



**Sunbeam Institute of Information Technology  
Pune and Karad**

## **Data structures and Algorithms**

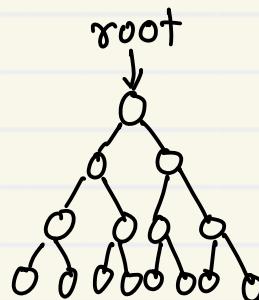
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# BST - Time complexity of operations

**Capacity:**

max number of nodes that can be added into a binary tree for give height.

height	Node
-1	0
0	1
1	3
2	7
3	15



$h$  - height of binary tree

$n$  - no. of elements in binary tree

$$n = 2^{h+1} - 1$$

$$n = 2^{h+1} - 1$$

$$\frac{h}{2} \approx n$$

$$\log_2^h = \log n$$

$$h \log 2 = \log n$$

$$h \approx \frac{\log n}{\log 2}$$

Time  $\propto$  Height

Time  $\propto \frac{\log n}{\log 2}$

$$T(n) = O(\log n)$$

Add :	$O(h)$	$O(\log n)$
Delete :	$O(h)$	$O(\log n)$
Search :	$O(h)$	$O(\log n)$

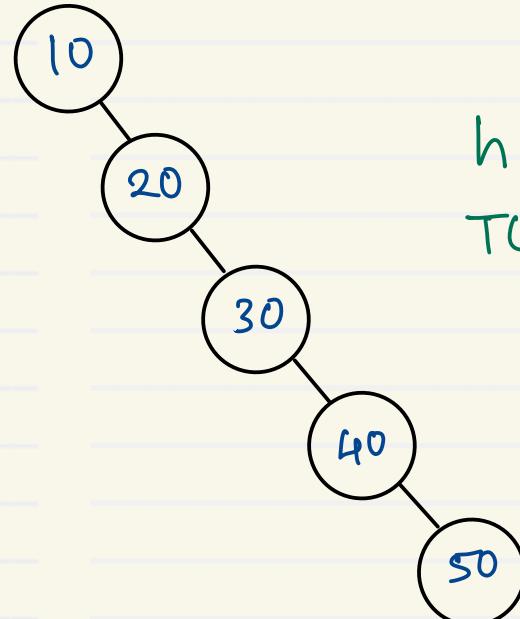
Traverse :

$O(n)$

# Skewed Binary Tree

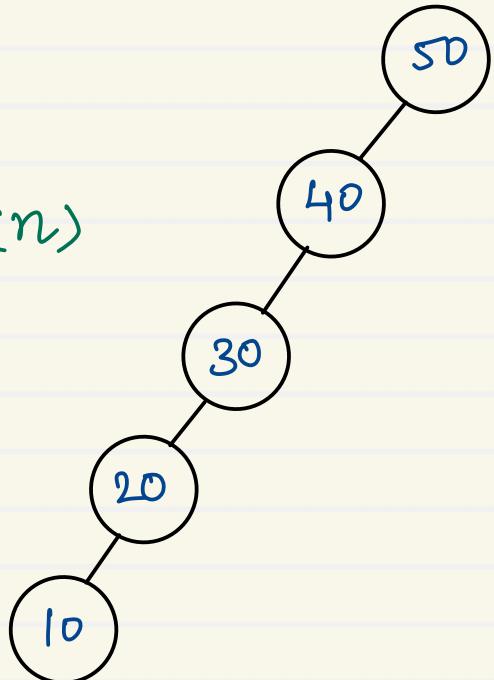
- In binary tree if only left or right links are used, tree grows only in one direction such tree is called as skewed binary tree
  - Left skewed binary tree
  - Right skewed binary tree
- Time complexity of any BST is  $O(h)$
- Skewed BST have maximum height ie same as number of elements.
- Time complexity of searching is skewed BST is  $O(n)$

Keys : 10, 20, 30, 40, 50



Keys : 50, 40, 30, 20, 10

$$h \approx n$$
$$T(n) = O(n)$$



# Balanced BST

- To speed up searching, height of BST should be minimum as possible
- If nodes in BST are arranged, so that its height is kept as less as possible, is called as Balanced BST

Balance factor = Height (left sub tree) - Height (right sub tree)

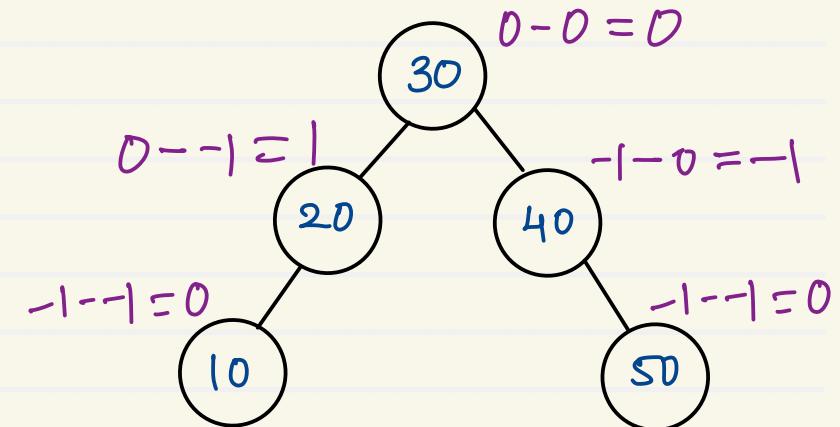
- tree is balanced if balance factors of all the nodes is either -1, 0 or +1
- balance factors =  $\{-1, 0, +1\}$
- A tree can be balanced by applying series of left or right rotations on imbalance nodes

