How Can We Correlate Inter-Domain Knowledge?

Reviewing
Consistent Structural Relation Learning for
Generalized Zero-Shot Segmentation
Peike et al., NeurlPS2020

Presentor: Sungguk Cha



Abstract

Recently, in image recognition tasks, approaches **using language domain knowledge directly correlating with visual knowledge** are actively researched.

In this talk, I will review an approach in which visual feature is learnt to be similar to language domain knowledge.

Closing, we will discuss "is it desirable to force visual feature to be like language embedding?"



Contents

- 1. Introduction to Correlating Language-Vision Knowledge in Image Recognition
- 2. Consistent Structural Relation Learning
- 3. Discussion



- Zero-Shot Learning
- Zero-Shot Classification Approaches
- Zero-Shot Segmentation Approaches



- Zero-Shot Learning
- Zero-Shot Classification Approaches
- Zero-Shot Segmentation Approaches



Zero-Shot Learning?

- 1. Supervised Learning
- 2. Few-Shot Learning
- 3. Zero-Shot Learning



Zero-Shot Learning?

- 1. Supervised Learning
- 2. Few-Shot Learning
- 3. Zero-Shot Learning



Zero-Shot Learning?

Supervised Learning

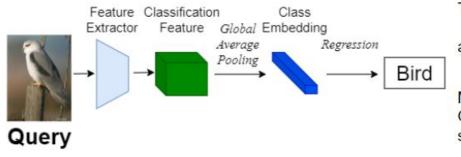


Figure: Image classification overview

Task definition:

Given an image, classify the query among **N** possible classes.

Method:

Given **E**-dimension class embedding, solve **N** regression problems.

Challenge:

Cannot predict any class except the **N** classes.



Zero-Shot Learning?

1. Supervised Learning

- Data hungry
- Cannot predict a novel class



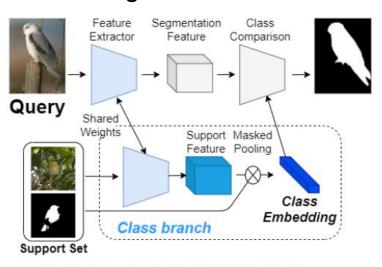
Zero-Shot Learning?

- 1. Supervised Learning
- 2. Few-Shot Learning
- 3. Zero-Shot Learning



Zero-Shot Learning?

Few-Shot Learning



- 1. Generate class embedding from support set
- 2. Compare segmentation feature and class embedding



Figure: Few-shot semantic segmentation

Zero-Shot Learning?

2. Few-Shot Learning

Learns to compare 'support image' and 'query image'



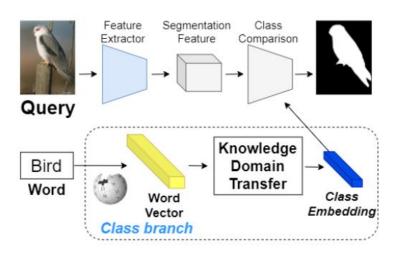
Zero-Shot Learning?

- 1. Supervised Learning
- 2. Few-Shot Learning
- 3. Zero-Shot Learning



Zero-Shot Learning?

3. Zero-Shot Learning



- Generate class embedding from a word
- 2. Compare segmentation feature and class embedding



Figure: Zero-shot semantic segmentation

Zero-Shot Learning?

3. Zero-Shot Learning

Learns to compare 'word vector originated feature' and 'query image'



- Zero-Shot Learning
- Zero-Shot Classification Approaches
- Zero-Shot Segmentation Approaches



Zero-Shot Classification Approaches

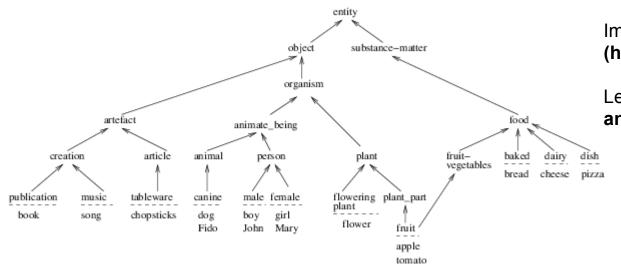


ImageNet 1k: 1,000 categories

ImageNet 23k: 23,000 categories

Zero-Shot Classification Approaches

MINDs Lab



ImageNet is based upon **WordNet** (hierarchy).

