## Sunghoon Im

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Department of Information and Communication Engineering

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RESEARCH INTERESTS

Computer Vision (3D reconstruction, Scene understanding)

Machine Learning (Deep learning, AI for social good)

Robot Vision (Sensor fusion, SLAM)

ACADEMIC APPOINTMENTS DGIST, Daegu, Korea

Sep 2019 - Present

Assistant Professor, Information and Communication Engineering

Carnegie Mellon University (CMU), Pittsburgh, US

Jun 2019 – Aug 2019

Visiting Scholar, Robotics Institute, working with Prof. Martial Hebert and Prof. Jean Oh.

Microsoft Research Asia (MSRA), Beijing, China

Feb 2018 – Aug 2018

Research Intern, Internet Graphics Group, working with Dr. Stephen Lin.

KAIST, Daejeon, Korea

Mar 2014 – Aug 2019

Research Assistant, Robotics and Computer Vision Lab., working with Prof. In So Kweon

**EDUCATION** 

KAIST, Daejeon, Korea

Ph.D., Electrical Engineering

Aug 2019

- Dissertation: "Robust 3D Imaging using a Single Hand-held Cameras"
- Advisor: Prof. In So Kweon

M.S., Electrical Engineering

Feb 2016

• Advisor: Prof. In So Kweon

Sogang University, Seoul, Korea

B.S., Electronic Engineering

Feb 2014

Summa cum laude

### **PUBLICATIONS**

# International Journal

- 1. **Sunghoon Im**, Hyowon Ha, Hae-Gon Jeon, Stephen Lin and In So Kweon, "Deep Depth from Uncalibrated Small Motion Clip", *IEEE Transactions on Pattern Analysis and Machine Intelligence* (**TPAMI**), Accepted (Apr 2021 expected).
- 2. Hae-Gon Jeon, Jaeheung Surh, **Sunghoon Im** and In So Kweon, "Ring Difference Filter for Fast and Noise Robust Depth from Focus", *IEEE Transactions on Image Processing* (**TIP**), Dec 2020.
- 3. **Sunghoon Im**, Hae-Gon Jeon and In So Kweon, "Robust Depth Estimation using Auto-Exposure Bracketing", *IEEE Transactions on Image Processing* (**TIP**), May 2019.

- Sunghoon Im, Hyowon Ha, Gyeongmin Choe, Hae-Gon Jeon, Kyungdon Joo and In So Kweon, "Accurate 3D Reconstruction from Small Motion Clip for Rolling Shutter Cameras", IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI), Apr 2019.
- 5. Gyeongmin Choe, Seong-heum Kim, **Sunghoon Im**, Joon-Young Lee, Srinivasa Narasimhan and In So Kweon, "RANUS: RGB and NIR Urban Scene Dataset for Deep Scene Parsing", *IEEE Robotics and Automation Letters* (**RAL**), Feb 2018.
- 6. Seunghak Shin, **Sunghoon Im**, Inwook Shim, Hae-Gon Jeon, and In So Kweon, "Geometry Guided 3D propagation for Depth from Small Motion", *IEEE Signal Processing Letters* (**SPL**), Dec 2017.

### **International Conference**

- Seokju Lee, Sunghoon Im, Stephen Lin and In So Kweon, "Instance-wise Depth and Motion Learning from Monocular Videos", The Thirty-Fifth AAAI Conference on Artificial Intelligence (AAAI), Feb 2021.
   Workshop on Machine Learning for Autonomous Driving & Workhop on Differentiable computer vision, graphics, and physics in machine learning (NeurIPSw), Dec 2020.
- 2. Hae-Gon Jeon, **Sunghoon Im**, Jean Oh and Martial Hebert, "Learning Shape-based Representation for Visual Localization in Extremely Changing Conditions", *IEEE International Conference on Robotics and Automations* (**ICRA**), May 2020.
- 3. Hae-Gon Jeon, **Sunghoon Im**, Byeong-Uk Lee, Dong-Geol Choi, Martial Hebert and In So Kweon, "DISC: A Large-scale Virtual Dataset for Simulating Disaster Scenarios", *IEEE/RSJ International Conference on Intelligence Robots and System* (**IROS**), Nov 2019.
- 4. Seokju Lee, **Sunghoon Im**, Stephen Lin and In So Kweon, "Learning Residual Flow as Dynamic Motion from Stereo Video", *IEEE/RSJ International Conference on Intelligence Robots and System* (**IROS**), Nov 2019.
- 5. **Sunghoon Im**, Hae-Gon Jeon, Stephen Lin and In So Kweon, "DPSNet: End-to-end Deep Plane Sweep Stereo", *International Conference on Learning Representations* (**ICLR**), May 2019.
- 6. Byeong-Uk Lee, Hae-Gon Jeon, **Sunghoon Im** and In So Kweon, "Depth Completion with Deep Geometry and Context Guidance", *IEEE International Conference on Robotics and Automations* (**ICRA**), May 2019.
- 7. **Sunghoon Im**, Hae-Gon Jeon and In So Kweon, "Robust Depth Estimation from Auto Bracketed Images", *In Proc. of IEEE Conference on Computer Vision and Pattern Recognition* (**CVPR**), Jun 2018.
- 8. Jaeheung Surh, Hae-Gon Jeon, Yunwon Park, **Sunghoon Im**, Hyowon Ha and In So Kweon, "Noise Robust Depth from Focus using a Ring Difference Filter", *In Proc. of IEEE Conference on Computer Vision and Pattern Recognition* (**CVPR**) [*Spotlight*], Jul 2017.
- 9. **Sunghoon Im**, Hyowon Ha, Francois Rameau, Hae-Gon Jeon, Gyeongmin Choe and In So Kweon, "All-around Depth from Small Motion with A Spherical Panoramic Camera", *In Proc. of European Conference on Computer Vision* (ECCV), Oct 2016.
- 10. Hyowon Ha, **Sunghoon Im**, Jaesik Park, Hae-Gon Jeon and In So Kweon, "High-quality Depth from Uncalibrated Small Motion Clip", *In Proc. of IEEE Conference on Computer Vision and Pattern Recognition* (**CVPR**) [*Oral*], Jun 2016.

