ROSRemoteRunner extends roslaunch.launch.ROSRemoteRunnerIF

+run_id
+rosconfig
+server
+pm
+logger
+listeners[]
+machine_list[]
+remote_processes[]

+__init__()
+add_process_listner()
+_start_child()
+start_children()
+_assume_failed()
+launch_remtoe_nodes()

+extends

ROSRemoteRunnerIF

+__init__()
+setup()
+add_process_listener()
+launch_remote_nodes()

Process

+package
+name
+args
+env
+respawn
+respawn_delay
+required
+lock
+exit_code
+spawn_count
+time_of_death

+__str__()
+get_info()
+start()
+is_alive()
+should_respawn()
+stop()
+get_exit_description()

+extends

DeadProcess extends Process

+exit_code
+lock
+spawn_count
+info

+__init__(p)
+get_info()
+start()
+is_alive()

+extends

RegistrationManager

+nodes {}
+thread_pool
+pulishers
+subscribers
+services
+param_subscribers

+__init__()
+reverse_lookup()
+get_node()
+_register()
+_unregister()
+register_service()
+register_publisher()
+register_param_subscriber()
+register_subscriber()
+unregister_service()
+unregister_subscriber()
+unregister_publisher()
+unregister_param_subscriber()
+_register_node_api()