nodes having balance factor other than  $\{-1, 0, +1\}$

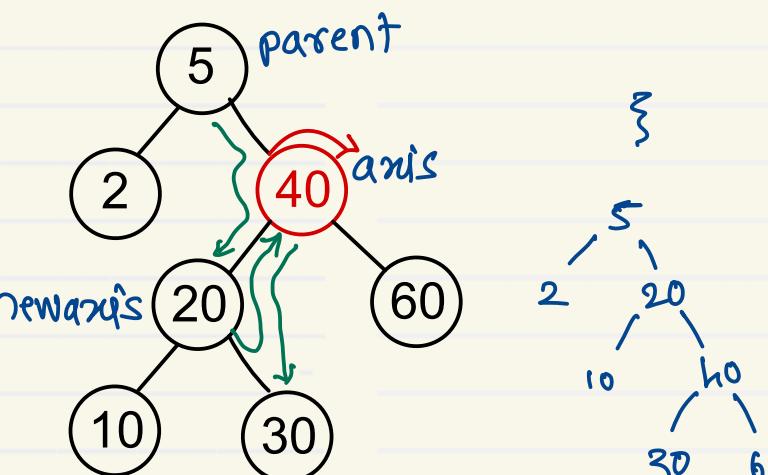
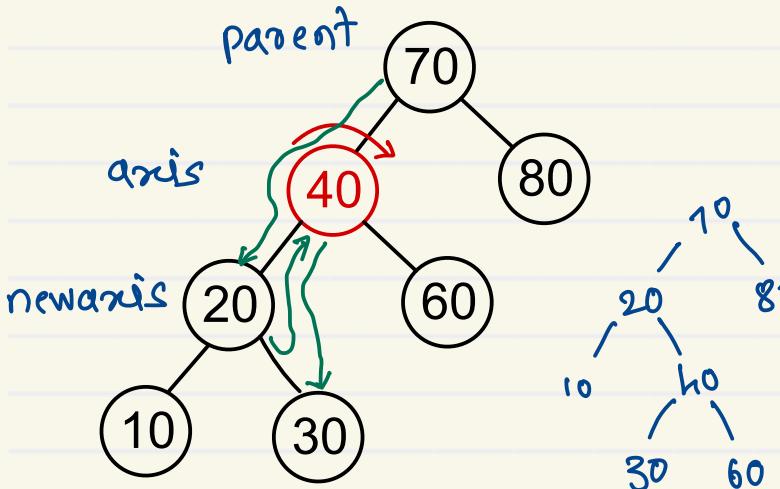
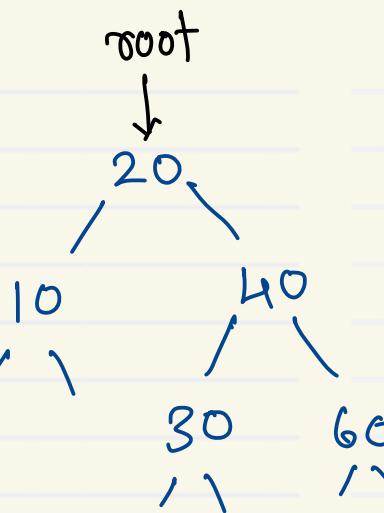
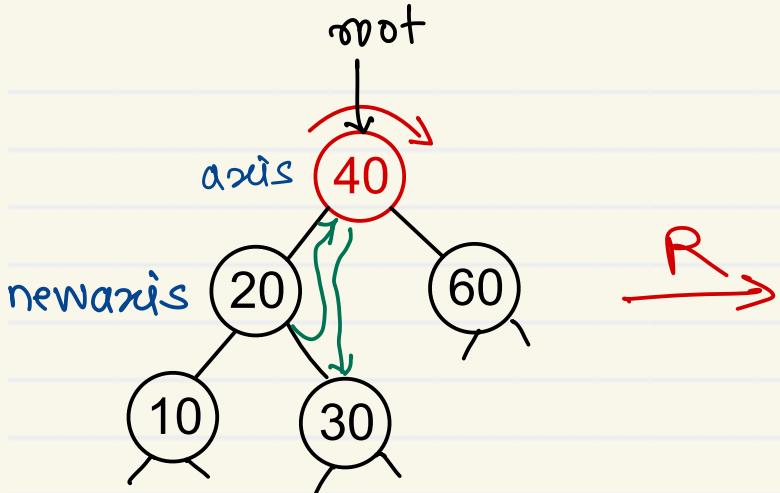
Types :