Learn relationship from word vector and hierarchy with GNN.

Zero-Shot Classification Approaches

- Wang *et al.*, Hyperbolic Visual Embedding Learning for Zero-Shot Recognition, CVPR 2020
- Kampffmeyer *et al.*, Rethinking knowledge graph propagation for zero-shot learning, CVPR 2019
- Liu *et al.*, Zero-shot recognition via semantic embeddings and knowledge graphs, CVPR 2018



- Zero-Shot Learning
- Zero-Shot Classification Approaches
- Zero-Shot Segmentation Approaches



Zero-Shot Segmentation Approaches

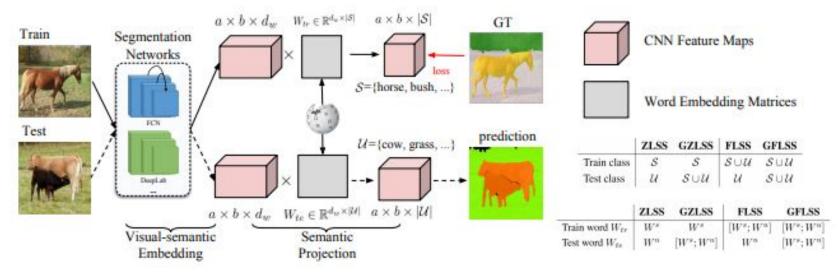
Low number of classes => Hard to utilize WordNet hierarchy

Task	Single-label Classification	Object Detection	Segmentation	Multi-label Classification
Number of Classes	ImageNet: 21,841 Open Images V5: 19,959	COCO2017: 172 PASCAL VOC2007: 20 Open Images V5: 600	Cityscapes: 19 PASCAL VOC2012: 20 ADE20k: 150* PASCAL CONTEXT: 59* Open Images V5: 350	COCO2017: 172 PASCAL VOC2007: 20 NUS-WIDE: 128 * Open Images V5: 600



