

Chapter-3

Digital Image Processing Operations

1. Compute D_e , D_4 , D_8 and D_m distance between two pixels x and y be $(0, 0)$ and $(6, 3)$ for the image below

Solution

Euclidean distance:

$$D_e = \sqrt{(x - s)^2 + (y - t)^2} = \sqrt{(0 - 6)^2 + (0 - 3)^2} = \sqrt{45}$$

City block distance:

$$D_4 = |(x - s)| + |(y - t)| = |0 - 6| + |0 - 3| = 9$$

Chess board distance:

$$D_8 = \max(|(x - s)|, |(y - t)|) = \max(6, 3) = 6$$

2. What is the connectivity?

Solution: The 1's are diagonal. Hence 8-connectivity.

3. Median is a non-linear operator as

Hint: median $(x_m + y_m)$ is not equal to median (x_m) + median (y_m) .

4. Consider the following two images.

$$f_1 = \begin{pmatrix} 10 & 40 & 30 \\ 40 & 100 & 90 \\ 90 & 80 & 70 \end{pmatrix}$$

$$f_2 = \begin{pmatrix} 40 & 140 & 90 \\ 140 & 100 & 90 \\ 90 & 80 & 190 \end{pmatrix}$$

Perform the arithmetic operations. Assume that all the operations are uint8.

Solution

$$f_1 + f_2 = f_2 = \begin{pmatrix} 10+40 & 40+140 & 30+90 \\ 40+140 & 100+100 & 90+90 \\ 90+90 & 80+80 & 70+190 \end{pmatrix} = \begin{pmatrix} 50 & 180 & 120 \\ 180 & 200 & 180 \\ 180 & 160 & 260 \end{pmatrix}$$

If unit 16 is used, the above is the answer. But if unit 8 is used the maximum is 255. So the value 260 is truncated to 255 to yield the matrix

5. What is the difference between image subtraction and image absolute difference?

Solution:

$$f_1 - f_2 = \begin{pmatrix} 10-40 & 40-140 & 30-90 \\ 40-140 & 100-100 & 90-90 \\ 90-90 & 80-80 & 70-190 \end{pmatrix} = \begin{pmatrix} -30 & -100 & -60 \\ -100 & 0 & 0 \\ 0 & 0 & -120 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

If the absolute difference is used, it is then

$$f_1 - f_2 = \begin{pmatrix} 10-40 & 40-140 & 30-90 \\ 40-140 & 100-100 & 90-90 \\ 90-90 & 80-80 & 70-190 \end{pmatrix} = \begin{pmatrix} 30 & 100 & 60 \\ 100 & 0 & 0 \\ 0 & 0 & 120 \end{pmatrix}$$

6. Consider the following two images.

$$f_1 = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$f_2 = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

Perform the logical operations AND, OR, NOT and difference.

Solution

AND

$$f_1 \& f_2 = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

OR

$$f_1 | f_2 = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

NOT

$$!f_1 = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix}$$

$$!f_2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

DIFFERENCE:

$$f_1 - f_2 = (f_1) \text{ \& } (!f_2) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$f_2 - f_1 = (f_2) \text{ \& } (!f_1) = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix}$$

7. Derive the inverse scaling transformation.

Solution:

The inverse scaling transformation is given as $A^{-1} = \frac{[Adjoint(A)]^T}{\det[A]}$

The scaling matrix is given as $A = \begin{pmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{pmatrix}$

The adjoint matrix of A is given as $\begin{pmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & s_x s_y \end{pmatrix}$

The determinant of A = $s_x s_y$

Therefore, the inverse transformation is given as $A^{-1} = \begin{pmatrix} \frac{1}{s_x} & 0 & 0 \\ 0 & \frac{1}{s_y} & 0 \\ 0 & 0 & 1 \end{pmatrix}$

8. Prove that transform and its inverse restore the original object.

Solution:

The original scaling transform is given as

The scaling matrix is given as $A = \begin{pmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{pmatrix}$

The inverse scaling transform is given as

$$A^{-1} = \begin{pmatrix} \frac{1}{s_x} & 0 & 0 \\ 0 & \frac{1}{s_y} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Therefore the multiplication of scaling and its inverse gives a matrix of

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

The multiplication of any matrix with unit matrix gives the same matrix. Hence the original object is unchanged.

