# QUATERNIONIC ANALYSIS

#### SUNAY MIDUTHURI

ABSTRACT. In this paper, we discuss the topic of Quaternionic Analysis, in which we attempt to extend complex analysis to the quaternions.

### 1. Introduction

Quaternions are a four-dimensional algebra that extend the idea of a complex numbers to create an entirely new number system. They were invented by the Irish mathematician William Rowan Hamilton in [Ham66]. Much of the modern theory of Quaternionic Analysis was developed by Fueter in [Fue35].

**Definition 1.1.** The set of quaternions, denoted  $\mathbb{H}$ , is a 4-dimensional vector space over  $\mathbb{R}$  with basis 1, i, j, k, where i, j, k are the elementary quaternions.

**Definition 1.2.** The elementary quaternions satisfy

$$i^2 = j^2 = k^2 = ijk = -1.$$

Furthermore, they are anticommutative, meaning that

$$ij = -ji$$
.

From this, we trivially obtain the result of Theorem 1.3.

**Theorem 1.3.** The elementary quaternions satisfy

$$ij = k, jk = i, ki = j.$$

We are now ready to extend the elementary quaternions to the larger set of quaternions.

**Definition 1.4.** A quaternion can be represented as a linear combination in the form

$$q = w + xi + yj + zk,$$

where  $x, y, z \in \mathbb{R}$ .

**Definition 1.5.** The conjugate of a quaternion q = w + xi + yj + zk is

$$\overline{q} = w - xi - yj - zk.$$

**Definition 1.6.** The magnitude of a quaternion q = w + xi + yj + zk is

$$|q| = \sqrt{w^2 + x^2 + y^2 + z^2}.$$

**Definition 1.7.** If  $q = t + xi + yj + zk \in H$ , then the real part Re(q) = t and the pure quaternion part Pu(q) = xi + yj + zk.

The quaternions  $\mathbb{H}$  form a 4-dimensional algebra over  $\mathbb{R}$ . If q is any quaternion linearly independent from 1, the vector subspace spanned by q and 1 is a subfield of  $\mathbb{H}$  that is isomorphic to  $\mathbb{C}$  [Sud98]. We can also embed  $\mathbb{C}$  in  $\mathbb{H}$ ; for instance, any quaternion  $q \in \mathbb{H}$  can be expressed in the form

$$q = v + jw$$

where  $v, w \in \mathbb{C}$  and j is an elementary quaternion.

### 2. Differential Forms

**Definition 2.1.** We define the differential of a function  $f: \mathbb{H} \to \mathbb{H}$  as

$$df = \frac{\partial f}{\partial t}dt + \frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy + \frac{\partial f}{\partial z}dz.$$

If this exists, we say that f is real-differentiable.

**Definition 2.2.** The differential of  $f: \mathbb{H} \to \mathbb{H}$  at a point q is then defined analogously to Definition 2.1 as a linear mapping  $df_q: \mathbb{H} \to \mathbb{H}$ .

**Definition 2.3.** We also define the quaternion gradient operator as

$$\Box = \frac{\partial}{\partial w} + i\frac{\partial}{\partial x} + j\frac{\partial}{\partial y} + k\frac{\partial}{\partial z}.$$

**Definition 2.4.** Finally, we define the differential of the identity function

$$dq = dt + i dx + j dy + k dz.$$

## 3. Functions

**Definition 3.1.** A quaternion function  $f : \mathbb{H} \to \mathbb{H}$  is quaternion-differentiable on the left at a point q if

$$\frac{df}{dq} = \lim_{h \to 0} \frac{f(q+h) - f(q)}{h}$$

exists as  $h \to 0$  from any direction in  $\mathbb{H}$ .

**Theorem 3.2.** Suppose that a function  $f : \mathbb{H} \to \mathbb{H}$  is defined and quaternion-differentiable on the left throughout a connected open set U. Then on U, f has the form

$$f(q) = aq + b,$$

where  $a, b \in \mathbb{H}$ .

