

ON A CONTROL PROBLEM FOR A HEAVY CHAIN WITH LOADS

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A control problem for a mixed hyperbolic problem is considered. The dependence between the control and the solution is given explicitly.

Keywords: Mixed problem, control problem, Hankel function.

In [1] some control problems for heavy chain systems, i.e. trolleys carrying a fixed length chain that may carry a load, were addressed in the partial derivatives equations framework.

The problem that follows was formulated as a result of the discussion on this theme.

Consider a crane carrying a mass $m > 0$ at the end of a heavy chain of length $l > 0$. The crane is put onboard the ship, and the load is traveling under the sea for civil engineering applications. It is desired to find a control algorithm to stabilize the load while system is subjected to disturbances consisting of a subsea stream occurring at a certain depth: over the subinterval of $(0, l)$.

Mathematically, the system is governed by the following mixed problem (assuming a homogeneous mass distribution):

$$\frac{\partial}{\partial x} \left((x + m)g \frac{\partial u(x, t)}{\partial x} \right) - \frac{\partial^2 u(x, t)}{\partial t^2} + f(x, t) = 0, \quad (1)$$

in the domain

$$(x, t) : \quad 0 < x < l, \quad t > 0,$$

with homogeneous initial conditions

$$u(x, 0) = 0, \quad \frac{\partial u(x, 0)}{\partial t} = 0, \quad (2)$$

and boundary value conditions

$$\frac{\partial^2 u(0, t)}{\partial t^2} = g \frac{\partial u(0, t)}{\partial x}, \quad u(l, t) = v(t), \quad (3)$$

with g the gravity constant, and $v(t)$ is freely chosen control variable. The function f represents the stream forces. The question is: how $u(0, t)$ depends on f and v ?

In the present paper we give an answer to this question.

By substituting

$$y = 2\sqrt{\frac{x+m}{g}}, \quad y_1 = 2\sqrt{\frac{m}{g}}, \quad y_2 = 2\sqrt{\frac{l+m}{g}},$$

$$u_1(y, t) = u(x, t), \quad f_1(y, t) = f(x, t)$$

we reduce it to a problem for the equation

$$\frac{\partial^2 u_1(y, t)}{\partial y^2} + \frac{1}{y} \frac{\partial u_1(y, t)}{\partial y} - \frac{\partial^2 u_1(y, t)}{\partial t^2} + f_1(y, t) = 0, \quad (4)$$

in the domain

$$(y, t) : \quad y_1 < y < y_2, \quad t > 0,$$

with homogeneous initial conditions

$$u_1(y, 0) = 0, \quad \frac{\partial u_1(y, 0)}{\partial t} = 0, \quad (5)$$

and boundary value conditions

$$\frac{\partial^2 u_1(y_1, t)}{\partial t^2} = \frac{2}{y_1} \frac{\partial u_1(y_1, t)}{\partial y}, \quad u_1(y_2, t) = v(t). \quad (6)$$

To solve (4)-(6) we use the Laplace transform:

$$X(y, s) = \int_0^{+\infty} e^{-st} u_1(y, t) dt,$$

$$F(y, s) = \int_0^{+\infty} e^{-st} f_1(y, t) dt, \quad V(s) = \int_0^{+\infty} e^{-st} v(t) dt.$$

As a result we obtain a problem for the ordinary differential equation with a parameter:

$$\frac{\partial^2 X(y, s)}{\partial y^2} + \frac{1}{y} \frac{\partial X(y, s)}{\partial y} - s^2 X(y, s) + F(y, s) = 0, \quad (7)$$

on the interval

$$y_1 < y < y_2$$

with condition

$$\lim_{s \rightarrow +\infty} s^2 X(y, s) = 0 \quad (8)$$

and boundary value conditions

$$s^2 X(y_1, s) = \frac{2}{y_1} \frac{\partial X(y_1, s)}{\partial y}, \quad X(y_2, s) = V(s). \quad (9)$$

By substituting

$$z = isy, \quad X(y, s) = Z(z, s), \quad H(z, s) = F(y, s),$$

we transform (7) to the equation

$$z \frac{\partial^2 Z(z, s)}{\partial z^2} + \frac{\partial Z(z, s)}{\partial z} + z Z(z, s) + H(z, s) = 0. \quad (10)$$

The general solution for (10) may be expressed as follows:

$$Z(z, s) = A(s)J_0(z) + B(s)Y_0(z) + \frac{\pi}{2} \int_0^z (Y_0(z)J_0(\xi) - J_0(z)Y_0(\xi)) \frac{\xi}{s^2} H(\xi, s) d\xi,$$

where $J_0(z)$ and $Y_0(z)$ are the Bessel functions. Hence:

$$X(y, s) = A(s)J_0(isy) + B(s)Y_0(isy) -$$

$$-\frac{\pi}{2} \int_0^y (Y_0(isy)J_0(is\tau) - J_0(isy)Y_0(is\tau))\tau F(\tau, s)d\tau.$$

