

# Secure and Dynamic Route Navigation through RSU-based Authentication in IoV for Smart City

# Abstract

- 1) One of the significant services provided by IOV is Vehicular Navigation.
- 2) A proper routing mechanism help drivers reach their destination to minimum time and with less fuel consumption
- 3) However such protocols often face security challenges
- 4) In this paper authors have proposed an authenticated navigation scheme with the help of pseudonym based asymmetric key cryptography
- 5) The architecture embodies GLP to find static route to a particular destination and message forwarding capabilities of RSUs to develop dynamic route after receiving feedback about traffic conditions

# Key Features of this Protocol

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- 1)Integrity
- 2)Anonymity
- 3)Unlinkability
- 4)robust protection from important security threats
- 5)minimal end to end delay
- 6)efficient real time routing

# Vehicular ad hoc networks

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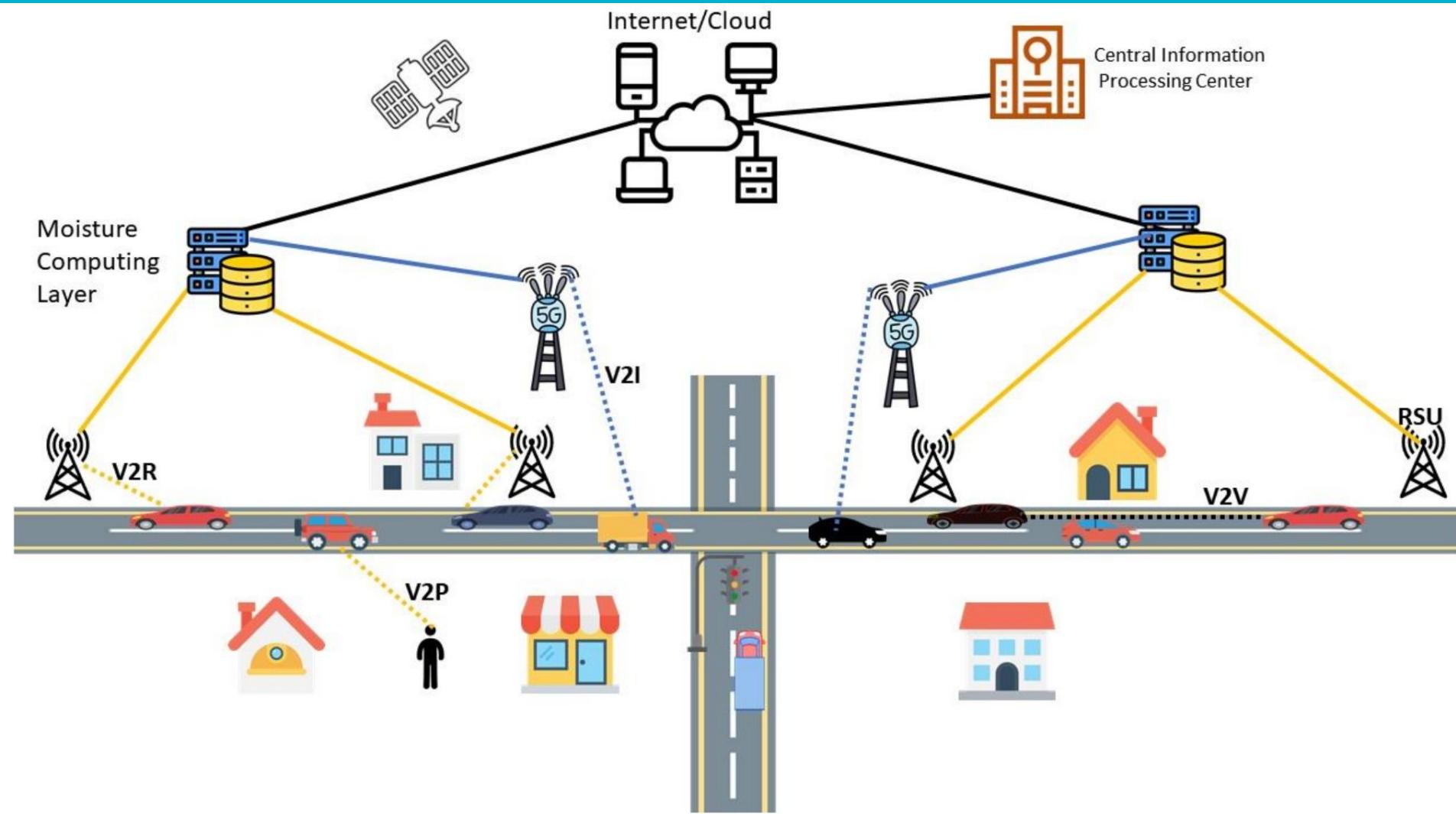
# Key INTRODUCTION Points

