

AMERICAN INTERNATIONAL UNIVERSITY- BANGLADESH

Faculty of Engineering

Lab Report



Experiment # 04

Experiment Title: Digital Timer project using millis() function to avoid the problems associated with delay().

Course Title:	MICROPROCESSOR AND EMBEDDED SYSTEMS LAB		
Course Code:	COE3104	Section:	A
Semester:	Spring 2022-23	Degree Program:	BSc in CSE/BSc in EEE
Course Teacher:	Md. Ali Noor		

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FACULTY COMMENTS	Marks Obtained	
	Total Marks	

Abstract:

As a prelude experiment, knowledge about digital timers and usage of the `Millis ()` function of Arduino the experiment was done to avoid problems associated with the `delay ()` function. With the help of the Arduino Uno's built-in timer, this experiment aims to teach participants how to configure an Arduino board, use a digital timer, turn on an LED once every minute, and use delay functions. For simulation purposes, this experiment required a few key pieces of hardware, including an Arduino Uno board, six LED lights, jumper wires, one tilt switch, and an Arduino IDE. A timer or counter is a distinctive piece of hardware found inside many microcontrollers. They are used simply for counting. The `Millis ()` function helps to solve problems with the `delay ()` function. It keeps track of the time Arduino has been running in milliseconds.

Objective:

In this experiment, a digital timer will build that turns on an LED every minute. From this, it will know how long the projects are working on by using Arduino built-in Timer.

Apparatus:

- Arduino Uno/Arduino Mega Microcontroller Board
- Tilt sensor (One)
- LEDs (Six)

Results:

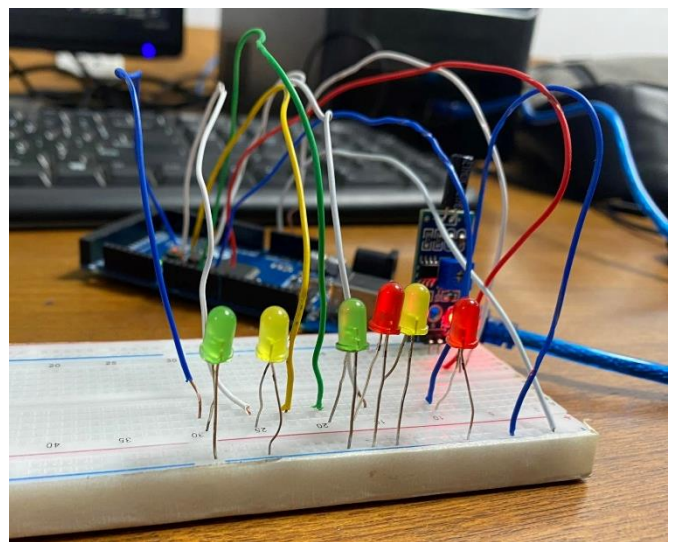
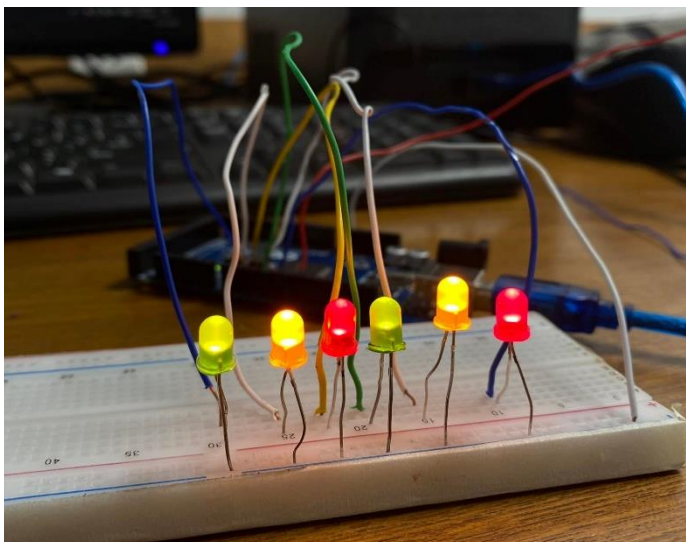


Fig 1: Practical circuit diagram

Simulation Results:

