 & 0 & 8 \\ 8 & 8 & 0 & 8 \\ 0 & 0 & 8 & 8 \\ 0 & 8 & 0 & 8 \end{bmatrix}$$

(ii) bit plane 3 and 4

$$K = \begin{bmatrix} 1000 & 0100 & 0000 & 1000 \\ 1000 & 1100 & 0000 & 1100 \\ 0100 & 0000 & 1100 & 1100 \\ 0000 & 1100 & 0100 & 1000 \end{bmatrix} = \begin{bmatrix} 8 & 4 & 0 & 8 \\ 8 & 12 & 0 & 12 \\ 4 & 0 & 12 & 12 \\ 0 & 12 & 4 & 8 \end{bmatrix}$$

(iii) bit plane 2, 3 and 4

$$K = \begin{bmatrix} 1010 & 0100 & 0010 & 1010 \\ 1000 & 1100 & 0000 & 1100 \\ 0110 & 0010 & 1110 & 1100 \\ 0010 & 1100 & 0100 & 1010 \end{bmatrix} = \begin{bmatrix} 10 & 4 & 2 & 10 \\ 8 & 12 & 0 & 12 \\ 6 & 2 & 14 & 12 \\ 2 & 12 & 4 & 10 \end{bmatrix}$$

(iv) bit-plane 1, 2, 3 & 4 :

$$K = \begin{bmatrix} 11 & 4 & 2 & 10 \\ 8 & 12 & 01 & 13 \\ 6 & 2 & 14 & 12 \\ 2 & 13 & 4 & 11 \end{bmatrix}$$

$$\text{Soln:- } 2:- \quad \therefore p_r(r) = 2 - \frac{2r}{3}$$

$$\& \quad p_z(z) = \frac{2z}{3}$$

\therefore Transformation (in terms of r & z):

$$\int_0^r p_r(r) dr = \int_0^z p_z(z) dz$$

$$\Rightarrow 2r - \frac{r^2}{3} = \frac{z^2}{3}$$

$$\Rightarrow z^2 = 6r - r^2$$

$$\Rightarrow r^2 - 6r = -z^2$$

$$\Rightarrow r^2 - 6r + 9 = 9 - z^2$$

$$\Rightarrow (r-3)^2 = (9-z^2)$$

$$\Rightarrow r-3 = -\sqrt{9-z^2}$$

$$\therefore \left\{ 0 \leq z, r \leq 3 \right\}$$

$$\Rightarrow r = 3 - \sqrt{9-z^2}$$

Soln:-

Soln:- 6 :- Advantages of gaussian filter :

→ uniform smoothing in all directions is achieved.

→ gaussian filter has advantages that its fourier transform is also a gaussian distribution centered around the zero frequency.

Advantages of box filter:-

→ It reduces the effect of smoothing on edges.

→ Simple and separable low pass filter.

Soln:- 7 :- We have to consider image $f(x, y)$ and spatial filter mask $w(x, y)$ using convolution.

∴ convolution is defined as

$$f(x, y) * w(x, y) = E_s = -a,$$

$$f(x, y) * w(x, y) = \sum_{s=-a}^a \sum_{t=-b}^b w(s, t) f(x-s, y-t)$$

where the dimensions of $w(x, y)$ is $(2a+1)(2b+1)$

∴ the elements of convolution array are formed

as the center the mark at particular pixel and then form the sum of products of mask

coefficients with corresponding pixels in the image. The mark traverse and convolution

operation is applied for each pixel in the image only once.

Now, if the coefficient of mark sum to zero

the sum of products of the coefficients with the same pixel also sum of to zero. Hence, for each pixel in image the sum of elements of convolution array sum to zero.

for ex :-

$$\omega(x, y) = [a \ b \ c] \text{ where } a+b+c=0$$

$$f(x, y) = [p \ q \ r \ s]$$

$$\therefore \text{zero padded square will be } f(x, y) = \begin{bmatrix} 0 & p & q & r & s & 0 \end{bmatrix}$$

