AN INTRODUCTION TO SPLINES

Trinity River Restoration Program Workshop on Outmigration: Population Estimation

October 6-8, 2009

AN INTRODUCTION TO SPLINES

- Linear Regression
 - Simple Regression and the Least Squares Method
 - Least Squares Fitting in R
 - Polynomial Regression
- 2 Smoothing Splines
 - Simple Splines
 - B-splines
 - Overfitting and Smoothness

AN INTRODUCTION TO BAYESIAN INFERENCE

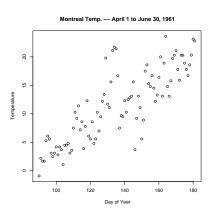
- 1 Linear Regression
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SIMPLE LINEAR REGRESSION

Daily temperatures in Montreal from April 1 (Day 81) to June 30 (Day 191), 1961.



Assumptions

Mean On average, the change in the response is proportional to the change in the predictor.

- Errors 1. The deviation in the response for any observation does not depend on any other observation.
 - 2. The average magnitude of the deviation is the same for all values of the predictor.

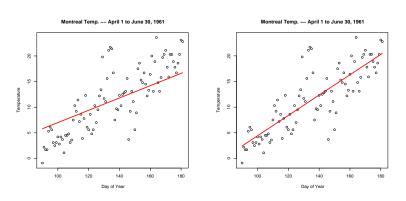
Mathematically

For
$$i = 1, ..., n$$
:

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

where $\epsilon_1, \ldots, \epsilon_n$ are independent with mean 0 and variance σ^2 .

EXAMPLE: THE MONTREAL DATA



THE RESIDUALS

Definition

Given values for β_0 and β_1 , the residual for the i^{th} observation is the difference between the observed and the predicted response:

$$e_i = y_i - \hat{y}_i$$

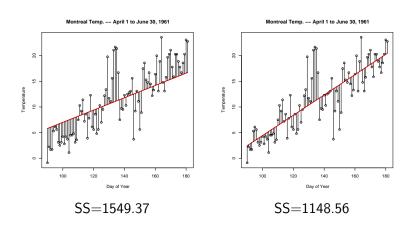
where
$$\hat{y}_i = \beta_0 + \beta_1 x_i$$
.

THE LEAST SQUARES CRITERION

The least squares method defines the best values of β_0 and β_1 to be those that minimize the sum of the squared residuals:

$$SS = \sum_{i=1}^{n} e_i^2 = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2.$$

EXAMPLE: THE MONTREAL DATA



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THE DATA

Suppose that the data is a data frame with elements:

- x: the days from 90 to 181
- y: the observed temperatures

```
> data = read.table("MontrealTemp1.txt")
> summary(data)
      х
Min. : 90.0 Min. :-0.90
               1st Qu.: 5.60
 1st Qu.:112.8
Median :135.5
               Median :11.55
Mean :135.5 Mean :11.46
               3rd Qu.:16.70
3rd Qu.:158.2
Max. :181.0
               Max. :23.60
```

FITTING THE MODEL

Fitting the model with 1m:

FITTING THE MODEL

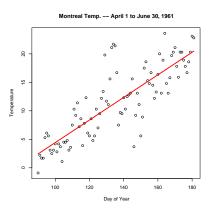
Fitting the model with 1m:

```
> lmfit = lm(y~x,data)
> attributes(lmfit)
$names
 [1] "coefficients" "residuals"
 [3] "effects"
                      "rank"
 [5] "fitted.values"
                      "assign"
 [7] "qr"
                       "df.residual"
 [9] "xlevels"
                      "call"
[11] "terms"
                      "model"
$class
[1] "lm"
>
```

THE FITTED LINE

Plotting the fitted line over the raw data:

THE FITTED LINE



Goodness-of-Fit Testing

Residual Diagnostics

The value of the residuals should not depend on x or y in any systematic way.