9.

Solution:

The resultant transform is multiplication of three transforms

1. First translate with $-x_r, -y_r$
2. Apply scaling transform
3. Apply translation now with $+x_r, +y_r$

This results in composite transform.

10. Consider the image $F = \begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix}$. Apply replication and interpolation techniques and show the result.

Given

$$F = \begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix}$$

Solution

Zero-hold interpolation:

$$F' = \begin{pmatrix} 2 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 3 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Linear interpolation:

After Row wise interpolation,

$$F'' = \begin{pmatrix} 2 & 1.5 & 1 & 0.5 \\ 0 & 0 & 0 & 0 \\ 3 & 2 & 1 & 0.5 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

After Column wise interpolation,

$$F'' = \begin{pmatrix} 2 & 1.5 & 1 & 0.5 \\ 2.5 & 1.75 & 1 & 0.5 \\ 3 & 2 & 1 & 0.5 \\ 1.5 & 1 & 0.5 & 0.25 \end{pmatrix}$$

11. Consider the image $F = \begin{pmatrix} 2 & 2 \\ 3 & 2 \end{pmatrix}$. Calculate the mean and entropy of the image.

Given

$$F = \begin{pmatrix} 2 & 2 \\ 3 & 2 \end{pmatrix}$$

Symbols	2	3
p_k	0.75	0.25

Solution

$$\text{Mean} = \frac{2+2+3+2}{4} = \frac{9}{4} = \mathbf{2.25}$$

$$\text{Entropy, } H = - \sum_{k=1}^n p_k \log_2 p_k$$

$$\begin{aligned} H &= - \sum_{k=1}^2 p_k \log_2 p_k \\ &= - [0.75 \log_2 0.75 + 0.25 \log_2 0.25] \end{aligned}$$

$$= 0.311 + 0.5$$

$$H = 0.811$$

12. Find the convolution and correlation of the following streams of data:

a) {1 7 9 6} and {1 3 5}

b) {1 2 3 4} and {1 1}

Solution

a) Correlation:

f	w
1 7 9 6	1 3 5

After zero padding,

i) 0 0 1 7 9 6 $y_0 = 5$

1 3 5
↑

ii) 0 0 1 7 9 6 $y_1 = 38$

1 3 5
↑

iii) 0 0 1 7 9 6 $y_2 = 67$

1 3 5
↑

iv) 0 0 1 7 9 6 $y_3 = 64$

1 3 5
↑

v) 0 0 1 7 9 6 $y_4 = 27$

1 3 5
↑

$$v) \quad 0 \ 0 \ 1 \ 7 \ 9 \ 6 \qquad y_5 = 6$$

1 3 5
 ↑

$$\text{Correlation output} = \{ 5 \ 38 \ 67 \ 64 \ 27 \ 6 \}$$

Convolution:

$$\begin{array}{ccc} & f & w \text{ rotated } 180^\circ \\ 1 & 7 & 9 \ 6 & 5 \ 3 \ 1 \end{array}$$

