RosStreamHandler extends logging.Handler

+_colorize
+_get_time

+__init__()
+emit()
+_write()

XmlRpcNode

+handler
+uri
+class ThreadingXMLRPCServer server
+port
+bool is_shutdown
+on_run_error

+__init__()
+shutdown()
+start()
+set_uri()
+run()
+_run_init()
+_run()

ROSLaunchParentHandler extends ROSLaunchBaseHandler

+child_processes
+listeners

+register(client, uri)
+list_children()
+process_died(process_name, exit_code)
+log(client, level, message)

+extends

ROSLaunchBaseHandler extends xmlrpc.XmlRpcHandler

+pm
+logger

+list_processes()
+process_info(process_name)
+get_pid()
+get_node_names()
+_shutdown()

+extends

XmlRpcHandler

+_ready(uri)
+_shutdown(reason)