*Proof.* [Sud98] If f is quaternion-differentiable on the left, we can write

$$df_q(h) = h\frac{df}{dq} = dq\frac{df}{dq}.$$

We then equate coefficients of t, x, y, z to obtain

$$\begin{split} \frac{df}{dq} &= \frac{\partial f}{\partial t} \\ &= -i \frac{\partial f}{\partial x} \\ &= -j \frac{\partial f}{\partial y} \\ &= -k \frac{\partial f}{\partial z}. \end{split}$$

Now suppose that q = v + jw, where v = t + ix and w = y - iz, and let f(q) = g(v, w) + jh(v, w), where g and h are complex functions of v and w. We can then separate our the previous equation into two sets of equations:

$$\frac{\partial g}{\partial t} = -i\frac{\partial g}{\partial x} = \frac{\partial h}{\partial y} = i\frac{\partial h}{\partial z},$$

and

$$\frac{\partial h}{\partial t} = i \frac{\partial h}{\partial x} = - \frac{\partial g}{\partial y} = i \frac{\partial g}{\partial z}.$$

We can write these in terms of complex derivatives as

$$\frac{\partial g}{\partial \overline{v}} = \frac{\partial h}{\partial \overline{w}} = \frac{\partial h}{\partial v} = \frac{\partial g}{\partial w} = 0,$$
$$\frac{\partial g}{\partial v} = \frac{\partial h}{\partial w},$$

and

$$\frac{\partial h}{\partial \overline{v}} = -\frac{\partial g}{\partial \overline{w}}.$$

Then, by Cauchy-Riemann, g is analytic in v and  $\overline{w}$ , and h is analytic in  $\overline{v}$  and w. Then

$$\frac{\partial^2 g}{\partial v^2} = \frac{\partial g}{\partial v} \left( \frac{\partial h}{\partial w} \right) = \frac{\partial g}{\partial w} \left( \frac{\partial h}{\partial v} \right) = 0,$$

from which we find that g is linear and the desired result follows.

**Definition 3.3.** Conformal mappings in quaternionic analysis, as in complex analysis, are those which preserve angles.

### 4. Regular Functions

**Definition 4.1.** We define the Left Cauchy-Riemann-Fueter equation of a function  $f : \mathbb{H} \to \mathbb{H}$  as

$$\frac{\partial_l f}{\partial \overline{a}} = \frac{\partial f}{\partial t} + i \frac{\partial f}{\partial x} + j \frac{\partial f}{\partial y} + k \frac{\partial f}{\partial z}.$$

**Definition 4.2.** Similarly, we define the Right Cauchy-Riemann-Fueter equation of a function  $f: \mathbb{H} \to \mathbb{H}$  as

$$\frac{\partial_r f}{\partial \overline{q}} = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial x}i + \frac{\partial f}{\partial y}j + \frac{\partial f}{\partial z}k.$$

**Definition 4.3.** A function  $f: \mathbb{H} \to \mathbb{H}$  is left-regular or right regular if

$$\frac{\partial_l f}{\partial \overline{q}} = 0$$

or

$$\frac{\partial_r f}{\partial \overline{a}} = 0,$$

respectively.

If we write q = v + jw, the equations simplify to

$$\frac{\partial g}{\partial \overline{v}} = \frac{\partial h}{\partial \overline{w}}, \quad \frac{\partial g}{\partial w} = -\frac{\partial h}{\partial v}.$$

**Definition 4.4.** A harmonic function  $f: \mathbb{H} \to \mathbb{H}$  is one that satisfies

$$\frac{\partial^2 f}{\partial t^2} + \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 0.$$

**Definition 4.5.** We define

$$\Gamma_r(df) = \frac{\partial f}{\partial t} + i \frac{\partial f}{\partial x} + j \frac{\partial f}{\partial y} + k \frac{\partial f}{\partial z}.$$

**Theorem 4.6.** The left differential  $\partial_l$  can be written as

$$\partial_l(f) = \frac{1}{2}\overline{\Gamma}_r(df).$$

**Theorem 4.7.** [Sud98] If f is a harmonic function, then

$$\partial_l f$$

is regular.