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- 1)Amalgnation of Internet of Things to VANETS has elevated vehicular communication to the next level known as Internet of vehicles
- 2)Disadvantages of VANETS
  - i)Low Network coverage area
  - ii)limited mobility
  - iii)restriction on number of vehicles
- 3)these will be rectified by internet of technologies hence this combo is powerful

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# INTERNET OF VEHICLES ARCHITECTURE



# ISSUES IN THE IOV ARCHITECTURE

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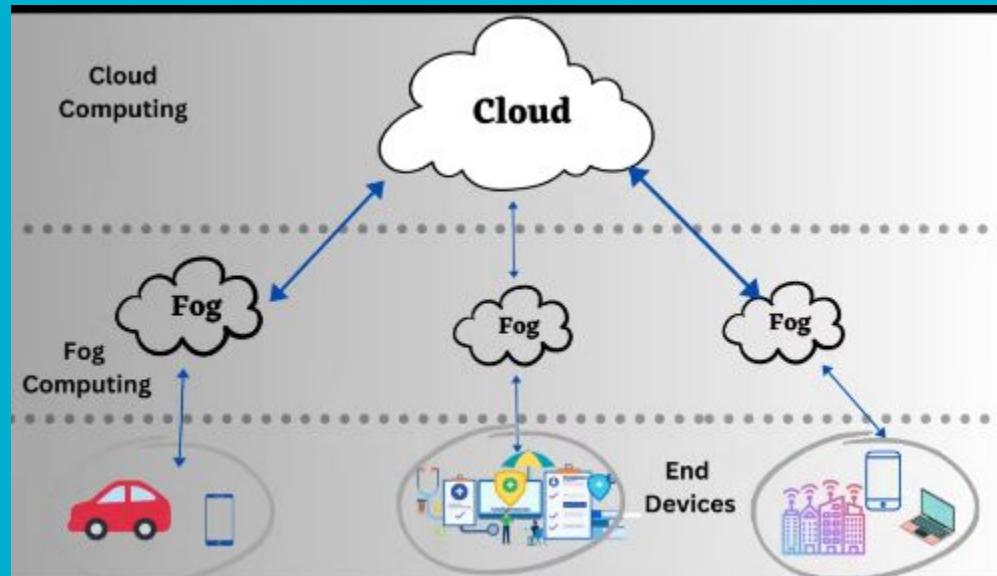
Three main issue in IOV Architecture

- 1) Since the cloud server is a centralized facility, it often encounters serious problems elaborated next. Firstly, it faces the issue of high computational latency due to the loads exerted by RSUs. Since all the RSUs are connected directly to the server, it often fails to provide real-time services to the drivers and passengers. It may lead to gross failure in fulfilling the objective of the IoV.
- 2) Secondly, breakdown of the cloud server leads to complete system failure unless there is an alternate arrangement

SOLUTION FOR THE ABOVE ISSUES IS FOG computing

# FOG COMPUTING

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Ref :- [https://www.youtube.com/shorts/wIJZE\\_xKSZ4](https://www.youtube.com/shorts/wIJZE_xKSZ4)

# Third Issue

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The third issue is the security havoc in the centralized server, thus causing extensive damage to human lives

To address the Third issue it is crucial to separate server data security from message authentication

# Key Features of The Proposed Framework

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- A secure and dynamic route navigation framework through **RSU-based authentication** for IoV.
- **Geo-Location Provider (GLP)** and RSUs collaborate to function **without involving vehicles directly**, reducing delay and dependency.
- Uses **ElGamal encryption, digital signatures, and public key certificates** for secure communication.
- **Lightweight design:** avoids heavy operations like ECC point multiplication or bilinear pairings.

# Security & Performance Highlights

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- Ensures **driver anonymity, session key secrecy, and unlinkability**.
- Defends against **collusion, Sybil, MITM, replay, and masquerading attacks**.
- **GLP acts as a trusted intermediary** between navigation requesters and RSU responders.
- Verified using **Scyther tool**, confirming **strong security guarantees and efficient performance**.