It is more convenient to use the modified Bessel functions, using the equality [2, p. 95]: $I_0(z)K_0'(z) - I_0'(z)K_0(z) = -1/z$,

$$X(y, s) = A(s)I_0(sy) + B(s)K_0(sy) + G(y, s),$$

where

$$G(y, s) = - \int_0^y (K_0(sy)I_0(s\tau) - I_0(sy)K_0(s\tau))\tau F(\tau, s)d\tau.$$

We find $A(s)$ and $B(s)$ by the boundary value conditions, using the formulae $I_0'(z) = I_1(z)$, $K_0'(z) = -K_1(z)$, $zI_2(z) = zI_0(z) - 2I_1(z) = zI_0(z) - 2I_0'(z)$, $zK_2(z) = zK_0(z) + 2K_1(z) = zK_0(z) - 2K_0'(z)$, [2, p. 93]:

$$sy_1(I_2(sy_1)A(s) + K_2(sy_1)B(s)) = \frac{2}{s} \frac{\partial G}{\partial y}(y_1, s) - sy_1G(y_1, s),$$

$$I_0(sy_2)A(s) + K_0(sy_2)B(s) = V(s) - G(y_2, s).$$

The determinant for this system is

$$\begin{aligned} \Delta(s) &= (sy_1I_0(sy_1) - 2I_1(sy_1))K_0(sy_2) - (sy_1K_0(sy_1) + 2K_1(sy_1))I_0(sy_2) = \\ &= sy_1(I_2(sy_1)K_0(sy_2) - K_2(sy_1)I_0(sy_2)). \end{aligned}$$

The system's solution is

$$\begin{aligned} A(s) &= \left(\left(\frac{2}{s} \frac{\partial G}{\partial y}(y_1, s) - sy_1G(y_1, s) \right) K_0(sy_2) + \right. \\ &\quad \left. + sy_1K_2(sy_1)(G(y_2, s) - V(s)) \right) / \Delta(s), \\ B(s) &= \left(sy_1I_2(sy_1)(V(s) - G(y_2, s)) - \right. \end{aligned}$$

$$-\left(\frac{2}{s} \frac{\partial G}{\partial y}(y_1, s) - sy_1 G(y_1, s)\right) I_0(sy_2) / \Delta(s).$$

Theorem 1. *All roots of the determinant $\Delta(s)$ lie on the imaginary axis.*

Proof. Since $\Delta(-iy) = \overline{\Delta(iy)}$, we may explore only the roots with positive imaginary part. We consider the corresponding spectral problem

$$X''(y) + \frac{X'(y)}{y} + \lambda X(y) = 0, \quad 0 < y_1 < y_2,$$

$$2X'(y_1) + \lambda y_1 X(y_1) = 0, \quad X(y_2) = 0.$$

By substituting $z = \sqrt{\lambda}y$, we obtain the equation

$$X''(z) + \frac{X'(z)}{z} + X(z) = 0, \quad 0 < z_1 < z_2, \quad (11)$$

and boundary value conditions

$$2X'(z_1) + z_1 X(z_1) = 0, \quad X(z_2) = 0. \quad (12)$$

We substitute the general solution for (11),

$$X(z) = AJ_0(z) + BY_0(z),$$

into boundary value conditions (12). We obtain the following system:

$$2AJ'_0(z_1) + 2BY'_0(z_1) + Az_1 J_0(z_1) + Bz_1 Y_0(z_1) = 0,$$

$$AJ_0(z_2) + BY_0(z_2) = 0,$$

where we exclude constants A and B . As a result, we write the characteristic equation for the spectral problem:

$$\Delta = (2J'_0(z_1) + z_1 J_0(z_1))Y_0(z_2) -$$

$$-(2Y'_0(z_1) + z_1 Y_0(z_1))J_0(z_2) = 0,$$

or

$$\begin{aligned} \Delta &= (2J'_0(\sqrt{\lambda}y_1) + \sqrt{\lambda}y_1 J_0(\sqrt{\lambda}y_1))Y_0(\sqrt{\lambda}y_2) - \\ &-(2Y'_0(\sqrt{\lambda}y_1) + \sqrt{\lambda}y_1 Y_0(\sqrt{\lambda}y_1))J_0(\sqrt{\lambda}y_2) = 0. \end{aligned} \quad (13)$$