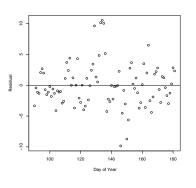
- Common indications of lack of fit:
 - trends with x or y (curves or clusters of high/low values)
 - constant increase/decrease (funnel shape)
 - increase followed by decrease (football shape)
 - very large (+ or -) values (outliers)
- Assessed by plotting e versus x and y.

RESIDUAL PLOTS

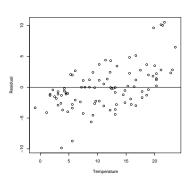
Plotting the residuals versus the predictor and response:

THE FITTED LINE





Residuals vs. Temperature



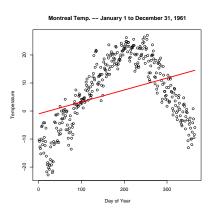
EXERCISES

- Montreal Temperature Data April 1 to June 30, 1961
 File: Intro_to_splines\Exercises\montreal_temp_1.R
 Use the provide code to fit the simple linear regression model to the Montreal temperature data from the spring of 1961, plot the fitted line, and produce the residual plots.
- Montreal Temperature Data Jan. 1 to Dec. 31, 1961
 File: Intro_to_splines\Exercises\montreal_temp_2.R
 Repeat exercise 1 with the data from all of 1961.

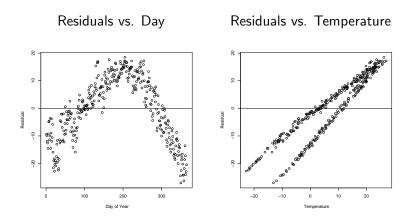
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MOTIVATION



MOTIVATION



POLYNOMIALS

Definition

A polynomial of degree D is a function formed by linear combinations of the powers of its argument up to D:

$$y = \beta_0 + \beta_1 x + \beta_2 x^2 + \dots + \beta_D x^D$$

Specific Polynomials

Linear
$$y = \beta_0 + \beta_1 x$$

Quadratic $y = \beta_0 + \beta_1 x + \beta_2 x^2$
Cubic $y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3$
Quartic $y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \beta_4 x^4$
Quintic $y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \beta_4 x^4 + \beta_5 x^5$

The Design Matrix

Definition

The design matrix for a regression model with n observations and p predictors is the matrix with n rows and p columns such that the value of the j^{th} predictor for the i^{th} observation is located in column j of row i.

Design matrix for a polynomial of degree *D*

POLYNOMIAL REGRESSION IN R

CONSTRUCTING THE DESIGN MATRIX - QUADRATIC

The design matrix for polynomial regression can be generated with the function outer():

```
> X = outer(data$x,1:D,"^")
> X[1:5,]
    [,1] [,2]
[1,] 1
[2.]
[3,]
[4,] 4 16
   5 25
[5.]
```

Note: we do not need to include the intercept column.

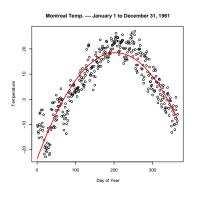
POLYNOMIAL REGRESSION IN R

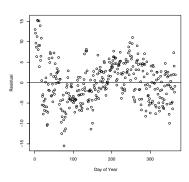
Least Squares Fitting – Quadratic

```
> lmfit = lm(y~X,data)
> attributes(lmfit)
$names
 [1] "coefficients" "residuals" ...
$class
[1] "lm"
> lmfit$coefficients
  (Intercept)
                          X 1
                                         X 2
-23.715358962 0.413901580 -0.001014625
```

POLYNOMIAL REGRESSION IN R

FITTED MODEL - QUADRATIC





EXERCISES

- 1. Montreal Temperature Data Jan. 1 to Dec. 31, 1961 File: Intro_to_splines\Exercises\montreal_temp_3.R Use the provided code to fit polynomial regression models of varying degree to the data for all of 1961. Models of different degree are constructed by setting the variable D (e.g., D=2 produces a quadratic model). What is the minimal degree required for the model to fit well?
- Montreal Temperature Data Jan. 1, 1961, to Dec. 31, 1962
 File: Intro_to_splines\Exercises\montreal_temp_4.R
 Repeat this exercise using the data from both 1961 and 1962.

