

# Wenhao Sun

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## Researching Experience

**Benchmarking real time workload on advance processors** Nov 2024 – Now

- Goal: Comprehensive workload analysis helps designers optimize system performance, resource allocation, and ensure application requirements are met.
- Method: Analyzing the execution behavior and influence of real-time tasks on advanced processor features (OoO, BP and LLC)

**Efficient Robotics Computing System** Nov 2023 – Nov 2024

- Designed a comprehensive perception-judgment-decision-execution pipeline for embodied robots and conducted experiments in both simulation and open real-world environments.
- Achieved robust close-loop task completion success rates on par with SOTA methods while reducing computational cost by 6.6x.

**Optimize Real-Time Embedding System For Embodied AI** Jan 2023 – Nov 2023

- Enhanced Linux to support both real-time and non-real-time capabilities, enabling motion control in the real-time domain and AI model inference in the non-real-time domain without interference.
- Successfully tested with 128 industrial servo motors under 4000 ms EtherCAT cycle, maintaining embedding system jitter within 50  $\mu$ s

## Researching Interest

**Embodied AI System Hardware-Software Co-Design**

- Hardware: Efficient and real-time hardware with Embodied AI application.
- Algorithm: Efficient Embodied Robotics computing pipeline enable robot thinking easily.
- Software: Real-time OS and toolchain friendly for robotics, controlling, and Embodied AI system.

## Education

**Institute of Computing Technology, Chinese Academy of Sciences (ICT, CAS)** Sep 2023 – Now  
MS in Computer Science

- GPA: 3.8/4.0      Ranking: 5% (Estimated)
- Advisor: [Prof. Yinhe Han](#) and [Dr. Yiming Gan](#)

**Hefei University of Technology (HFUT)** Sep 2019 – June 2023  
BS in Survey and Mapping

- GPA: 3.5/4.3      Ranking: 3/37 (Obtain the guaranteed admission)
- Advisor: Assoc. Prof. Chunju Zhang

## Publications

**DaDu-E: Rethinking the Role of Large Language Model in Robotic Computing Pipeline** *Submitted Dec 2024*  
(Submitted to *Journal of Field Robotics, JFR*)

**Wenhao Sun**, Sai Hou, Zixuan Wang, Bo Yu, Shaoshan Liu, Xu Yang, Shuai Liang, Yiming Gan, Yinhe Han  
[Paper](#) [Demo](#)

**Aphelios: A Selective Lock-step Neural Processing Unit Design** *Accepted Apr 2025*  
(Accepted by *The 35th edition of ACM/IEEE Great Lakes Symposium on VLSI, GLSVLSI 2025*)

**Wenhao Sun**, Yiming Gan, Yuhui Hao, Yinhe Han

**Investigating Performance and Real-Time Trade-offs in Out-of-Order Processors** *Accepted May 2025*  
(Accepted by *Workshop of 2025 International Symposium on Computer Architecture, ISCA 2025*)

**Wenhao Sun**, Yuhui Hao, Yiyang Huang

## KARMA: Augmenting Embodied AI Agents with Long-and-short Term Memory Systems

Accepted Feb 2025

(Accepted by 2025 IEEE International Conference on Robotics & Automation, ICRA 2025)

Zixuan Wang, Bo Yu, Junzhe Zhao, Wenhao Sun, Sai Hou, Shuai Liang, Xing Hu, Yinhe Han, Yiming Gan

[Paper](#)  [Demo](#)

## Internship

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Embedded Software and Operating System Engineer, [Sinsegye](#)

Feb 2023 – Aug 2023

- Optimized Linux real-time performance on diverse kinds of CPU/GPU.
- Tested performance of servos, PLC controllers and kinds of hardware devices.
- Adapting Cambrion NPU on the real-time embedding system.

## Technologies

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**Languages:** Python, C/C++, Verilog, Shell, ST, SQL

**System:** Linux, ROS, Gem5, Xenomai

**Tools:** Gazebo, Moveit, GDB, Open-source EDA, WebGIS, Robot and Servo Motor hardware debugging

**English Ability:** TOEFL(103)

## Awards

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2023 Outstanding Graduates of Anhui Province (Top 3% )

2023 Postgraduate Scholarships of UCAS

2024 Postgraduate Scholarships of UCAS