

Secure and Dynamic Route Navigation through —RSU-based Authentication in IoV for Smart City

Abstract

- 1) One of the significant services provided by IOV is Vehicular Navigation.
- 2) A proper routing mechanism helps drivers reach their destination in minimum time and with less fuel consumption.
- 3) However, such protocols often face security challenges.
- 4) In this paper, authors have proposed an authenticated navigation scheme with the help of pseudonym-based asymmetric key cryptography.
- 5) The architecture embodies GLP to find static route to a particular destination and message forwarding capabilities of RSUs to develop dynamic route after receiving feedback about traffic conditions.

Key Features of this Protocol

- 1) Integrity
- 2) Anonymity
- 3) Unlinkability
- 4) robust protection from important security threats
- 5) minimal end to end delay
- 6) efficient real time routing

Vehicular ad hoc networks



Key INTRODUCTION Points

1)Amalgnation of Internet of Things to VANETS has elevated vehicular communication to the next level known as Internet of vehicles

2)Disadvantages of VANETS

i)Low Network coverage area

ii)limited mobility

iii)restriction on number of vehicles

3)these will be rectified by internet of technologies hence this combo is powerful

INTERNET OF VEHICLES ARCHITECTURE

Internet/Cloud

Central Information
Processing Center

Moisture
Computing Layer

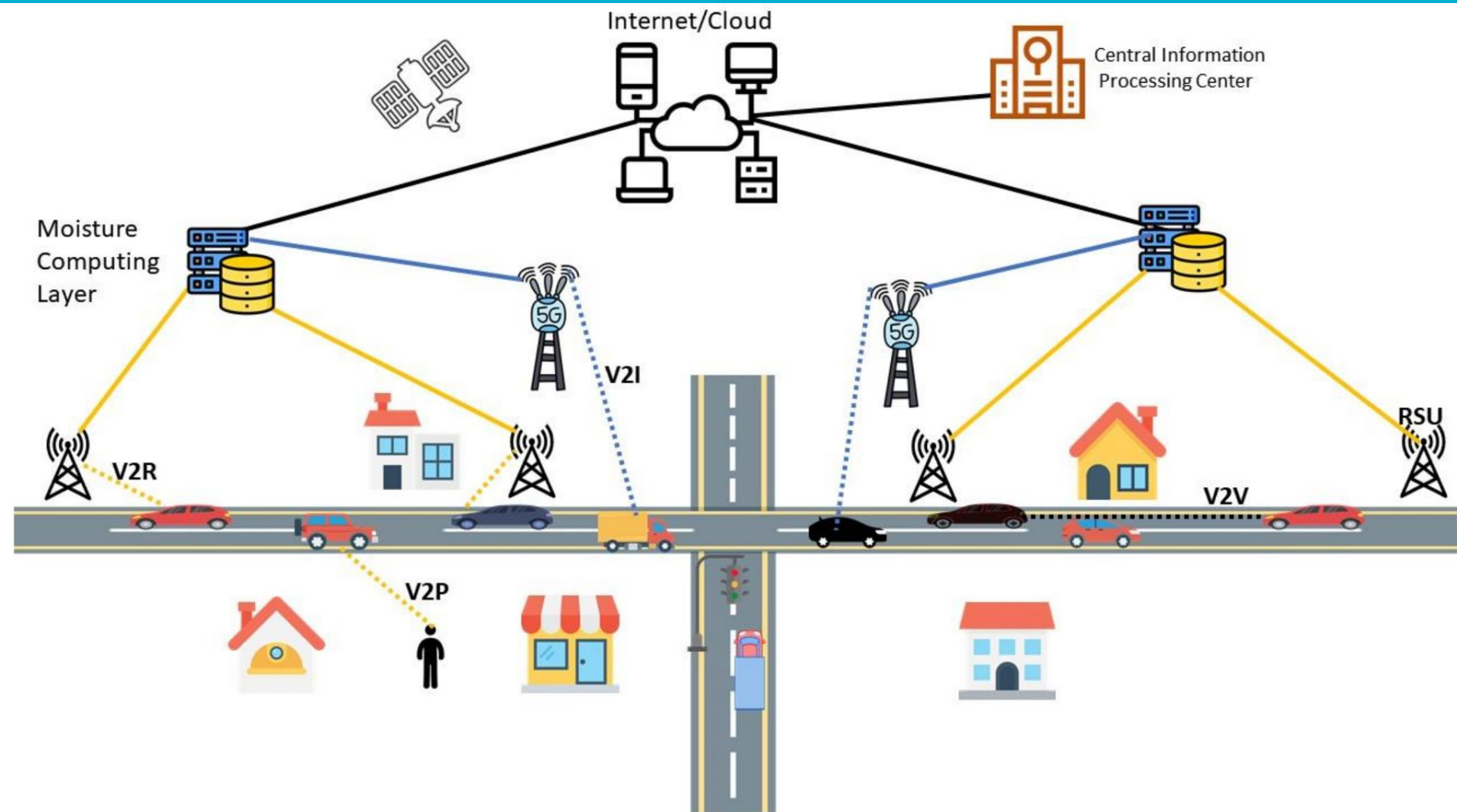
V2I

V2R

V2P

V2V

RSU



ISSUES IN THE IOV ARCHITECTURE

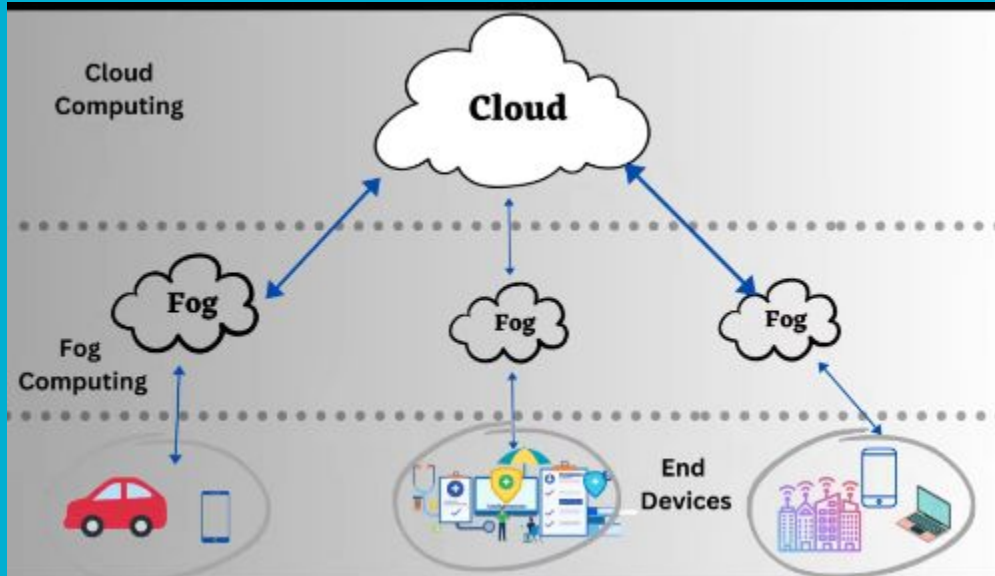
Three main issue in IOV Architecture