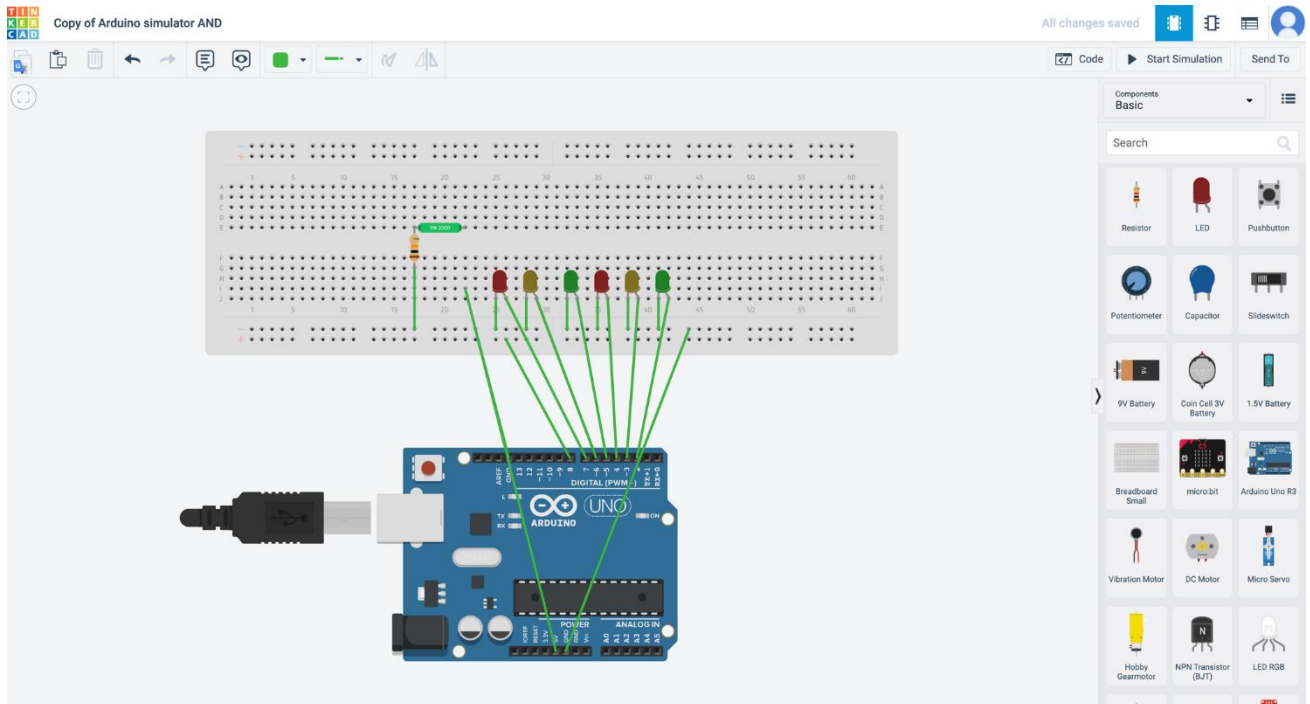


Fig 2: Simulated circuit diagram with lights off

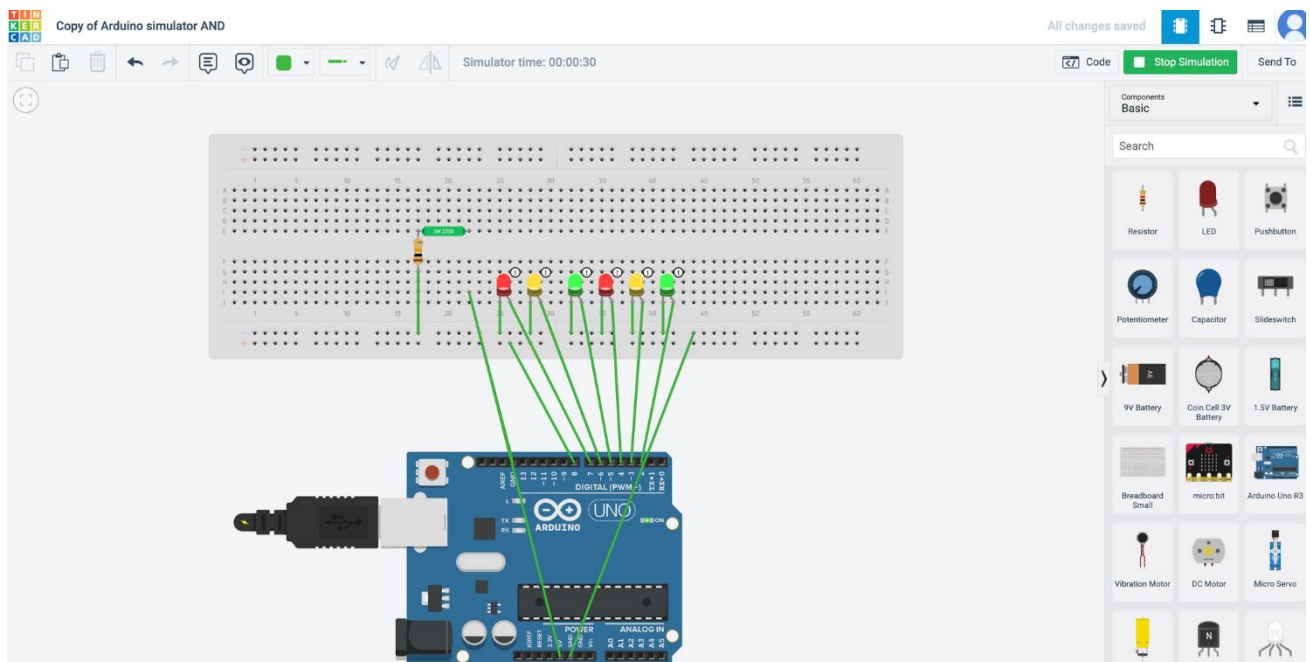


Fig 3: Simulated circuit diagram with lights on

Code:

millies_function | Arduino 1.8.19

File Edit Sketch Tools Help



millies_function

```
const int switchPin = 8;
unsigned long previousTime = 0;
int switchState = 0;
int prevSwitchState = 0;
int led = 2;
long interval = 2000;
void setup() {
  for(int x = 2;x<8;x++){
    pinMode(x, OUTPUT);
  }
  pinMode(switchPin, INPUT);
}
void loop(){
  unsigned long currentTime = millis();
  if(currentTime - previousTime > interval) {
    previousTime = currentTime;
    digitalWrite(led, HIGH);
    led++;
    if(led == 7){
    }
  }
  switchState = digitalRead(switchPin);
  if(switchState != prevSwitchState){
    for(int x = 2;x<8;x++){
      digitalWrite(x, LOW);
    }
    led = 2;
    previousTime = currentTime;
  }
}
```

Done uploading.

Sketch uses 1768 bytes (0%) of program storage space. Maximum is 253952 bytes.

Global variables use 19 bytes (0%) of dynamic memory, leaving 8173 bytes for local variables. Maximum is 8192 bytes.

millies_function | Arduino 1.8.19

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millies_function

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int switchState = 0;
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int led = 2;
long interval = 2000;
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  for(int x = 2;x<8;x++){
    pinMode(x, OUTPUT);
  }
  pinMode(switchPin, INPUT);
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void loop(){
  unsigned long currentTime = millis();
  if(currentTime - previousTime > interval) {
    previousTime = currentTime;
    digitalWrite(led, HIGH);
    led++;
    if(led == 7){
    }
  }
  switchState = digitalRead(switchPin);