After zero padding,

$$i) \quad 0 \ 0 \ 1 \ 7 \ 9 \ 6 \qquad y_0 = 1$$

5 3 1
 ↑

$$ii) \quad 0 \ 0 \ 1 \ 7 \ 9 \ 6 \qquad y_1 = 10$$

5 3 1
 ↑

$$iii) \quad 0 \ 0 \ 1 \ 7 \ 9 \ 6 \qquad y_2 = 35$$

5 3 1
 ↑

$$iv) \quad 0 \ 0 \ 1 \ 7 \ 9 \ 6 \qquad y_3 = 68$$

5 3 1
 ↑

$$v) \quad 0 \ 0 \ 1 \ 7 \ 9 \ 6 \qquad y_4 = 63$$

5 3 1
 ↑

$$v) \quad 0 \ 0 \ 1 \ 7 \ 9 \ 6 \qquad y_5 = 30$$

5 3 1
 ↑

Convolution output = { 1 10 35 68 63 30 }

b) Correlation:

f	w
1 2 3 4	1 1

After zero padding,

i) 0 1 2 3 4 $y_0 = 1$

1 1
↑

ii) 0 1 2 3 4 $y_1 = 3$

1 1
↑

iii) 0 1 2 3 4 $y_2 = 5$

1 1
↑

iv) 0 1 2 3 4 $y_3 = 7$

1 1
↑

v) 0 1 2 3 4 $y_4 = 4$

1 1
↑

Correlation output = { 1 3 5 7 4 }

Convolution:

$$\begin{array}{cc}
 f & w \text{ rotated } 180^\circ \\
 1 \ 2 \ 3 \ 4 & 1 \ 1
 \end{array}$$

After zero padding,

$$\begin{array}{cc}
 \text{i) } 0 \ 1 \ 2 \ 3 \ 4 & y_0 = 1 \\
 1 \ 1 & \\
 \uparrow &
 \end{array}$$

$$\begin{array}{cc}
 \text{ii) } 0 \ 1 \ 2 \ 3 \ 4 & y_1 = 3 \\
 1 \ 1 & \\
 \uparrow &
 \end{array}$$

$$\begin{array}{cc}
 \text{iii) } 0 \ 1 \ 2 \ 3 \ 4 & y_2 = 5 \\
 1 \ 1 & \\
 \uparrow &
 \end{array}$$

$$\begin{array}{cc}
 \text{iv) } 0 \ 1 \ 2 \ 3 \ 4 & y_3 = 7 \\
 1 \ 1 & \\
 \uparrow &
 \end{array}$$

$$\begin{array}{cc}
 \text{v) } 0 \ 1 \ 2 \ 3 \ 4 & y_4 = 4 \\
 1 \ 1 & \\
 \uparrow &
 \end{array}$$

Convolution output = { 1 3 5 7 4 }

Since the filter is symmetric, correlation and convolution produce the same result.

13. Find the convolution and correlation of the following streams of data:

$$\text{a) } F = \begin{pmatrix} 7 & 3 & 3 \\ 2 & 2 & 2 \\ 2 & 2 & 1 \end{pmatrix} \text{ and } I = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$\text{b) } F = \begin{pmatrix} 7 & 2 & 3 \\ 2 & 2 & 1 \\ 2 & 1 & 1 \end{pmatrix} \text{ and } I = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

Solution

a) Image dimension is 3 X 3.

Template dimension is 2 X 2.

The output dimension will be (3+2-1) X (3+2-1) i.e., 4 X 4.

Correlation:

F is padded with 1 row of 0's on all sides.

After padding,

$$F = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

1)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

2)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

3)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

4)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

5)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

6)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

7)

0	0	0	0	0
0	7	3	3	0
0	¹ 2	¹ 2	2	0
0	¹ 2	⁻¹ 2	1	0
0	0	0	0	0

8)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	¹ 2	¹ 2	1	0
0	¹ 0	⁻¹ 0	0	0

9)

0	0	¹ 0	¹ 0	0
0	7	¹ 3	⁻¹ 3	0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

10)

0	0	0	0	0
0	7	¹ 3	¹ 3	0
0	2	¹ 2	⁻¹ 2	0
0	2	2	1	0
0	0	0	0	0

11)

0	0	0	0	0
0	7	3	3	0
0	2	¹ 2	¹ 2	0
0	2	¹ 2	⁻¹ 1	0
0	0	0	0	0

12)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	¹ 2	¹ 1	0
0	0	¹ 0	⁻¹ 0	0

13)