1) Since the cloud server is a centralized facility, it often encounters serious problems elaborated next. Firstly, it faces the issue of high computational latency due to the loads exerted by RSUs. Since all the RSUs are connected directly to the server, it often fails to provide real-time services to the drivers and passengers. It may lead to gross failure in fulfilling the objective of the IoV.

2) Secondly, breakdown of the cloud server leads to complete system failure unless there is an alternate arrangement

SOLUTION FOR THE ABOVE ISSUES IS FOG computing

FOG COMPUTING



Ref :- https://www.youtube.com/shorts/wIJZE_xKSZ4

Third Issue

The third issue is the security havoc in the centralized server, thus causing extensive damage to human lives

To address the Third issue it is crucial to separate server data security from message authentication

Key Features of The Proposed Framework

- A secure and dynamic route navigation framework through **RSU-based authentication** for IoV.
- **Geo-Location Provider (GLP)** and RSUs collaborate to function **without involving vehicles directly**, reducing delay and dependency.
- Uses **ElGamal encryption**, **digital signatures**, and **public key certificates** for secure communication.
- **Lightweight design**: avoids heavy operations like ECC point multiplication or bilinear pairings.

Security & Performance Highlights

- Ensures **driver anonymity**, **session key secrecy**, and **unlinkability**.
- Defends against **collusion**, **Sybil**, **MITM**, **replay**, and **masquerading attacks**.
- **GLP acts as a trusted intermediary** between navigation requesters and RSU responders.
- Verified using **Scyther tool**, confirming **strong security guarantees** and **efficient performance**.

