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In the three-dimensional Cartesian coordinate system, the gradient of some function ($\nabla \phi$) is given by:
 $\nabla \phi = \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$ where $\hat{i}, \hat{j}, \hat{k}$ are the standard unit vectors. The gradient of a tensor field, $\nabla \cdot \mathbf{T}$, of order n , is generally written as $\nabla \cdot \mathbf{T}$ and is a tensor field of order $n + 1$. In particular, if the tensor field has order 0 (i.e. a scalar), ϕ , the resulting gradient, $\nabla \phi$,

Vector calculus identities - Wikipedia

It depends mainly on the geometry of the structure and the required accuracy of the solution. For example ZELAND IE3D is based on MoM solution of integral equation which has an excellent accuracy ...

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