LocalProcess extends Process +run_id +popen +log_output +started +stopped +cwd +log_dir +pid +is_node +started +lock +__init__() +get_info() +_configure_logging() +start() +_log_name() +is_alive() +get_exit_description() +_stop_unix() +_stop_win32() +stop() +Operation3()

master.Master +DEFAULT_MASTER_PORT +num_workers +master_node

+port

+uri

+handler

+_init_()

+start()

+stopp()

+ok()

ROSMasterHandler +uri +done +thread_pool +ps_lock +reg_manager +publishers +subscribers +services +param_subscribers +topics_types +param_server +__init__() +_shutdown() + ready() + ok() +shutdown() +getUri() +getPid() +deleteParam() +setParam() +getParam() +searchParam() +subscribeParam() +unsubscribeParam() +hasParam() +getParamNames() +_notify() +_notify_param_subscribers() +param_update_task() +_notify_topic_subscribers() +registerService() +lookupService() +unregisterService() +registerSubscriber() +unregisterSubscriber() +registerPublisher() +unregisterPublisher() +lokkupNode() +getPublishedTopics() +getTopicTypes() +getSystemState()

