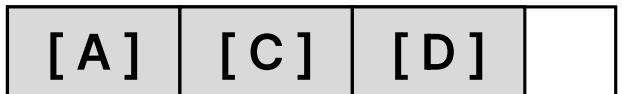


Traditional Ordered Approach

[File A, File C, File D]



Insert File B

[File A, File B, File C, File D]

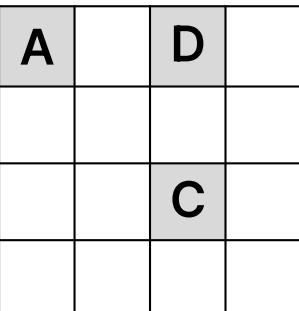


DeepVis Hash-based Spatial Mapper

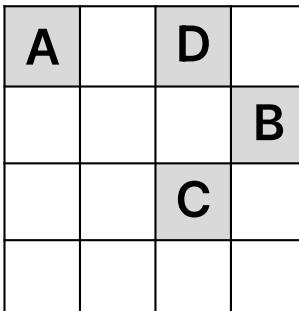
[A] → Hash (A) → (1, 1)

[C] → Hash (C) → (3, 3)

[D] → Hash (D) → (3, 1)



Insert File B



A, B, C
Unchanged

[B] → Hash (B) → (4, 2)