- AVL Tree
- Red Black Tree
- Splay Tree

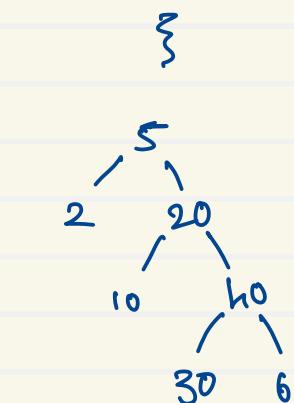
Keys : 30, 40, 20, 50, 10



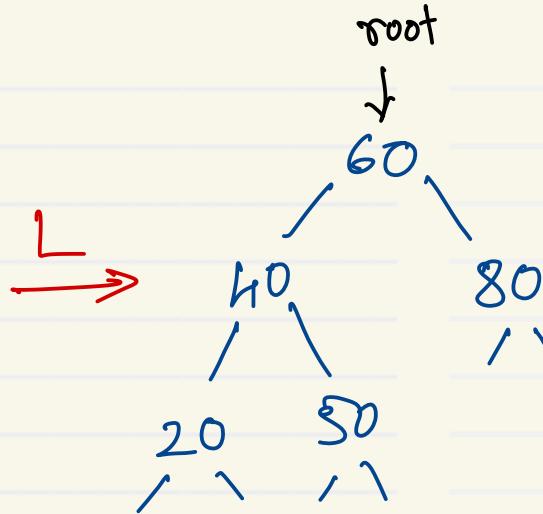
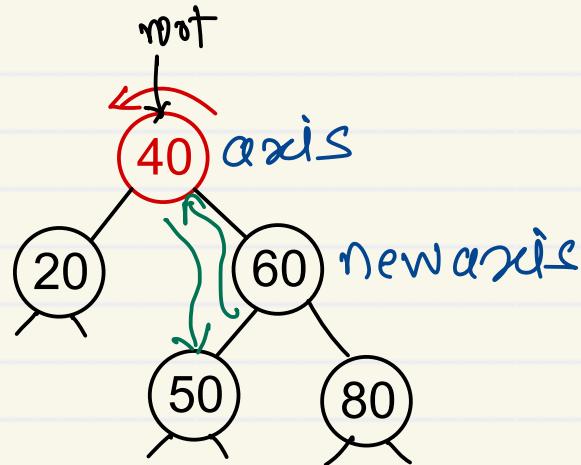
# Right Rotation



```
void rightRotation( axis, parent ) {
    newaxis = axis.left;
    axis.left = newaxis.right;
    newaxis.right = axis;
    if( axis == root )
        root = newaxis;
    else if( axis == parent.left )
        parent.left = newaxis;
    else if( axis == parent.right )
        parent.right = newaxis;
}
```



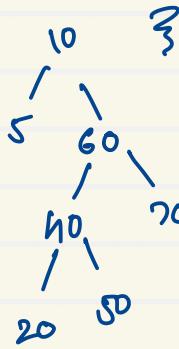
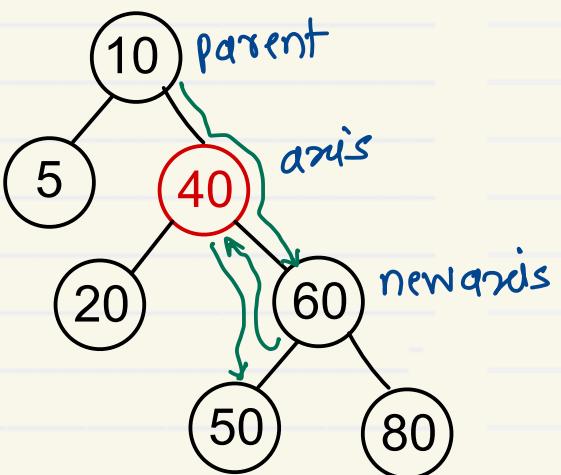
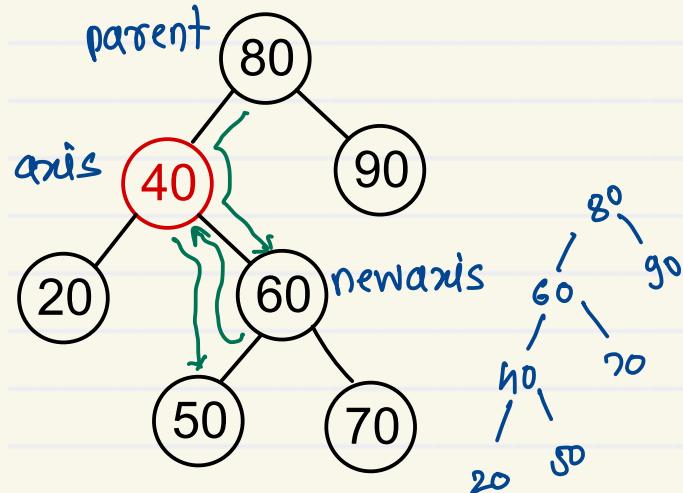
# Left Rotation



```

void leftRotation( axis, parent ) {
    newaxis = axis.right;
    axis.right = newaxis.left;
    newaxis.left = axis;
    if( axis == root )
        root = newaxis;
    else if( axis == parent.left )
        parent.left = newaxis;
    else if( axis == parent.right )
        parent.right = newaxis;
}

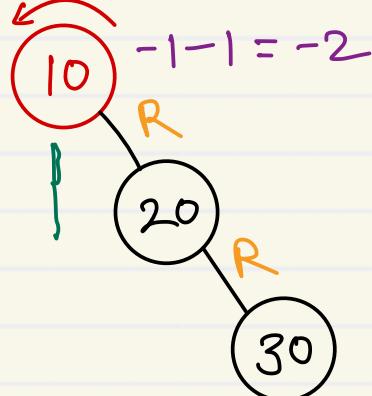
```