Mathematical Preliminaries-Cryptographic Foundations

- Our protocol uses:
 - **ElGamal-based encryption, decryption, and digital signature**
 - **Cryptographic hash functions**
- Operations are performed over a **multiplicative group G** with generator **g**
- Common operations: **Multiplication** and **Exponentiation**

The ElGamal Cryptosystem

Key Generation (Alice – message receiver)

Select p	p is a very large prime number
Find a primitive root of p : g	
Choose a random integer a as her private key	$1 < a < p-1$
Compute e : $e = g^a \bmod p$	
Public key: (p, g, e)	

Encryption (Bob – message sender)

Plaintext: m	$m < p$
Select a random integer: b	$1 < b < p-1$
Compute two values C_1 and C_2 , where	
$C_1 = g^b \bmod p$	
$C_2 = m * e^b \bmod p$	
Ciphertext: (C_1, C_2)	

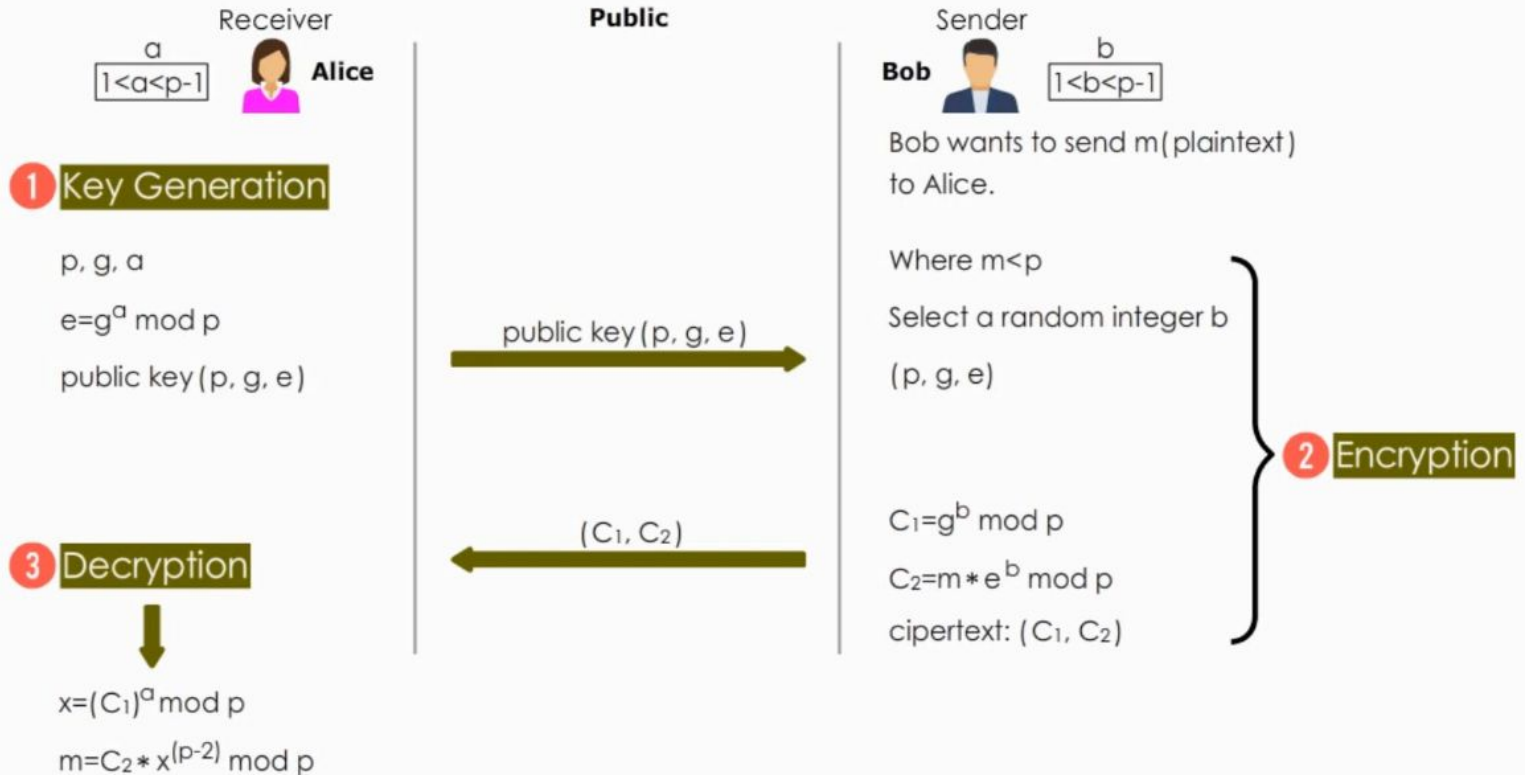
Decryption (Alice – message receiver)