0	0	0	¹ 0	¹ 0
0	7	3	¹ 3	⁻¹ 0
0	2	2	2	0
0	2	2	1	0
0	0	0	0	0

14)

0	0	0	0	0
0	7	3	¹ 3	¹ 0
0	2	2	¹ 2	⁻¹ 0
0	2	2	1	0
0	0	0	0	0

15)

0	0	0	0	0
0	7	3	3	0
0	2	2	¹ 2	¹ 0
0	2	2	¹ 1	⁻¹ 0
0	0	0	0	0

16)

0	0	0	0	0
0	7	3	3	0
0	2	2	2	0
0	2	2	¹ 1	¹ 0
0	0	0	¹ 0	⁻¹ 0

Output of the correlation is

$$\begin{pmatrix} -7 & 4 & 0 & 3 \\ 5 & 10 & 6 & 5 \\ 0 & 5 & 5 & 3 \\ 2 & 4 & 3 & 1 \end{pmatrix}$$

Convolution:

F is padded with 1 row of 0's on all sides.

After padding,

$$F = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

filter rotated 180°

1) $\begin{array}{ccccc} & -1 & 0 & 0 & 0 \\ & 0 & 1 & 3 & 3 \\ 0 & 2 & 2 & 2 & 0 \\ & 0 & 2 & 2 & 1 \\ & 0 & 0 & 0 & 0 \end{array}$

2) $\begin{array}{ccccc} & 0 & 0 & 0 & 0 \\ & -1 & 0 & 3 & 3 \\ & 0 & 1 & 2 & 2 \\ 0 & 2 & 2 & 1 & 0 \\ & 0 & 0 & 0 & 0 \end{array}$

3) $\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ & -1 & 0 & 2 & 2 \\ & 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array}$

4) $\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ & -1 & 0 & 2 & 1 \\ & 0 & 1 & 0 & 0 \end{array}$

5) $\begin{array}{ccccc} 0 & -1 & 0 & 0 & 0 \\ 0 & 1 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$

6) $\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 3 & 3 & 0 \\ 0 & 1 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$

7) $\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & -1 & 2 & 2 & 0 \\ 0 & 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$

8) $\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & -1 & 2 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 \end{array}$

9) $\begin{array}{ccccc} 0 & 0 & -1 & 0 & 0 \\ 0 & 7 & 1 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$

10) $\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & -1 & 3 & 0 \\ 0 & 2 & 1 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$

$$11) \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$12) \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$13) \begin{bmatrix} 0 & 0 & 0 & -10 & 10 \\ 0 & 7 & 3 & 13 & 10 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$14) \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & -13 & 10 \\ 0 & 2 & 2 & 12 & 10 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$15) \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & -12 & 10 \\ 0 & 2 & 2 & 1 & 10 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$16) \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 3 & 3 & 0 \\ 0 & 2 & 2 & 2 & 0 \\ 0 & 2 & 2 & -11 & 10 \\ 0 & 0 & 0 & 10 & 10 \end{bmatrix}$$

Output of the convolution is

$$\begin{pmatrix} 7 & 10 & 6 & 3 \\ 9 & 0 & 4 & -1 \\ 4 & 4 & 3 & -1 \\ 2 & 0 & -1 & -1 \end{pmatrix}$$

b) Image dimension is 3 X 3.

Template dimension is 2 X 2.

The output dimension will be (3+2-1) X (3+2-1) i.e., 4 X 4.

Correlation:

F is padded with 1 row of 0's on all sides.

After padding,

$$F = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 2 & 3 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 2 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Initial filter position is

1	0	1	0	0	0	0
1	0	1	7	3	3	0
	0	2	2	2	2	0
	0	2	2	1	0	
	0	0	0	0	0	

Then the mask is moved through all the elements to obtain the final output as

$$\begin{pmatrix} 7 & 9 & 5 & 3 \\ 9 & 13 & 8 & 4 \\ 4 & 7 & 5 & 2 \\ 2 & 3 & 2 & 1 \end{pmatrix}$$

Convolution:

F is padded with 1 row of 0's on all sides.

