

Lecture 17

Theorem:— Let A be any $n \times n$ matrix. Then

the induced 2-norm of A is

$$\|A\|_2 = \max_j (\lambda_j(A^*A))^{1/2}$$

where $\lambda_j(A^*A)$ are the eigenvalues of A^*A .

proof:

$$\|A\|_2 = \max_{\substack{x \in \mathbb{C}^n \\ \text{such that} \\ \|x\|_2 = 1}} (\|Ax\|_2)$$

$$= \max_{\|x\|_2 = 1} \sqrt{\langle Ax, Ax \rangle} \quad \text{— standard inner product.}$$

$$= \max_{\|x\|_2 = 1} \sqrt{\langle A^*Ax, x \rangle} \quad \left(\because \langle x, Ay \rangle = \langle A^*x, y \rangle \right)$$

$$= \sqrt{\max_{\|x\|_2 = 1} \langle A^*Ax, x \rangle}$$

$$= \sqrt{\max_{\substack{x \neq 0 \\ n \in \mathbb{C}^n}} \frac{\langle A^*Ax, x \rangle}{\langle x, x \rangle}}$$

$$= \sqrt{\max_j \lambda_j(A^*A)} \quad \left(\text{by Rayleigh quotient thm} \right)$$

$$= \max_j \sqrt{\lambda_j(A^*A)}$$

Theorem:- Suppose $A_{n \times n}$ is an invertible matrix. Then $\|A^{-1}\| = \frac{1}{\min_{\|x\|=1} (\|Ax\|)}$

proof:-

$$\text{Let } Ax = y$$

$$\Rightarrow x = A^{-1}y$$

Now

$$\min_{\|x\|=1} \|Ax\| = \min_{\substack{x \neq 0 \\ \text{in } \mathbb{C}^n}} \left(\frac{\|Ax\|}{\|x\|} \right)$$

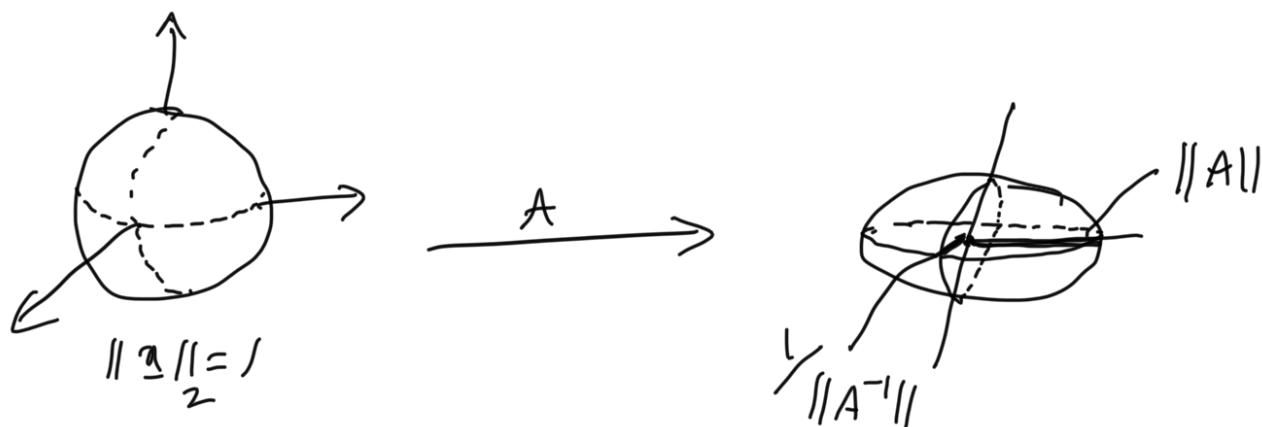
$$= \min_{\substack{y \neq 0 \\ \text{in } \mathbb{C}^n}} \left(\frac{\|y\|}{\|A^{-1}y\|} \right)$$

$$= \min_{\substack{y \neq 0 \\ \text{in } \mathbb{C}^n}} \left(\frac{1}{\left(\frac{\|A^{-1}y\|}{\|y\|} \right)} \right)$$

$$= \frac{1}{\max_{\substack{y \neq 0 \\ \text{in } \mathbb{C}^n}} \left(\frac{\|A^{-1}y\|}{\|y\|} \right)}$$

$$= \frac{1}{\|A^{-1}\|}$$

$$\Rightarrow \|A^{-1}\| = \frac{1}{\min_{\|x\|=1} (\|Ax\|)}$$



An induced $\|A\|$ represents the maximum extend to which a vector on the unit sphere can be stretched by A & $\frac{1}{\|A^{-1}\|}$ measures the extend to which a non-singular matrix A^{-1} can be shrink vectors on the unit sphere

Decomposition of matrices.