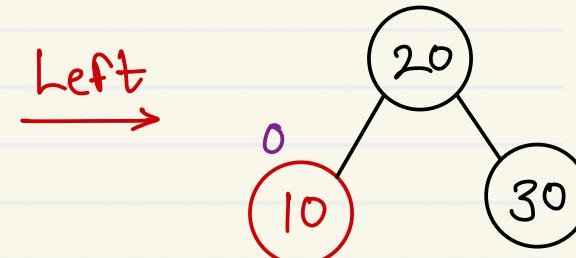


## Rotation cases : Right-Right case (RR Imbalance)

Keys : 10, 20, 30



→ apply left rotation on imbalance node



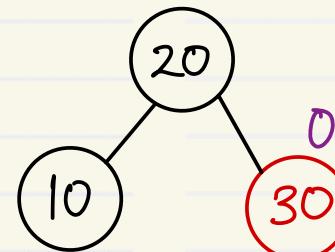
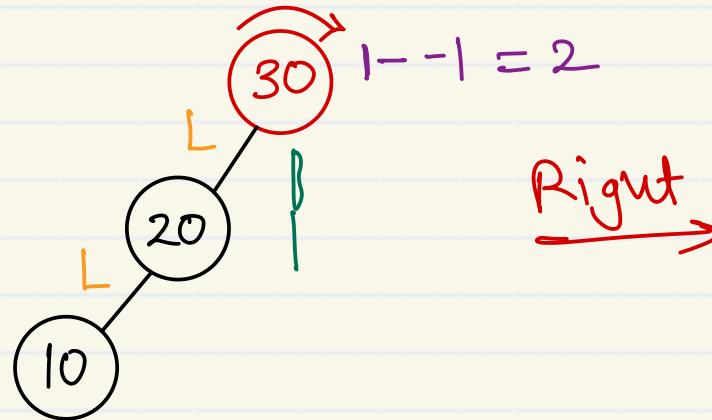
```
if( bf < -1 && value > trav.right.data){  
    leftRotation(trav, parent);  
}
```



## Rotation cases : Left-Left case ( LL Imbalance)

↳ apply right rotation on imbalance node

Keys : 30, 20, 10

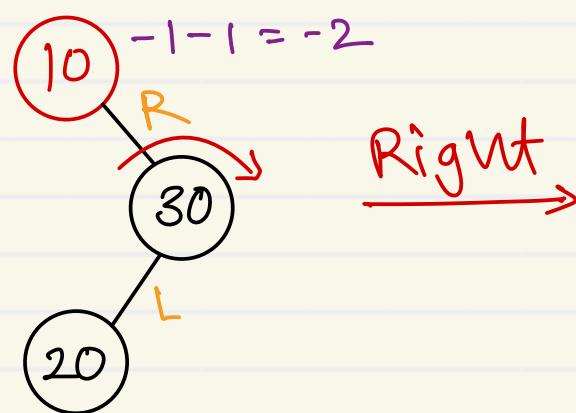


```
if( bf > +1 && value < trav.left.data){  
    rightRotation(trav, parent);  
}
```

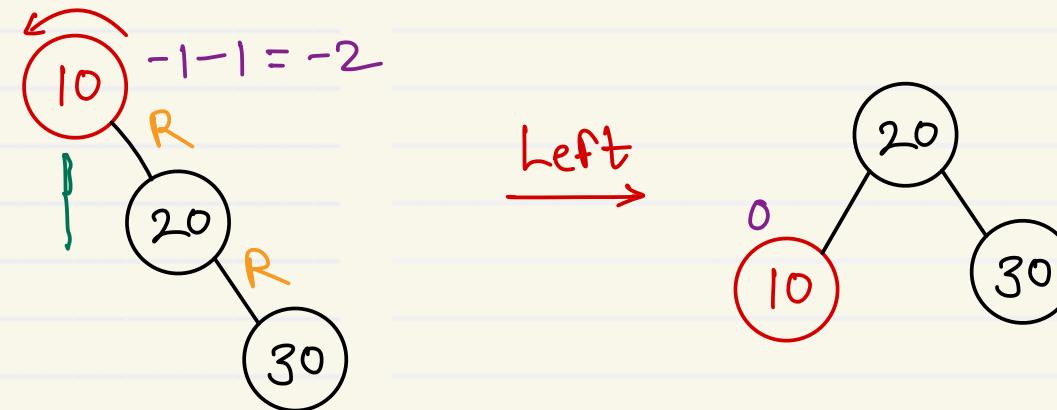


## Rotation cases : Right-Left case (RL Imbalance)

Keys : 10, 30, 20



↳ first apply right rotation on right of imbalance node  
second apply left rotation on imbalance node



if ( $bf < -1 \ \&\& \ value < trav.\text{right}.\text{data}$ ) {  
    rightRotation (trav.right, trav)  
    leftRotation (trav, parent)}

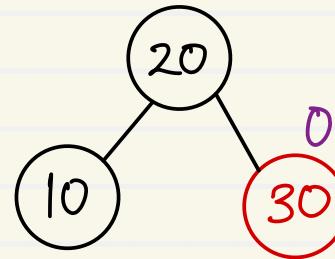
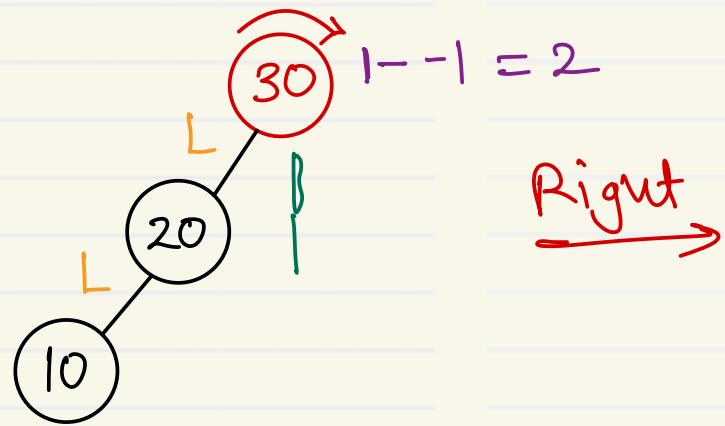
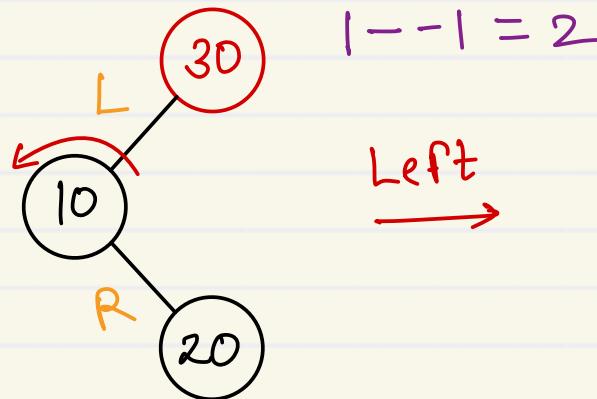
}



