



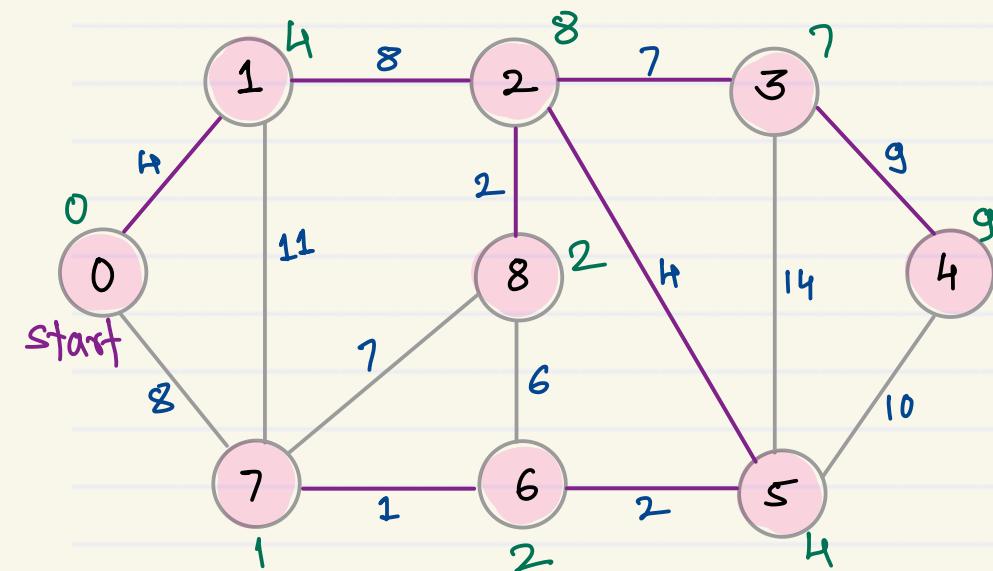
**Sunbeam Institute of Information Technology
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Data structures and Algorithms

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Initialisations

- Create a set mst to keep track of vertices included in MST.
- Also keep track of parent of each vertex. Initialise parent of each vertex to -1.
- Assign a key to all vertices in the input graph. Key of all vertices should be initialised to INF. The start vertex key should be 0.



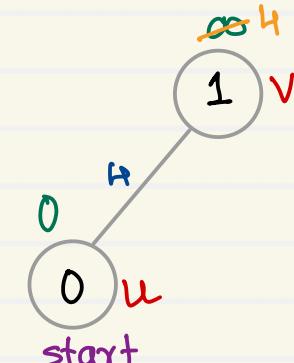
	Key	Parent
0	0	-1
1	4	0
2	8	1
3	7	2
4	9	3
5	11	2
6	2	5
7	1	6
8	2	2

wt = 37

Algorithm

While mst doesn't include all vertices

- Pick a vertex u which is not there in mst and has minimum key.
- Include vertex u in mst.
- Update key and parent of all adjacent vertices of u which are not there in mst
 - For each adjacent vertex v, if weight of edge u-v is less than the current key of v, then update the key as weight of u-v.
 - Record u as parent of v.

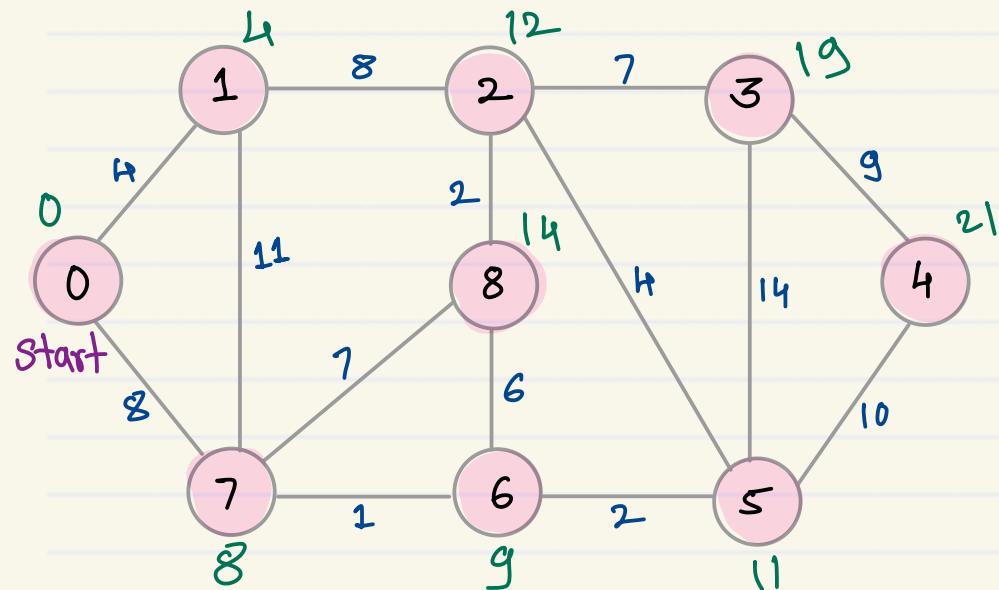


```

if (adjMat[u][v] < key[v]) {
  key[v] = adjMat[u][v];
  parent[v] = u;
}
  