- QR-decomposition.
- Cholesky decomposition
- Singular value decomposition.

Def:- Householder transformation:-

Let $\underline{w} \in \mathbb{C}^n$ be a unit vector.

i.e., $\|\underline{w}\| = 1$. Throughout $\|\cdot\|$ is the vector 2-norm

$$\text{ie } \|\underline{w}\| = \sqrt{|w_1|^2 + \dots + |w_n|^2}$$

A matrix $P_{n \times n}$ over \mathbb{C} of the form

$$P = I - 2 \frac{\underline{w} \underline{w}^*}{\|\underline{w}\|^2},$$

is called a Householder transformation.

Note that $\frac{\underline{w}^* \underline{w}}{\|\underline{w}\|^2} = \|\underline{w}\|^2 = 1$

Other names: elementary Hermitian matrix
or elementary reflector.

Properties

① P is a Hermitian matrix.

i.e., $P^* = P$.

Proof:-

$$\begin{aligned} P^* &= (I - 2 \frac{\underline{w} \underline{w}^*}{\|\underline{w}\|^2})^* \\ &= I^* - 2 (\frac{\underline{w} \underline{w}^*}{\|\underline{w}\|^2})^* \\ &= I - 2 \frac{(\underline{w}^*)^* \underline{w}^*}{\|\underline{w}\|^2} \end{aligned}$$

$$= I - 2 \underline{\omega} \underline{\omega}^*$$

$$= P.$$

② P is unitary. i.e., $P^*P = PP^* = I$.

proof:-

$$P^*P = PP = (I - 2\underline{\omega}\underline{\omega}^*)(I - 2\underline{\omega}\underline{\omega}^*)$$

$$= I - 2\underline{\omega}\underline{\omega}^* - 2\underline{\omega}\underline{\omega}^* + 4(\underline{\omega}\underline{\omega}^*)(\underline{\omega}\underline{\omega}^*)$$

$$= I - 4\underline{\omega}\underline{\omega}^* + 4\underline{\omega}(\underline{\omega}^*\underline{\omega})\underline{\omega}^*$$

$$= I - 4\underline{\omega}\underline{\omega}^* + 4\underline{\omega}(1)\underline{\omega}^*$$

$$= I - 4\cancel{\underline{\omega}}\underline{\omega}^* + 4\cancel{\underline{\omega}}\underline{\omega}^*$$

$$= I.$$

③ $P^2 = I \Rightarrow P$ is involutory.

④ $\|x\| = \|Px\| \quad \forall x \in \mathbb{C}^n$.

proof:-

$$\|Px\|^2 = \langle Px, Px \rangle$$

$$= (Px)^*(Px)$$

$$= x^* P^* P x$$

$$= x^* I x$$

$$= \|x\|^2$$

$$\Rightarrow \|Px\| = \|x\|.$$

Theorem!— Given a non-zero vector $\underline{x} = (x_1, \dots, x_n)$ in \mathbb{R}^n (or in \mathbb{C}^n), there exists a householder transformation $P = I - 2\underline{\omega}\underline{\omega}^*$ of size n for some $\underline{\omega} \in \mathbb{R}^n$, $\underline{\omega}^*\underline{\omega} = 1$, such that

$$P\underline{x} = \alpha \underline{e}_1 \quad \text{for some } \alpha \in \mathbb{R}$$

$$\& \quad \underline{e}_1 = (1, 0, \dots, 0) \in \mathbb{R}^n.$$

proof:— Let $m = \|\underline{x}\| = \sqrt{|x_1|^2 + \dots + |x_n|^2}$

we need to find a unit vector $\underline{\omega}$ satisfying all the conditions of the thm.