- 11. Hae-Gon Jeon, Joon-Young Lee, **Sunghoon Im**, Hyowon Ha and In So Kweon, "Stereo Matching with Color and Monochrome Cameras in Low-light Conditions", *In Proc. of IEEE Conference on Computer Vision and Pattern Recognition* (**CVPR**), Jun 2016.
- 12. **Sunghoon Im**, Hyowon Ha, Gyeongmin Choe, Hae-Gon Jeon, Kyungdon Joo and In So Kweon, "High Quality Structure from Small Motion for Rolling Shutter Cameras", *In Proc. of IEEE International Conference on Computer Vision* (**ICCV**), Dec 2015.
- 13. **Sunghoon Im**, Gyeongmin Choe, Hae-Gon Jeon and In So Kweon, "Depth from Accidental Motion using Geometry Prior", *In Proc. of IEEE International Conference on Image Processing* (**ICIP**) [*Top 10% paper*], Sep 2015.

#### **Other Publications**

- 1. Jaeheung Surh, Hae-Gon Jeon, Hyowon Ha, **Sunghoon Im** and In So Kweon, "Fast Depth from Defocus with Your Mobile Phone for Synthetic Defocus", *In Proc. of the 28th Workshop on Image Processing and Image Understanding* (**IPIU**), Feb 2016.
- 2. **Sunghoon Im**, Hae-Gon Jeon, Hyowon Ha and In So Kweon, "Depth Estimation from Light Field Cameras", *In Proc. of the 12th International Conference on Ubiquitous Robots and Ambient Intelligence* (URAI), Oct 2015.
- 3. Dong-jin Kim, Donggeun Yoo, **Sunghoon Im**, Namil Kim, T. Sirinukulwattana and In So Kweon, "Relative Attributes with Deep Convolutional Neural Network", *In Proc. of the 12th International Conference on Ubiquitous Robots and Ambient Intelligence* (URAI), Oct 2015.

### PATENTS Registration

- 1. METHOD AND APPARATUS FOR ESTIMATING DEPTH USING RING DIFFERENCE FILTER, Publication date: Sep 28, 2018. (10-2017-0091717)
- 2. DEPTH MAP ACQUISITION DEVICE AND DEPTH MAP ACQUISITION METHOD, Publication date: Apr 19, 2018. (10-2016-0103546)
- 3. METHOD AND APPARATUS FOR ACQUIRING DEPTH MAP FROM ALL-AROUND CAMERA, Publication date: Apr 17, 2018. (10-2016-0167525)
- 4. DEPTH INFORMATION ACQUIRING DEVICE AND METHOD THEREOF, Publication date: Aug 11, 2017. (10-2016-0076766)
- 5. APPARATUS AND METHOD FOR DEPTH MAP GENERATION, Publication date: Jun. 02, 2016. (10-2016-0015703)

### RESEARCH GRANTS

### On-going projects

- 1. Multi-spectral Stereo-based Dynamic Scene Understanding
  - Principal investigator
  - Young Researcher Program, National Research Foundation of Korea (NRF)
  - 2020.03.01 2023.02.28 (36 months, ₩300M)
- 2. A study on learning-based novel-view synthesis algorithms for multi-view LF images
  - Principal investigator
  - ETRI, ICT RD program of MSIP/IITP
  - 2020.03.01 2020.11.30 (9 months, ₩40M)

# 3. Development of Low Latency VR·AR streaming Technology based on 5G edge cloud

- · Research participant
- Institute of Information communications Technology Planning Evaluation(IITP)
- 2020.04.01 2023.12.31 (45 months, \text{\psi}240M)

# 4. Collaborative AI based Autonomous Driving System toward Safe, Reliable, and Scalable Human-in-the-Loop Cloud Mobility Service

- Research participant
- P-COE (Center of Excellence), DGIST
- 2020.05.01 2022.12.31 (32 months, \text{\psi}195M)

### 5. Advancement of geographic data construction system based on deep learning

- Research participant
- Dabeeo
- 2020.06.15 2020.12.15 (6 months, \text{\psi}16M)

### Finished projects

## 1. All-around 3D reconstruction with hand-held VR cameras for augmented reality

- Principal investigator
- Global Ph.D. Fellowship, National Research Foundation of Korea (NRF)
- 2016.03.01 2019.02.28 (36 months, \(\pi\)60M + Full scholarship)

### **TEACHING**

- Introduction to Deep Learning, Fall 2020.
- Deep Learning, Spring 2020.
- Computer Vision, Fall 2019.