Zero-Shot Segmentation Approaches

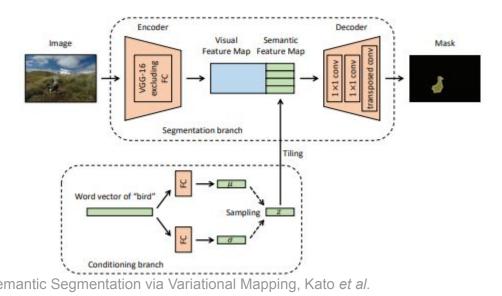
Word vector as a classifier





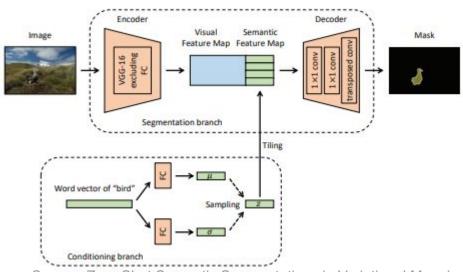
Zero-Shot Segmentation Approaches

Word vector as a class embedding



Zero-Shot Segmentation Approaches

Word vector as a class embedding



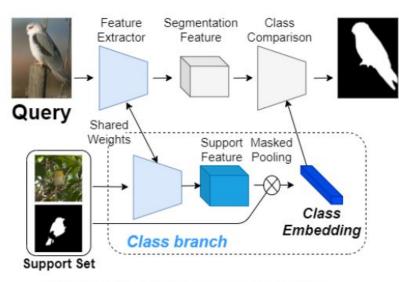
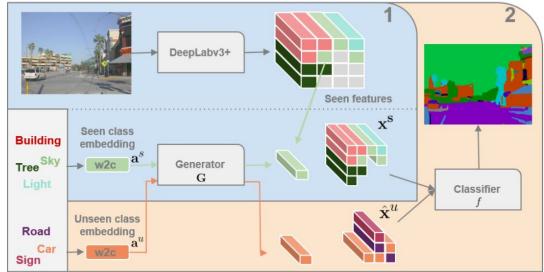
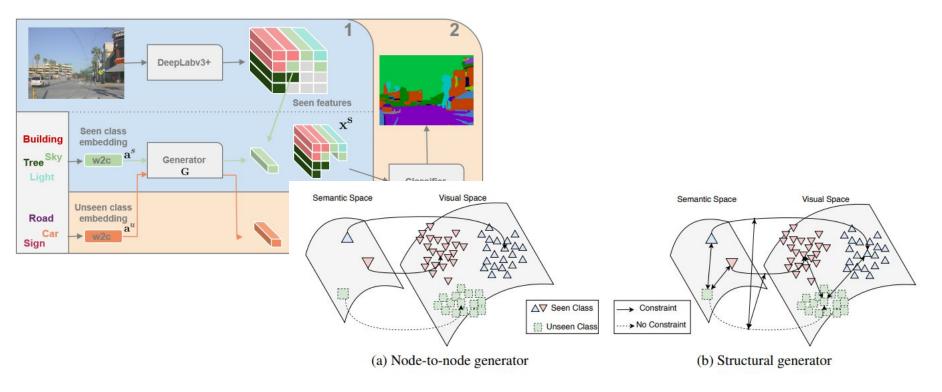


Figure: Few-shot semantic segmentation

Zero-Shot Segmentation Approaches

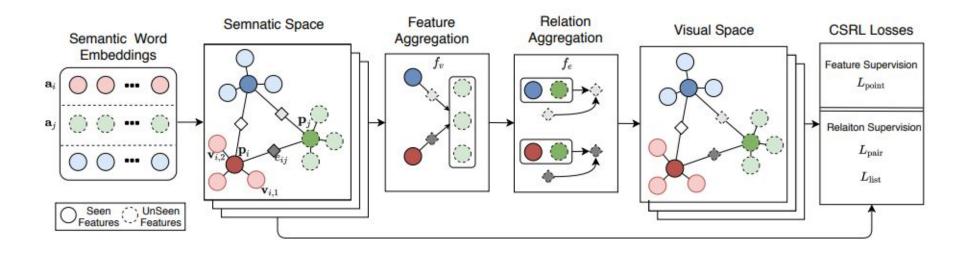
Synthesize visual feature from word vector



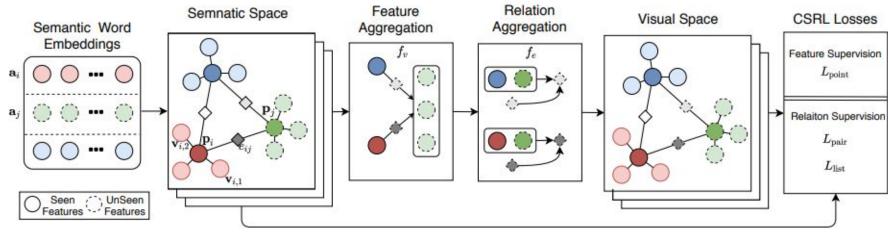




Zero-Shot Semantic Segmentation, Bucher et al.







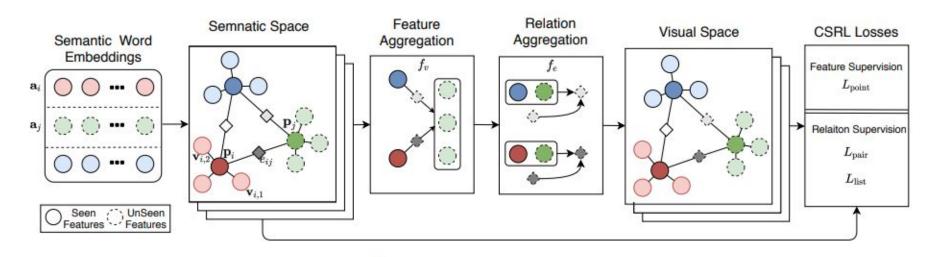
$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

