



Microprocessor & Computer Architecture (μ pCA)

UE19CS252

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Microprocessor & Computer Architecture (μ pCA)

Pipeline Processor- Hazards

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Syllabus



~~Unit 1: Basic Processor Architecture and Design~~

Unit 2: Pipelined Processor and Design

- ~~• 3 Stage ARM Processor~~
- ~~• 5 Stage Pipeline Processor~~
- ~~• Introduction to Pipeline Processor~~
- ~~• Understanding the Pipeline Execution~~
- What May Go Wrong
 - Introduction to Hazards
 - Attacking Hazards
 - Performance with Stalls
 - Structural Hazards

Unit 3: Memory Design

Unit 4: Input/Output Device Design

Unit 5: Advanced Architecture

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Text 1: “Computer Organization and Design”, Patterson, Hennessey, 5th Edition, Morgan Kaufmann, 2014.

Reference 1:“Computer Architecture: A Quantitative Approach”, Hennessey, Patterson, 5th Edition, Morgan Kaufmann, 2011.

Appendix C	Pipelining: Basic and Intermediate Concepts	
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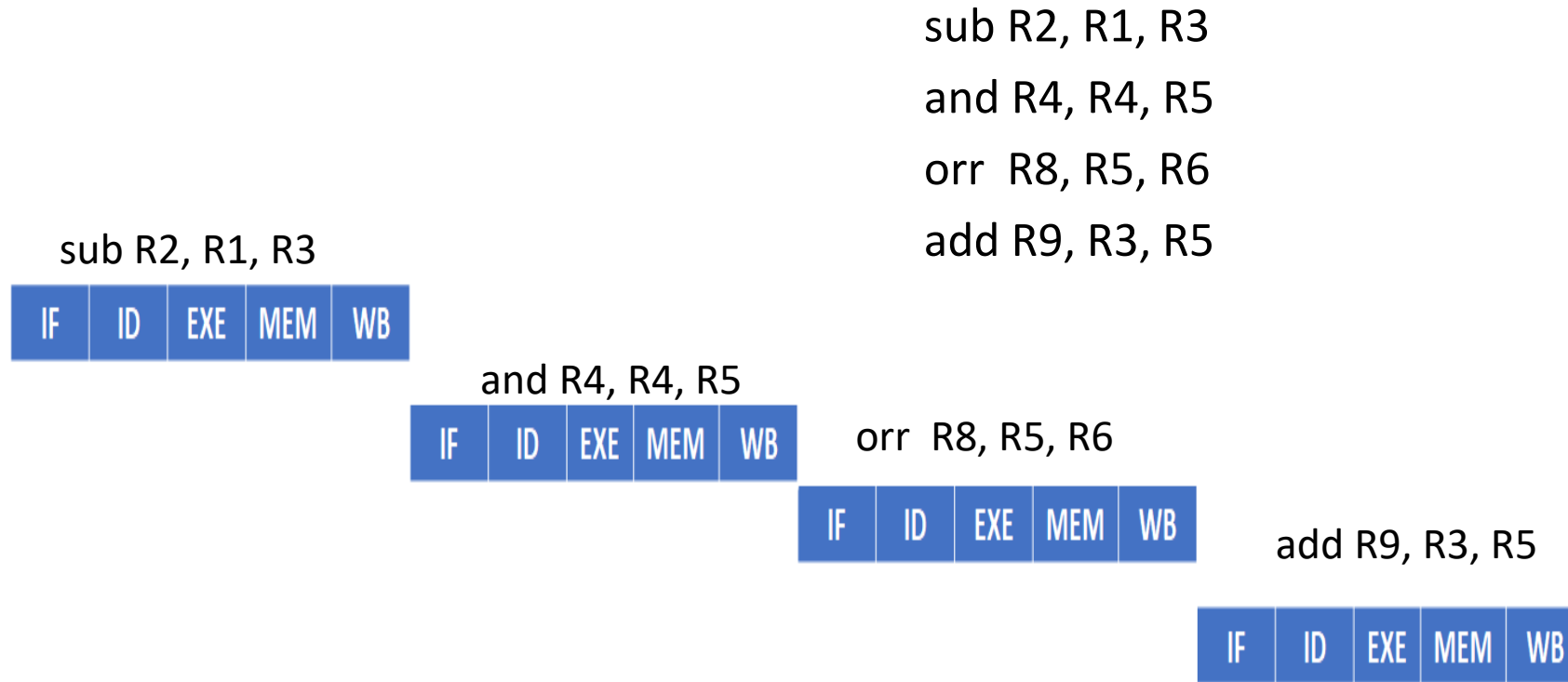
Facts About Pipeline Processor



- Pipelining increases the CPU instruction throughput. *(Pipeline Throughput)* Ideally, $CPI = 1$.
- Pipelining does not reduce the execution time of an instruction. *(Pipeline Latency)*
- Infact, it slightly increases the execution time due to the increased control overhead of the pipeline stage register delays.
- All instructions that share a pipeline must have the same stages in the same order.
 - ✓ **Add** does nothing during Mem stage
 - ✓ **sw** does nothing during WB stage
 - ✓ **b{cond}** does nothing in EX, MEM & WB stage

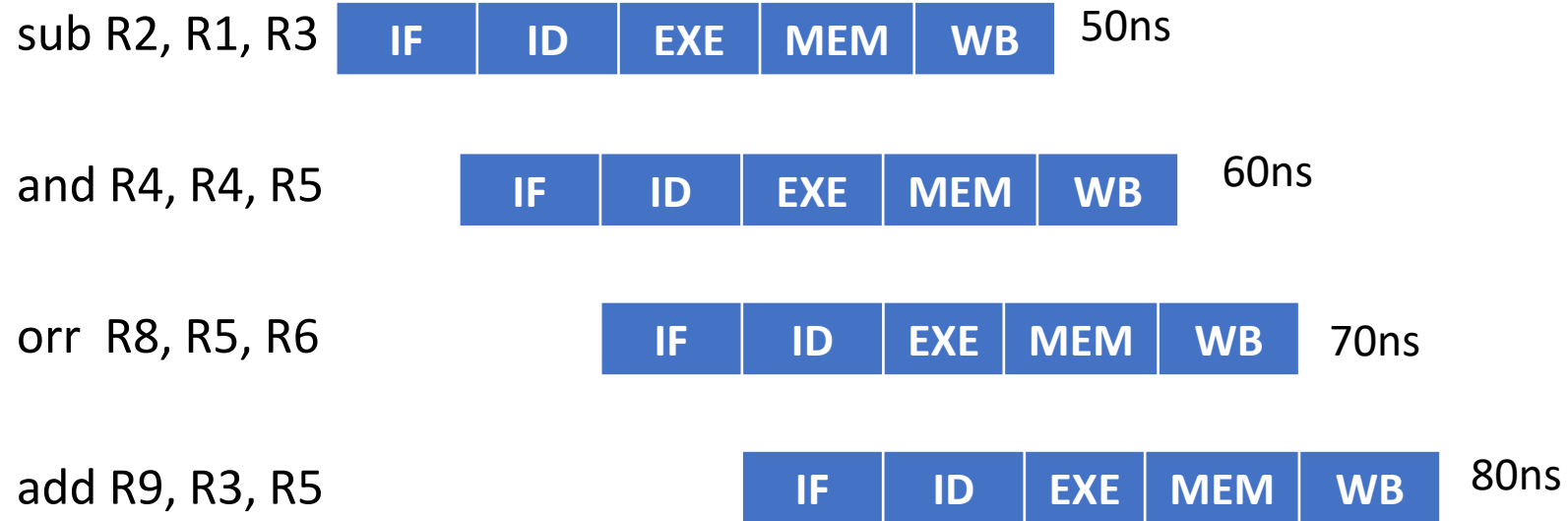
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Non-Pipeline Execution