```

Initialisations

- Create a set spt to keep track of vertices included in shortest path tree.
- Track distance of all vertices in the input graph. Distance of all vertices should be initialised to INF. The start vertex distance should be 0.



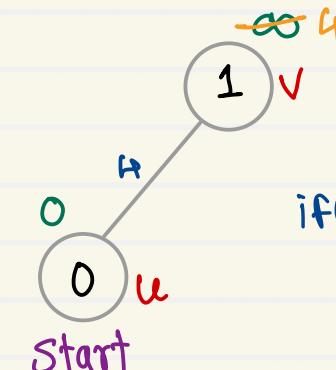
	Dist
0	0
1	4
2	12
3	19
4	21
5	11
6	9
7	8
8	14

Algorithm

While spt doesn't include all vertices

- Pick a vertex u which is not there in spt and has minimum distance.
- Include vertex u in spt.
- Update distances of all adjacent vertices of u which are not there in spt

For each adjacent vertex v, if distance of u + weight of edge u-v is less than the current distance of v, then update it's distance as distance of u + weight of edge u-v.



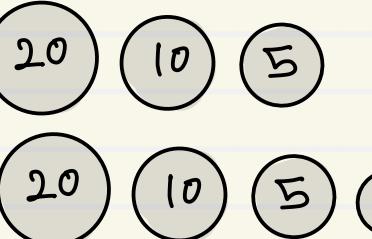
```
if(dist[u] + adjMat[u][v] < dist[v])
    dist[v] = dist[u] + adjMat[u][v];
```

- A greedy algorithm is any algorithm that follows the problem solving heuristic of making the locally optimal choice at each stage with the intent of finding a global optimum.
 - We can make choice that seems best at the moment and then solve the sub problems that arise later.
 - The choice made by a greedy algorithm may depend on choices made so far, but not on future choices or all the solutions to the sub problem.
 - It iteratively makes one greedy choice after another, reducing each given problem into a smaller one.
 - A greedy algorithm never reconsiders it's choices.
 - A greedy strategy may not always produce an optimal solution.
-
- Greedy algorithm decides minimum number of coins to give while making change.
 - Available coins : 50, 20, 10, 5, 2, 1

amount = 36

$$36 - 20 = 16$$


$$16 - 10 = 6$$


$$6 - 5 = 1$$

$$1 - 1 = 0$$




Recursion

- Function calling itself is called as recursive function
- For each function call, stack frame is created on the stack.
(FAR)
- Thus it needs more space as well as more time for execution.
- However recursive functions are easy to program.
- Typical divide and conquer problems are solved using recursion.
- For recursive functions two things are must
 1. Recursive call (explain process in terms of itself)
 2. Terminating or base condition (where to stop)

Recursive problems:

1. Simple (loop alternative)
e.g. factorial, power, factors
2. Divide & Conquer
e.g. binary search, tree algo, quick sort, merge sort.
3. Overlapping problem
e.g. fibonacci
$$T_n = T_{n-1} + T_{n-2}$$
$$T_1 = T_2 = 1$$



Recursion - Fibonacci series (n^{th} term)