# Mathematical Preliminaries-Cryptographic Foundations

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- Our protocol uses:
  - ElGamal-based encryption, decryption, and digital signature
  - Cryptographic hash functions
- Operations are performed over a **multiplicative group G** with generator **g**
- Common operations: **Multiplication** and **Exponentiation**

# The ElGamal Cryptosystem

## Key Generation (Alice – message receiver)

Select p	p is a very large prime number
Find a primitive root of p: g	
Choose a random integer <b>a</b> as her private key	$1 < a < p-1$
Compute e: $e = g^a \text{ mod } p$	
Public key: (p,g,e)	

## Encryption (Bob- message sender)

Plaintext: m	$m < p$
Select a random integer: <b>b</b>	$1 < b < p-1$
Compute two values $C_1$ and $C_2$ , where	
$C_1 = g^b \text{ mod } p$	
$C_2 = m * e^b \text{ mod } p$	
Ciphertext: $(C_1, C_2)$	

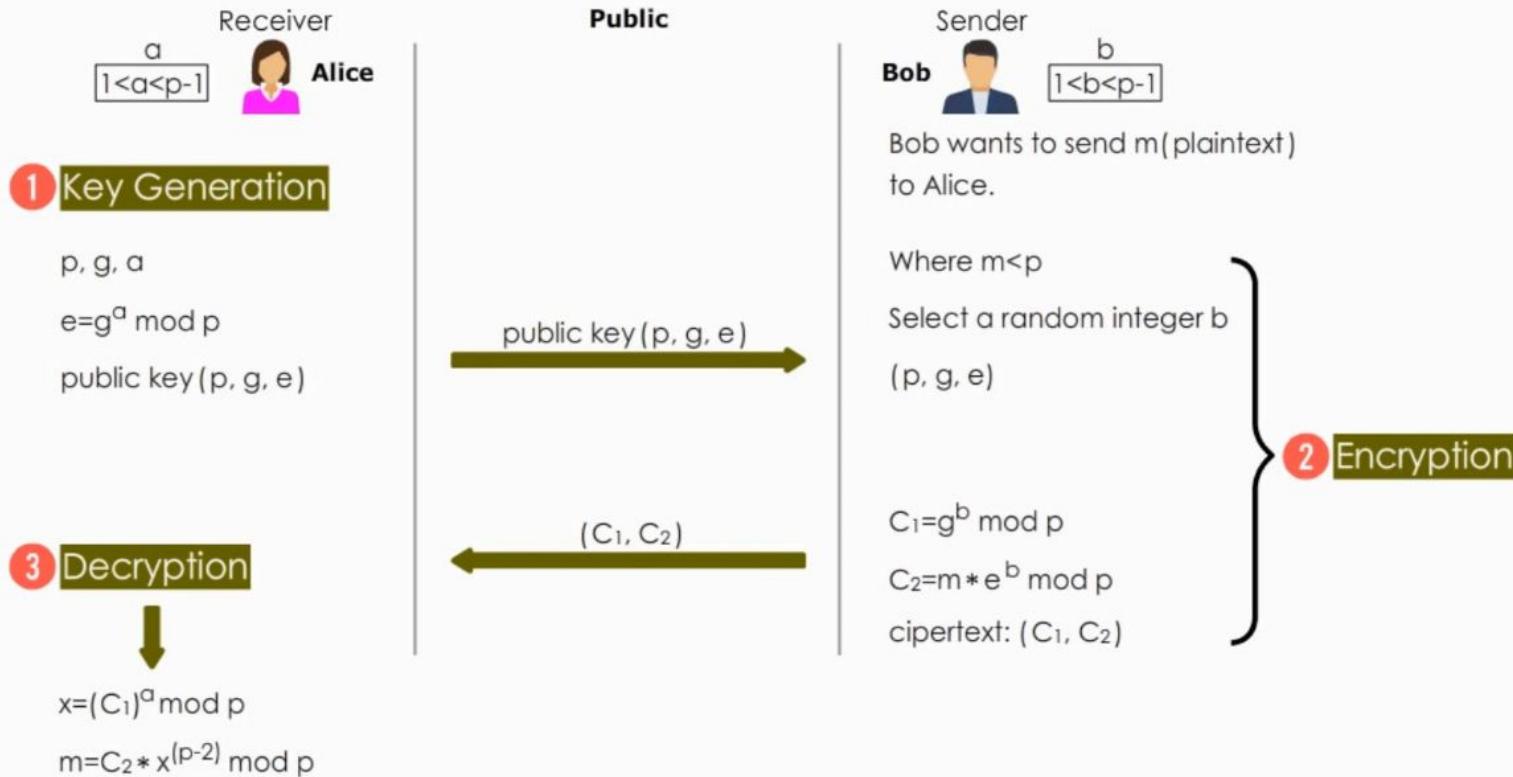
## Decryption (Alice – message receiver)