  if(switchState != prevSwitchState){
    for(int x = 2;x<8;x++){
      digitalWrite(x, LOW);
    }
    led = 2;
    previousTime = currentTime;
  }
  prevSwitchState = switchState;
}
```

Done uploading.

Sketch uses 1768 bytes (0%) of program storage space. Maximum is 253952 bytes.

Global variables use 19 bytes (0%) of dynamic memory, leaving 8173 bytes for local variables. Maximum is 8192 bytes.

Discussion and Conclusion:

The implementation of a digital timer using Arduino's `millis()` function to avoid issues with the `delay()` function demonstrated that `millis()` can offer a more precise and reliable timer. During the `delay()` function can impede program execution and result in issues in some applications, the `Millis()` function allows for more flexible program flow and multitasking. Therefore, when implementing timing-dependent tasks in Arduino programs, it is advised to use the `millis()` function rather than `delay()`.

The experiment's goal was achieved, and a digital timer was built. Our course teacher and lab instructor walked us through the procedure and demonstrated how to run this code correctly. We have learned about the `millis()` function and how to use the tilt sensor to build the digital timer. The circuit has been meticulously designed, and Arduino programming has been used to create it. LEDs were turned on every minute, and whenever the tilt function was touched or moved, lights started to turn on from the beginning. The tinkercad software was used to simulate and verify the experiment's outcome.

References:

1. AIUB LAB MANUAL
2. <https://www.arduino.cc/>.
3. ATmega328 manual
4. <https://www.avrfreaks.net/forum/tut-c-newbies-guide-avr-timers>
5. <http://maxembedded.com/2011/06/avr-timers-timer0>
6. Jeremy Blum; Exploring Arduino: Tools and Techniques for Engineering Wizardry.