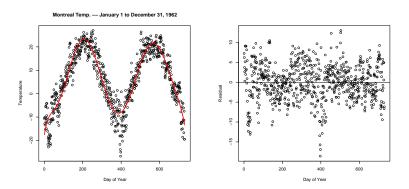
AN INTRODUCTION TO BAYESIAN INFERENCE

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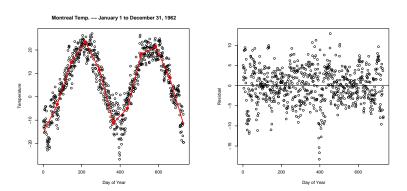
MOTIVATION



How is the temperature changing in the spring of 1962?

$$y = -7.6 - 8.3x - 0.3x^{2} - 5.2 \times 10^{4}x^{-3} + 4.4 \times 10^{-6}x^{4}$$
$$-2.1 \times 10^{-8}x^{5} + 6.0 \times 10^{-11}x^{6} - 8.9 \times 10^{-14}x^{7} + 5.5 \times 10^{-17}x^{8}$$

A Linear Spline for the Montreal Temperature Data



How is the temperature changing in the spring of 1962?

$$y = -144.5 + .3x$$

LINEAR SPLINES

Definition

A linear spline is a continuous function formed by connecting linear segments. The points where the segments connect are called the knots of the spline.

HIGHER ORDER SPLINES

Definition

A spline of degree D is a function formed by connecting polynomial segments of degree D so that:

- the function is continuous,
- \blacktriangleright the function has D-1 continuous derivatives, and
- ▶ the *D*th derivative is constant between knots.

SIMPLES SPLINES

THE TRUNCATED POLYNOMIALS

Definition

The truncated polynomial of degree D associated with a knot ξ_k is the function which is equal to 0 to the left of ξ_k and equal to $(x - \xi_k)^D$ to the right of ξ_k .

$$(x - \xi_k)_+^D = \begin{cases} 0 & x < \xi_k \\ (x - \xi_k)^D & x \ge \xi_k \end{cases}$$

The equation for a spline of degree D with K knots is:

$$y = \beta_0 + \sum_{d=1}^{D} \beta_d x^d + \sum_{k=1}^{K} b_k (x - \xi_k)_+^{D}$$

SIMPLE SPLINES

The Design Matrix

The design matrix for a spline of degree D with K knots is the n by 1 + D + K matrix with entries:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^D & (x_1 - \xi_1)_+^D & \cdots & (x_1 - \xi_K)_+^D \\ 1 & x_2 & x_2^2 & \cdots & x_2^D & (x_2 - \xi_1)_+^D & \cdots & (x_2 - \xi_K)_+^D \\ 1 & x_3 & x_3^2 & \cdots & x_3^D & (x_3 - \xi_1)_+^D & \cdots & (x_3 - \xi_K)_+^D \\ & & \vdots & & & & \\ 1 & x_n & x_n^2 & \cdots & x_n^D & (x_n - \xi_1)_+^D & \cdots & (x_n - \xi_K)_+^D \end{bmatrix}$$

SIMPLE SPLINES IN R

THE DESIGN MATRIX

After defining the degree and the locations of the knots, the design matrix can be generated with the functions outer and cbind:

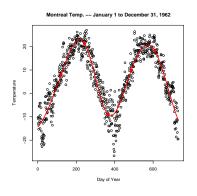
```
> K = 5
> knots = 730 * (1:K)/(K+1)
> X1 = outer(data$x,1:D,"^")
> X2 = outer(data$x,knots,">") *
       outer(data$x,knots,"-")^D
> X = cbind(X1,X2)
> \text{ round}(X[c(1,150,300),1:5],1)
     [,1] [,2] [,3]
                               [,4] \quad [,5]
[1,]
                                0.0
[2,]
    150 22500 3375000 22745.4
    300 90000 27000000 5671495.4 181963
[3,]
```

