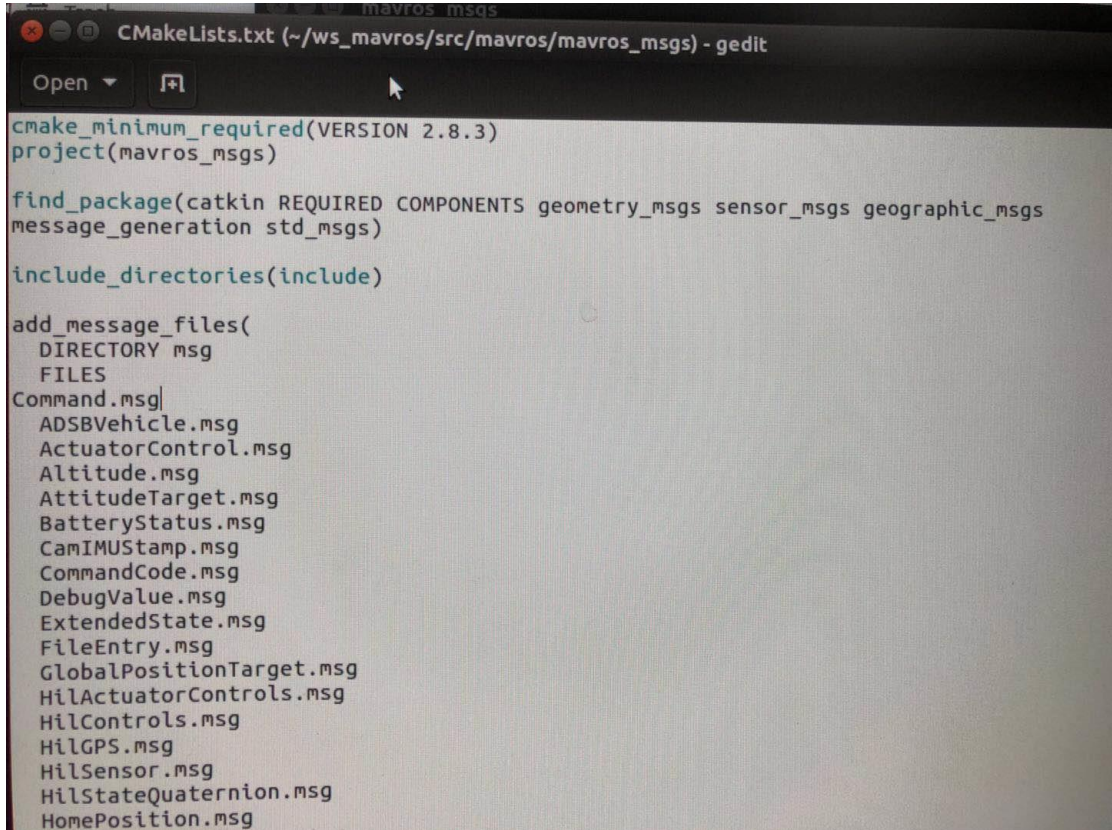


1. 打开文件夹目录至 ws_mavros/src/mavros/mavros_msgs/msg
2. 复制 Command.msg 文件到该目录下
3. 打开文件夹目录至 ws_mavros/src/mavros/mavros_msgs
4. 打开 CMakeLists.txt 文件，在 add_message_files() 列表中添加 Command.msg（如下图），保存



```
CMakeLists.txt (~/ws_mavros/src/mavros/mavros_msgs) - gedit

cmake_minimum_required(VERSION 2.8.3)
project(mavros_msgs)

find_package(catkin REQUIRED COMPONENTS geometry_msgs sensor_msgs geographic_msgs
message_generation std_msgs)

include_directories(include)

add_message_files(
  DIRECTORY msg
  FILES
  Command.msg
  ADSBVehicle.msg
  ActuatorControl.msg
  Altitude.msg
  AttitudeTarget.msg
  BatteryStatus.msg
  CamIMUStamp.msg
  CommandCode.msg
  DebugValue.msg
  ExtendedState.msg
  FileEntry.msg
  GlobalPositionTarget.msg
  HilActuatorControls.msg
  HilControls.msg
  HilGPS.msg
  HilSensor.msg
  HilStateQuaternion.msg
  HomePosition.msg
)
```

5. 打开终端，重新编译 mavros 包，不报错，代表成功。