### **EDITOR**

• The Information and Communications Technology Express (ICT Express)

# REVIEWER (JOURNAL)

- International Journal of Computer Vision (IJCV)
- Computer Vision and Image Understanding (CVIU)
- Pattern Recognition (PR)
- Neurocomputing
- IEEE Robotics and Automation Letters (RAL)
- IEEE Access
- International Journal of Control, Automation and Systems (IJCAS)
- IEIE Transactions on Smart Processing and Computing (IEIE SPC)
- Journal of Institute of Control, Robotics and Systems (ICROS)

# REVIEWER (CONFERENCE)

- IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2019, 2020
- IEEE International Conference on Computer Vision (ICCV) 2019
- European Conference on Computer Vision (ECCV) 2020
- Conference on Neural Information Processing Systems (NeurIPS) 2020
- International Conference on Machine Learning (ICML) 2020
- International Conference on Learning Representations (ICLR) 2021
- Association for the Advancement of Artificial Intelligence (AAAI) 2020, 2021
- IEEE International Conference on Robotics and Automations (ICRA) 2021
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2017
- Asian Conference on Computer Vision (ACCV) 2020.
- IEEE Winter Conference on Applications of Computer Vision (WACV), 2020

|               | • International Conference on Control, Automation and Systems (ICCAS), 2020   |  |
|---------------|---|--|
| TUTORIAL      | Multiple View Geometry, KETI Sangam, Aug-Oct 2020   |  |
| Invited talks | <ul> <li>ETRI (Electronics and Telecommunications Research Institute), Daejeon</li> <li>ETRI (Electronics and Telecommunications Research Institute), Daegu</li> <li>GIST</li> <li>KETI (Korea Electronics Technology Institute), Sangam</li> <li>POSTECH</li> <li>KETI (Korea Electronics Technology Institute), Pangyo</li> </ul>   | Oct 2020<br>Oct 2020<br>Jun 2020<br>Jan 2020<br>Dec 2019<br>Nov 2019   |
|               | <ul> <li>RETI (Korea Electronics Technology Institute), Pangyo</li> <li>DGIF (Daegu Technopolis Grand Innovation Festival)</li> <li>ETRI (Electronics and Telecommunications Research Institute), Daejeon</li> <li>Sogang University</li> <li>Lunit</li> <li>SAIT (Samsung Advanced Institute of Technology)</li> <li>Koh Young Technology</li> </ul>   | Oct 2019<br>Sep 2019x<br>Sep 2019<br>Aug 2019<br>Apr 2019<br>Jan 2019  |
| AWARDS        | <ul> <li>Excellent Student Award, 2018 Research Performance Evaluation, KAIST EE</li> <li>Best Poster Award, 2018 Samsung AI Forum, Samsung Research</li> <li>Excellent Intern Award, Microsoft Research Asia (MSRA)</li> <li>Honor Student Award, 2017 Research Performance Evaluation, KAIST EE</li> <li>Kim Choong-Ki Award, 2016 Research Performance Evaluation, KAIST EE</li> <li>Best Poster Presentation Award, IPIU 2017</li> <li>Qualcomm Innovation Award 2016, Qualcomm Korea Corp. and KAIST</li> <li>Silver prize, 22th HumanTech Paper Award, Samsung Electronics Co., Ltd.</li> <li>Best Poster Award, IWRCV 2015 General Chair</li> <li>Official Best 10% Paper Selection, ICIP 2015 Organizing Committee</li> <li>Design Project Competition(Silver Prize), Sogang University</li> <li>Prize for the top first percentile GPA, Sogang University</li> <li>Sep 2011, Feb 20</li> </ul> | Apr 2019<br>Sep 2018<br>Aug 2018<br>Apr 2017<br>Feb 2017<br>Mar 2016<br>Feb 2016<br>Nov 2015<br>Sep 2015<br>Nov 2013 |
| Honors        | 1, 6 6  | Oct 2020<br>Jun 2019<br>May 2019<br>Oct 2018<br>Aug 2016<br>July 2016<br>Feb 2014<br>2 – Feb 2013<br>2 – Feb 2014    |

• Languages: Python, MATLAB, C, C++, LATEX

• Deep Learning Framework: Pytorch, Torch, Tensorflow

IT SKILLS

• International Conference on 3D Vision (3DV) 2020

Last Update: 2020/10/31