- Recursive formula

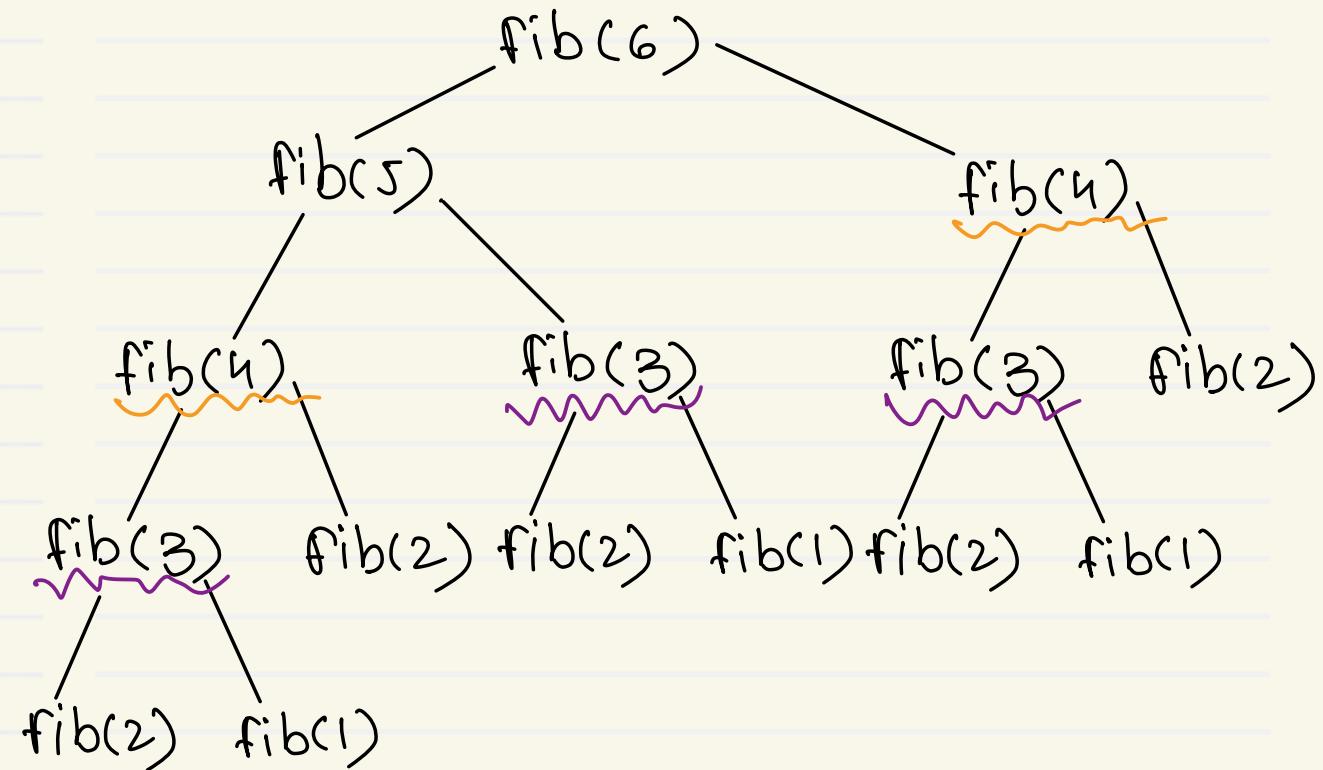
$$T_n = T_{n-1} + T_{n-2}$$

- Terminating condition

$$T_1 = T_2 = 1$$

- Overlapping sub problem

```
int fib(int n) {  
    if (n == 1 || n == 2)  
        return 1;  
    return fib(n-1) + fib(n-2);  
}
```



