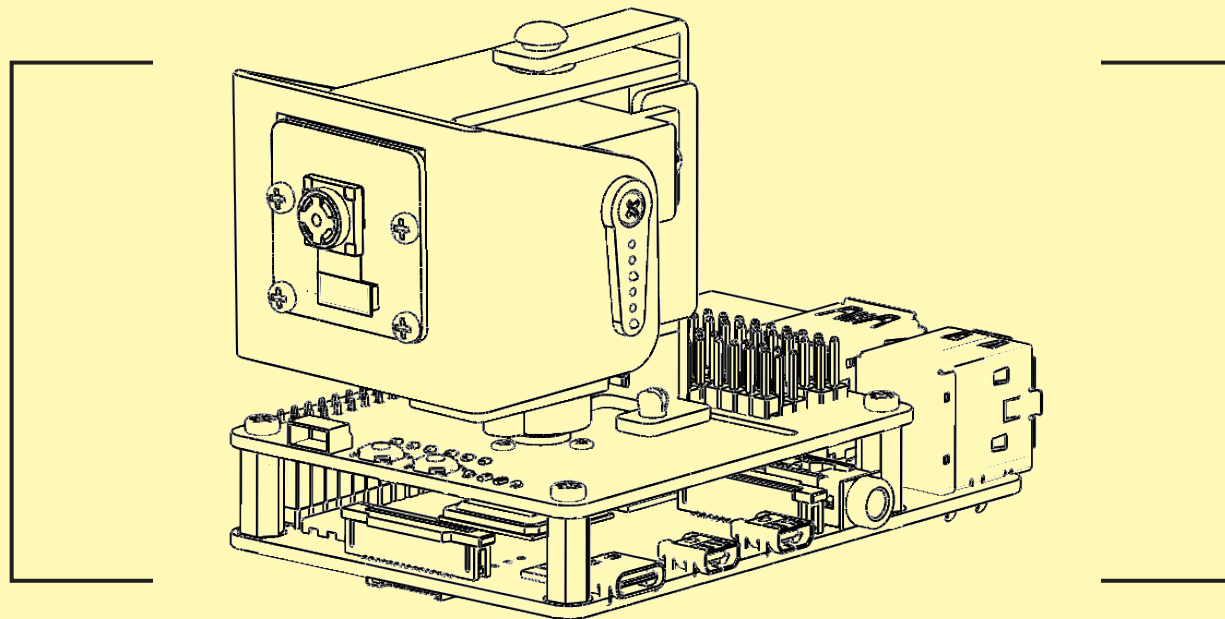
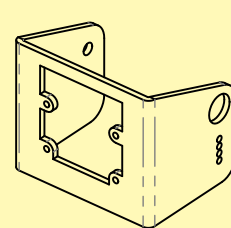


SUNFOUNDER PAN-TILT HAT KIT

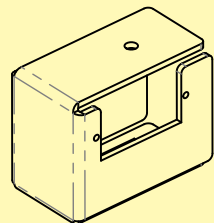
Get tutorial at: pantilt-v3.rtf.d.io



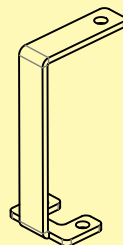
PART LIST



A1 Plate



A2 Plate



A3 Plate



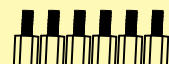
M1.5 x 4
Self-tapping Screw



R3055 Rivet



M2 x 4
Screw



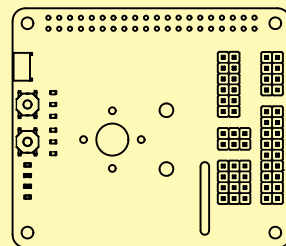
M2.5 x 8 + 6
Standoff



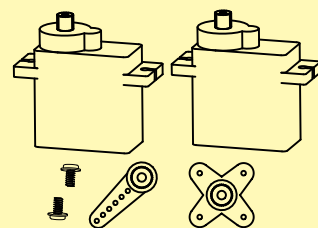
M2.5 x 6
Screw



M2.5 x 11
Standoff



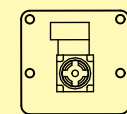
Pan-tilt HAT



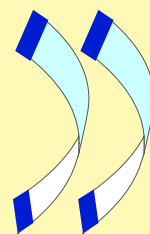
Servo (with package)



Metal Washer



Camera Module

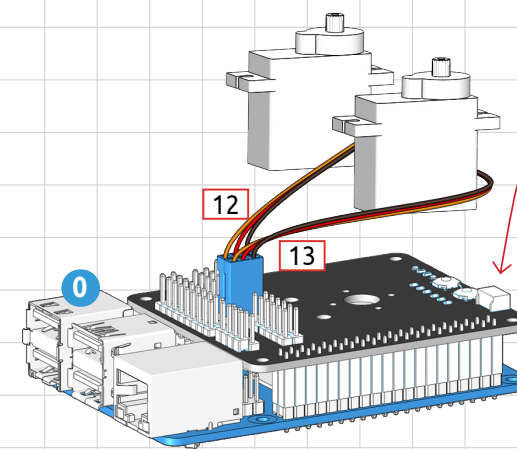


FFC Cable



Screwdriver

ASSEMBLE



Temporarily combine Pan-tilt HAT and Raspberry Pi.

Check details in the online tutorial
pantilt-v3.rtf.d.io

After finish "Quick Guide on Python", 12 & 13 was set to calibrate the servo angle to 0°. Therefore, before assembling each servo, you need to plug the servo pin into each one of them.

NOTE: This function will be invalid after writing any programs.