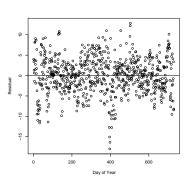
SIMPLE SPLINES IN R

FITTING THE SPLINE MODEL

SIMPLE SPLINES IN R

FITTED CUBIC SPLINE





EXERCISES

Montreal Temperature Data - Jan. 1 to Dec. 31, 1961
 File: Intro_to_splines\Exercises\montreal_temp_5.R
 Use the code provided to fit splines of varying degree and with different numbers of knots to the data from 1961 and 1962.

An Introduction to Bayesian Inference

- 2 Smoothing Splines
 - Simple Splines
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THE B-SPLINE BASIS

TROUBLES WITH TRUNCATED POLYNOMIALS

Splines computed from the truncated polynomials may be numerically unstable because:

- the values in the design matrix may be very large, and
- the columns of the design matrix may be highly correlated.

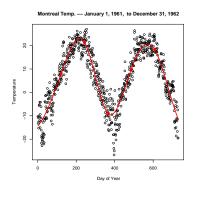
THE B-SPLINE BASIS IN R

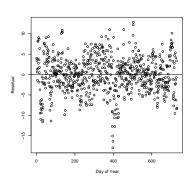
GENERATING THE DESIGN MATRIX AND FITTING THE MODEL

The B-spline design matrix can be constructed via the function bs provided by the splines library:

THE B-SPLINE BASIS IN R

FITTED CUBIC B-SPLINE MODEL





EXERCISES

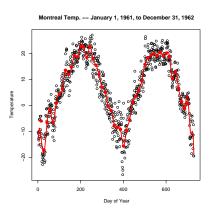
Montreal Temperature Data - Jan. 1 to Dec. 31, 1961
 File: Intro_to_splines\Exercises\montreal_temp_6.R
 Fit B-splines to the data from 1961 and 1962 using the code in the file. Increase the number of knots to see how this affects the fit of the curve. What happens when the number of knots is very large, say K = 50?

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MOTIVATION

A cubic spline with 50 knots:



Overfitting and Smoothness

KNOT SELECTION

Concept

The shape of a spline can be controlled by carefully choosing the number of knots and their exact locations in order to:

- 1. allow flexibility where the trend changes quickly, and
- 2. avoid overfitting where the trend changes little.

Challenge

Choosing the number of knots and their location is a very difficult problem to solve.

PENALIZATION

Concept

We can also balance overfitting and smoothness by controlling the size of the spline coefficients.

PENALIZATION FOR TRUNCATED POLYNOMIALS

Penalization for the Linear Spline

Consider the equation for each segment of the spline:

▶ The spline is smooth if $b_1, b_2, ..., b_K$ are all close to 0.

Penalized Least Squares

$$PSS = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2 + \lambda \sum_{k=1}^{K} b_k^2$$

PENALIZATION FOR THE B-SPLINE BASIS

Penalization for the B-spline

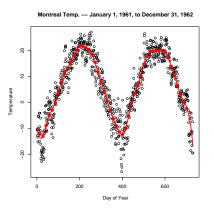
The spline is smooth if b_1, b_2, \ldots, b_K are all close to each other. (But not necessarily close to 0.)

Penalized Least Squares

$$PSS = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2 + \lambda \sum_{k=3}^{K} ((b_k - b_{k-1}) - (b_{k-1} - b_{k-2}))^2$$

A PENALIZED CUBIC B-SPLINE

A penalized cubic B-spline with 50 knots and $\lambda = 5$:



EXERCISES

Montreal Temperature Data - Jan. 1 to Dec. 31, 1961
 File: Intro_to_splines\Exercises\montreal_temp_7.R
 Fit penalized cubic B-splines to the Montreal temperature
 data for 1961 and 1962 using the provided code.