If Each stage takes 10ns, the latency will be 50 ns and the throughput is 200 ns

Pipelining is Good



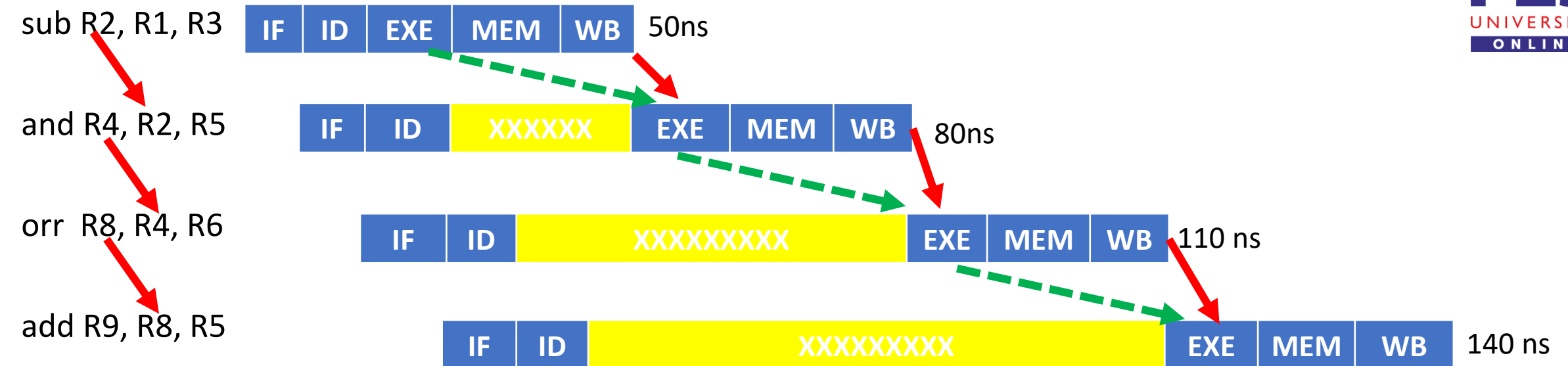
If Each stage take 10ns, the latency will be 50 ns

If Each stage take 10ns, the throughput is 80 ns instead of 200 ns

- Is Good, When every instruction is independent of the other and can execute in the pipeline without any constraint
- But in application programs, most of the statements are dependent on each other
 - $C = A + B;$
 - $E = C * D;$
- This causes constraint on the pipeline to execute these dependent instructions in given 5 cycles.
 - Increases Latency

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Pipelining, What May Go Wrong?



If Each stage take 10ns, the latency will be 50 ns

If Each stage take 10ns, the throughput is 80 ns instead of 200 ns

With gap between stages, the throughput is 140 ns instead of 80ns

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Pipelining, What May Go Wrong? → Hazards



- Situations that prevent the next instruction in the instruction stream from executing during its designated cycle
- Condition that prevents an instruction in the pipe from executing its next scheduled pipe stage
- Where one instruction cannot immediately follow another
- Hazards reduce the performance from the ideal speedup gained by pipelining

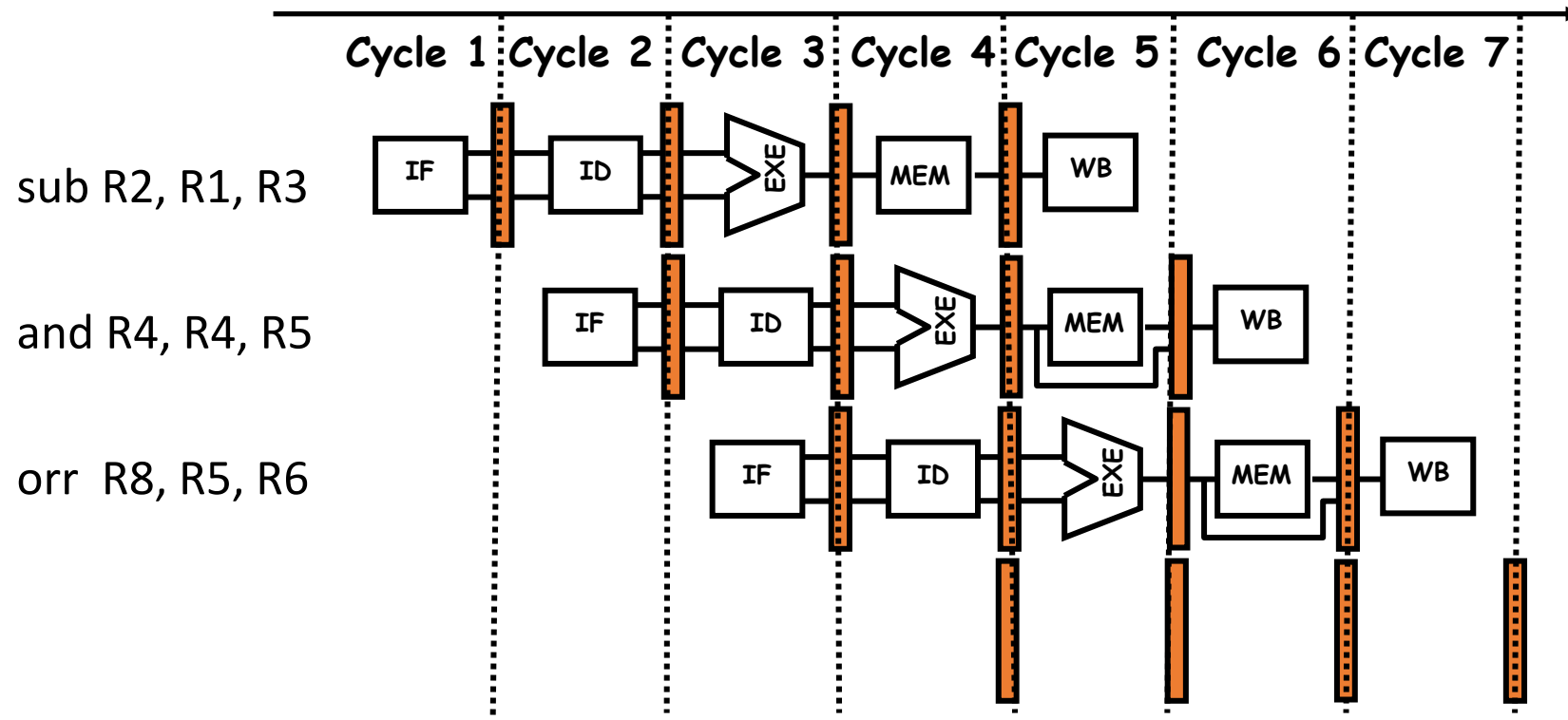
- **Structural Hazard:**
 - Due to structure of the pipeline
 - Hardware cannot support combination of instructions in the pipeline needing the same resources
- **Data Hazard:**
 - Due to data dependencies between instructions
 - Instruction depends on the result of prior instruction still in the pipeline
- **Control Hazard:**
 - Due to control instructions
 - Pipelining of branches & other instructions that change the PC