Ciphertext: $(C_1, C_2)$
Plaintext:
$x = (C_1)^a \text{ mod } p$
$m = C_2 * x^{(p-2)} \text{ mod } p$

# The ElGamal Cryptosystem

Three steps with math formulas



# Digital Signature

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Digital signature is equivalent to an hand written signature

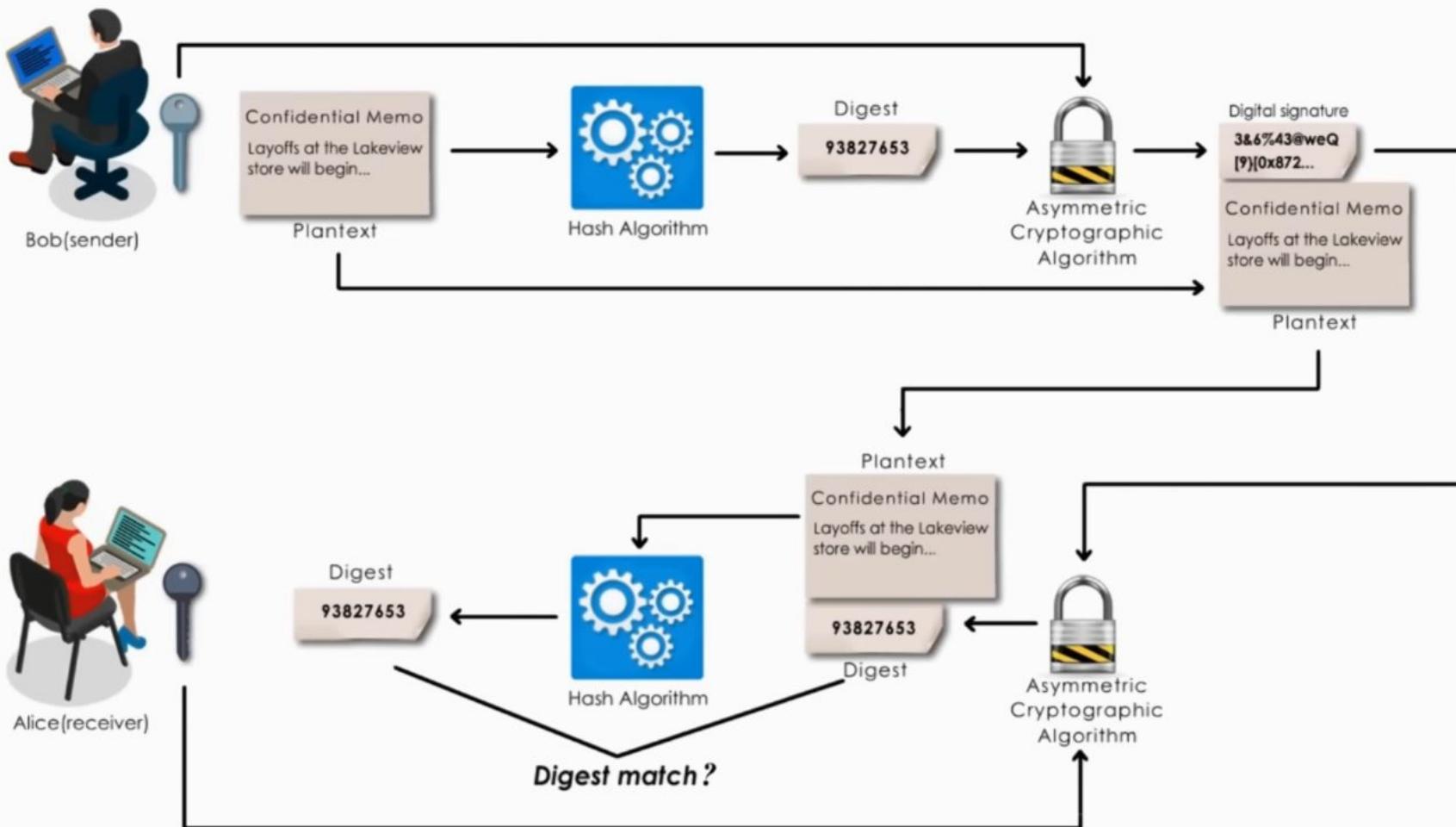
A Digital signature basically serves Three purposes

1)Authentication-A DS gives the receiver a reason to believe the message was created and sent by the claimed sender