The roots of characteristic equation (13) are positive numbers. If λ_n and λ_m are distinct eigenvalues, $X_n(y)$ and $X_m(y)$ are their corresponding eigenfunctions, then the following relation holds:

$$\begin{aligned} &(\lambda_m - \lambda_n) \int_{y_1}^{y_2} y X_n(y) X_m(y) dy = \\ &= \int_{y_1}^{y_2} [(y X_n''(y) + X_n'(y)) X_m(y) - (y X_m''(y) + X_m'(y)) X_n(y)] dy = \\ &= \int_{y_1}^{y_2} [(y X_n'(y))' X_m(y) - (y X_m'(y))' X_n(y)] dy = \\ &= y_1 X_m'(y_1) X_n(y_1) - y_1 X_n'(y_1) X_m(y_1) = (\lambda_n - \lambda_m) \frac{y_1^2}{2} X_n(y_1) X_m(y_1). \end{aligned}$$

It delivers the equality

$$\int_{y_1}^{y_2} y X_n(y) X_m(y) dy + \frac{y_1^2}{2} X_n(y_1) X_m(y_1) = 0.$$

This equality allows us [3, 4] to introduce in a Hilbert space H , which is the direct product of spaces $L_2(y_1, y_2)$ and C , a scalar product and a corresponding positive self-adjoint compact operator with the same eigenvalues as the spectral problem. In fact, the considered spectral problem may be rewritten in the following integral form:

$$X(y) = \lambda \int_{y_1}^{y_2} \ln\left(\frac{2y_2}{|\xi - y| + (\xi + y)}\right) \xi X(\xi) d\xi -$$

$$-\frac{\lambda y_1^2}{2} \ln\left(\frac{y}{y_2}\right) X(y_1).$$

If $U = (X(y), X_1)$ and $W = (Z(y), Z_1)$ are two elements of H with the scalar product

$$(U, W) = \int_{y_1}^{y_2} y X(y) \overline{Z(y)} dy + \frac{y_1^2}{2} X_1 \overline{Z_1},$$

then such operator L is delivered by the formula

$$\begin{aligned} LU = & \left(\int_{y_1}^{y_2} \ln\left(\frac{2y_2}{|\xi - y| + (\xi + y)}\right) \xi X(\xi) d\xi - \right. \\ & - \frac{\lambda y_1^2}{2} \ln\left(\frac{y}{y_2}\right) X_1, \int_{y_1}^{y_2} \ln\left(\frac{y_2}{\xi}\right) \xi X(\xi) d\xi - \\ & \left. - \frac{\lambda y_1^2}{2} \ln\left(\frac{y_1}{y_2}\right) X_1 \right). \end{aligned}$$

The spectral problem takes the form $LU = \mu U$, where $\mu = 1/\lambda$.

Theorem 2. *Asymptotical behavior as $\operatorname{Re} s \rightarrow +\infty$*

$$\Delta(s) \sim -\frac{\sqrt{y_1/y_2}}{2} e^{(y_2 - y_1)s}.$$

Proof. According to asymptotics of the modified Bessel functions as $\operatorname{Re} z \rightarrow +\infty$,

$$I_\nu(z) \sim \frac{1}{\sqrt{2\pi z}} e^z, \quad K_\nu(z) \sim \frac{\sqrt{\pi}}{\sqrt{2z}} e^{-z} :$$

$$\begin{aligned}\Delta(s) &\sim \frac{sy_1 - 2}{2s\sqrt{y_1y_2}}e^{(y_1-y_2)s} - \frac{sy_1 + 2}{2s\sqrt{y_1y_2}}e^{(y_2-y_1)s} \sim \\ &\sim -\frac{sy_1 + 2}{2s\sqrt{y_1y_2}}e^{(y_2-y_1)s} \sim -\frac{\sqrt{y_1/y_2}}{2}e^{(y_2-y_1)s}.\end{aligned}$$

Corollary. $X(y, s)$ -image (i.e. origin of that function) equals to zero at $t < 0$.

