

$$\rho(AA^T) = \rho(A)$$

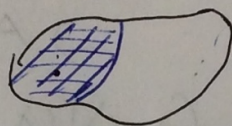
Part I $\rho(AA^T) \subseteq \rho(A)$ (for property 2)

Part II To show $\rho(A) \subseteq \rho(AA^T)$ ✓

$$\left\{ \begin{array}{l} \text{Let } \underline{z} \in [\rho(AA^T)]^\perp \\ \Leftrightarrow \underline{z}^T(AA^T) = \underline{0}^T \end{array} \right.$$

$$\Rightarrow \underline{z}^T(AA^T)\underline{z} = \underline{0}^T \underline{z}$$

$$\Rightarrow (A^T \underline{z})^T (A^T \underline{z}) = 0$$



$$\Rightarrow A^T \underline{z} = \underline{0}$$

$$\left\{ \begin{array}{l} \Rightarrow \underline{z}^T A = \underline{0}^T \\ \Leftrightarrow \underline{z} \in (\rho(A))^\perp \end{array} \right.$$

$$\Rightarrow (\rho(AA^T))^\perp \subseteq (\rho(A))^\perp$$

$$\Leftrightarrow \underline{\rho(A)} \subseteq \underline{\rho(AA^T)} \text{ (proved)}$$

$$\begin{aligned} & \frac{1}{n} \left[\sum_{i=1}^n (x_i - \bar{x})^2 \right] \\ &= \frac{1}{n} \left[\sum_{i=1}^n (x_i^2 - 2x_i\bar{x} + \bar{x}^2) \right] \\ &= \frac{1}{n} \left[\sum_{i=1}^n x_i^2 - 2\bar{x} \left(\sum_{i=1}^n x_i \right) + n\bar{x}^2 \right] \\ &= \frac{1}{n} \left[\sum_{i=1}^n x_i^2 - 2\bar{x} (n\bar{x}) + n\bar{x}^2 \right] \\ &= \frac{1}{n} \left[\sum_{i=1}^n x_i^2 - n\bar{x}^2 \right] \\ &= \frac{1}{n} \sum x_i^2 - \bar{x}^2 \end{aligned}$$

$$\sum x_i = n\bar{x}$$

1. Express sample mean $\frac{1}{n} \sum_{i=1}^n x_i$ in vector notation:

$$\bar{X} = \left(\frac{1}{n} \quad \frac{1}{n} \quad \dots \quad \frac{1}{n} \right) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \frac{1}{n} \underline{1}^T \underline{X}$$

$$\underline{1} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$$

Vector dot product

2. Express sample variance $\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$ in vector notation:

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2 &= \frac{1}{n} \left(\sum x_i^2 \right) - \bar{x}^2 = \frac{1}{n} \underline{X}^T \underline{X} - \frac{1}{n^2} (\underline{1}^T \underline{X})^2 \\ &= \frac{1}{n} (\underline{X}^T \underline{I}_n \underline{X}) - \frac{1}{n^2} [\underline{X}^T \underline{1} \underline{1}^T \underline{X}] \\ &= \frac{1}{n} \left[\underline{X}^T \underline{I}_n \underline{X} - \underline{X}^T \left(\frac{1}{n} \underline{1} \underline{1}^T \right) \underline{X} \right] \\ &= \frac{1}{n} \underline{X}^T \left(\underline{I}_n - \frac{1}{n} \underline{1} \underline{1}^T \right) \underline{X} \end{aligned}$$

Quadratic form.

$$\underline{1}^T \underline{1} = n$$

Is $\left(\underline{I}_n - \frac{1}{n} \underline{1} \underline{1}^T \right)$ an idempotent matrix? YES

3. Consider $f_1(x) = 1$, $f_2(x) = x-2$, $f_3(x) = (x-2)^2$

Does $\{f_1(x), f_2(x), f_3(x)\}$ construct a basis

of \mathbb{P}_2 ?

$$f_1(x) = 1 = (1 \ 0 \ 0) \begin{pmatrix} x^0 \\ x^1 \\ x^2 \end{pmatrix} \quad f_3(x) = (x-2)^2 = x^2 - 4x + 4 = (4 \ -4 \ 1) \begin{pmatrix} x^0 \\ x^1 \\ x^2 \end{pmatrix}$$

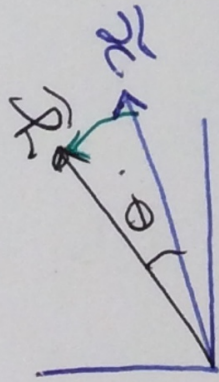
$$f_2(x) = x-2 = (-2 \ 1 \ 0) \begin{pmatrix} x^0 \\ x^1 \\ x^2 \end{pmatrix} \quad \mathcal{C} \begin{pmatrix} 1 & -2 & 4 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \end{pmatrix} = \mathbb{R}^3 = \text{sp} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 4 \\ -4 \\ 1 \end{pmatrix} \right\} \equiv \mathbb{P}_2$$

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$$\underline{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\underline{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

what is the relation between $(x_1^2 + x_2^2)$ and $(y_1^2 + y_2^2)$?



$$\underline{y} = A \underline{x}$$

A is orthogonal matrix.

$$\Rightarrow A^T A = I.$$

$$\begin{aligned} \underline{\underline{\sum y_i^2}} &= \underline{\underline{y^T y}} = (A x)^T (A x) = x^T (A^T A) x = x^T I x \\ &= x^T x = \underline{\underline{\sum x_i^2}}. \end{aligned}$$

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