2)Non repudiation-The receiver cant deny he didnt receive a message later on

3)Integrity-a DS assure no altering of the message is occurred

A digital signatures uses asymmetric key cryptography -public key cryptosystem



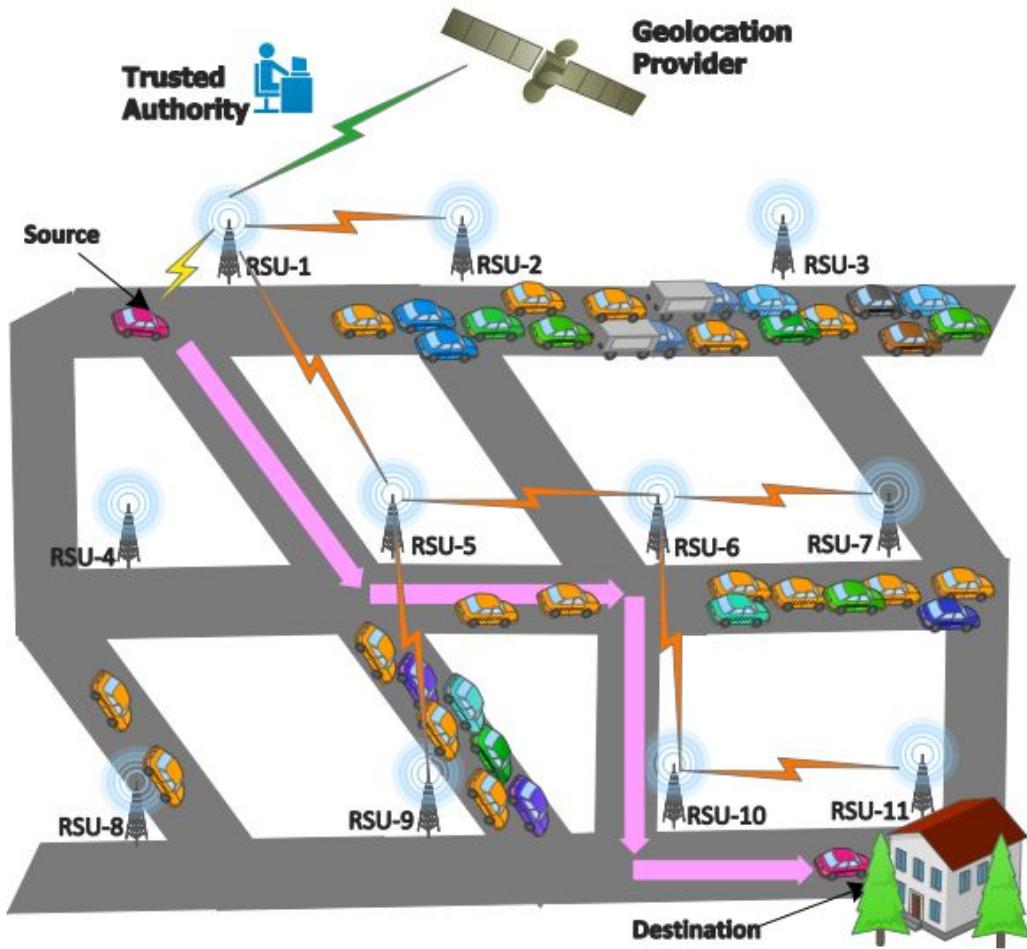


Fig. 2: Route selection in our navigation model.

TABLE I: Notations used in our proposed protocol

Notations	Meaning
$GLP, V_i$	Geolocation Provider, Vehicle $i$
$R_j, TA$	Road Side Unit $j$ , Trusted Authority
$ID_{V_i}, ID_{R_j}$	Identity of $V_i$ , Identity of $R_j$
$PID_{V_i}, PRID_j$	Pseudo-identity of $V_i$ , Pseudo-identity of $R_j$
$SND$	Session-ID created by RSU
$SID$	Session-ID created by GLP
$s, l, v$	Random numbers
$PR_x, PU_x$	Private key of entity $x$ , Public key of entity $x$
$g, G$	$g$ is a generator of group $G$
$h(.)$	One-way hash function $h : \{0, 1\}^* \rightarrow G$
$ENC_{PU_x}(M_k)$	Encryption of message $M_k$ with public key $PU_x$ of entity $x$
$SIG_{PR_x}(M_k)$	Signature on message $M_k$ with private key $PR_x$ of entity $x$
$Cert_x, T$	Public key certificate of entity $x$ , Timestamps

# Working of The Protocol

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there are mainly 5 steps discussed in the Research paper IN this section

- 1)System initialisation
- 2)Geolocation Provider Registration
- 3)RSU registration
- 4)Vehicle Registration
- 5)Navigation Scheme