The roots of the determinant are simple poles (see below) located on the imaginary axes. To discard the corresponding singularities, we have to discard the residues in the roots. Let $\Delta(\lambda_k) = 0, \text{Im}\lambda_k > 0, k = 1, 2, 3, \dots$, then

$$\text{res}_{s=\lambda_k} X(y, s) = I_0(\lambda_k y) \text{res}_{s=\lambda_k} A(s) + K_0(\lambda_k y) \text{res}_{s=\lambda_k} B(s),$$

using the equalities $I_1'(z) = -\frac{1}{z}I_1(z) - I_0(z)$ and $K_1'(z) = -\frac{1}{z}K_1(z) + K_0(z)$,

$$(sy_1 I_0(sy_1) - 2I_1(sy_1))K_0(sy_2) = (sy_1 K_0(sy_1) + 2K_1(sy_1))I_0(sy_2).$$

$$\Delta'(\lambda_k) \text{res}_{s=\lambda_k} X(y_1, s) = \Delta'(\lambda_k) \left(I_0(\lambda_k y_1) \text{res}_{s=\lambda_k} A(s) + K_0(\lambda_k y_1) \text{res}_{s=\lambda_k} B(s) \right) =$$

$$\begin{aligned}&= I_0(\lambda_k y_1) \left(\left(\frac{2}{\lambda_k} \frac{\partial G}{\partial y}(y_1, \lambda_k) - \lambda_k y_1 G(y_1, \lambda_k) \right) K_0(\lambda_k y_2) + \right. \\ &\quad \left. + (\lambda_k y_1 K_0(\lambda_k y_1) + 2K_1(\lambda_k y_1))(G(y_2, \lambda_k) - V(\lambda_k)) \right) + \\ &\quad + K_0(\lambda_k y_1) \left((\lambda_k y_1 I_0(\lambda_k y_1) - 2I_1(\lambda_k y_1))(V(\lambda_k) - G(y_2, \lambda_k)) - \right. \\ &\quad \left. - \left(\frac{2}{\lambda_k} \frac{\partial G}{\partial y}(y_1, \lambda_k) - \lambda_k y_1 G(y_1, \lambda_k) \right) I_0(\lambda_k y_2) \right) =\end{aligned}$$

$$\begin{aligned}
&= I_0(\lambda_k y_1) \left(\left(\frac{2}{\lambda_k} \frac{\partial G}{\partial y}(y_1, \lambda_k) - \lambda_k y_1 G(y_1, \lambda_k) \right) K_0(\lambda_k y_2) + \right. \\
&+ (\lambda_k y_1 I_0(\lambda_k y_1) - 2I_1(\lambda_k y_1)) \frac{K_0(\lambda_k y_2)}{I_0(\lambda_k y_2)} (G(y_2, \lambda_k) - V(\lambda_k)) \Big) + \\
&+ K_0(\lambda_k y_1) \left((\lambda_k y_1 I_0(\lambda_k y_1) - 2I_1(\lambda_k y_1)) (V(\lambda_k) - G(y_2, \lambda_k)) - \right. \\
&\quad \left. - \left(\frac{2}{\lambda_k} \frac{\partial G}{\partial y}(y_1, \lambda_k) - \lambda_k y_1 G(y_1, \lambda_k) \right) I_0(\lambda_k y_2) \right) = \\
&= \left(\left(\frac{2}{\lambda_k} \frac{\partial G}{\partial y}(y_1, \lambda_k) - \lambda_k y_1 G(y_1, \lambda_k) \right) + \right. \\
&\quad \left. + \frac{\lambda_k y_1 I_0(\lambda_k y_1) - 2I_1(\lambda_k y_1)}{I_0(\lambda_k y_2)} (G(y_2, \lambda_k) - V(\lambda_k)) \right) \times \\
&\quad \times (I_0(\lambda_k y_1) (K_0(\lambda_k y_2) - K_0(\lambda_k y_1) (I_0(\lambda_k y_2))).
\end{aligned}$$

By discarding the residues, we obtain the condition:

$$V(\lambda_k) = G(y_2, \lambda_k) - \frac{\lambda_k^2 y_1 G(y_1, \lambda_k) - 2G'_y(y_1, \lambda_k)}{\lambda_k^2 y_1 I_2(\lambda_k y_1)} I_0(\lambda_k y_2).$$

We also note that if f and v may be continued analytically as entire or meromorphic functions, then so does X .

Theorem 3. *All zeroes of the determinant $\Delta(s)$ are simple.*

Proof. We set $k = y_2/y_1 > 0, x = z_1$, then $z_2 = kx$, and the determinant may be rewritten as follows:

$$\Delta(-ix) = (2J'_0(x) + xJ_0(x))Y_0(kx) - (2Y'_0(x) + xY_0(x))J_0(kx).$$

We consider a function

$$P(x) = \frac{\Delta(-ix)}{(2J'_0(x) + xJ_0(x))Y_0(kx)} = \frac{2Y'_0(x) + xY_0(x)}{2J'_0(x) + xJ_0(x)} - \frac{J_0(kx)}{Y_0(kx)}.$$