**Theorem 4.8.** [Sud98] Let u be a real-valued function defined on a star-shaped open set  $U \subseteq \mathbb{H}$ . If U is harmonic and has a continuous second derivative, there exists a regular function f defined on U such that Re(f) = u.

### 5. Integrals

**Definition 5.1.** We define the 3-form

to be the alternating trilinear form

$$\langle w, Dq(x, y, z) \rangle = v(w, x, y, z),$$

where the volume form

$$v = dt \wedge dx \wedge dy \wedge dz$$
.

Geometrically, Dq(x, y, z) is the quaternion perpendicular to x, y, z with magnitude equal to the volume of the parallelepiped given by x, y, z.

**Theorem 5.2.** [Sud98]  $Dq(a,b,c) = \frac{1}{2}(c\overline{a}b - b\overline{a}c)$ .

**Theorem 5.3.** [Sud98] A differentiable function f is regular at q if and only if

$$Dq \wedge df_q = 0.$$

From this result, we find that

$$\int_{\partial D} Dq \ f = 0$$

if f is regular and continuously differentiable on a set D. We also obtain the Cauchy-Fueter Integral Formula:

**Theorem 5.4.** If f is regular on every point of a 4-parallelopiped C and  $q_0 \in C$ ,

$$f(q_0) = \frac{1}{2\pi^2} \int_{\partial C} \frac{(q - q_0)^{-1}}{|q - q_0|^2} Dq f(q).$$

Finally, we get to Cauchy's theorem:

**Theorem 5.5.** Suppose f is regular in an open set U, and let C be a rectifiable 3-chain which is homologous to 0 in the singular homology of U. Then

$$\int_C Dq \ f = 0.$$

We end with one application of quaternions to number theory.

## 6. Lagrange's Four-Square Theorem

In this section, we examine Lagrange's Four-Squares Theorem and its proof using quaternionic analysis. The theorem statement is as follows:

Conjecture 6.1 (Lagrange's Four-Square Theorem). Every nonnegative integer p can be written as

$$p = a^2 + b^2 + c^2 + d^2,$$

where a, b, c, and d are nonnegative integers.

To prove this, we'll first need several definitions to develop the necessary theory.

**Definition 6.2.** A Lipschitz quaternion is a quaternion of the form

$$a + bi + cj + dk$$

where  $a, b, c, d \in \mathbb{Z}$ .

**Definition 6.3.** The Hurwitz Integers are the set of all quaternions with all-integer or all-half-integer components; that is, any Hurwitz Integer h can be expressed in the form

$$h = \frac{1}{2}a(1+i+j+k) + bi + cj + dk,$$

where a, b, c are all integers.

The following theorem then follows trivially.

**Theorem 6.4.** The sum of any two Hurwitz Integers is itself a Hurwitz integer.

**Definition 6.5.** A Hurwitz integer a is a multiple of a Hurwitz integer b if and only if there is a Hurwitz integer c such that a = bc.

**Definition 6.6.** [CW11] A Hurwitz Prime is a Hurwitz Integer which has no non-trivial factors (that is, factors other than elementary quaternions and

$$\pm \frac{1}{2} \pm \frac{1}{2}i \pm \frac{1}{2}j \pm \frac{1}{2}k$$

).

From now on, we'll refer to typical primes  $p \in Z$  as "regular primes", and Hurwitz Primes as "Hurwitz Primes" to clearly differentiate the two.