Ciphertext: (C_1, C_2)
Plaintext:
$x = (C_1)^a \bmod p$
$m = C_2 * x^{(p-2)} \bmod p$

The ElGamal Cryptosystem

Three steps with math formulas



Digital Signature

Digital signature is equivalent to an hand written signature

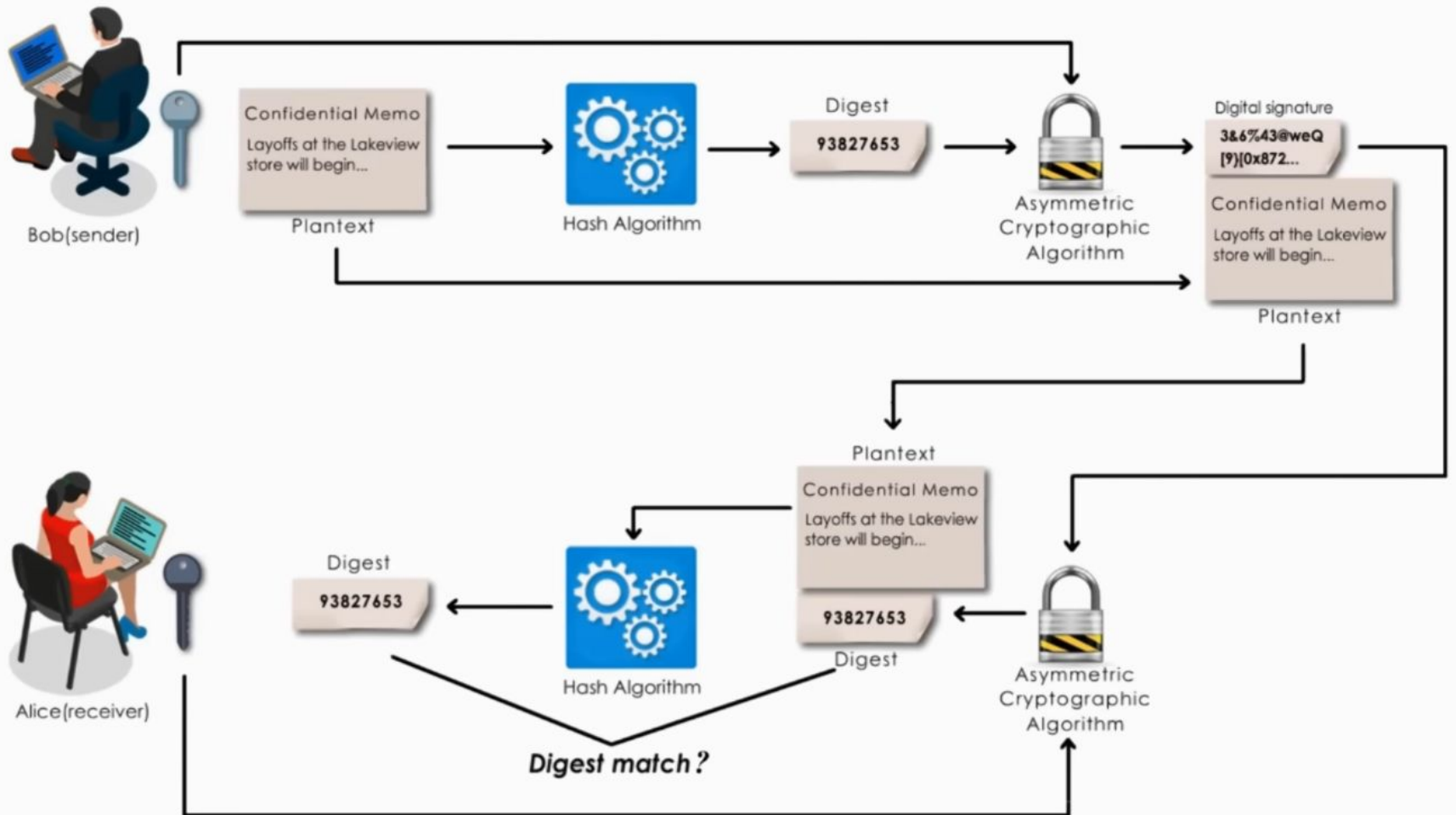
A Digital signature basically serves Three purposes

1)Authentication-A DS gives the receiver a reason to believe the message was created and sent by the claimed sender