# Rotation cases : Left-Right case (LR Imbalance)

Keys : 30, 10, 20

→ first apply left rotation on left of imbalance node  
second apply right rotation on imbalance node

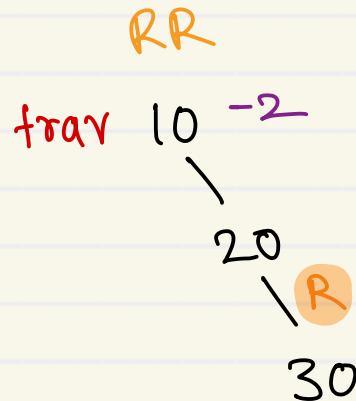


```
if( bf > +1 && value > trav.left.data){  
    leftRotation(trav.left, trav);  
    rightRotation(trav, parent);  
}
```

3

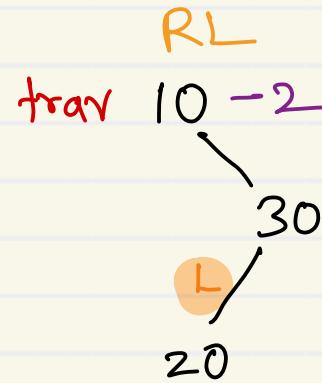
Balance factor = { -1, 0, +1 }

$BF < -1$



$$\text{value} = 30$$

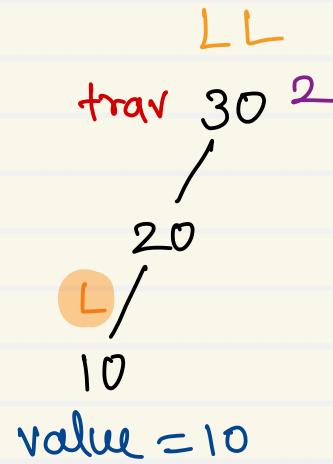
$\text{value} > \text{trav.right.data}$



$$\text{value} = 20$$

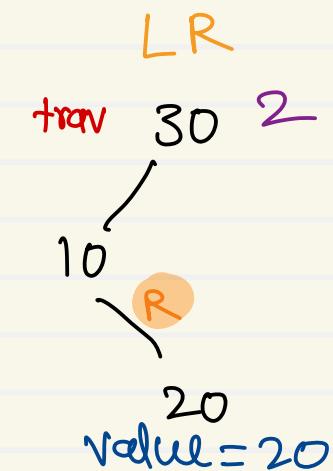
$\text{value} < \text{trav.right.data}$

$BF > +1$



$$\text{value} = 10$$

$\text{value} < \text{trav.left.data}$



$$\text{value} = 20$$

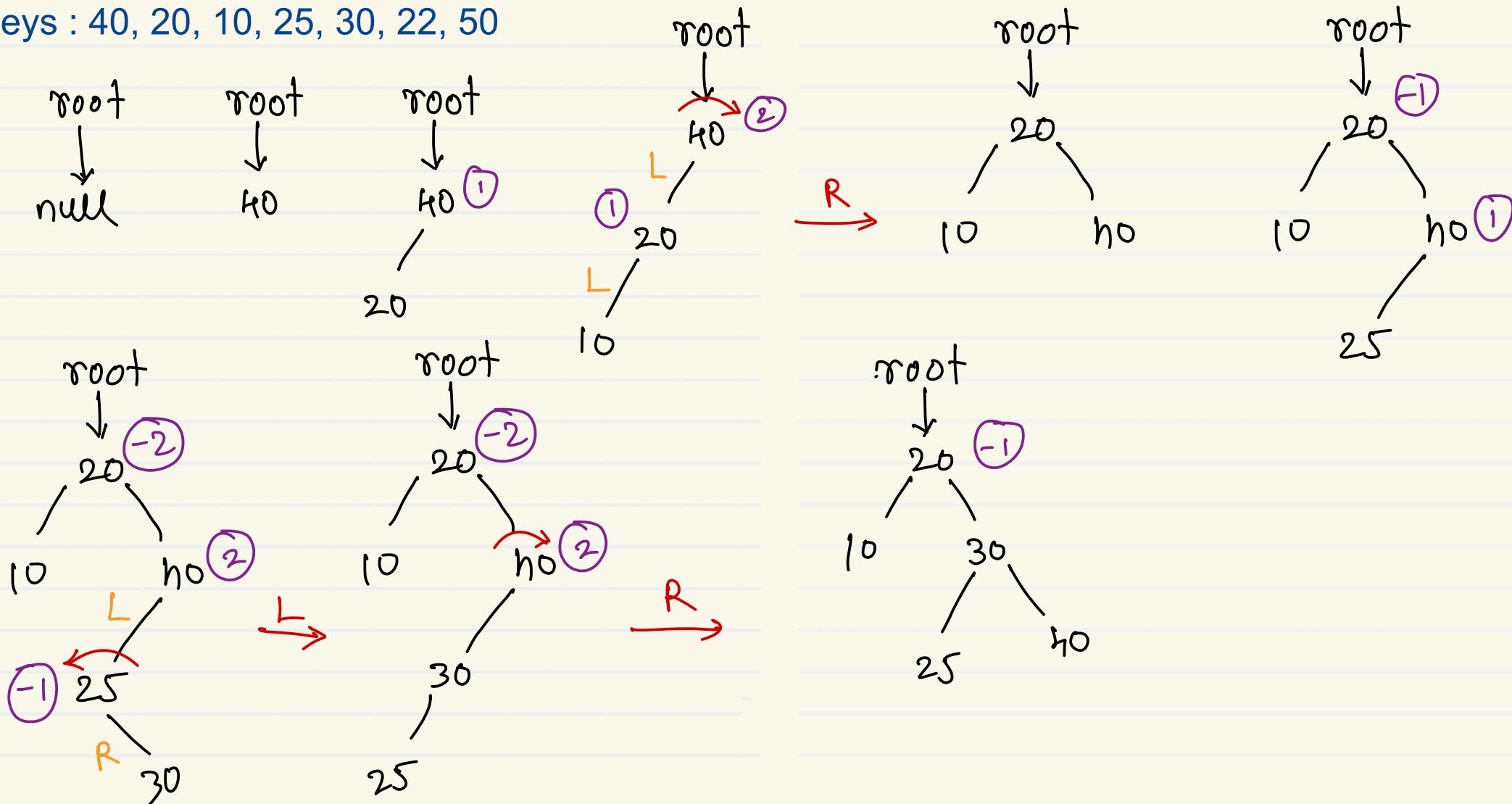
$\text{value} > \text{trav.left.data}$



- self balancing binary search tree
- on every insertion and deletion of a node, tree is getting balanced by applying rotations on imbalance nodes
- The difference between heights of left and right sub trees can not be more than one for all nodes
- Balance factors of all the nodes are either -1 , 0 or +1
- All operations of AVL tree are performed in  $O(\log n)$  time complexity