Stalls

- Common solution for any type of hazard is to **stall** the pipeline until the hazard is resolved (Stall Cycles)
- This is achieved by inserting one or more **“bubbles”** in the pipeline
- To do this, hardware or software must **detect** that a hazard has occurred (Hazard Detection)

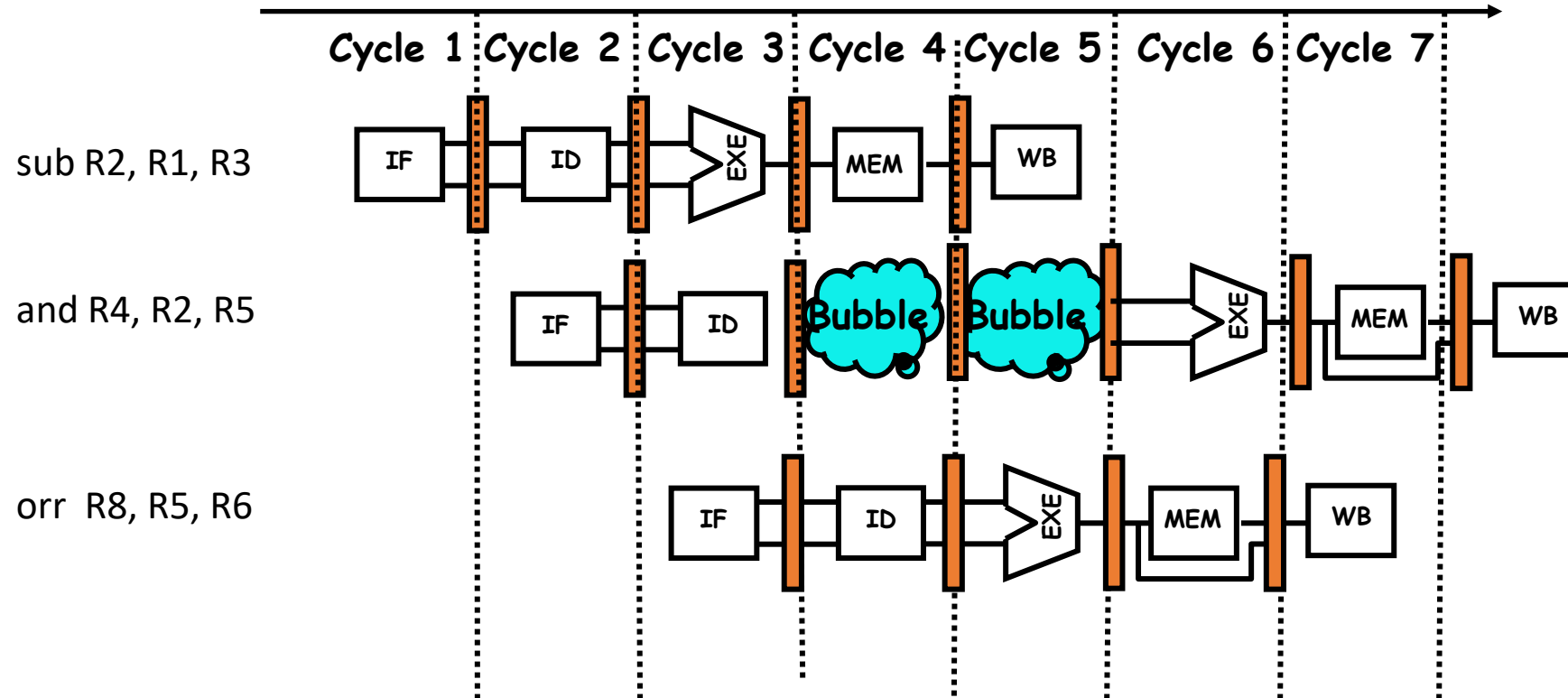
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Stalls



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Stalls



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Stalls

Instruction Number	Clock number									
	1	2	3	4	5	6	7	8	9	10
sub R2, R1, R3	IF	ID	EX	MEM	WB					
and R4, R2, R5		IF	ID	stall	stall	EX	MEM	WB		
orr R8, R5, R6			IF	ID	EX	MEM	WB			

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Disadvantage

- Stall cycle is a waste cycle
 - Opportunity wasted to execute one instruction
- Adds to pipeline delay and hence increases CPI
 - $(CPI > 1)$
 - Ex: If 30% are load/store, with only one memory; $CPI \geq 1.3$
- Not a preferred solution
- Affects performance of pipeline architecture

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Performance of Pipelines with Stalls



A stall causes the pipeline performance to degrade the ideal performance.

$$\text{Speedup from pipelining} = \frac{\text{Average instruction time unpipelined}}{\text{Average instruction time pipelined}}$$

$$\begin{aligned} &= \frac{\text{CPI}_{\text{unpipelined}} * \text{Clock Cycle Time}_{\text{unpipelined}}}{\text{CPI}_{\text{pipelined}} * \text{Clock Cycle Time}_{\text{pipelined}}} \\ &= \frac{\text{CPI}_{\text{unpipelined}}}{1 + \text{Pipeline stall cycles per instruction}} \end{aligned}$$