2)Non repudiation-The receiver cant deny he didnt receive a message later on

3)Integrity-a DS assure no altering of the message is occurred

A digital signatures uses asymmetric key cryptography -public key cryptosystem



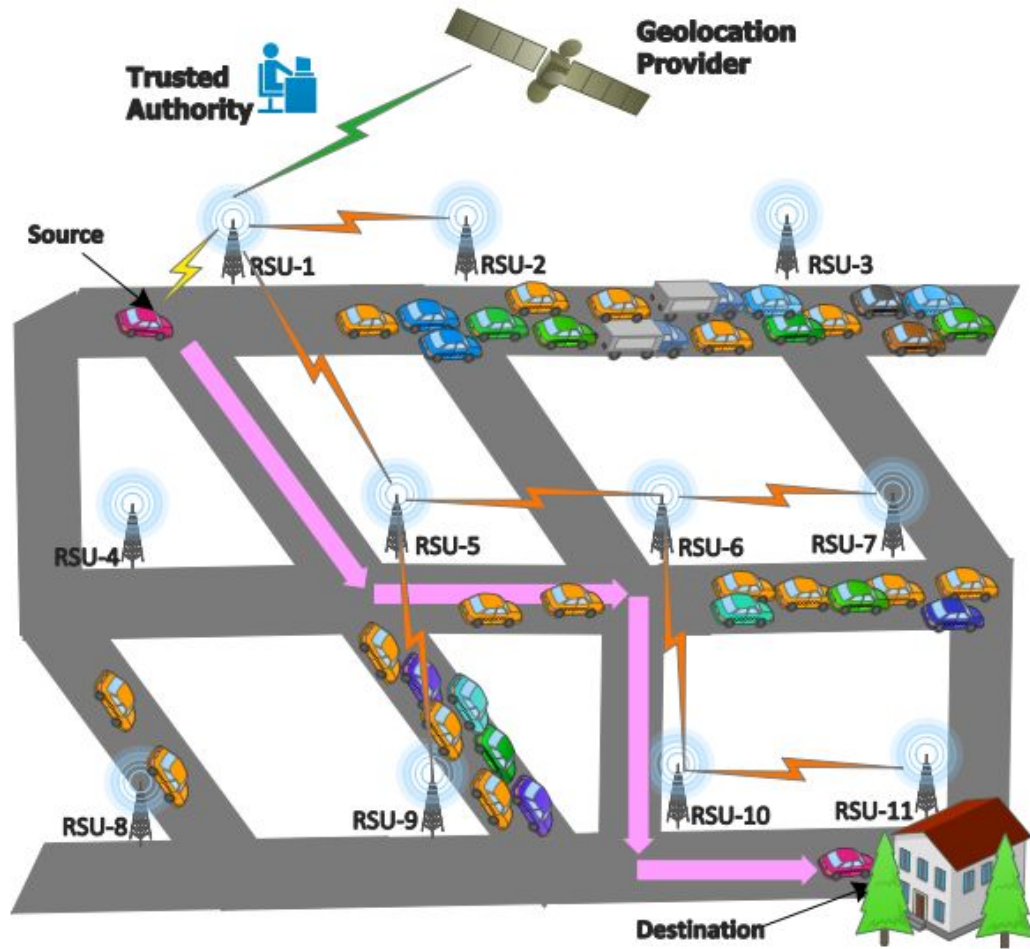


Fig. 2: Route selection in our navigation model.

TABLE I: Notations used in our proposed protocol

Notations	Meaning
GLP, V_i	Geolocation Provider, Vehicle i
R_j, TA	Road Side Unit j , Trusted Authority
ID_{V_i}, ID_{R_j}	Identity of V_i , Identity of R_j
$PID_{V_i}, PRID_j$	Pseudo-identity of V_i , Pseudo-identity of R_j
SND	Session-ID created by RSU
SID	Session-ID created by GLP
s, l, v	Random numbers
PR_x, PU_x	Private key of entity x , Public key of entity x
g, G	g is a generator of group G
$h(.)$	One-way hash function $h : \{0, 1\}^* \rightarrow G$
$ENC_{PU_x}(M_k)$	Encryption of message M_k with public key PU_x of entity x
$SIG_{PR_x}(M_k)$	Signature on message M_k with private key PR_x of entity x
$Cert_x, T$	Public key certificate of entity x , Timestamps

Working of The Protocol

there are mainly 5 steps discussed in the Research paper IN this section

- 1)System initialisation
- 2)Geolocation Provider Registration
- 3)RSU registration
- 4)Vehicle Registration
- 5)Navigation Scheme

System Initialisation

Performed by: Trusted Authority (TA)

- **Step 1:** Select a multiplicative group G of order q , with generator g
- **Step 2:** Choose a master secret key $s \in \mathbb{Z}_{q}^{*}$
- **Step 3:** Compute public key:

$$PUTA = g^s \bmod q$$

- **Step 4:** Choose a one-way hash function $h(.)$
- **Step 5:** Create a **digital certificate**:

$$CertTA = \langle TA, PUTA, SIGPRTA(TA, PUTA) \rangle$$

- **Step 6:** Publish system parameters:

$$\langle G, q, g, h(.), CertTA \rangle$$

✓ These parameters are then shared with RSUs and vehicles for secure communication and authentication.