We prove that $P(x)$ has no multiple roots at $x > 0$. On the contrary, if $P(x) = P'(x) = 0$, then we set $v(f, g) = f'g - g'f$, so:

$$\begin{aligned}
& v(xJ_0(x) + 2J'_0(x), xY_0(x) + 2Y'_0(x)) = \\
& = (xJ_0(x) + 2J'_0(x))'(xY_0(x) + 2Y'_0(x)) - \\
& - (xJ_0(x) + 2J'_0(x))(xY_0(x) + 2Y'_0(x))' = \\
& = (J_0 + xJ'_0(x) + 2J''_0(x))(xY_0(x) + 2Y'_0(x)) - \\
& - (J_0 + xJ'_0(x) + 2J''_0(x))(xY_0(x) + 2Y'_0(x))' = \\
& = (x^2 - 2)v(J_0(x), Y_0(x)) + 2x(J''_0(x)Y_0(x) - Y''_0(x)J_0(x)) + \\
& + 4(J''_0(x)Y'_0(x) - Y''_0(x)J'_0(x)) = \\
& = (x^2 - 2)v(J_0(x), Y_0(x)) + 2((J'_0(x) + xJ_0(x))Y_0(x) - (Y'_0(x) + xY_0(x))J_0(x)) - \\
& - (4/x)((J'_0(x) + xJ_0(x))Y'_0(x) - (Y'_0(x) + xY_0(x))J'_0(x)) = \\
& = x^2v(J_0(x), Y_0(x)) = -2x, \\
& v(J_0(kx), Y_0(kx)) = k(J'_0(kx)Y_0(kx) - J'_0(kx)Y_0(kx)) = -2k/x.
\end{aligned}$$

Hence, the equalities $P(x) = P'(x) = 0$ take the form:

$$\frac{2Y'_0(x) + xY_0(x)}{2J'_0(x) + xJ_0(x)} = \frac{J_0(kx)}{Y_0(kx)},$$

$$\left(Y_0(x) + 2\frac{Y'_0(x)}{x}\right)^2 = \left(\frac{Y_0(kx)}{\sqrt{k}}\right)^2, \quad \left(J_0(x) + 2\frac{J'_0(x)}{x}\right)^2 = \left(\frac{J_0(kx)}{\sqrt{k}}\right)^2.$$

Or, taking into account the equality

$$\frac{d}{dx}H_0^{(1)}(x) = -H_1^{(1)}(x)$$

($H_\nu^{(1)}(x) = J_\nu(x) + iY_\nu(x)$ is the Hankel function of the first kind):

$$H_0^{(1)}(x) - 2H_1^{(1)}(x)/x = \pm(J_0(kx) \pm iY_0(kx))\sqrt{k}, x > 0$$

(any two of four signs are possible).

For certainty we consider the first case (the other cases may be done in a quite same manner, as it follows from the proof given below):

$$H_0^{(1)}(x) - 2H_1^{(1)}(x)/x = H_0^{(1)}(kx)\sqrt{k}.$$

We use the known formula [2]:

$$H_\nu^{(1)}(x) = \left(\frac{2}{\pi x}\right)^{1/2} \frac{e^{i(x-\pi\nu/2-\pi/4)}}{\Gamma(\nu+1/2)} \int_0^\infty e^{-u} u^{\nu-1/2} \left(1 + \frac{iu}{2x}\right)^{\nu-1/2} du.$$

The main equality takes the form:

$$\begin{aligned} \int_0^\infty e^{-u} u^{-1/2} \left(1 + \frac{iu}{2x}\right)^{-1/2} du + \frac{4}{ix} \int_0^\infty e^{-u} u^{1/2} \left(1 + \frac{iu}{2x}\right)^{1/2} du = \\ = \frac{e^{i(k-1)x}}{\sqrt{k}} \int_0^\infty e^{-u} u^{-1/2} \left(1 + \frac{iu}{2kx}\right)^{-1/2} du. \end{aligned}$$

Integrating the second integral by parts, we obtain:

$$\begin{aligned} \int_0^\infty e^{-u} u^{-1/2} \left(1 + \frac{iu}{2x}\right)^{-1/2} \left(1 + \frac{2i}{x} - \frac{2u}{x^2}\right) du = \\ = \frac{e^{i(k-1)x}}{\sqrt{k}} \int_0^\infty e^{-u} u^{-1/2} \left(1 + \frac{iu}{2kx}\right)^{-1/2} du. \end{aligned}$$