Note 1: Ignoring the cycle time overhead of pipelining and assume the stages are all perfectly balanced, then the cycle time of the two machines are equal

Note 2: Ideal CPI of pipeline processor is almost always =1

$$\begin{aligned} \text{CPI}_{\text{pipelined}} &= \text{Ideal CPI} + \text{Pipeline stall clock cycles per instruction} \\ &= 1 + \text{Pipeline stall clock cycles per instruction} \end{aligned}$$

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Performance of Pipelines with Stalls

If all instructions take the same number of cycles, which must also equal the number of pipeline stages (the depth of the pipeline) then unpipelined CPI is equal to the depth of the pipeline

$$\text{Speedup} = \frac{\text{Pipeline depth}}{1 + \text{Pipeline stall cycles per instruction}}$$

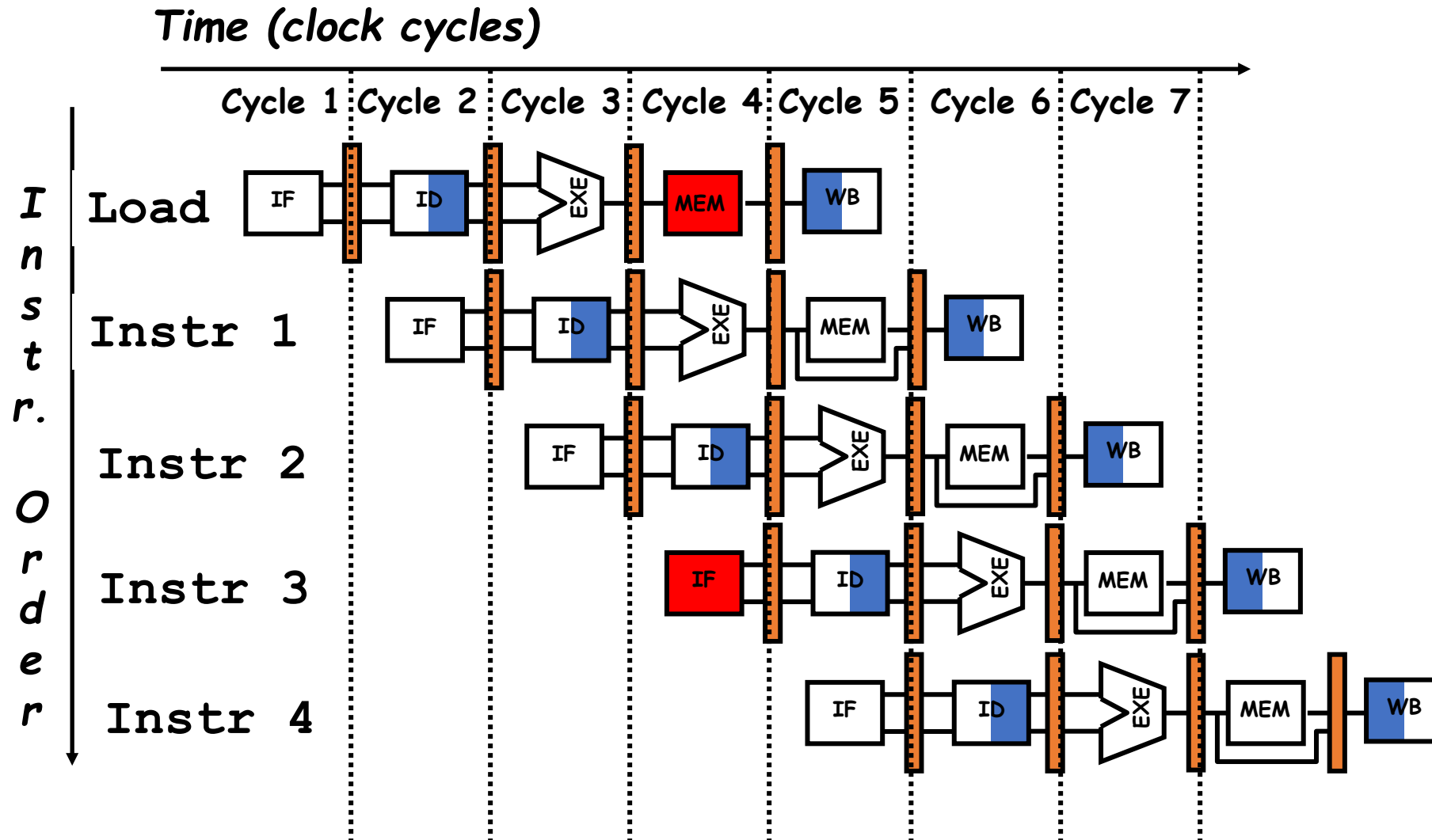
If there are no pipeline stalls, this leads to the intuitive result that pipelining can improve performance by the depth of pipeline.



- If a **resource conflict** arises due to a hardware **resource** being **required by more than one instruction in a single cycle**, and one or more such instructions cannot be accommodated, then a structural hazard occurs, for example:
 - **when a pipelined machine has a shared single-memory for data and instructions.**
 - Unified Memory
 - **when a machine has only one register file write port**
 - Skip MEM stage for add/sub..
 - **when a machine has overlapping of read and write**
 - Overlap ID & WB