# System Initialisation

**Performed by:** Trusted Authority (TA)

- **Step 1:** Select a multiplicative group  $G$  of order  $q$ , with generator  $g$
- **Step 2:** Choose a master secret key  $s \in \mathbb{Z}_q^*$
- **Step 3:** Compute public key:

$$\text{PUTA} = g^s \bmod q$$

- **Step 4:** Choose a one-way hash function  $h(\cdot)$
- **Step 5:** Create a digital certificate:

$$\text{Cert}_{\text{TA}} = \langle \text{TA}, \text{PUTA}, \text{SIGPRTA}(\text{TA}, \text{PUTA}) \rangle$$

- **Step 6:** Publish system parameters:

$$\langle G, q, g, h(\cdot), \text{Cert}_{\text{TA}} \rangle$$

✓ These parameters are then shared with RSUs and vehicles for secure communication and authentication.

Let's assume:

- TA ID: "TA"
- Public Key (from earlier): `PUTA = 6`
- Hash function: `h( . )` (e.g., SHA-256 or similar)

## Digital Certificate Construction:

makefile

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```
CertTA = <"TA", PUTA, SIGPRTA("TA", 6)>
        = <"TA", 6, Signature>
```

## Published System Parameters:

php-template

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```
<G = Z^23, q = 23, g = 5, h( . ), CertTA>
```

📌 These values are distributed securely to:

- RSUs (for registration and route verification)
- Vehicles (for pseudonym-based authentication)

# GLP REGISTRATION

**Goal:** Register the **Geo-Location Provider (GLP)** securely with the **Trusted Authority (TA)**

**Steps:**

1. GLP → TA: Sends identity proof over a **secure channel** (e.g., TLS)
2. TA → GLP:

- Generates a **pseudo-identity**:

$$\text{PIDGLP} = h(s \parallel \text{IDGLP})$$

- Selects a random number  $l \in \mathbb{Z}_q^*$
- Computes **private key**:

$$\text{PRGLP} = g^l$$

- Computes **public key**:

$$\text{PUGLP} = \text{PRGLP}^s$$

3. GLP stores:

PIDGLP , PRGLP , PUGLP for future use

- Prime order:  $q = 23$
- Generator:  $g = 5$
- Master secret (from TA):  $s = 6$
- GLP ID = "GLP1" → Hash:  $h(s \mid\mid \text{IDGLP}) = 14$
- Random number selected by TA:  $l = 3$

### Calculations:

- $\text{PRGLP} = g^l \bmod q = 5^3 \bmod 23 = 125 \bmod 23 = 10$
- $\text{PUGLP} = \text{PRGLP}^s \bmod q = 10^6 \bmod 23 = 1,000,000 \bmod 23 = 6$

**Goal:** Securely register a **Roadside Unit (RSU)** with the **Trusted Authority (TA)**

**Steps:**

1. RSU → TA: Sends:

- Identity proof (IDRSUj)
- Location code (LCj)  
(Over a **secure channel**)

2. TA computes:

- Pseudo-ID:  $\text{PRID}_j = h(s \parallel \text{IDRSU}_j \parallel \text{LC}_j)$
- Private Key:  $\text{PRRSU}_j$  (randomly chosen)
- Public Key:  $P_{\text{URSU}_j} = g^{\text{PRRSU}_j}$

3. TA creates a digital certificate:

ini

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```
CertRSUj = <PRIDj, LCj, PURSUj, SIGPRTA(PURSUj, PRIDj, LCj)>
```

4. TA sends to RSU:

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```
<CertRSUj, CertGLP, PRRSUj>
```

5. RSU stores in a **tamper-proof device** and **publishes** its public key.

- Prime order: `q = 23`, Generator: `g = 5`
- TA's master secret: `s = 6`
- RSU ID = "RSU1"
- Location Code = "ZoneA"
- Hash → `h(s || IDRSUj || LCj) = 17`

TA assigns:

- Pseudo-ID: `PRIDj = 17`
- Private Key (chosen randomly): `PRRSUj = 4`
- Public Key:  $P_{URSUj} = g^{PRRSUj} \bmod q = 5^4 \bmod 23 = 625 \bmod 23 = 4$

Certificate:

`ini`

```
CertRSUj = <17, "ZoneA", 4, SIGPRTA(4, 17, "ZoneA")>
```

Sent Securely to RSU:

```
<CertRSUj, CertGLP, PRRSUj = 4>
```

💡 RSU stores all this in its **tamper-proof device** and **publishes** its public key for others to verify.