$$T(n) = O(2^n)$$



Memoization

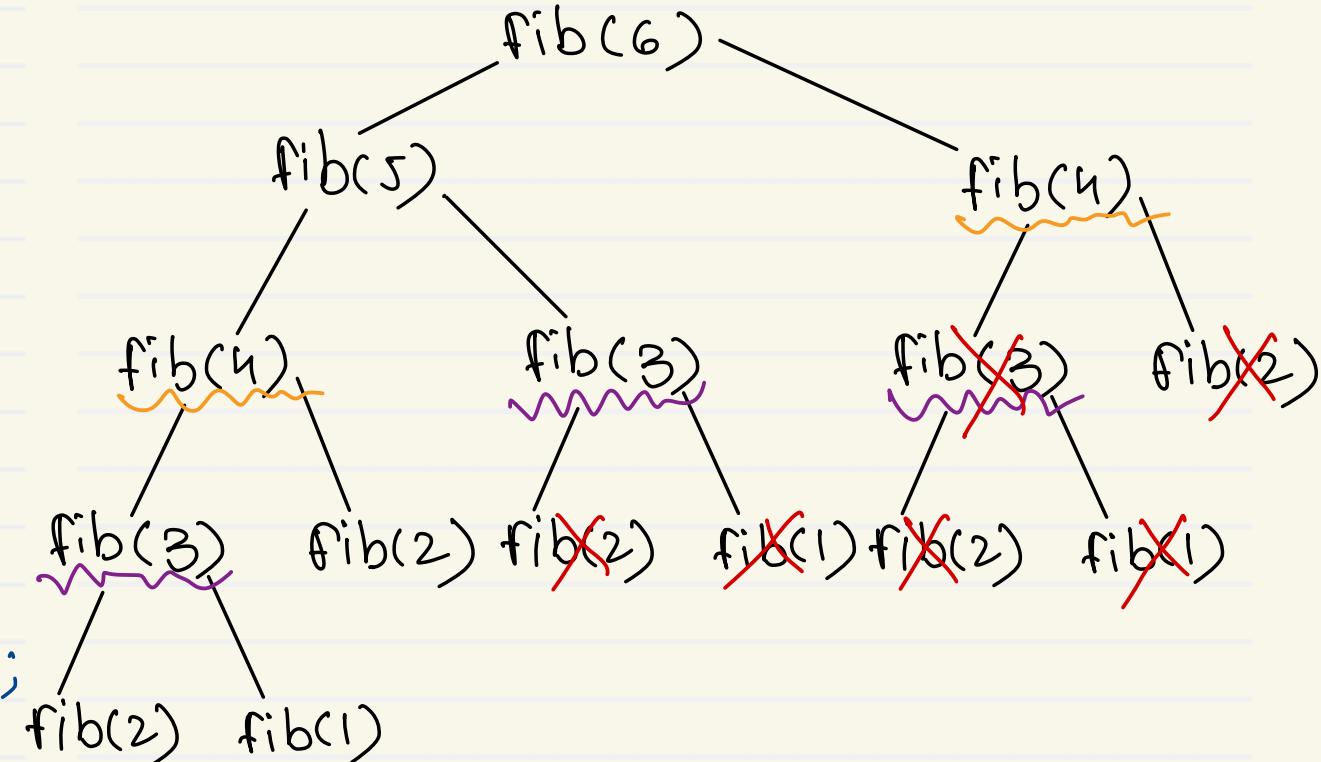
- It's based on the Latin word memorandum meaning "to be remembered"
- Memoization is a technique used in computing to speed up programs.
- This is accomplished by memorizing the calculation results of processed input such as the results of function calls.
- If the same input or a function call with the same parameters is used, the previously stored results can be used again and unnecessary calculation are avoided.
- Need to rewrite recursive algorithms. Using simple arrays or map/dictionary.
- Memoization uses top down approach.



Memoization - Fibonacci series

```
int terms[] = new int[n+1];
```

```
int fib(int n) {
    if (terms[n] != 0)
        return terms[n];
    if (n == 1 || n == 2) {
        terms[n] = 1;
        return 1;
    }
    terms[n] = fib(n-1) + fib(n-2);
    return terms[n];
}
```



- Dynamic programming is another optimization over recursion.
- Typical DP problem give choices (to select from) and ask for optimal result (maximum or minimum).
- Technically it can be used for the problems having two properties
 1. Overlapping sub problems
 - To solve problem, we need to solve it's sub problems multiple times.
 2. Optimal sub structure
 - Optimal solution of problem can be obtained using optimal solutions of its sub problems.
- DP solution is bottom up approach.
- DP uses 1D or 2D array to save state.
- DP algorithms solve the sub problem in a iteration and improves upon it in subsequent iterations.

```
int dpFib(int n) {  
    int terms[ ] = new int[n+1];  
    terms[1] = terms[2] = 1;  
    for(int i=3; i<=n; i++)  
        terms[i] = terms[i-1] + terms[i-2];  
    return terms[i];  
}
```

$$n = 6$$

1	1	2	3	5	8	13
0	1	2	3	4	5	6