

LINEAR ALGEBRA

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SYSTEM OF LINEAR EQUATIONS:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

\vdots

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

m equations

n unknowns

Consider the four arrays:

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix},$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix},$$

$$b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

All of these arrays are examples of **MATRICES**.

The above system of equations can be expressed in matrix form as:

$$Ax = b$$

A : Coefficient matrix

x : vector of unknowns

b : right hand side vector

It is convenient to define Augmented matrix

$$[A|b] = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} & : & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & : & b_2 \\ \vdots & \vdots & \ddots & \vdots & : & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & : & b_m \end{bmatrix}$$

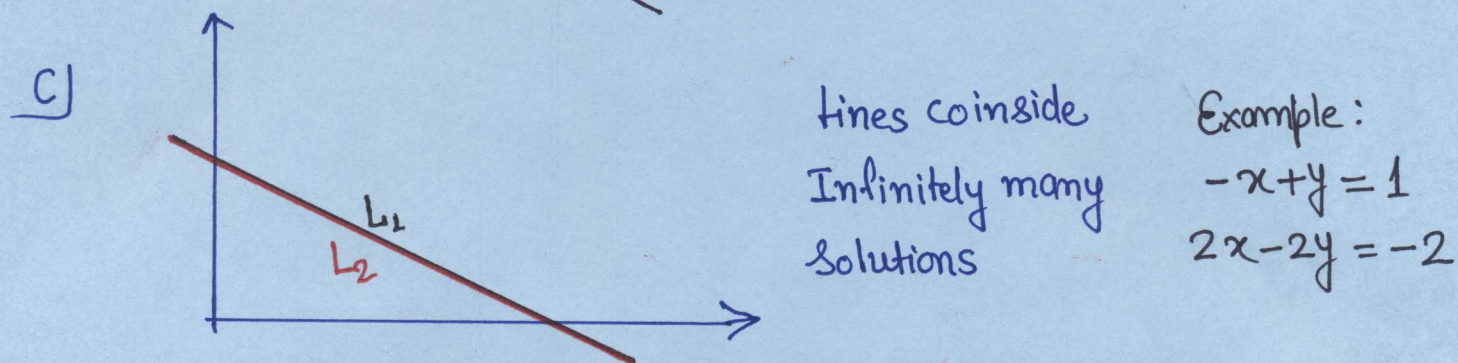
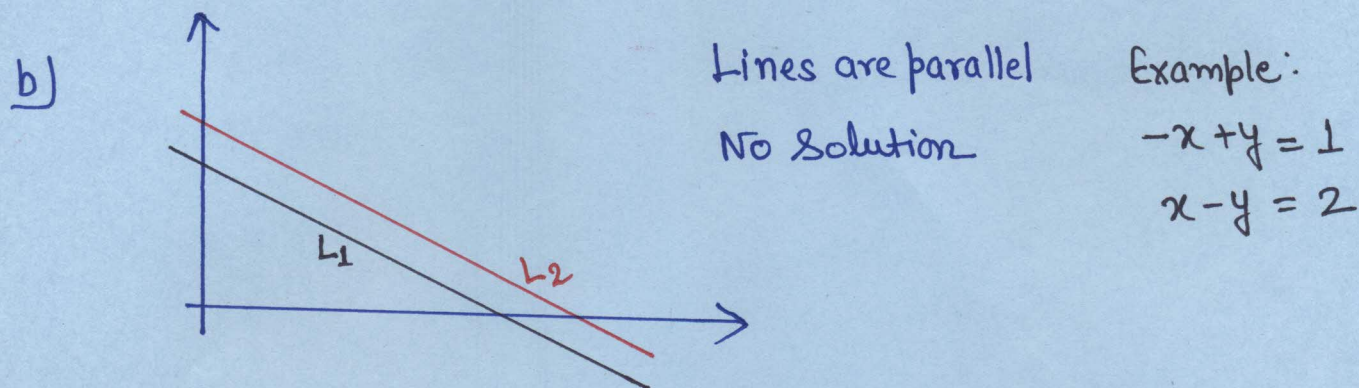
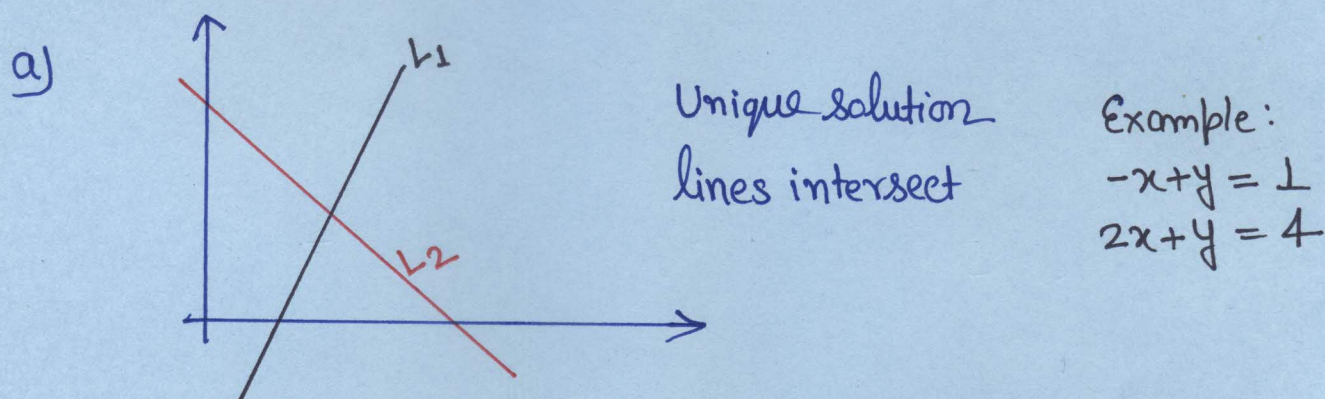
Def: A system of equations is **consistent** if it has at least one solution, and **inconsistent** if it has no solution.