$$\mathcal{V} := \{\mathbf{v}_{i,n} | \forall i \in [1, |\mathcal{S} \cup \mathcal{U}|], n \in [1, N]\}$$

$$\mathcal{E} := \{e_{ij} | \forall i, j \in [1, |\mathcal{S} \cup \mathcal{U}|]\}$$

$$\{\mathbf{a}_j | \mathbf{a}_j \in \mathcal{A}\}_{j=1}^{|\mathcal{S} \cup \mathcal{U}|}$$
 word vector $\mathbf{v}_{i,n}^0 = [\mathbf{a}_i \oplus \mathbf{z}_{i,n}]$ concat word vector and $\mathbf{z} \sim \mathsf{N}(0, 1)$ $e_{ij}^0 = \mathbf{a_i} \cdot \mathbf{a_j} / \|\mathbf{a_i}\|_2 \|\mathbf{a_j}\|_2$ cosine similarity



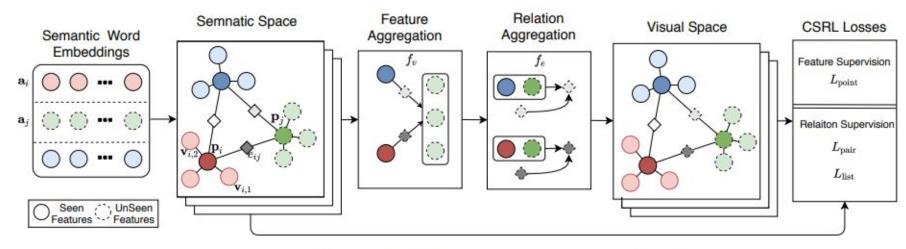


Feature Aggregation

$$\mathbf{p}_i^{\ell-1} = \frac{1}{N} \sum_{n=1}^N \mathbf{v}_{i,n}^{\ell-1} \quad \text{node representative feature} \quad \text{(prototype)}$$

$$\mathbf{v}_{i,n}^{\ell} = f_v^{\ell}([\mathbf{v}_{i,n}^{\ell-1} \oplus \sum_{j=1, j\neq i}^{|\mathcal{S} \cup \mathcal{U}|} e_{ij}^{\ell-1} \mathbf{p}_i^{\ell-1}]; \phi_v^{\ell})$$





Relation Aggregation

$$\begin{split} e^{\ell}_{ij} &= f^{\ell}_{e}(|\mathbf{p}^{\ell}_{i} - \mathbf{p}^{\ell}_{j}|; \phi^{\ell}_{e})e^{\ell-1}_{ij} & \text{aggregation} \\ \tilde{e}^{\ell}_{ij} &= \frac{\exp(e_{ij}/\gamma)}{\sum_{j'=1}^{|\mathcal{S}|} \exp(e_{ij'}/\gamma)} & \text{normalization} \end{split}$$



Supervision on seen class

x := visual feature

\hat{x} := **generated** visual feature

Make generator to synthesize feature similar to visual feature

$$\mathcal{L}_{\text{point}} = \frac{1}{|\mathcal{S}|} \sum_{c=1}^{|\mathcal{S}|} [\mathbb{E}_{\mathbf{x}, \mathbf{x}' \sim \mathcal{X}^c} K(\mathbf{x}, \mathbf{x}') + \mathbb{E}_{\hat{\mathbf{x}}, \hat{\mathbf{x}}' \sim \hat{\mathcal{X}}^c} K(\hat{\mathbf{x}}, \hat{\mathbf{x}}') - 2\mathbb{E}_{\mathbf{x} \sim \mathcal{X}^c, \hat{\mathbf{x}} \sim \hat{\mathcal{X}}^c} K(\mathbf{x}, \hat{\mathbf{x}})]$$



이유성 3 days ago

K(x,y)를 두 feature vector f(x)와 f(y)의 내적으로 생각하고(실제로 가능합니다). 저 MMD 식은 X에서 f(x)의 기댓값 mu x와 hat(X) 에서의 f(\hat(x))의 기댓값 mu Y에 대해 mu Xmu_Y의 L2 norm을 구한 것으로 해석할 수 있습 니다.