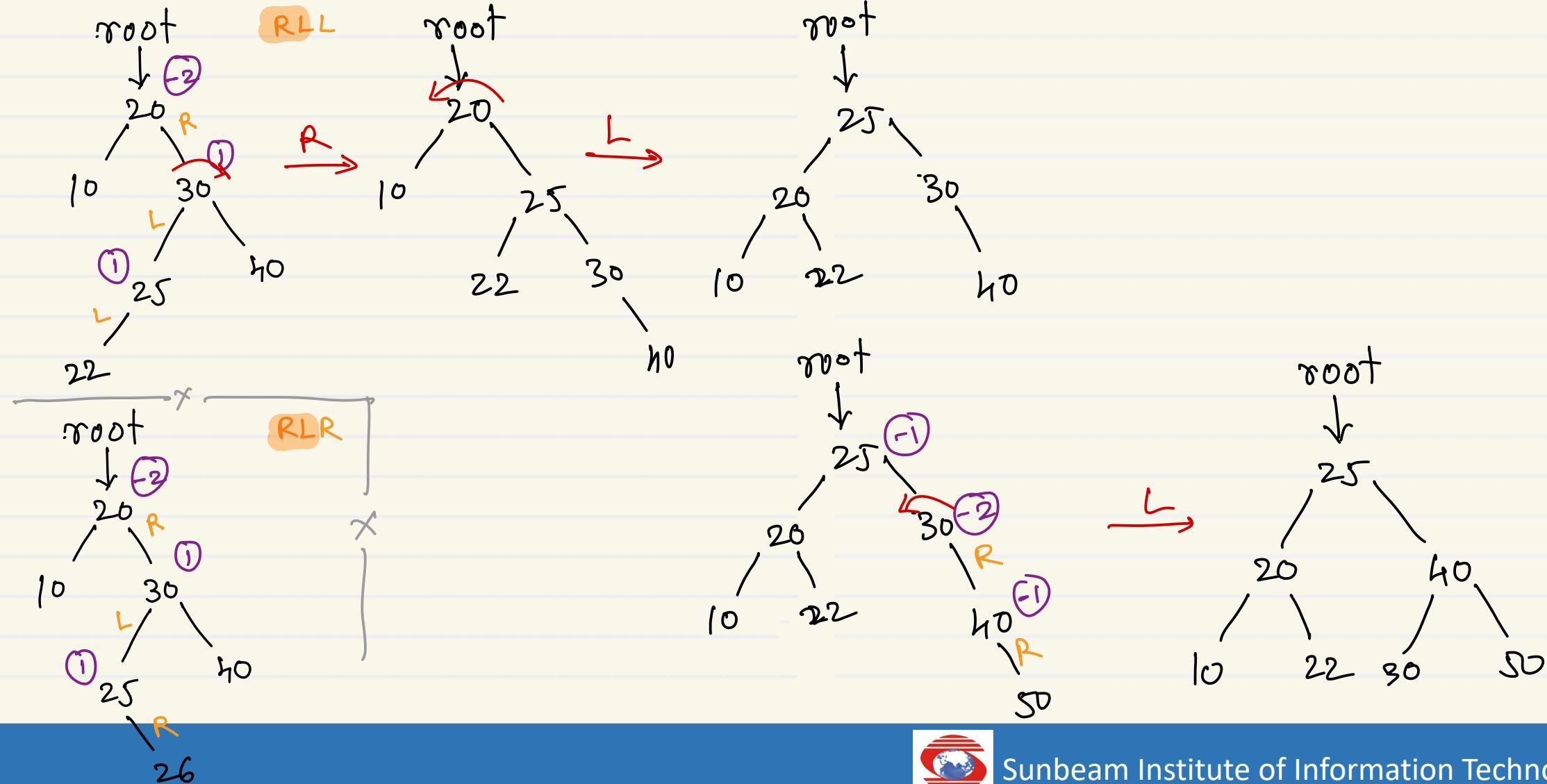
# AVL Tree - Add Node

Keys : 40, 20, 10, 25, 30, 22, 50

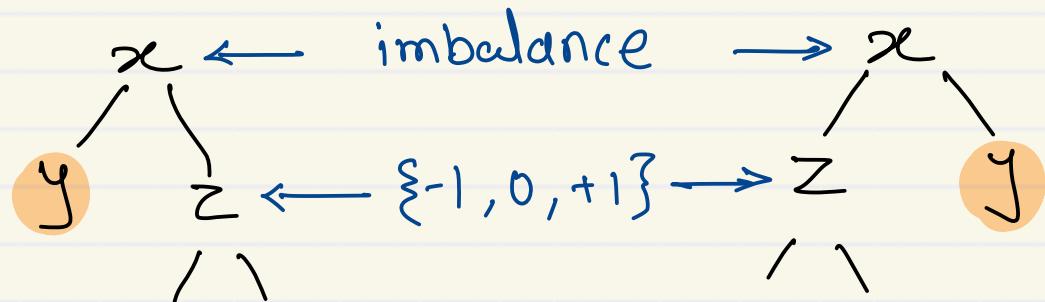


# AVL Tree - Add Node

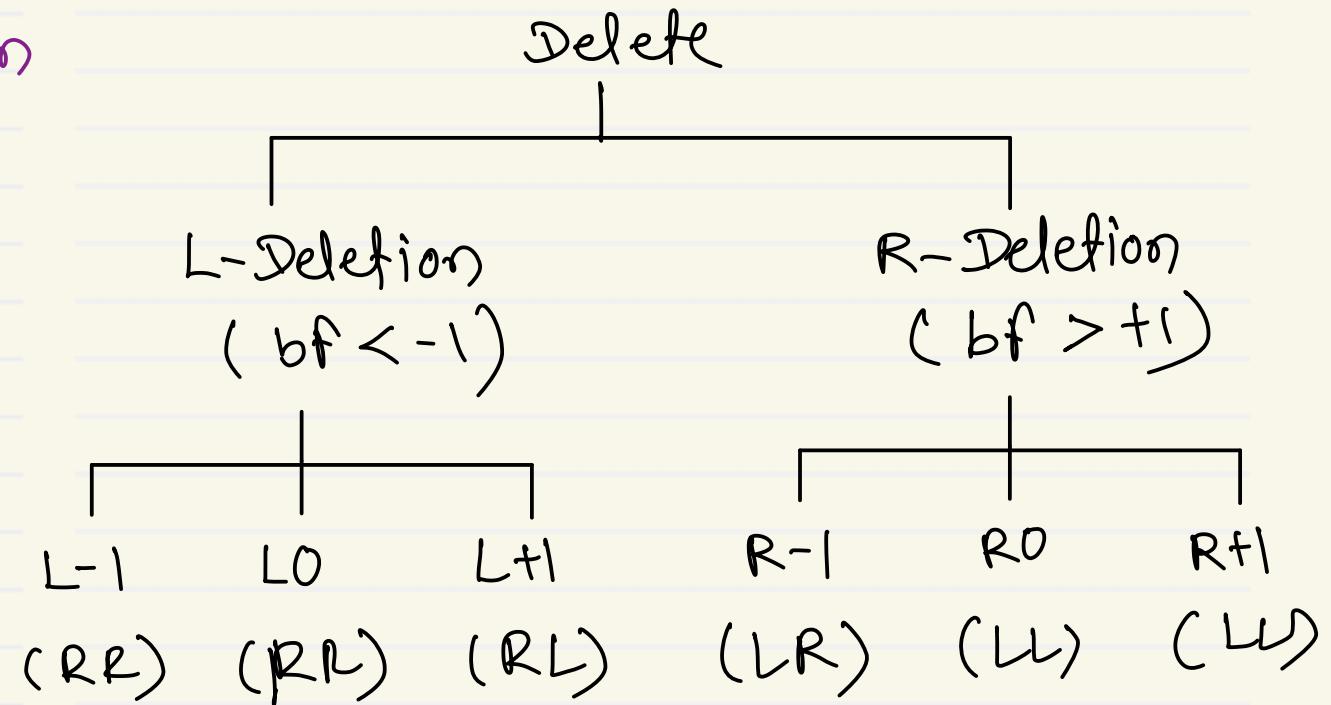