SOLUTION OF SYSTEM OF LINEAR EQUATIONS:

Consider the system of two unknowns:

$$\left. \begin{array}{l} a_{11}x_1 + a_{12}x_2 = b_1 \\ a_{21}x_1 + a_{22}x_2 = b_2 \end{array} \right\} \text{ represent straight lines}$$

Possible cases of solution:



Similarly, case of 3 unknowns can be interpreted with the help of planes (hyperplanes)

SOLUTION METHODS:

- A) Method of determinants - Cramer's rule
 - B) Matrix inversion method, $Ax=b \Rightarrow x=A^{-1}b$
 - C) Gauss Elimination Method
 - D) Iterative Method - Jacobi & Gauss Seidel Method
- Direct Method (Exact solution)
 Approximate solution

GAUSS - ELIMINATION METHOD:

Consider

$$\begin{aligned} 6x + 4y &= 2 & \text{---(1)} \\ 3x - 5y &= -34 & \text{---(2)} \end{aligned}$$

STEP 1: Multiply eq. (1) by $\frac{1}{2}$ and subtract it from (2)

$$\begin{aligned} 6x + 4y &= 2 & \text{---(3)} \\ -7y &= -35 & \text{---(4)} \end{aligned}$$

STEP 2: Solution

$$y = 5$$

$$x = \frac{1}{6}(2 - 4 \times 5) = -3$$

Using augmented matrix

$$\left[\begin{array}{cc|c} 6 & 4 & 2 \\ 3 & -5 & -34 \end{array} \right] \quad \text{corresponding to (1) \& (2)}$$

$$R_2 \rightarrow R_2 - \frac{1}{2}R_1 : \left[\begin{array}{cc|c} 6 & 4 & 2 \\ 0 & -7 & -35 \end{array} \right] \quad \text{corresponding to (3) \& (4)}$$

← This is called Echelon form

In short: $[A|b] \xrightarrow[\text{Elimination}]{\text{Gauss}} [A'|b'] \leftarrow \text{Echelon form}$

Back substitution : $y = 5, x = -3.$

ELEMENTARY ROW OPERATIONS OR TRANSFORMATIONS FOR MATRICES

1. Interchange of i th and j th rows $R_i \leftrightarrow R_j$
2. Multiplication of the i th row by a non-zero number λ ,

$$R_i \rightarrow \lambda R_i$$

3. Addition of λ times the j th row to the i th row

$$R_i \rightarrow R_i + \lambda R_j$$

EQUIVALANCE OF MATRICES

If B be $m \times n$ matrix obtained from $m \times n$ matrix A by finite number of elementary transformations of A , then A is called equivalent to B , denoted by $A \sim B$ (A is equivalent to B).

PROPERTIES OF AN EQUIVALANCE RELATION \sim

- (i) Reflexivity $A \sim A$
- (ii) Symmetry: if $A \sim B$ then $B \sim A$
- (iii) Transitivity: If $A \sim B$, $B \sim C$ then $A \sim C$