**Lemma 6.7.** [CW11] If positive integers p and q can be written as the sum of four squares, so can their product.

*Proof.* Suppose that 
$$p = a^2 + b^2 + c^2 + d^2$$
 and  $q = w^2 + x^2 + y^2 + z^2$ . Then, if  $\alpha = a + bi + cj + dk$  and  $\beta = w + xi + yj + zk$ ,

we know that  $p = ||\alpha||^2$  and  $q = ||\beta||^2$ , for some Lipschitz quaternions  $\alpha$  and  $\beta$ . Then  $uv = ||\alpha^2||| \cdot |\beta||^2 = ||\alpha\beta||^2 = ||A||^2$  for some Lipschitz quaternion A, from which the desired result follows.

This means that it suffices to show the Lagrange Four-Square Theorem for all regular primes. The following two lemmas from [CW11] are given without proof, as said proofs are not particularly relevant to the Lagrange Four-Square Theorem.

**Lemma 6.8.** Let p be a Hurwitz prime. If

$$p|\alpha\beta$$
,

either  $p|\alpha$  or  $p|\beta$ .

**Lemma 6.9.** If p is an odd regular prime, there exist integers l and m such that

$$p|1 + l^2 + m^2$$
.

**Theorem 6.10.** If p is an odd regular prime, it is not a Hurwitz Prime.

*Proof.* We'll use contradiction. Suppose that p is a Hurwitz prime. Now, by Lemma 6.9, there exist integers l and m such that

$$p|1 + l^2 + m^2.$$

But

$$(1+li+mj)(1-li-mj) = (1+(li+mj))(1-(li+mj))$$

$$= (1)^2 - (li+mj)(li+mj)$$

$$= 1 - (-l^2 - m^2 + li \cdot mj + mj \cdot li)$$

$$= 1 + l^2 + m^2 - lm(i \cdot j - j \cdot i)$$

$$= 1 + l^2 + m^2.$$

Then, by Lemma 6.8, if  $p|1+l^2+m^2$ , we must have p|1+li+mj or p|1-li-mj. But then

$$\frac{1}{p} \pm \frac{li + mj}{p}$$

is a Hurwitz Integer, which is impossible, as p>2. Therefore, p is not a Hurwitz Integer.  $\square$ 

**Theorem 6.11.** Let p be a regular odd prime. Then p can be written as the sum of four squares.

*Proof.* Since p is not a Hurwitz prime, it can be factored as

$$(6.1) p = (a+bi+cj+dk)\alpha.$$

Then

$$\overline{p} = p = \overline{\alpha}(a - bi - cj - dk).$$

Multiplying, we obtain

$$p^{2} = (a + bi + cj + dk)\alpha \overline{\alpha}(a - bi - cj - dk) = (a^{2} + b^{2} + c^{2} + d^{2})||a||^{2}.$$

Since p is not a Hurwitz prime, the original factorization in (1) is nontrivial; therefore, we know that both parts of the factorization

$$p^2 = (a^2 + b^2 + c^2 + d^2)||a||^2$$

are equal to p. Then  $a^2 + b^2 + c^2 + d^2 = p$ , as desired.

Finally, we are ready to prove Lagrange's Four-Square Theorem.

**Theorem 6.12** (Lagrange's Four-Square Theorem). Every nonnegative integer n can be written as

$$n = a^2 + b^2 + c^2 + d^2,$$

where a, b, c, and d are nonnegative integers.

*Proof.* We start with base cases. We have

$$1 = 0^2 + 0^2 + 0^2 + 1^2$$

and

$$2 = 1^2 + 1^2 + 0^2 + 0^2.$$

By Theorem 6.11, any odd regular prime can be expressed in this form as well. Let

$$n = \prod_{i=1}^{k} p_i^{e_i}.$$

Since each of the  $p_i$  can be written in the desired form, Lemma 6.7 produces the desired result.

### References

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- [Ham66] William Roward Hamilton. Elements Of Quaternions. Longmans, Green, 1866.
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