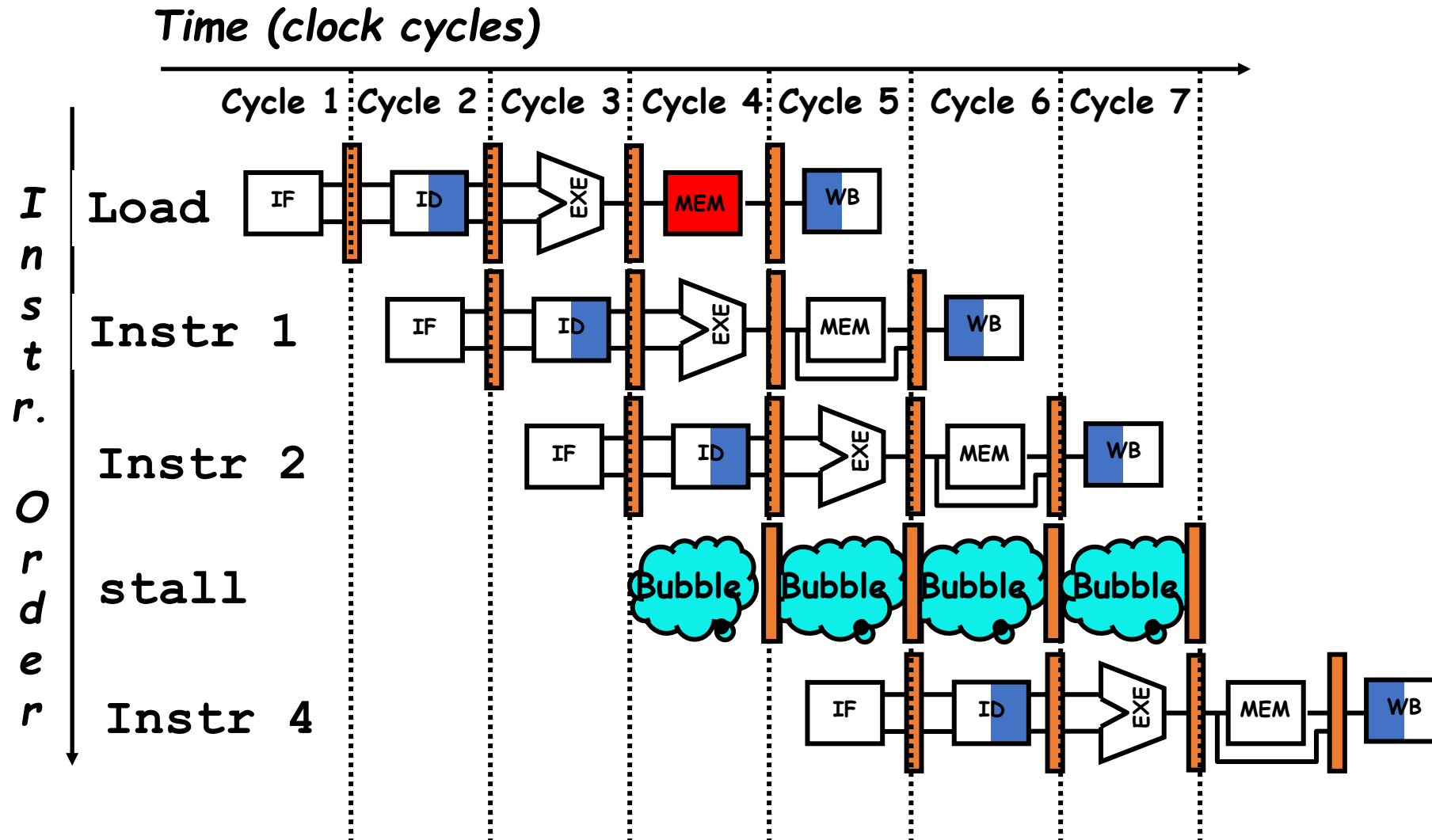
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Structural Hazard: IF VS MEM:



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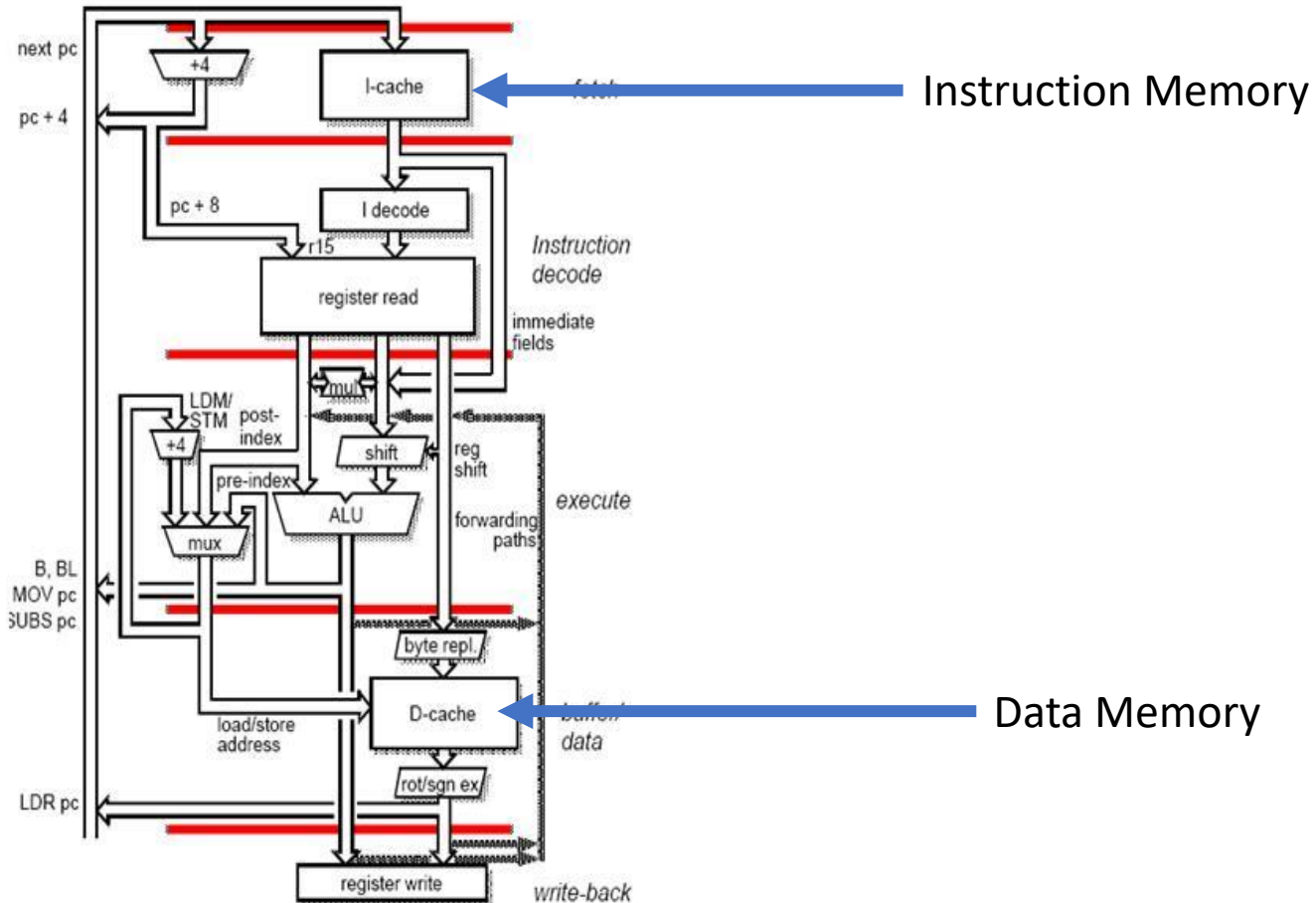
Structural Hazard: IF VS MEM:



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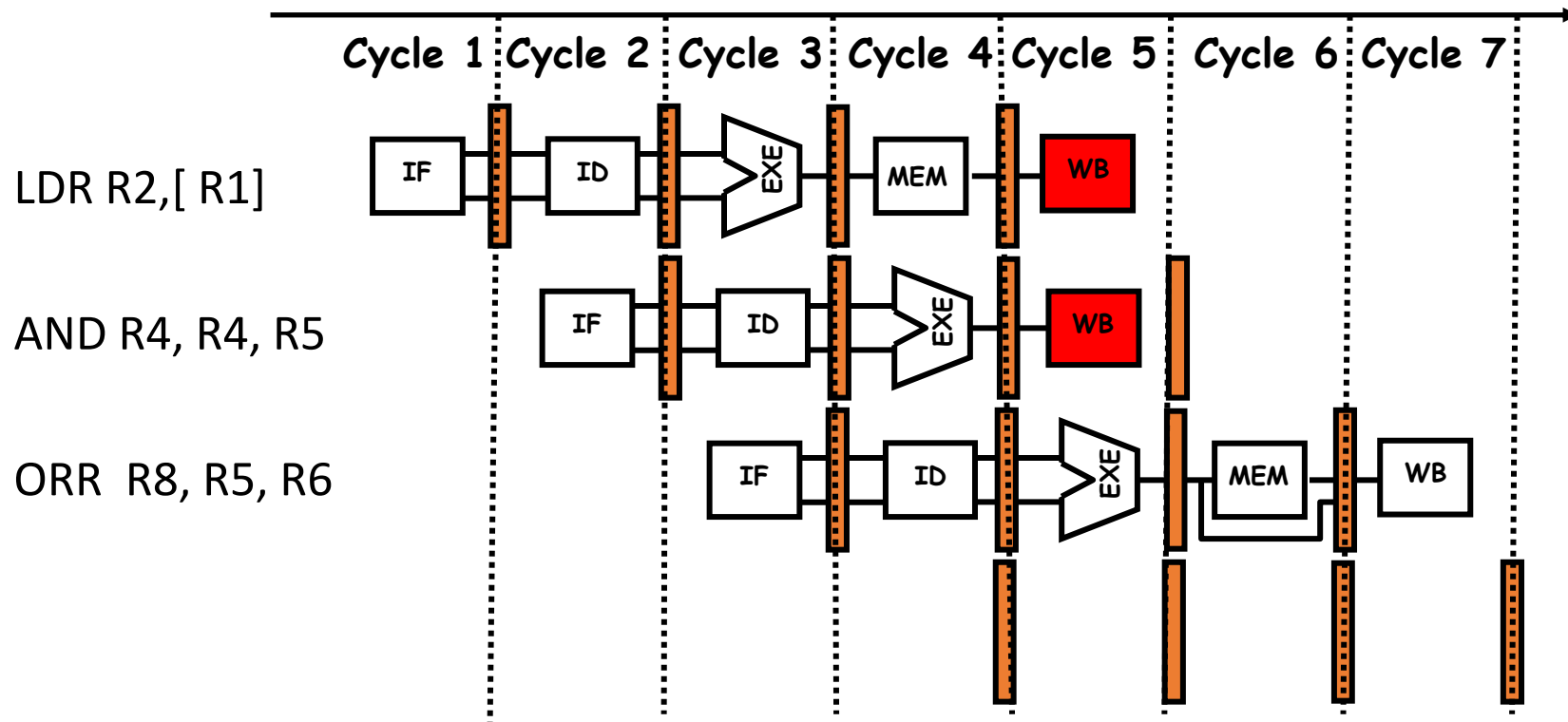
Structural Hazard: IF VS MEM: Solution

- Replication of resources
 - Split Memory (Instruction Memory & Data Memory)



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Structural Hazard: WB Vs WB:

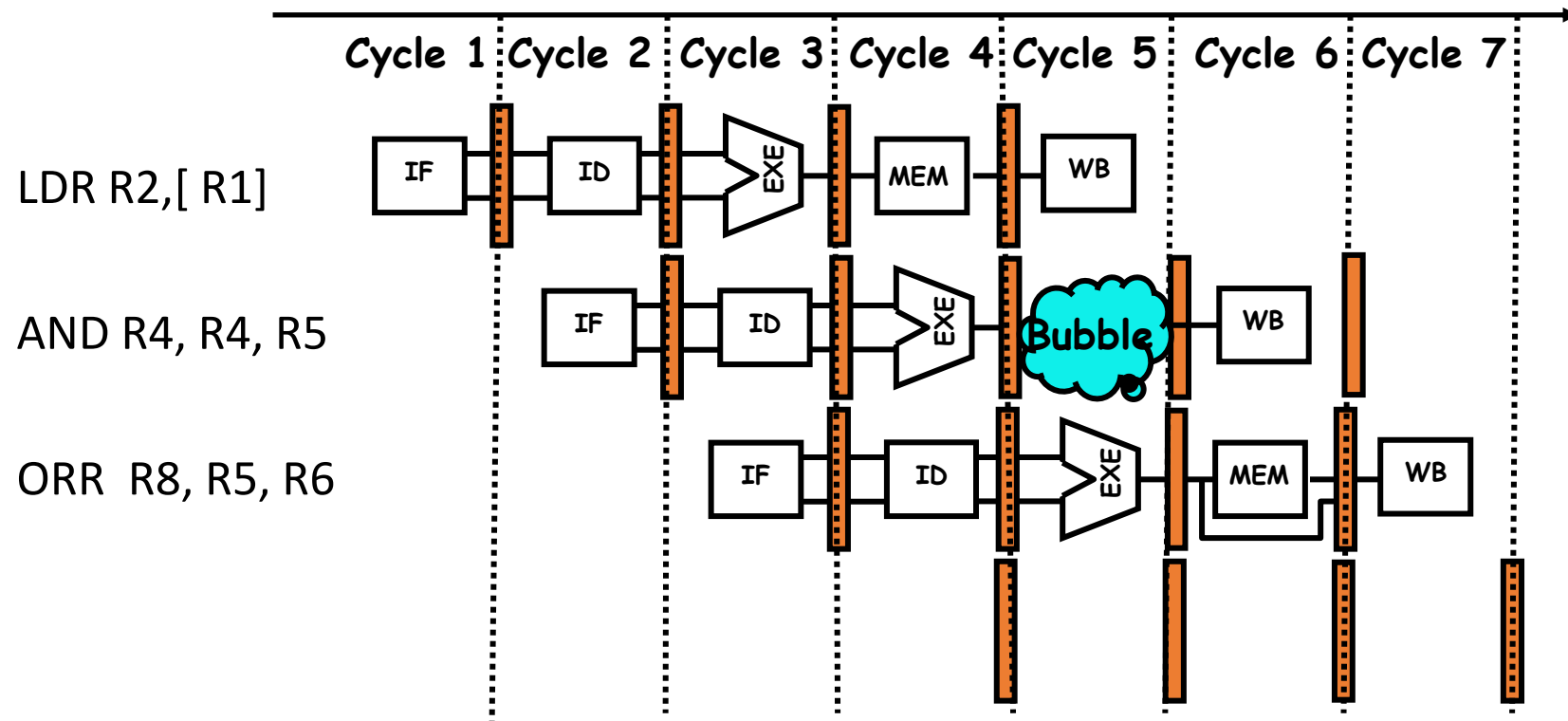


2 ways to solve this pipeline hazard.