\therefore convolution array,

$$f(x, y) * \omega(x, y) = [cp \ bp+cq \ ap+bg+cr \\ aq+br+cs \ ar+bs \ as]$$

\therefore add elements we get

$$p(a+b+c) + q(a+b+c) + r(a+b+c) + s(a+b+c)$$

$$\therefore a+b+c=0 \Rightarrow \text{above expression} = 0.$$

Qn:- 8:- Consider the horizontally & vertically.
 \therefore each mask yields a value = 0 when centered
 a pixel of an unbroken 3-pixel segment
 oriented in direction favoured by mask.

$$\therefore \text{horizontal} \rightarrow \begin{array}{|c|c|c|} \hline 0 & 0 & 0 \\ \hline -1 & -2 & 1 \\ \hline 0 & 0 & 0 \\ \hline \end{array}$$

$$\therefore \text{vertical} \rightarrow \begin{array}{|c|c|c|} \hline 0 & 1 & 0 \\ \hline 0 & -2 & 0 \\ \hline 0 & 1 & 0 \\ \hline \end{array}$$

Soln :- 4 :- (a) image 1 :-

$$P(r_0) = 2/64$$

$$P(r_5) = 16/64$$

$$P(r_1) = 2/64$$

$$P(r_6) = 12/64$$

$$P(r_2) = 2/64$$

$$P(r_7) = 8/64$$

$$P(r_3) = 8/64$$

$$P(r_8) = 1/64$$

$$P(r_4) = 12/64$$

$$P(r_9) = 1/64$$

Plot :-

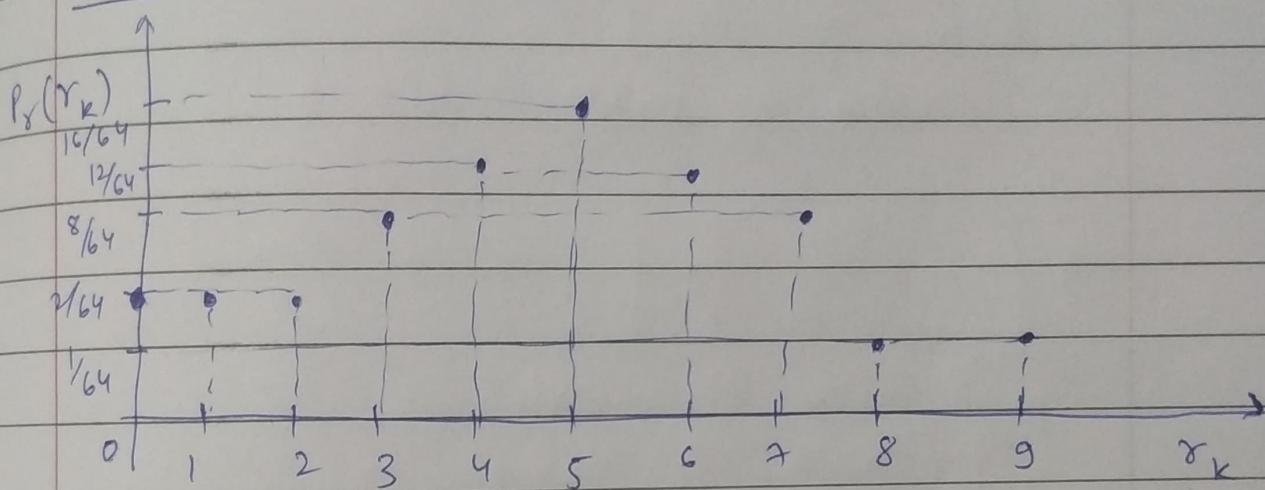


image 2 :-

$$P(r_0) = 1/64$$

$$P(r_5) = 1/64$$

$$P(r_1) = 1/64$$

$$P(r_6) = 10/64$$

$$P(r_2) = 1/64$$

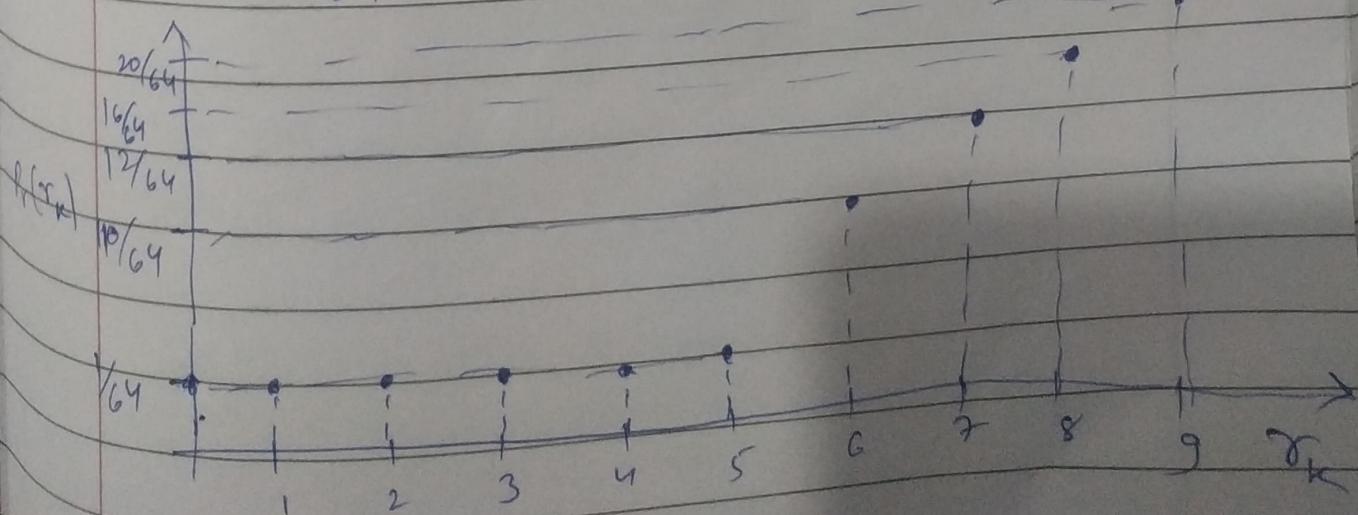
$$P(r_7) = 12/64$$

$$P(r_3) = 1/64$$

$$P(r_8) = 16/64$$

$$P(r_4) = 1/64$$

$$P(r_9) = 20/64$$



Soln:-

3: (a) for checker board pattern:

let the dark intensity be M & light intensity be 0.

$$B = \frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

