Ex. Determine the characteristic roots and the characteristic vectors of the matrix:

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 4 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

eigenvalues $\gamma = 2, 2, 3$.

Noti: eigenvalues of a triangular matrix are its diagonal elements.

ergenspace of $\lambda=2$:

$$\begin{bmatrix} 0 & 0 & 0 \\ 4 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \chi_3 = 0, \quad \chi_1 = 6, \quad \chi_2 = \infty.$$

eigenvector
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
.

Geometric multiplicity of $\lambda=2$: 1

Algebraic " $\lambda = 2$: 2

Eigenspace of
$$\lambda = 3$$
:
$$\begin{bmatrix}
-1 & 0 & 0 \\
4 & -1 & 0 \\
0 & 0 & 0
\end{bmatrix}
\begin{bmatrix}
\chi_1 \\
\chi_2 \\
\chi_3
\end{bmatrix} = \begin{bmatrix}
0 \\
0 \\
0
\end{bmatrix} = \chi_1 = 6$$

$$\chi_2 = 6$$

$$\chi_3$$
: free fouram.

eigenspace:
$$\propto \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Algebraic multiplicity of $\lambda=3:1$. Geometric multiplicity of $\lambda=3:1$. Ex. Find the dimension of the eigenspace of

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

Char. polynomial $(\lambda-1)^3 = 0$

$$\Rightarrow \lambda = 1, 1, 1.$$

Algebraic multiplicity of $\lambda=1:3$

ergenspace:
$$(4\lambda I)\chi = 0 \Rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\chi_2 = \alpha_1 \quad \chi_3 = \alpha_2 : \quad \chi_1 = -\alpha_2$$

$$\begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} = \propto_1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \propto_2 \begin{bmatrix} \bullet & 1 \\ 0 \\ 1 \end{bmatrix}$$
 Dimension of eigenspace: 2.

Ex. Find the dimension of eigenspace of

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\lambda = 1, L, 1$$
.

$$(A-\lambda I) \chi = 0 \Rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \\ 0 \end{bmatrix}$$

$$\begin{array}{l}
\chi_3 = \alpha_3, \quad \chi_2 = \alpha_2, \quad \chi_1 = \alpha_1 \\
\chi_1 \\
\chi_2 \\
\chi_3
\end{array} = \alpha_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \alpha_3 \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Similarity of Matrices:

An mxn matrix B is called similar to on mxn matrix A if $B = P^{-1}AP$ for some non-singular matrix P.

The If B is similar to A then B has the same eigenvalues as A. If x is an eigenvector of A then $y = p^{-1}x$ is an eigenvector of B corresponding to the same eigenvalue.

 $\begin{array}{ll}
P_{\underline{roof}}: & Ax = \lambda x \Rightarrow \lambda P^{1}x = P^{1}Ax \\
\Rightarrow \lambda P^{1}x = P^{1}A(PP^{1})x \\
&= P^{1}AP(P^{1}x) \\
\lambda(P^{1}x) = B(P^{1}x)
\end{array}$

 \Rightarrow λ is an eigenvalue of B and \vec{P} is an eigenvector corresponding to the eigenvalue λ .

The If A and B are square matrixes similar to each other then they have the same characteristic polynomial.

Persol: B = P'AP $det(B-\lambda I) = det(P'AP - P'(\lambda I)P)$

$$= \det \left(p^{-1} (A - \lambda I) p \right)$$

$$= \det (p^{-1}) \det (A - \lambda I) \det (p)$$

$$= \det (A - \lambda I).$$

Def: A square matrix A is said to be diagonalizable if there exists an involvible matrix P such that PTAP is a diagonal matrix (i.e., A is similar to a diagonal matrix)

Theorem: tet A be an nxn matrix. Then A is diagonalizable iff A has n linearly independent eigenvectors.

Theorem: If an nxn matrix A has n distinct eigenvalues, then A is diagonalizable.

Remark: The matrix P which diagonalizes A is called Model matrix of A whose columns are the eigenvectors corresponding to different eigenvalues.

Example 1:

$$A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$$
 eigenvalues 1 & 6

eigenvectors
$$\begin{bmatrix} -1 \\ 1 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

$$P = \begin{bmatrix} -L & 4 \\ 1 & L \end{bmatrix} \qquad P^{-1} = \begin{bmatrix} -L | S & 4 | S \\ 1 | S & 1 | S \end{bmatrix}$$

$$P^{\dagger}AP = \begin{bmatrix} 1 & 0 \\ 0 & 6 \end{bmatrix}$$

Example: 2:
$$A = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$$

eigenvectors
$$\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$$
, $\begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$, $\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$

$$P = \begin{bmatrix}
L & -1 & 2 \\
2 & 0 & -1 \\
0 & 2 & 1
\end{bmatrix} \qquad
\vec{P}AP = \begin{bmatrix}
2 & 0 & 0 \\
0 & 2 & 0 \\
0 & 0 & 8
\end{bmatrix}$$

Example: 8:
$$A = \begin{bmatrix} 2 & 0 & 0 \\ 4 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$
 eigenvalues $2 \quad 2 \quad 3$ eigenvectors $=$ The given matrix is not diagonalizable.

Application of Diagonalization:

9) Power of Matrices

$$P^{1}AP = D$$

$$\Rightarrow A = PDP^{1}$$

$$A^{2} = (PDP^{1})(PDP^{1})$$

$$= PD(P^{1})DP^{1}$$

$$= PD^{2}P^{1}$$
Similarly
$$A^{3} = (PD^{2}P^{1})(PD^{2}P^{1}) = PD^{3}P^{1}$$
and
$$A^{m} = PD^{m}P^{1}$$

Example: Find
$$A^5$$
 for $A = \begin{bmatrix} 1 & 4 \\ 1/2 & 0 \end{bmatrix}$

ligenvalues -1 2

eigenvectors
$$\begin{bmatrix} 2 \\ -1 \end{bmatrix}$$
, $\begin{bmatrix} 4 \\ 1 \end{bmatrix}$

$$P = \begin{bmatrix} 2 & 4 \\ -1 & 1 \end{bmatrix} \qquad \vec{P}' = \frac{1}{6} \begin{bmatrix} 1 & -4 \\ 1 & 2 \end{bmatrix}$$

$$A^{5} = \frac{1}{5} \begin{bmatrix} 2 & 4 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} (-1)^{5} & 0 \\ 0 & 2^{5} \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 2 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 2 & 4 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 32 \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 21 & 44 \\ 5.5 & 10 \end{bmatrix}$$

b) Solution of system of linear differential equation

Consider the system of linear equation

$$\mathring{X}(t) = A X(t)$$

Let us assume that A is dragonalizable, then

$$\Rightarrow \quad \bar{p}^{\perp} \, \mathring{x}(t) = \quad D \, \bar{p}^{\perp} \, X(t)$$

OR
$$\left[\bar{p}^{L}X(t)\right]' = D\left[\bar{p}'X(t)\right]$$

Substitute: PX(t)=: Ytt)

$$=) \begin{bmatrix} \mathring{y}_{n}(t) \\ \vdots \\ \mathring{y}_{n}(t) \end{bmatrix} = \begin{bmatrix} \lambda_{1} & 0 \\ 0 & \lambda_{n} \end{bmatrix} \begin{bmatrix} y_{1}(t) \\ \vdots \\ y_{n}(t) \end{bmatrix}$$