After padding,

$$F = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 7 & 2 & 3 & 0 \\ 0 & 2 & 2 & 1 & 0 \\ 0 & 2 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Initial filter position is

1	0	1	0	0	0	0
1	0	1	7	3	3	0
	0	2	2	2	2	0
	0	2	2	1	0	
	0	0	0	0	0	

Then the mask is moved through all the elements to obtain the final output as

$$\begin{pmatrix} 7 & 9 & 5 & 3 \\ 9 & 13 & 8 & 4 \\ 4 & 7 & 5 & 2 \\ 2 & 3 & 2 & 1 \end{pmatrix}$$

Since the filter is symmetric, both correlation and convolution produce same output.

14. A triangle is marked by the points A(1, 1), B(5, 5) and C(10, 10).

- Apply translation of $\delta x = 3$ and $\delta y = 4$
- Apply rotation with degrees 45, 90, 180 and 270
- Consider the image perform zooming and mirroring along x, y and z axes

Given

A triangle with A(1, 1), B(5, 5) and C(10, 10).

Solution

- Apply translation of $tx = 3$ and $ty = 4$

$$\begin{bmatrix} x' & y' & 1 \end{bmatrix} = \begin{bmatrix} x & y & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ tx & ty & 1 \end{bmatrix}$$

For A:

$$\begin{bmatrix} x' & y' & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 4 & 1 \end{bmatrix} \quad (\text{where } tx = 3 \text{ and } ty = 4)$$

$$\begin{bmatrix} x' & y' & 1 \end{bmatrix} = \begin{bmatrix} 4 & 5 & 1 \end{bmatrix} \therefore \begin{bmatrix} x' & y' \end{bmatrix} = \begin{bmatrix} 4 & 5 \end{bmatrix}$$

For B:

$$[x' \ y' \ 1] = [1 \ 5 \ 5] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 4 & 1 \end{bmatrix} \quad (\text{where } tx = 3 \text{ and } ty = 4)$$

$$[x' \ y' \ 1] = [8 \ 9 \ 1] \quad \therefore [x' \ y'] = [8 \ 9]$$

For C:

$$[x' \ y' \ 1] = [1 \ 10 \ 10] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 4 & 1 \end{bmatrix} \quad (\text{where } tx = 3 \text{ and } ty = 4)$$

$$[x' \ y' \ 1] = [13 \ 14 \ 1] \quad \therefore [x' \ y'] = [13 \ 14]$$

So, after translation, the triangle will be marked by the points

A'(4, 5), B'(8, 9) and C'(13, 14).

b) Apply rotation with degrees 45, 90, 180 and 270

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\theta = 45^\circ$$

For A:

$$[x' \ y' \ 1] = [1 \ 1 \ 1] \begin{bmatrix} 0.707 & -0.707 & 0 \\ 0.707 & 0.707 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [1.414 \ 0 \ 1] \quad \therefore [x' \ y'] = [1.414 \ 0]$$

For B:

$$[x' \ y' \ 1] = [5 \ 5 \ 1] \begin{bmatrix} 0.707 & -0.707 & 0 \\ 0.707 & 0.707 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [7.07 \ 0 \ 1] \quad \therefore [x' \ y'] = [7.07 \ 0]$$

For C:

$$[x' \ y' \ 1] = [10 \ 10 \ 1] \begin{bmatrix} 0.707 & -0.707 & 0 \\ 0.707 & 0.707 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [14.14 \ 0 \ 1] \quad \therefore [x' \ y'] = [14.14 \ 0]$$

So, after rotation, the triangle will be marked by the points

A'(1.414, 0), B'(7.07, 0) and C'(14.14, 0).

$$\theta = 90^\circ$$

For A:

$$[x' \ y' \ 1] = [1 \ 1 \ 1] \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [1 \ -1 \ 1] \quad \therefore [x' \ y'] = [1 \ -1]$$