Let's assume:

- TA ID: "TA"
- Public Key (from earlier): $PUTA = 6$
- Hash function: $h(.)$ (e.g., SHA-256 or similar)

Digital Certificate Construction:

makefile

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```
CertTA = <"TA", PUTA, SIGPRTA("TA", 6)>  
        = <"TA", 6, Signature>
```

Published System Parameters:

php-template

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```
<G =  $Z^{*23}$ , q = 23, g = 5, h(.), CertTA>
```

📌 These values are distributed securely to:

- RSUs (for registration and route verification)
- Vehicles (for pseudonym-based authentication)

GLP REGISTRATION

Goal: Register the **Geo-Location Provider (GLP)** securely with the **Trusted Authority (TA)**

Steps:

1. **GLP → TA:** Sends identity proof over a **secure channel** (e.g., TLS)

2. **TA → GLP:**

- Generates a **pseudo-identity**:

$$\text{PIDGLP} = h(s \parallel \text{IDGLP})$$

- Selects a random number $l \in \mathbb{Z}^*_q$

- Computes **private key**:

$$\text{PRGLP} = g^l$$

- Computes **public key**:

$$\text{PUGLP} = \text{PRGLP}^s$$

3. **GLP stores:**

PIDGLP , PRGLP , PUGLP for future use

- Prime order: $q = 23$
- Generator: $g = 5$
- Master secret (from TA): $s = 6$
- GLP ID = "GLP1" \rightarrow Hash: $h(s \parallel \text{IDGLP}) = 14$
- Random number selected by TA: $l = 3$

Calculations:

- $\text{PRGLP} = g^l \bmod q = 5^3 \bmod 23 = 125 \bmod 23 = 10$
- $\text{PUGLP} = \text{PRGLP}^s \bmod q = 10^6 \bmod 23 = 1,000,000 \bmod 23 = 6$

Goal: Securely register a **Roadside Unit (RSU)** with the **Trusted Authority (TA)**

Steps:

1. **RSU** → **TA**: Sends:

- Identity proof (**IDRSUj**)
- Location code (**LCj**)
(Over a **secure channel**)

2. **TA** computes:

- Pseudo-ID: $PRIDj = h(s || IDRSUj || LCj)$
- Private Key: **PRRSUj** (randomly chosen)
- Public Key: $P_{URSUj} = g^{PRRSUj}$

3. **TA** creates a digital certificate:

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$CertRSUj = \langle PRIDj, LCj, PURSUj, SIGPRTA(PURSUj, PRIDj, LCj) \rangle$

4. **TA** sends to **RSU**:

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$\langle CertRSUj, CertGLP, PRRSUj \rangle$

5. **RSU** stores in a **tamper-proof device** and **publishes** its public key.



- Prime order: $q = 23$, Generator: $g = 5$
- TA's master secret: $s = 6$
- RSU ID = "RSU1"
- Location Code = "ZoneA"
- Hash $\rightarrow h(s \parallel IDRSUj \parallel LCj) = 17$

TA assigns:

- Pseudo-ID: $PRIDj = 17$
- Private Key (chosen randomly): $PRRSUj = 4$
- Public Key: $P_{URSUj} = g^{PRRSUj} \bmod q = 5^4 \bmod 23 = 625 \bmod 23 = 4$



Certificate:

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$CertRSUj = \langle 17, "ZoneA", 4, SIGPRTA(4, 17, "ZoneA") \rangle$

Sent Securely to RSU:

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$\langle CertRSUj, CertGLP, PRRSUj = 4 \rangle$

 RSU stores all this in its **tamper-proof device** and **publishes** its public key for others to verify.