Keys : 40, 20, 10, 25, 30, 22, 50



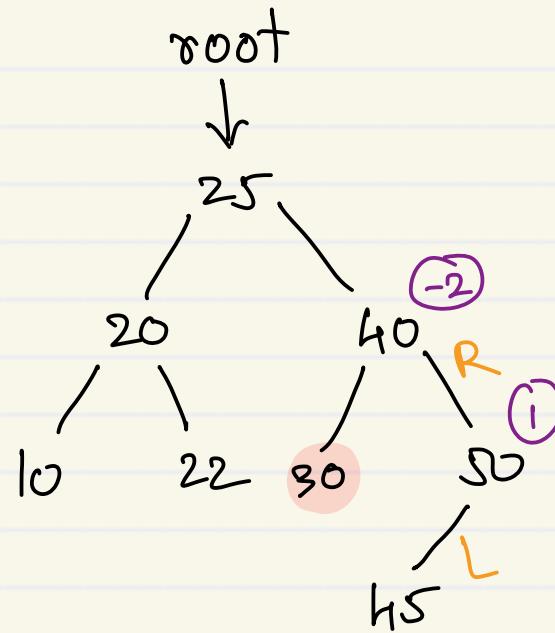
L- Deletion



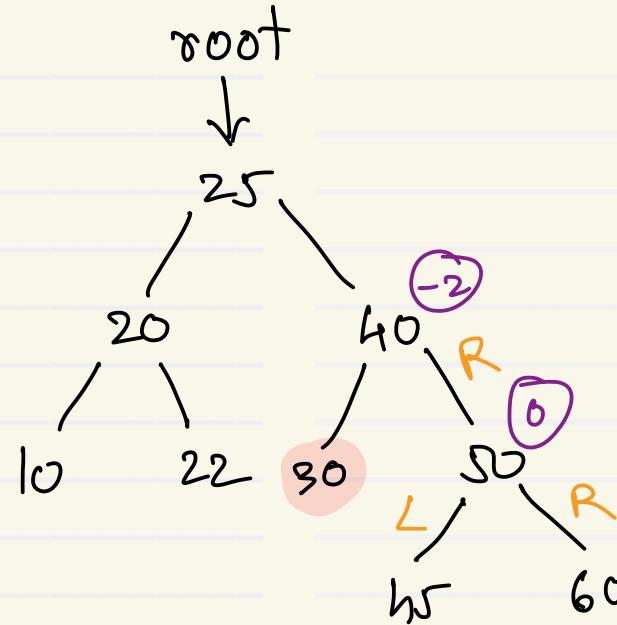
R- Deletion



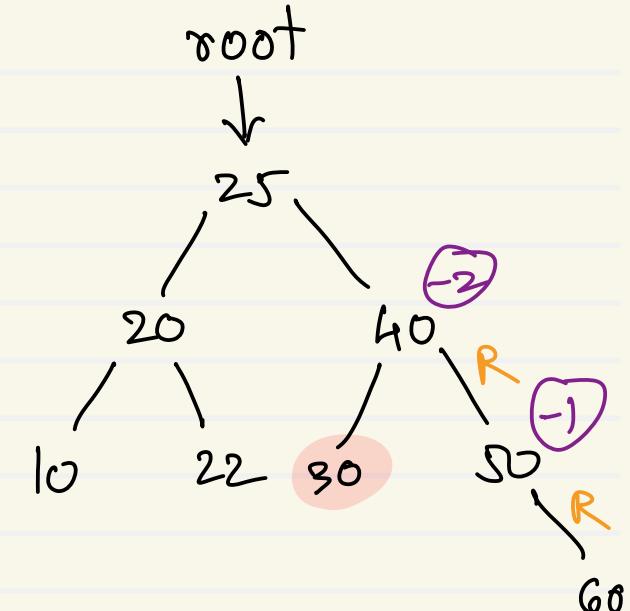
# AVL Tree - Delete Node



L+1  
(RL)