For B:

$$[x' \ y' \ 1] = [5 \ 5 \ 1] \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [5 \ -5 \ 1] \quad \therefore [x' \ y'] = [5 \ -5]$$

For C:

$$[x' \ y' \ 1] = [10 \ 10 \ 1] \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [10 \ -10 \ 1] \quad \therefore [x' \ y'] = [10 \ -10]$$

So, after rotation, the triangle will be marked by the points

A'(1, -1), B'(5, -5) and C'(10, -10).

$$\theta = 180^\circ$$

For A:

$$[x' \ y' \ 1] = [1 \ 1 \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-1 \ -1 \ 1] \quad \therefore [x' \ y'] = [-1 \ -1]$$

For B:

$$[x' \ y' \ 1] = [5 \ 5 \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-5 \ -5 \ 1] \quad \therefore [x' \ y'] = [-5 \ -5]$$

For C:

$$[x' \ y' \ 1] = [10 \ 10 \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-10 \ -10 \ 1] \quad \therefore [x' \ y'] = [-10 \ -10]$$

So, after rotation, the triangle will be marked by the points

A'(-1, -1), B'(-5, -5) and C'(-10, -10).

$$\theta = 270^\circ$$

For A:

$$[x' \ y' \ 1] = [1 \ 1 \ 1] \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-1 \ 1 \ 1] \quad \therefore [x' \ y'] = [-1 \ 1]$$

For B:

$$[x' \ y' \ 1] = [5 \ 5 \ 1] \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-5 \ 5 \ 1] \quad \therefore [x' \ y'] = [-5 \ 5]$$

For C:

$$[x' \ y' \ 1] = [10 \ 10 \ 1] \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-10 \ 10 \ 1] \quad \therefore [x' \ y'] = [-10 \ 10]$$

So, after rotation, the triangle will be marked by the points

A'(-1, 1), B'(-5, 5) and C'(-10, 10).

c) Consider the image perform mirroring along x, y and z axes

Along x-axis:

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

For A:

$$[x' \ y' \ 1] = [1 \ 1 \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [1 \ -1 \ 1] \quad \therefore [x' \ y'] = [1 \ -1]$$

For B:

$$[x' \ y' \ 1] = [5 \ 5 \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [5 \ -5 \ 1] \quad \therefore [x' \ y'] = [5 \ -5]$$

For C:

$$[x' \ y' \ 1] = [10 \ 10 \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [10 \ -10 \ 1] \quad \therefore [x' \ y'] = [10 \ -10]$$

So, after rotation, the triangle will be marked by the points

A'(1, -1), B'(5, -5) and C'(10, -10).

Along y-axis:

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

For A:

$$[x' \ y' \ 1] = [1 \ 1 \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-1 \ 1 \ 1] \quad \therefore [x' \ y'] = [-1 \ 1]$$

For B:

$$[x' \ y' \ 1] = [5 \ 5 \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-5 \ 5 \ 1] \quad \therefore [x' \ y'] = [-5 \ 5]$$

For C:

$$[x' \ y' \ 1] = [10 \ 10 \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[x' \ y' \ 1] = [-10 \ 10 \ 1] \quad \therefore [x' \ y'] = [-10 \ 10]$$

So, after rotation, the triangle will be marked by the points

A'(-1, 1), B'(-5, 5) and C'(-10, 10).

Since this is 2D triangle, mirroring along z-axis gives the same points.

15.

Solution:

$$mean = \frac{548}{9} = 60.89$$

$$mode = 10$$

median = 67

Sum of difference = 15342.888

Variance = 1704.7654

Standard Deviation = 41.2888

16.

Solution:

$$= 0.4 \log(0.4) + 0.3 \log(0.3) + 0.2 \log(0.2) + 0.1 \log(0.1)$$

$$= -[-0.5288-0.5211-0.4644-0.3322]$$

$$= 1.8465$$