✓ Slide 1: Vehicle Registration – Explanation

Overview of the Registration Process:

- Each vehicle submits **ID proof** securely to the **Trusted Authority (TA)**.
- After one-time verification, TA issues a **Tamper-Proof Device (TPD)** (or **Hardware Security Module**).
- TA generates:
 - **Pseudo-identity:** $P_IDVi = h(s \parallel IDVi)$
 - **TPD Activation Password:** $PwVi$
 - **Random number:** $v \in \mathbb{Z}_{p}^{*}$
 - **Private Key:** $PRVi = g^v$
 - **Public Key:** $PUVi = PRVi^s = g^{vs}$
 - **Public Key Certificate:**
 $CertVi = \langle P_IDVi, PUVi, SIGPRTA(T \parallel P_IDVi \parallel PUVi) \rangle$

Final Output (Sent to Vehicle securely):

$\langle P_IDVi, PwVi, PUVi, PRVi, CertVi \rangle$ along with the TPD.

12 34 Slide 2: Vehicle Registration – Numerical Example

Assume:

- $IDVi = "KA01AB1234"$
- $s = 9$, $v = 4$, $g = 2$
- $h()$ is a hash function (e.g., SHA-256 simplified for illustration)

Step-by-step:

1. $P_IDVi = h(9 \parallel "KA01AB1234") = h("9KA01AB1234") \rightarrow \text{e.g., "a4c1..."}$
2. $PRVi = g^v = 2^4 = 16$
3. $PUVi = PRVi^s = 16^9 = 68719476736$
4. $CertVi = \langle "a4c1...", 68719476736, SIGPRTA(...) \rangle$






Delivered securely:

$\langle "a4c1...", PWVi, 68719476736, 16, CertVi \rangle + TPD$





Navigation Scheme

- Real-time route discovery is challenging in urban traffic due to dynamic conditions.
- AI/ML-based sub-optimal solutions exist, but secure communication is critical.
- Goal: Find safe, optimal routes with minimal delay, fuel, and risk.
- RSUs & GLP assist vehicles by:
 - Authenticating queries
 - Finding static + dynamic routes
 - Ensuring privacy and robustness

RSU and GLP Role in Navigation

1.  Vehicle → RSU: Sends (source, destination) query.
2.  RSU authenticates vehicle & forwards query to GLP.
3.  GLP:
 - Uses Dijkstra's algorithm to compute route options.
 - Maps zones to RSUs.
 - Sends ACK to original RSU (route not revealed).
4.  GLP → Neighboring RSUs: Sends route sketch to start dynamic route discovery.
5.  Each RSU:
 - Caches route
 - Forwards to next RSU if traffic/weather is favorable
 - Drops otherwise (session time-out triggers retry)

Route Finalization & Vehicle Reply

6.  RSUs forward query hop-by-hop until reaching destination RSU.
7.  Destination RSU:
 - Sends reply backward through upstream RSUs
 - Reaches GLP
8.  GLP selects reply with lowest hop count
9.  GLP → Original RSU → Vehicle:
 - Sends final route
 - If δT timeout occurs → Vehicle retries via same/new RSU

 Ensures secure, traffic-aware, efficient navigation

Authentication and Navigation

Vehicle – RSU Communication

- ◆ Step 1:

- Vehicle Vi receives beacon from RSU1 (R1)
- Sends message M1 to R1:

$M1 = \langle PRID1, CertVi, T, NQ, SIGPRVi(h(PRID1 || NQ || T)) \rangle$

- PRID1: RSU pseudonym
- CertVi: Vehicle certificate issued by TA
- T: Timestamp
- NQ: Navigation query (initially null)

◆ Step 2:

- RSU1 verifies CertVi using TA's public key
- If valid, uses PUVi (from CertVi) to verify SIGPRVi
- On success: identifies a navigation query request from Vi

RSU1 Responds to Vehicle

- ◆ Step 3:

- RSU1 generates a session-ID (SND)
- Encrypts (SND, CertGLP) using PUVi

- Sends Message M2:

M2 = <PRID1, PIDVi, CertR1, T,
SIGPRR1(PRID1, PIDVi, T),
ENCPUVi(SND, CertGLP)>

◆ Step 4:

- Vehicle verifies SIGPRR1 and timestamp T
- Decrypts encrypted part to get SND and CertGLP
- Prepares navigation query $NQ = \langle S, D \rangle$

- Sends Message M3:

$M3 = \langle PIDVi, PRID1, T, ENCPUGLP(PIDVi, PRID1, SND, NQ),$
 $SIGPRVi(h(PIDVi, PRID1, T)) \rangle$

RSU1 \Rightarrow GLP Communication

- ◆ Step 1:

- RSU1 verifies SIGPRVi (can't decrypt NQ)
- Forwards encrypted NQ to GLP

- Message M4:

M4 = <PRID1, CertR1, PIDGLP, T,
ENCPUGLP(PIDVi, PRID1, SND, NQ),
SIGPRR1(h(PRID1, PIDGLP, T))>

◆ Step 2:

- GLP verifies CertR1, checks timestamp freshness
- Decrypts with its private key to get $\langle \text{PIDVi}, \text{PRID1}, \text{SND}, \text{NQ} \rangle$
- Sends acknowledgment to RSU1

GLP \Rightarrow RSUs (Path Discovery)

- GLP finds possible routes for $NQ = \langle S, D \rangle$:

$RT1 = R1 \rightarrow R2 \rightarrow R6 \rightarrow R7 \rightarrow R11$

$RT2 = R1 \rightarrow R5 \rightarrow R6 \rightarrow R10 \rightarrow R11$

$RT3 = R1 \rightarrow R5 \rightarrow R9 \rightarrow R10 \rightarrow R11$

$RT4 = R1 \rightarrow R5 \rightarrow R6 \rightarrow R7 \rightarrow R11$

- Sends to next-hop RSUs:

- To R2:

$ENCPUR2(NQ, RT1, T, SID, CertRSU1), SIGPRGLP(h(NQ, RT1, T, SID))$

-
- To R5:

ENCPUR5(NQ, RT2, RT3, RT4, T, SID, CertGLP), SIGPRGLP(h(...))

- GLP stores map(SND, SID), NQ, vehicle & RSU IDs

RSU₅ ➤ RSU₆ & RSU₉

- R2 detects traffic jam → remains silent

- R5 is active:

- Sends to R6:

ENCPUR6(NQ, RT2, RT4, T, SID, CertRSU5),

SIGPRR5(h(NQ, RT2, RT4, T, SID))

- Sends to R9:

ENCPUR9(NQ, RT3, T, SID, CertRSU5),

SIGPRR5(h(NQ, RT3, T, SID))

- R5 stores <NQ, SID, R6, R9>

RSU6 ➤ RSU7 & RSU10

- R9 has traffic jam → silent

- R6 forwards:

- To R7:

ENCPUR7(NQ, RT4, T, SID, CertRSU6),

SIGPRR6(h(...))

- To R10:

ENCPUR10(NQ, RT2, T, SID, CertRSU6),

SIGPRR6(h(...))

- Stores <NQ, SID, R7, R10>

RSU₁₀ ➤ RSU₁₁ and Backpropagation Begins

- ◆ R7 has traffic jam → silent

- ◆ R10 sends to R11:

ENCPUR₁₁(NQ, RT₂, T, SID, CertR₁₀),
SIGPRR₁₀(h(...))

- ◆ R11 detects it's the destination:

- Sends back to R10:

<ENCPUR₁₀(T, SID, R₁₁), h(T||SID||R₁₁)>

Route Reply (Backtracking Path)

◆ R10 → R6:

ENCPUR6(T, SID, R10, R11), h(...)

◆ R6 → R5:

ENCPUR5(T, SID, R6, R10, R11), h(...)

◆ R5 → GLP:

ENCPUGLP(T, SID, R5, R6, R10, R11), h(...)

Final Route Response to Vehicle

- GLP matches <NQ, SID> and retrieves old SND
- Constructs final navigation reply:

NR = <R1, R5, R6, R10, R11>

NRE = ENCPUVi(SND, NQ, NR)

- Sends:

<PRID1, PIDVi, CertGLP, NRE>,

SIGPRGLP(PRID1, PIDVi, SND)

RSU1 \Rightarrow Vehicle (Final Delivery)

- ◆ RSU1 verifies signature, matches SND
- ◆ Sends to Vi:

$RM = \langle PRID1, PIDVi, SND, NRE \rangle,$
 $SIGPRR1(h(PRID1, PIDVi, SND, NRE))$

- ◆ Vehicle:
 - Matches SND
 - Decrypts NRE with its private key
 - Extracts NQ and NR (Navigation Route)

TABLE II: Performance Comparison

Features	VSPN[11]	SPNS[13]	PiSim[14]	EPNS[16]	Ours
Computation Cost	High	High	High	Low	Low
Cryptography	ECC, Bilinear Pairing	AES, ElGamal, Bilinear Pairing	Bilinear Pairing	Secure Multiparty Computation	ElGamal
Group signature	Yes	Yes	Yes	No	No
Crowdsourcing	No	Yes	Yes	No	No
Fog computing	No	Yes	No	No	No
Message Forwarding	point-to-point	broadcast	broadcast	broadcast	point-to-point
Network Traffic	Low	High	High	High	Low

Thank you