- Stall the stage
- Let all the instruction follow all stages, AND may take longer than usual

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Structural Hazard: WB Vs WB: → Solution 1

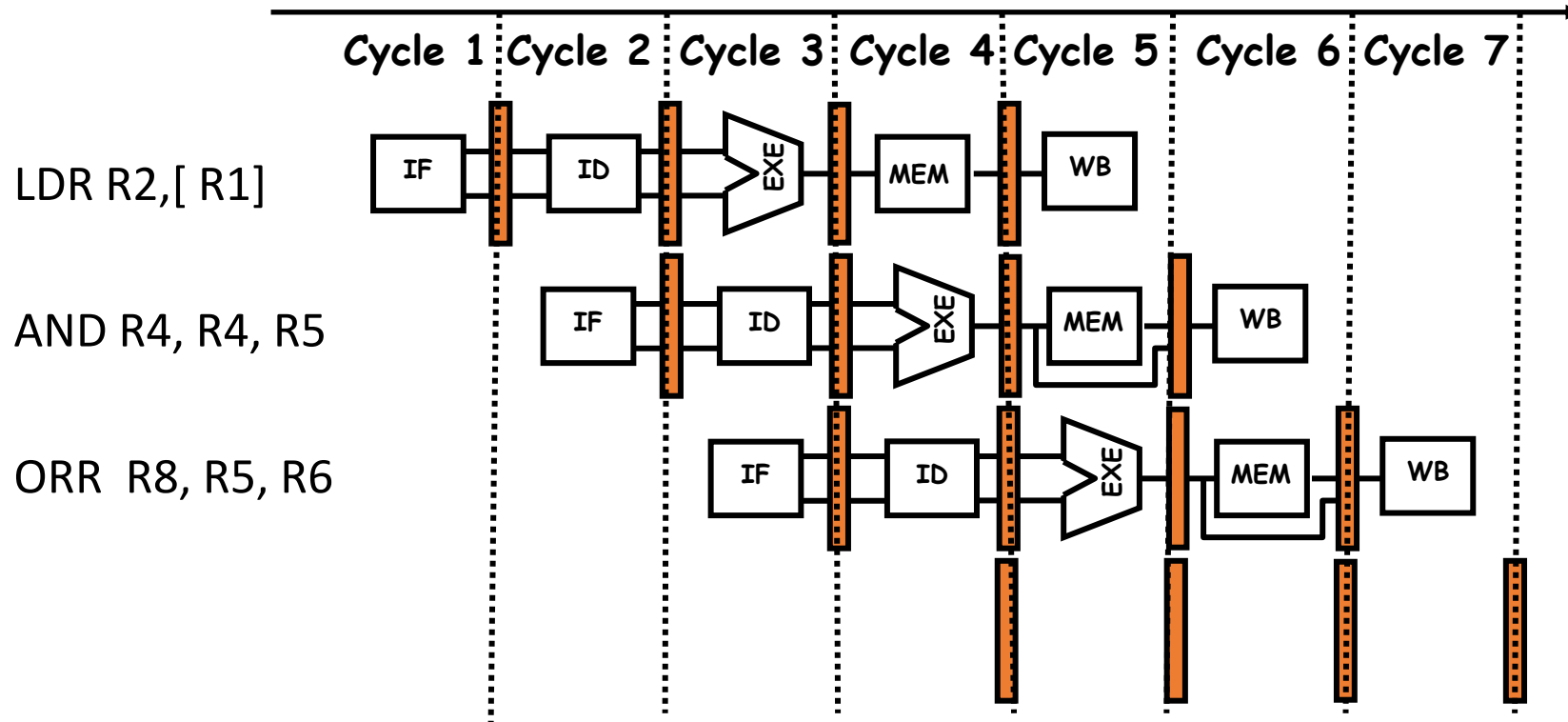


2 ways to solve this pipeline hazard.

- Stall the stage
- Let all the instruction follow all stages, AND may take longer than usual

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Structural Hazard: WB Vs WB: → Solution 2