Finally, using the formula

$$\begin{aligned} \int_0^\infty e^{-u} u^{-1/2} \left(1 + \frac{iu}{2x}\right)^{-1/2} \left(-\frac{2u}{x^2}\right) du = \\ = \left(-\frac{1}{x^2}\right) \int_0^\infty e^{-u} u^{-1/2} \left(1 + \frac{iu}{2x}\right)^{-3/2} du, \end{aligned}$$

we obtain the equality

$$\begin{aligned} \int_0^{\infty} e^{-u} u^{-1/2} \left(1 + \frac{iu}{2x}\right)^{-1/2} \left(1 + \frac{2i}{x} - \frac{2}{x(2x + iu)}\right) du = \\ = \frac{e^{i(k-1)x}}{\sqrt{k}} \int_0^{\infty} e^{-u} u^{-1/2} \left(1 + \frac{iu}{2kx}\right)^{-1/2} du, \end{aligned}$$

which we rewrite as follows:

$$\begin{aligned} \int_0^{\infty} e^{it} t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} \left(1 + \frac{2i}{x} - \frac{2}{x(2x + t)}\right) dt = \\ = \frac{e^{i(k-1)x}}{\sqrt{k}} \int_0^{\infty} e^{it} t^{-1/2} \left(1 + \frac{t}{2kx}\right)^{-1/2} dt. \end{aligned}$$

We multiply both sides of this equality by $e^{i\alpha}$. Let ϕ is a value which delivers the maximum to the function

$$\begin{aligned} f(\alpha) = \operatorname{Im} \int_0^{\infty} e^{i(t+\alpha)} t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} \left(1 + \frac{2i}{x} - \frac{2}{x(2x + t)}\right) dt = \\ = \int_0^{\infty} \cos(t + \alpha) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} \frac{2}{x} dt + \\ + \int_0^{\infty} \sin(t + \alpha) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} \left(1 - \frac{2}{x(2x + t)}\right) dt. \end{aligned}$$

The statement of the theorem will be proved if we prove the inequality

$$\max_{\alpha} \operatorname{Im} \int_0^{\infty} e^{i(t+\alpha)} t^{-1/2} \left(1 + \frac{t}{2kx}\right)^{-1/2} dt =$$

$$= \max_{\alpha} \int_0^{\infty} \sin(t + \alpha) t^{-1/2} \left(1 + \frac{t}{2kx}\right)^{-1/2} dt \leq f(\phi),$$

or

$$\max_{\alpha} g(\alpha) \leq f(\phi),$$

where

$$g(\alpha) = \int_0^{\infty} \sin(t + \alpha) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} dt.$$

Let ψ is a value which delivers the maximum to $g(\alpha)$. Then

$$g'(\psi) = \int_0^{\infty} \cos(t + \psi) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} dt = 0,$$

$$\cos(\psi) \int_0^{\infty} (\cos t) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} dt =$$

$$= \sin(\psi) \int_0^{\infty} (\sin t) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} dt.$$

Hence

$$\begin{aligned} f(\psi - \alpha) &= \int_0^{\infty} \cos(t + \psi - \alpha) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} \frac{2}{x} dt + \\ &+ \int_0^{\infty} \sin(t + \psi - \alpha) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} \left(1 - \frac{1}{x^2(1 + t/(2x))}\right) dt = \\ &= \left(\frac{2}{x} \sin \alpha + \cos \alpha\right) \int_0^{\infty} \sin(t + \psi) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} dt - \end{aligned}$$

$$\begin{aligned}
& -\frac{\cos \alpha}{x^2} \int_0^{\infty} \sin(t + \psi) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-3/2} dt + \\
& + \frac{\sin \alpha}{x^2} \int_0^{\infty} \cos(t + \psi) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-3/2} dt.
\end{aligned}$$

We set

$$\begin{aligned}
A &= \int_0^{\infty} \sin(t + \psi) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-1/2} dt, \\
B &= \int_0^{\infty} \sin(t + \psi) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-3/2} dt, \\
C &= \int_0^{\infty} \cos(t + \psi) t^{-1/2} \left(1 + \frac{t}{2x}\right)^{-3/2} dt.
\end{aligned}$$

Then the demanded inequality may be rewritten as follows:

$$\left(A - \frac{B}{x^2}\right) \cos \alpha + \left(\frac{2A}{x} + \frac{C}{x^2}\right) \sin \alpha \geq A.$$

It is solvable if

$$\left(A - \frac{B}{x^2}\right)^2 + \left(\frac{2A}{x} + \frac{C}{x^2}\right)^2 \geq A^2,$$

or

$$2A(2A - B)x^2 + B^2 + 4xAC + C^2 \geq 0.$$

It is more convenient to rewrite this inequality as follows: $\psi = \pi/4 + \theta$,

$$\begin{aligned}
A_1 &= \int_0^{\infty} e^{-2x\nu} \nu^{-1/2} (1 + \nu^2)^{-1/4} \cos\left(\theta - \frac{1}{2} \arctg \nu\right) d\nu > 0, \\
B_1 &= \int_0^{\infty} e^{-2x\nu} \nu^{-1/2} (1 + \nu^2)^{-3/4} \cos\left(\theta - \frac{3}{2} \arctg \nu\right) d\nu > 0,
\end{aligned}$$

$$C_1 = - \int_0^{\infty} e^{-2x\nu} \nu^{-1/2} (1 + \nu^2)^{-3/4} \sin\left(\theta - \frac{3}{2} \operatorname{arctg} \nu\right) d\nu.$$