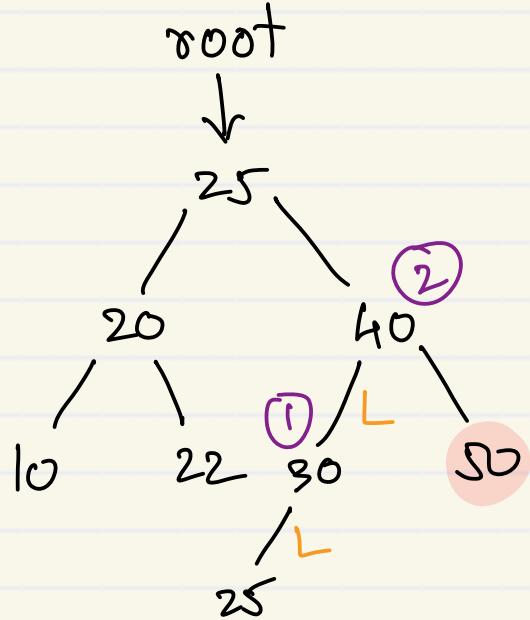


LO  
(RR)

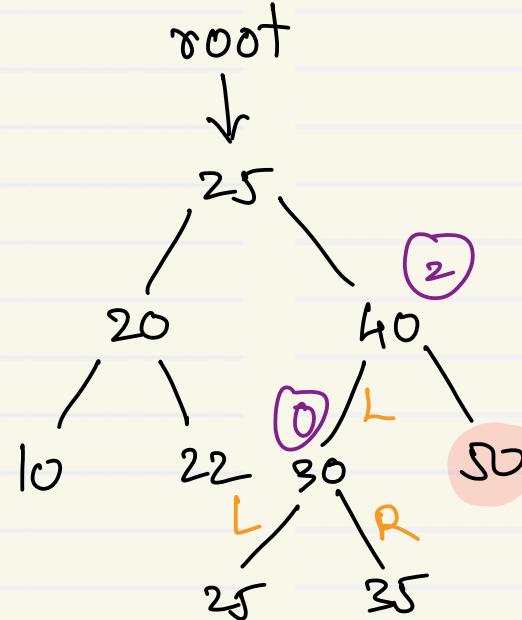


L-1  
(RR)

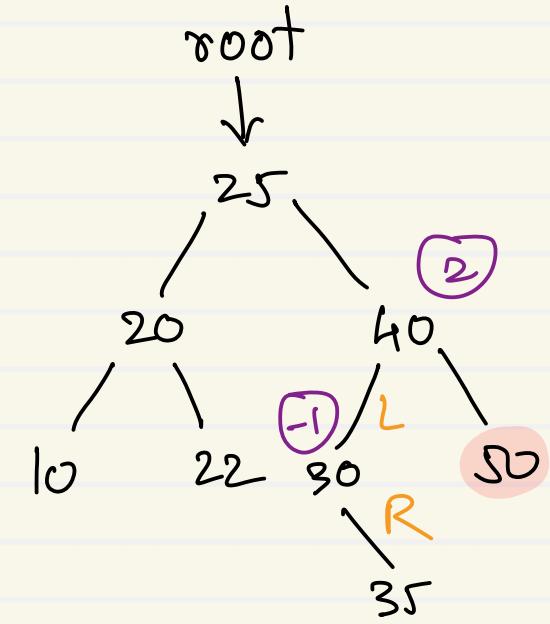
## AVL Tree - Delete Node



R + 1  
( LL )



RD  
( LL )



R - 1  
( L R )