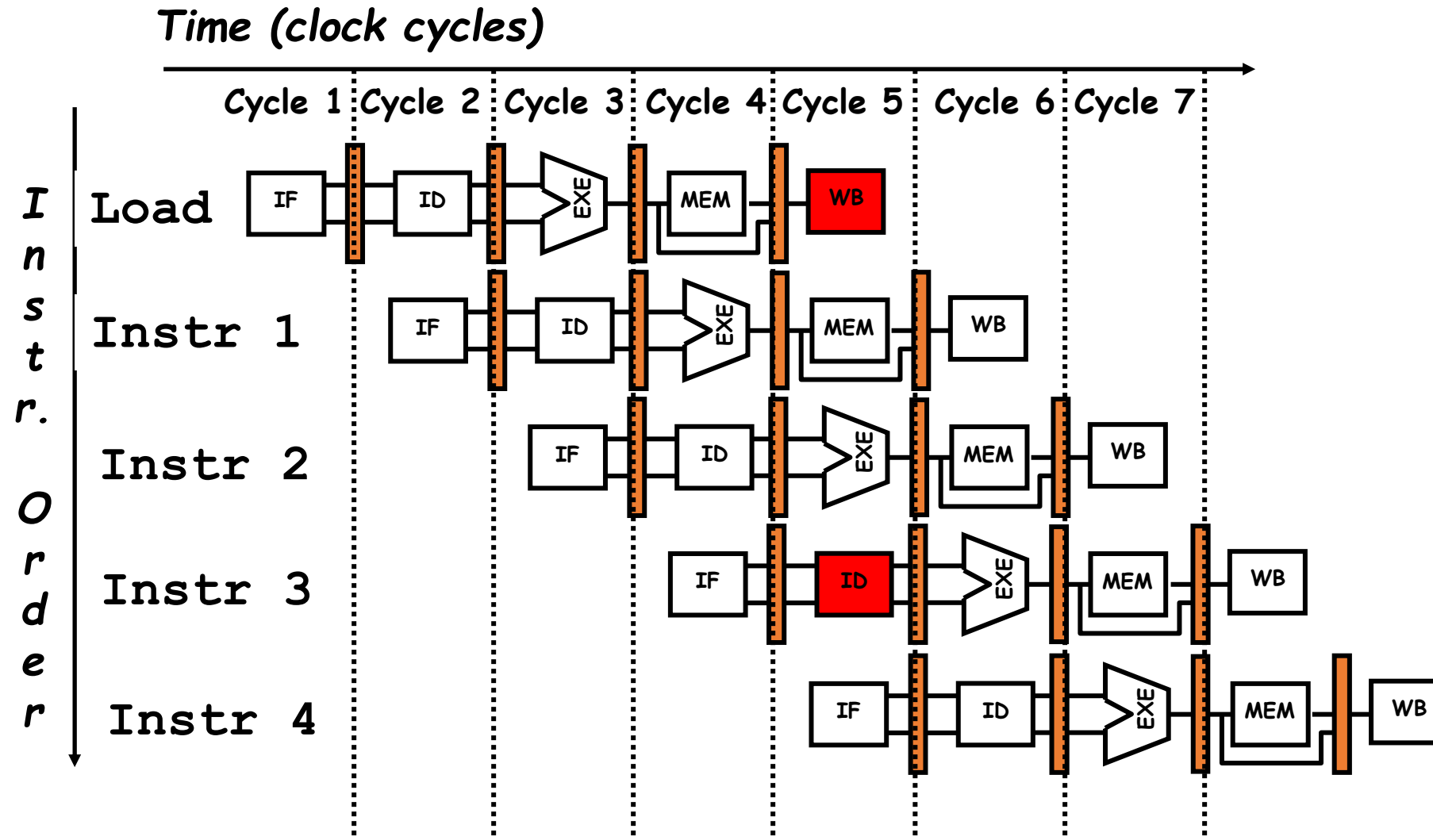


2 ways to solve this pipeline hazard.

- **Stall the stage**
- **Let all the instruction follow all stages, AND may take longer than usual**

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Structural Hazard: ID VS WB



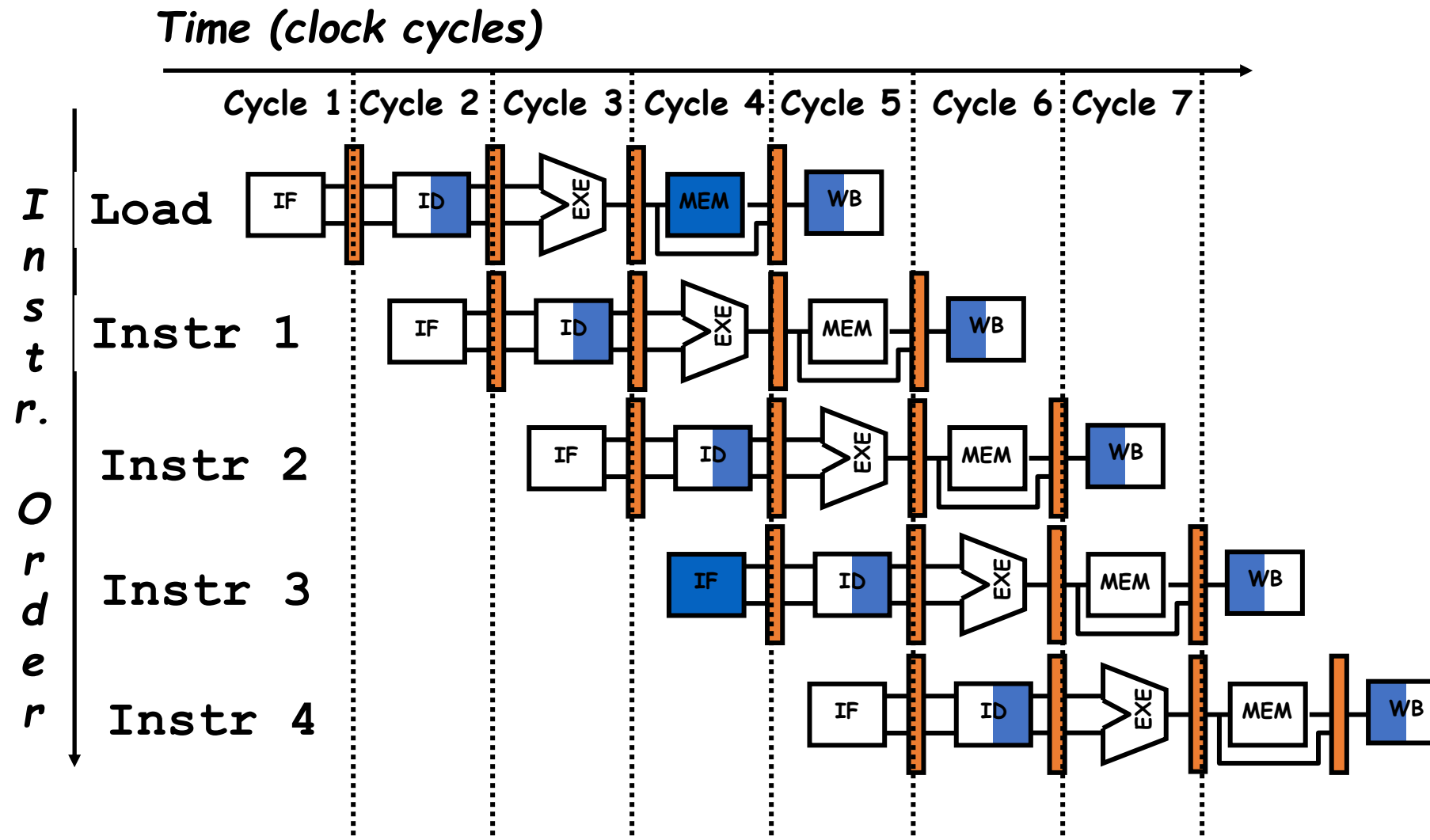
Partitioning/Overlapping

1st half of the cycle Reg Write

2nd half of the same cycle Reg Read

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Partitioning/Overlapping



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Performance (with stalls)



- $n \gg k$; **Speedup = k; no. of stages (also known as Depth of Pipeline)**
- *For 5-stage pipeline with stalls:*
- $Speed\ up = \frac{Depth\ of\ Pipeline}{CPI} = 5$
- $Speed\ up = \frac{Depth\ of\ Pipeline}{1 + Pipeline\ Stall\ cycles\ per\ instruction}$
- If stalls are 0, then Speedup = k = 5
- If say, 30% are Load/Store in a unified memory pipeline, then every load/store overlap with IF will introduce 3 stalls. Thus: $CPI = 1 + (3 \times 0.3) = 1.9$
- $Speed\ up = \frac{5}{1 + (3 \times 0.3)} = 2.63$

Data Hazards





THANK YOU

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