We note that

$$\int_0^{\infty} e^{-2x\nu} \nu^{-1/2} (1 + \nu^2)^{-1/4} \cos\left(\theta + \frac{\pi}{4} - \frac{1}{2} \operatorname{arctg} \nu\right) d\nu = 0,$$

and by the monotonousness of the function before the cosine we obtain:
 $\frac{\pi}{4} < \psi < \frac{3\pi}{8}$, i.e. $0 < \theta < \frac{\pi}{8}$.

The following inequality holds:

$$\gamma A_1 \geq B_1, \tag{14}$$

where $\gamma = (1 + \sqrt{2})/2$. In fact, let $\nu = \operatorname{tg}(2t)$, $0 < t < \pi/4$, then the inequality

$$\sqrt{1 + \nu^2} \cos\left(\theta - \frac{1}{2} \operatorname{arctg} \nu\right) \geq \cos\left(\theta - \frac{3}{2} \operatorname{arctg} \nu\right),$$

which implies estimate (14), takes the form

$$\cos(\theta - t) \geq \cos(2t) \cos(\theta - 3t),$$

or $\cos(\theta - t) \geq \cos(\theta - 5t)$. We set

$$f(t) = \cos(\theta - t) / \cos(\theta - 5t), \quad 0 < t < \pi/4,$$

then

$$\begin{aligned} f(t) &= \cos(4t) + \sin(4t) \operatorname{tg}(\theta - t) \leq \\ &\leq \sqrt{1 + \operatorname{tg}^2(\theta - t)} = 1 / \cos(\theta - t) \leq \sqrt{2} = 2\gamma - 1. \end{aligned}$$

Estimate (14) is proved; it also implies $2A_1 > B_1$.

Also,

$$B_1 > -C_1. \tag{15}$$

In fact,

$$\begin{aligned}
B_1 + C_1 &= \int_0^\infty e^{-2x\nu} \nu^{-1/2} (1+\nu^2)^{-3/4} \left(\cos\left(\theta - \frac{3}{2} \operatorname{arctg} \nu\right) - \sin\left(\theta - \frac{3}{2} \operatorname{arctg} \nu\right) \right) d\nu = \\
&= \sqrt{2} \int_0^{\pi/2} e^{-2x \operatorname{tg} t} \sin\left(\frac{\pi}{4} - \theta + \frac{3t}{2}\right) \frac{dt}{\sqrt{\sin t}} > 0,
\end{aligned}$$

since

$$0 < \frac{\pi}{4} - \theta < \frac{\pi}{4} - \theta + \frac{3t}{2} < \pi - \theta < \pi.$$

Corollary of (15): if $C_1 < 0$, then $B_1^2 > C_1^2$.

Now we prove the main inequality ($x \geq 0$):

$$2A_1(2A_1 - B_1)x^2 + B_1^2 + 4xA_1C_1 + C_1^2 \geq 0.$$

We omit index 1 below. If $C \geq 0$, then the inequality is obviously true by the corollary of estimate (14). If $C < 0$, then we transform the expression as follows:

$$2A(2A - B)x^2 + B^2 + 4xAC + C^2 = B(B - 2Ax^2) + (2xA + C)^2.$$

In the case $x < \sqrt{B/(2A)}$ the main inequality is obviously true. If $x \geq \sqrt{B/(2A)}$, then we introduce a constant $0 < q \leq 1$ and estimate the expression by using inequalities (14), (15) and their corollaries:

$$\begin{aligned}
&2A(2A - B)x^2 + B^2 + 4xAC + C^2 = \\
&= (1 - q^2)(2Ax)^2 - (1 - q^2)C/q^2 - 2ABx^2 + B^2 + (2qxA + C/q)^2 \geq \\
&\geq (1 - q^2)(2AB - C^2/q^2) \geq \\
&\geq (1 - q^2)(2B^2/\gamma - C^2/q^2) \geq (1/q^2 - 1)(q^2 - \gamma/2)2C^2/\gamma.
\end{aligned}$$

As the last step, we set $q = \sqrt{\gamma/2} < 1$. The theorem is proved.