## ✓ Slide 1: Vehicle Registration – Explanation

### Overview of the Registration Process:

- Each vehicle submits ID proof securely to the Trusted Authority (TA).
- After one-time verification, TA issues a Tamper-Proof Device (TPD) (or Hardware Security Module).
- TA generates:
  - Pseudo-identity:  $P\_IDVi = h(s \parallel IDVi)$
  - TPD Activation Password:  $PWVi$
  - Random number:  $v \in Z^{*}_p$
  - Private Key:  $PRVi = g^v$
  - Public Key:  $PUVi = PRVi^s = g^{vs}$
  - Public Key Certificate:

$CertVi = <P\_IDVi, PUVi, SIGPRTA(T \parallel P\_IDVi \parallel PUVi)>$

### Final Output (Sent to Vehicle securely):

$<P\_IDVi, PWVi, PUVi, PRVi, CertVi>$  along with the TPD.

## Slide 2: Vehicle Registration – Numerical Example

Assume:

- $IDVi = "KA01AB1234"$
- $s = 9, v = 4, g = 2$
- $h()$  is a hash function (e.g., SHA-256 simplified for illustration)

Step-by-step:

1.  $P\_IDVi = h(9 \mid\mid "KA01AB1234") = h("9KA01AB1234") \rightarrow \text{e.g., "a4c1..."}$
2.  $PRVi = g^v = 2^4 = 16$
3.  $PUVi = PRVi^s = 16^9 = 68719476736$
4.  $CertVi = <"a4c1...", 68719476736, SIGPRTA(...)>$

Delivered securely:

$<"a4c1...", PWVi, 68719476736, 16, CertVi> + TPD$

# Navigation Scheme

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- Real-time route discovery is challenging in urban traffic due to dynamic conditions.
- AI/ML-based sub-optimal solutions exist, but secure communication is critical.
- Goal: Find safe, optimal routes with minimal delay, fuel, and risk.
- RSUs & GLP assist vehicles by:
  - Authenticating queries
  - Finding static + dynamic routes
  - Ensuring privacy and robustness

## ## RSU and GLP Role in Navigation

1.  Vehicle → RSU: Sends (source, destination) query.
2.  RSU authenticates vehicle & forwards query to GLP.
3.  GLP:
  - Uses Dijkstra's algorithm to compute route options.
  - Maps zones to RSUs.
  - Sends ACK to original RSU (route not revealed).
4.  GLP → Neighboring RSUs: Sends route sketch to start dynamic route discovery.
5.  Each RSU:
  - Caches route
  - Forwards to next RSU if traffic/weather is favorable
  - Drops otherwise (session time-out triggers retry)

## ## Route Finalization & Vehicle Reply

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6.  RSUs forward query hop-by-hop until reaching destination RSU.

7.  Destination RSU:

- Sends reply backward through upstream RSUs
- Reaches GLP

8.  GLP selects reply with lowest hop count

9.  GLP → Original RSU → Vehicle:

- Sends final route
- If  $\delta T$  timeout occurs → Vehicle retries via same/new RSU

 Ensures secure, traffic-aware, efficient navigation

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# Authentication and Navigation

# Vehicle – RSU Communication

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- Step 1:

- Vehicle  $V_i$  receives beacon from RSU1 (R1)
- Sends message M1 to R1:

$M1 = \langle PRID1, CertVi, T, NQ, SIGPRVi(h(PRID1 || NQ || T)) \rangle$

- PRID1: RSU pseudonym
- CertVi: Vehicle certificate issued by TA
- T: Timestamp
- NQ: Navigation query (initially null)

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◆ Step 2:

- RSU1 verifies CertVi using TA's public key
- If valid, uses PUVi (from CertVi) to verify SIGPRVi
- On success: identifies a navigation query request from Vi

# RSU1 Responds to Vehicle

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- ◆ Step 3:

- RSU1 generates a session-ID (SND)
- Encrypts (SND, CertGLP) using PUVi

- Sends Message M2:

M2 = <PRID1, PIDVi, CertR1, T,  
SIGPRR1(PRID1, PIDVi, T),  
ENCPUVi(SND, CertGLP)>

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- ◆ Step 4:

- Vehicle verifies SIGPRR1 and timestamp T
- Decrypts encrypted part to get SND and CertGLP
- Prepares navigation query NQ =  $\langle S, D \rangle$

- Sends Message M3:

$M3 = \langle PIDVi, PRID1, T, ENCPUGLP(PIDVi, PRID1, SND, NQ),$   
 $SIGPRVi(h(PIDVi, PRID1, T)) \rangle$

# RSU<sub>1</sub> → GLP Communication

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- ◊ Step 1:

- RSU1 verifies SIGPRVi (can't decrypt NQ)
- Forwards encrypted NQ to GLP

- Message M4:

M4 = <PRID1, CertR1, PIDGLP, T,  
ENCPUGLP(PIDVi, PRID1, SND, NQ),  
SIGPRR1(h(PRID1, PIDGLP, T))>

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## ◆ Step 2:

- GLP verifies CertR1, checks timestamp freshness
- Decrypts with its private key to get <PIDVi, PRID1, SND, NQ>
- Sends acknowledgment to RSU1

# GLP $\Rightarrow$ RSUs (Path Discovery)

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- GLP finds possible routes for NQ =  $\langle S, D \rangle$ :

RT1 = R1 → R2 → R6 → R7 → R11

RT2 = R1 → R5 → R6 → R10 → R11

RT3 = R1 → R5 → R9 → R10 → R11

RT4 = R1 → R5 → R6 → R7 → R11

- Sends to next-hop RSUs:

- To R2:

ENCPUR2(NQ, RT1, T, SID, CertRSU1), SIGPRGLP( $h(NQ, RT1, T, SID)$ )

- 
- To R5:

ENCPUR5(NQ, RT2, RT3, RT4, T, SID, CertGLP), SIGPRGLP(h(...))

- GLP stores map(SND, SID), NQ, vehicle & RSU IDs

# RSU5 $\Rightarrow$ RSU6 & RSU9

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- R2 detects traffic jam → remains silent

- R5 is active:

- Sends to R6:

ENCPUR6(NQ, RT2, RT4, T, SID, CertRSU5),

SIGPDR5( $h(NQ, RT2, RT4, T, SID)$ )

- Sends to R9:

ENCPUR9(NQ, RT3, T, SID, CertRSU5),

SIGPDR5( $h(NQ, RT3, T, SID)$ )

- R5 stores  $\langle NQ, SID, R6, R9 \rangle$

# RSU6 → RSU7 & RSU10

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- ◆ R9 has traffic jam → silent

- ◆ R6 forwards:

- To R7:

ENCPUR7(NQ, RT4, T, SID, CertRSU6),

SIGPRR6(h(...))

- To R10:

ENCPUR10(NQ, RT2, T, SID, CertRSU6),

SIGPRR6(h(...))

- ◆ Stores <NQ, SID, R7, R10>

# RSU<sub>10</sub> → RSU<sub>11</sub> and Backpropagation Begins

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- ❖ R7 has traffic jam → silent

- ❖ R10 sends to R11:

ENCPUR11(NQ, RT2, T, SID, CertR10),  
SIGPRR10(h(...))

- ❖ R11 detects it's the destination:

- Sends back to R10:

<ENCPUR10(T, SID, R11), h(T||SID||R11)>

# Route Reply (Backtracking Path)

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- ◆ R10 → R6:

ENCPUR6(T, SID, R10, R11), h(...)

- ◆ R6 → R5:

ENCPUR5(T, SID, R6, R10, R11), h(...)

- ◆ R5 → GLP:

ENCPUGLP(T, SID, R5, R6, R10, R11), h(...)

# Final Route Response to Vehicle

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- GLP matches <NQ, SID> and retrieves old SND
- Constructs final navigation reply:

NR = <R1, R5, R6, R10, R11>

NRE = ENCPUVi(SND, NQ, NR)

- Sends:  
<PRID1, PIDVi, CertGLP, NRE>,  
SIGPRGLP(PRID1, PIDVi, SND)

# RSU1 → Vehicle (Final Delivery)

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- ◆ RSU1 verifies signature, matches SND
- ◆ Sends to Vi:

RM = <PRID1, PIDVi, SND, NRE>,

SIGPRR1(h(PRID1, PIDVi, SND, NRE))

- ◆ Vehicle:
  - Matches SND
  - Decrypts NRE with its private key
  - Extracts NQ and NR (Navigation Route)

TABLE II: Performance Comparison

Features	VSPN[11]	SPNS[13]	PiSim[14]	EPNS[16]	Ours
Computation Cost	High	High	High	Low	Low
Cryptography	ECC, Bilinear Pairing	AES, ElGamal, Bilinear Pairing	Bilinear Pairing	Secure Multiparty Computation	ElGamal
Group signature	Yes	Yes	Yes	No	No
Crowdsourcing	No	Yes	Yes	No	No
Fog computing	No	Yes	No	No	No
Message Forwarding	point-to-point	broadcast	broadcast	broadcast	point-to-point
Network Traffic	Low	High	High	High	Low

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Thank you