

Faster-RCNN

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1 train-frcnn

1.1 introduction

This file is training the faster RCNN. It will load the config params firstly, then initialize the network params used by the command line params. You must choose pascal_voc or simple, then you will get all images. Using `get_anchor_gt()` to get the anchors. Then it defines the network architecture. The network includes `base_networks`(Resnet, VGG, Inception), `rpn` and `classifier`. Train the network and calculate the loss in the end.

1.2 functions

- [sys.setrecursionlimit](#)

It can change the maximum recursion depth.

- [OptionParse](#)

You can create an instance of `OptionParser`, populate it with options, and parse the command line.

(1) `path`: Path to training data.

(2) `parser`: Parser to use one of `simple` or `pascal_voc`.

(3) `num_rois`: Number of ROIs per iteration which be randomly selected.

(4) `horizontal_flips`: Augment with horizontal flips in training.

(5) `vertical_flips`: Augment with vertical flips in testing.

(6) `rot_90`: Augment with 90 degree rotations in training.

(7) `num_epoch`: Number of epochs.

(8) `config_filename`: Location to store all the metadata related to the training to be used when testing.

(9) `output_weight_path`: Output path for weights.

(10) `input_weight_path`: Input path for weights. If not specified, will try to load default weights provided by keras.

2 test-frcnn

3 measure-map

4 keras-frcnn

4.1 config

- [verbose](#)
- [use_horizontal_flips](#)
Augment with horizontal flips in training.
- [use_vertical_flips](#)
Augment with vertical flips in training.
- [anchor_box_scales](#)
Set a list with multi-scales of anchor.
- [anchor_box_ratios](#)
Set a list with multi-ratios(height : width) of a anchor.
- [im_size](#)
Set the image size.
- [img_channel_mean](#)
- [img_scaling_factor](#)
- [num_rois](#)
- [rpn_stride](#)
- [balanced_classes](#)
- [std_scaling](#)
- [classifier_regr_std](#)

- [rpn_min_overlap](#)
- [rpn_max_overlap](#)
- [classifier_min_overlap](#)
- [classifier_max_overlap](#)
- [class_mapping](#)
- [image_dim_ordering](#)
- [model_path](#)

4.2 data-augment

- [copy](#)
 copy(x) will return a shallow copy of x. deepcopy(x) will return a deep copy of x. In case of shallow copy, a reference of object is copied in other object. It means that any changes made to a copy of object do reflect in the original object. In case of deep copy, a copy of object is copied in other object. It means that any changes made to a copy of object do not reflect in the original object.
- [augment](#)
 Using three methods to enhance the image data. There are 1. use_horizontal_flips, 2. use_vertical_filps and 3. rot_90. The function will return the augment images and original images.

4.3 data-generators

- [get_img_output_length](#)
 It calculate the size of the image after four convlutions. The kernel size is [7,3,1,1], padding size is 6 and stride is 2. Then can calculate the output size.

$$output_size = \frac{input_size - kernel_size + stride}{stride} \quad (1)$$

- [area](#)
 Input is a box A, then will return the area of A.

- [union](#)

Inputs are two boxes A and B. A(or B) is [x_A_min, y_A_min, x_A_max, y_A_max]

$$\begin{cases} x_{min} = \min(x_{A_{min}}, x_{B_{min}}) \\ y_{min} = \min(y_{A_{min}}, y_{B_{min}}) \\ x_{max} = \max(x_{A_{max}}, x_{B_{max}}) \\ y_{max} = \max(y_{A_{max}}, y_{B_{max}}) \end{cases} \quad (2)$$

According to the above formula, then

$$\begin{cases} w = x_{max} - x_{min} \\ h = y_{max} - y_{min} \end{cases} \quad (3)$$

So it will return quadruples [x, y, w, h]. It represents the largest region after the merge.

- [intersection](#)

Input are two boxes A and B. A(or B) is [x_A_min, y_A_max, y_A_max]

$$\begin{cases} x_{min} = \max(x_{A_{min}}, x_{B_{min}}) \\ y_{min} = \max(y_{A_{min}}, y_{B_{min}}) \\ x_{max} = \min(x_{A_{max}}, x_{B_{max}}) \\ y_{max} = \min(y_{A_{max}}, y_{B_{max}}) \end{cases} \quad (4)$$

According to the above formula. Then

$$\begin{cases} w = x_{max} - x_{min} \\ h = y_{max} - y_{min} \end{cases} \quad (5)$$

So it will return quadruples [x, y, w, h]. It represents the intersection region.

- [get_new_img_size](#)

The size of original image is adjusted according to the length of the minimum side of the input.

$$\begin{cases} \frac{width}{height} = \frac{new_width}{new_height} \\ new_width = img_min_size & \text{if } width < height \\ new_height = img_min_size & \text{if } width > height \end{cases}$$

- [SimpleSelector](#)

- [SimpleSelector::skip_sample_for_balanced_class](#)

- [calc_rpn](#)

- [threadsafe_iter](#)

- [threadsafe_generator](#)
- [get_anchor_gt](#)
-

4.4 FixBatchNormalization

4.5 losses

- [rpn_loss_regr](#)
- [rpn_loss_cls](#)
- [class_loss_regr](#)
- [class_loss_cls](#)

4.6 pascal-voc-parse

4.7 resnet

This is the model of resnet50. Reference: [Deep Residual Learning for Image Recognition](<https://arxiv.org/abs/1512.03385>)

- [identity_block](#)
- [identity_block_td](#)
- [conv_block](#)
- [conv_block_td](#)
- [nn_base](#)
- [classifier_layers](#)
- [rpn](#)
- [classifier](#)

4.8 roi-helpers

4.9 RoiPoolingConv

4.10 simple-parser

5 requirements

- [h5py](#)

- Keras==2.0.3
- numpy
- opencv-python
- sklearn