Now we explore the distribution of the determinant's roots on the upper halfplane, in fact, on the upper imaginary semiaxis. We set

$$\Delta(x) = -x\delta(x), \quad \delta(x) = J_2(x)Y_0(kx) - Y_2(x)J_0(kx).$$

To continue $\delta(x)$ analytically from the positive semiaxis to the right halfplane we will use the following formulae [2, pp. 29, 88, 185]:

$$H_\nu^{(1)}(x) = J_\nu(x) + iY_\nu(x), \quad H_\nu^{(2)}(x) = J_\nu(x) - iY_\nu(x);$$

$$J_n(x) = \sum_{m=0}^{\infty} \frac{(-1)^m (x/2)^{n+2m}}{m!(n+m)!}, \quad n = 0, 1, 2, \dots;$$

$$H_\nu^{(1)}(x) = \left(\frac{2}{\pi x}\right)^{1/2} \frac{e^{i(x-\pi\nu/2-\pi/4)}}{\Gamma(\nu+1/2)} \int_0^\infty e^{-u} u^{\nu-1/2} \left(1+\frac{iu}{2x}\right)^{\nu-1/2} du, \quad \operatorname{Re} \nu > -1/2;$$

$$H_\nu^{(2)}(x) = \left(\frac{2}{\pi x}\right)^{1/2} \frac{e^{i(x-\pi\nu/2-\pi/4)}}{\Gamma(\nu+1/2)} \int_0^\infty e^{-u} u^{\nu-1/2} \left(1-\frac{iu}{2x}\right)^{\nu-1/2} du, \quad \operatorname{Re} \nu > -1/2.$$

If $x = iy, y > 0$, we use $H_0^{(1)} : \delta(x) = -i(J_2(x)H_0^{(1)}(kx) - H_2^{(1)}(x)J_0(kx))$.
If $x = -iy, y > 0$, we use $H_0^{(2)} : \delta(x) = i(J_2(x)H_0^{(2)}(kx) - H_2^{(2)}(x)J_0(kx))$.
In both cases $\operatorname{Im}\delta(x) = 0$. We also note that if $x \rightarrow 0$ then $J_n(x) = (x/2)^n/n! + O(x^{n+2})$ and [2, p. 75]

$$Y_n(x) = -\left(\frac{x}{2}\right)^{-n} \sum_{m=0}^{n-1} \frac{(n-m-1)!}{m!} \left(\frac{x}{2}\right)^{2m} + 2(\gamma + \ln\left(\frac{x}{2}\right))J_n(x) + O(x^n),$$

hence $\delta(x) \sim Cx^{-2}$ when $x \rightarrow 0$.

Since $s = 0$ is a regular point for $X(y, s)$, we may consider function

$$F(x) = -x^2\delta(x) = x^2(Y_2(x)J_0(kx) - J_2(x)Y_0(kx)),$$

which is analytic on the right half plane and has only real roots. To count the number of its roots, N , which lie on the interval $(0, R)$ on the real axis, we use the argument principle. We take a contour which consists

of the interval $[-iR, iR]$ and the semicircle $\Gamma = \{z : r = R, -\pi/2 \leq \phi \leq \pi/2\}$. The interval $[-iR, iR]$ gives no contribution to the variation of the argument since $F(z)$ is real there. On the semicircle we use the asymptotic formulae [2, p. 222]

$$J_n(z) \sim \sqrt{\frac{2}{\pi z}} \left(\cos\left(z - \frac{\pi n}{2} - \frac{\pi}{4}\right) (1 + \dots) - \sin\left(z - \frac{\pi n}{2} - \frac{\pi}{4}\right) \left(\frac{4n^2 - 1}{8z} + \dots\right) \right),$$

$$Y_n(z) \sim \sqrt{\frac{2\pi}{z}} \left(\sin\left(z - \frac{\pi n}{2} - \frac{\pi}{4}\right) (1 + \dots) + \cos\left(z - \frac{\pi n}{2} - \frac{\pi}{4}\right) \left(\frac{4n^2 - 1}{8z} + \dots\right) \right),$$

Hence, if R is large enough then $F(z) \sim 2k^{-1/2}z \sin((k-1)z)$. Therefore, N exceeds on 1 number of roots of $\sin((k-1)z)$ which lie on the interval $(0, R)$, so $N = 1 + [(k-1)R/\pi]$ (we may always suppose that the right end of the interval is not a root).

The authors are thankful to N.Petit for the idea, and academician E.I.Moiseev for useful discussions.

The article is partially supported by the Russian Foundation for Fundamental Research (projects 13-01-00241-a, 14-01-00163-a, 14-01-90005-Bel-a) and the Program for Leading Scientific Schools Support (NSh-5461.2014.9).

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