for $\begin{bmatrix} M & 0 & M \\ 0 & M & 0 \\ M & 0 & M \end{bmatrix}$ as centre

$$\therefore \text{value of pixel} = 5M/9$$

\therefore for $\begin{bmatrix} 0 & M & 0 \\ M & 0 & M \\ 0 & M & 0 \end{bmatrix}$ \therefore its value = $\frac{4M}{9}$

\therefore pixel with M converted to $5M/9$

pixel with 0 converted to $4M/9$

(b) 3×3 median filter:-

$$\begin{bmatrix} M & 0 & M \\ 0 & M & 0 \\ M & 0 & M \end{bmatrix} \quad \therefore \text{median} = M$$

$$\begin{bmatrix} 0 & M & 0 \\ M & 0 & M \\ 0 & M & 0 \end{bmatrix} \quad \text{median} = 0$$

\therefore pixel with M converted to M
" " 0 " " 0

(c) Laplacian mask with center -8.

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -8 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\therefore \begin{bmatrix} M & 0 & M \\ 0 & M & 0 \\ M & 0 & M \end{bmatrix} \text{ value is } -8M + 4M = -4M$$

$$\begin{bmatrix} 0 & M & 0 \\ M & 0 & M \\ 0 & M & 0 \end{bmatrix} \text{ value is } 4M$$

\therefore pixel with M converted to $-4M$
pixel with 0 converts to $4M$

d) $\begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix}$

$$\therefore \begin{bmatrix} M & 0 & M \\ 0 & M & 0 \\ M & 0 & M \end{bmatrix} \Rightarrow \begin{aligned} \text{value} &= -M + M - M + M \\ &= 0 \end{aligned}$$

$$\begin{bmatrix} 0 & M & 0 \\ M & 0 & M \\ 0 & M & 0 \end{bmatrix} \Rightarrow \begin{aligned} \text{value} &= -2M + 2M \\ &= 0 \end{aligned}$$

\therefore M pixel converts to 0
0 pixel converts to 0.