$$\text{Now} \quad \|\underline{x}\|^2 = \|P\underline{x}\|^2 = \|\alpha \underline{e}_1\|^2 = |\alpha|^2 \|\underline{e}_1\|^2 = |\alpha|^2$$

$$\Rightarrow m^2 = |\alpha|^2$$

$$\Rightarrow \boxed{\alpha = \pm m = \pm \|\underline{x}\|}$$

$$\text{Let } \underline{\omega} = \begin{pmatrix} \omega_1 \\ \vdots \\ \omega_n \end{pmatrix} \& P = I - 2 \underline{\omega}\underline{\omega}^*.$$

$$\text{Now } P\underline{x} = \alpha \underline{e}_1$$

$$\Rightarrow (I - 2\underline{\omega}\underline{\omega}^*)\underline{x} = \alpha \underline{e}_1.$$

$$\Rightarrow \underline{x} - 2 \underbrace{\underline{\omega}\underline{\omega}^*}_{\substack{1 \times n \\ n \times 1}} \underline{x} = \pm m \underline{e}_1.$$

$$\Rightarrow \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} - 2 \begin{pmatrix} \omega_1 \underline{\omega}^* \underline{x} \\ \omega_2 \underline{\omega}^* \underline{x} \\ \vdots \\ \omega_n \underline{\omega}^* \underline{x} \end{pmatrix} = \begin{pmatrix} \pm m \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} x_1 - 2\omega_1 \underline{\omega}^* \underline{x} \\ x_2 - 2\omega_2 \underline{\omega}^* \underline{x} \\ \vdots \\ x_n - 2\omega_n \underline{\omega}^* \underline{x} \end{pmatrix} = \begin{pmatrix} \pm m \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\Rightarrow \boxed{\begin{array}{l} x_1 - 2\omega_1 \underline{\omega}^* \underline{x} = \pm m \\ x_j - 2\omega_j \underline{\omega}^* \underline{x} = 0 \quad \forall j = 2, \dots, n. \end{array}}$$

let $q = \underline{\omega}^* \underline{x}$.

Then

$$\left. \begin{array}{l} x_1 = \pm m + 2\omega_1 q \\ 2\omega_j q = x_j \quad \forall j = 2, \dots, n. \end{array} \right\} \rightarrow \textcircled{*}$$

$$\Rightarrow \omega_j = \frac{x_j}{2q} \quad \forall j = 2, 3, \dots, n.$$

Now $\|\underline{\omega}\| = 1 \Rightarrow \omega_1^2 + \dots + \omega_n^2 = 1$

$$\Rightarrow \left(\frac{x_1 \mp m}{2q} \right)^2 + \frac{x_2^2}{4q^2} + \dots + \frac{x_n^2}{4q^2} = 1$$

(from $\textcircled{*}$)

$$\Rightarrow (x_1 \mp m)^2 + x_2^2 + \dots + x_n^2 = 4q^2$$

$$\Rightarrow x_1^2 \mp 2mx_1 + m^2 + x_2^2 + \dots + x_n^2 = 4q^2$$

$$\Rightarrow \mp 2mx_1 + m^2 + m^2 = 4q^2$$

$$\Rightarrow \boxed{4q^2 = 2m(m \mp x_1)}$$

Among the two values admissible for $2q^2$ choose the largest one for numerical stability.

i.e.,

$$\boxed{2q^2 = m(m + \text{sign}(x_1)x_1)}$$

where

$$\text{sign}(x_1) = \begin{cases} 1 & \text{if } x_1 \geq 0 \\ -1 & \text{if } x_1 < 0. \end{cases}$$

$$\begin{aligned} \therefore \underline{w} &= \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix} = \begin{pmatrix} \frac{x_1 \mp m}{2q} \\ x_2/2q \\ \vdots \\ x_n/2q \end{pmatrix} \\ &= \frac{1}{2q} \begin{pmatrix} x_1 \mp m \\ x_2 \\ \vdots \\ x_n \end{pmatrix}. \end{aligned}$$

$$\text{let } \underline{u} = \begin{pmatrix} x_1 \mp m \\ x_2 \\ \vdots \\ x_n \end{pmatrix}.$$

$$\underline{w} = \frac{1}{2q} \underline{u}.$$

$$\text{Thus } P = I - 2 \underline{w} \underline{w}^T$$

$$= I - \frac{2}{4q^2} \underline{u} \underline{u}^T$$

$$\boxed{P = I - \frac{1}{2q^2} \underline{u} \underline{u}^T}$$

$$, m = \|\underline{x}\|$$

$$\text{where } \underline{u} = \begin{pmatrix} x_1 \mp m \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

&

$$2q^2 = m(m + \text{sign}(x_1)x_1)$$

$$\alpha = \pm m = -\text{sign}(x_1) \|\underline{x}\|$$

check that $P\underline{x} = \alpha \underline{e}_1$.