대략 [(x1+...+xn)/n - (y1+...+ym)/m]^2을 전개한 형태로 보아도 좋아요 (edited)



Supervision on relationships (pair-wise consistency)

Constrain final relation to be similar to the initial relation

$$\mathcal{L}_{\text{pair}}(\mathbf{M}^{\mathcal{A}}, \mathbf{M}^{\hat{\mathcal{X}}}) = \frac{1}{|\mathcal{U}|} \sum_{i=1}^{|\mathcal{U}|} D_{\text{KL}}[\mathbf{M}_{i}^{\mathcal{A}} || \mathbf{M}_{i}^{\hat{\mathcal{X}}}]$$

 $\mathbf{M} = \{e_{ij}^{\ell} | \forall i \in [1, |\mathcal{U}|], j \in [1, |\mathcal{S}|]\} \in \mathbb{R}^{|\mathcal{U}| \times |\mathcal{S}|}$ Relation matrix

Initial relation matrix $\mathbf{M}^{\mathcal{A}}$

 $\mathbf{M}^{\mathcal{X}}$ Final relation matrix



Supervision on relationships (list-wise consistency)

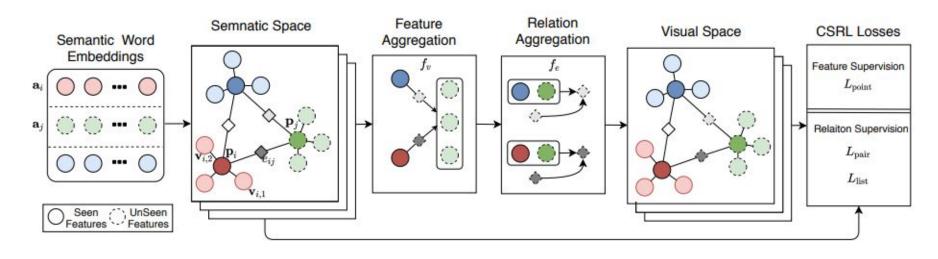
Learn to preserve correlation ranking

$$\pi(i)$$
 i-th permutation

$$P(\pi|\mathbf{M}_i) = \prod_{j=1}^{|\mathcal{S}|} \frac{\exp(e_{i\pi(j)}/\gamma)}{\sum_{k=j}^{|\mathcal{S}|} \exp(e_{i\pi(k)}/\gamma)}$$

$$\mathcal{L}_{\text{list}}(\mathbf{M}^{\mathcal{A}}, \mathbf{M}^{\hat{\mathcal{X}}}) = \frac{1}{|\mathcal{U}|} \sum_{i=1}^{|\mathcal{U}|} D_{\text{KL}}[P(\pi \in \mathcal{P} | \mathbf{M}_{i}^{\mathcal{A}}) || P(\pi \in \mathcal{P} | \mathbf{M}_{i}^{\hat{\mathcal{X}}})]$$





$$\mathcal{L}(\phi) = \mathcal{L}_{point} + \mathcal{L}_{pair} + \mathcal{L}_{list}$$



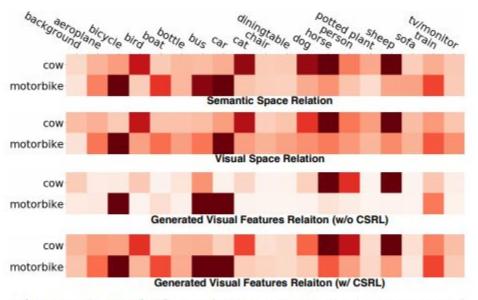


Figure 4: Relations between unseen (cow and motorbike) and seen categories.



Discussion

- 1. Is it **desirable** letting visual feature space be similar to language feature space?
- 2. We have no explicit intuition how visual feature space is looking like. Then, which form of the space can be desirable?