(e) Similarly, vertical Sobel

M pixel converts to 0

0 pixel converts to 0

Symmetry)

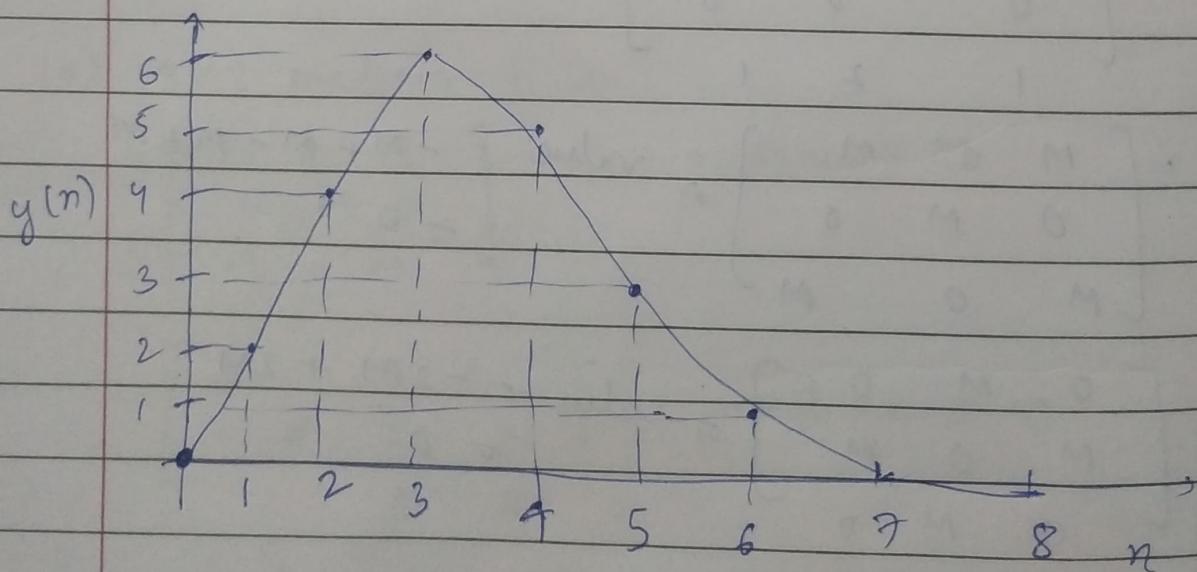
Solⁿ :- 5 :- consider $s(n)$ & $m(n)$ becomes

$$s(n) = [0, 1, 1, 1, 0]$$

$$m(n) = [2, 2, 2, 1, 0]$$

$$\therefore s(n) * m(n) = \sum_{k=-\infty}^{\infty} s(k) m(n-k)$$

$$\therefore y(n) = [0, 2, 4, 6, 5, 3, 1, 0, 0]$$



$$\text{S.I.M.: } 10; \epsilon(a) \quad \therefore k = \begin{bmatrix} 11 & 4 & 2 & 10 \\ 8 & 12 & 1 & 13 \\ 6 & 2 & 14 & 12 \\ 2 & 13 & 4 & 11 \end{bmatrix}$$

\therefore for 2D-DFT

$$F(u, v) = \sum_{x=0}^{m-1} \sum_{y=0}^{n-1} f(x, y) e^{-2\pi j \left(\frac{ux}{m} + \frac{vy}{n} \right)}$$

$$\therefore m = 4, n = 4$$

$$F(0, 0) = \sum_{x=0}^3 \sum_{y=0}^3 f(0, 0) e^{-2\pi j (0)}$$

$$= \sum_{x=0}^3 \sum_{y=0}^3 f(0, 0)$$

$$\Rightarrow F(0, 0) = 125.$$

(c) aliasing refers to the sampling phenomenon that cause different signals to becomes indistinguishable from one another after sampling.

Aliasing can be controlled & reduced by smoothing the imp. fn. to alternate its higher freq.

(d) finite duration discrete signal can be generated from indefinite duration discrete signal by passing the ~~indefinite~~ infinite duration discrete signal into low pass filter with cut off freq.