Sung-Yeon Park

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Research Interests

- 3D Scene Understanding, Large Language Models, Scene Reconstruction, Generative World Models, Spatial Reasoning
- Digital Twin Simulation, Autonomous Driving

EDUCATION

Purdue University

Ph.D. at Digital Twin Lab;

Seoul National University

B.S. and M.S. in Civil and Environmental Engineering;

West Lafayette, IN, USA Aug 2024 -Seoul, South Korea March 2017 - Feb 2023

WORK EXPERIENCES

- Glucofit Machine Learning Engineer (Mar 2023 Jun 2024)
- Deer Mobility Data Scientist (July 2020 Sep 2020)
- Samsung Creative Lab In-house Venture Accelerator Intern (Jan 2020 Feb 2020)

Conference Papers (Selected)

- Park, S.-Y., Lee, A., Lu, J., Cui, C., Jiang, L., Gupta, R., Han, K., Moradipari, A., Wang, Z.* (preprint). SIMSplat: Predictive Driving Scene Editing with Language-aligned 4D Gaussian Splatting.
- Cui, C., Zhou, Y., Peng, J., **Park**, **S.-Y.**, Yang, Z., Sankaranarayanan, P., Zhang, J., Zhang, R., & Wang, Z.* (preprint). ViLaD: A Large Vision Language Diffusion Framework for End-to-End Autonomous Driving.
- Park, S.-Y., Cui, C., Ma, Y., Moradipari, A., Gupta, R., Han, K., & Wang, Z.* (2025, Oct 19-23). NuPlanQA: A Large-Scale Dataset and Benchmark for Multi-View Driving Scene Understanding in Multi-Modal Large Language Models. International Conference on Computer Vision, (ICCV), Hawaii, United States.
- C. Cui, Yang, Z., Zhou, Y., Peng, J., Park, S.-Y., Zhang, C., Ma, Y., Cao, X., Ye, W., Feng, Y., Panchal, J., Li, L., Chen, Y., & Wang, Z.*(2025, Oct 19-25). On-Board Vision-Language Models (VLMs) for Personalized Motion Control of Autonomous Vehicles. International Conference on Intelligent Robots and Systems (IROS) Hangzhou, China.
- Park, S.-Y., Lee, M.-J., Choi, H.-H., Kang, J.-H., Park, Y.-A., Cho, J.-H., Lee, A.,& Kim, D.-K.* (2024, Jan 4-8). VLAAD: Vision and Language Assistant for Autonomous Driving. IEEE/CVF Winter Conference on Applications of Computer Vision (WACV), Hawaii, United States.
- Park, S.-Y., Lee, M.-J., Choi, H.-H., Kang, J.-H., Park, Y.-A., Cho, J.-H., Lee, A.,& Wang, Z.* (2025, Jan 5-9). Bird's-Eye-View Reasoning on Driving Scene with Large Language Model. Transportation Research Board 104th Annual Meeting, (TRB), Washington D.C., United States.

JOURNAL PUBLICATIONS

- Park, S.-Y., Joo, Y.-J., & Kim, D.-K.* (2023). Order Dispatching in Ride-pooling with Walking Points Search. Transportation Research Record, 0(0). https://doi.org/10.1177/03611981231175890
- Park, S.-Y., Ham, S.-W., & Kim, D.-K.*. (2023). User Segmentation based on Travel Regularity in E-scooter Sharing Service. Transportation Research Record, 2677(7), 290–306. https://doi.org/10.1177/03611981231152256

Professional Activities

- Workshop Organizer
 - WACV 2026 Workshop on Large Language and Vision Models for Autonomous Driving
 - ICCV 2025 Workshop on Distillation of Foundation Models for Autonomous Driving
 - ITSC 2024 Workshop on Large Language and Vision Models for Autonomous Driving
- Journal Reviewer
 - IEEE Internet Computing
 - IEEE Transactions on Intelligent Vehicles
 - IEEE Transactions on Intelligent Transportation Systems
 - Transportation Research Record

Honors and Awards

- Best Paper Award (The 2023 Transportation Research Board Annual Meeting) Feb, 2023
- Best Paper Award (The 40th International Conference of the Korean Society of Transportation) Sep, 2022
- Outstanding Graduate Student Instructor (College of Engineering, Seoul National University) April, 2022
- Outstanding Graduate Award (Korean Society of Transportation) February, 2021

Scholarships

- Lotte Foundation Scholarship 2017-F, 2018-S, 2018-F, 2019-S, 2019-F, 2020-S, 2020-F
- Samsung Dream Scholarship 2018-F, 2019-S
- DL Construction based Scholarship from Seoul National University 2019-F, 2020-S
- Seoul National University Gwanak Foundation Scholarship 2020-F

TEACHING ASSISTANT

- \bullet 457.301(001) Transportation Planning 2021-S, 2022-S
- \bullet 457.208(001) Transportation Engineering 2021-F, 2022-F
- 457.526A(001) Public Transportation Engineering 2022-S
- \bullet 457.405(001) Introduction to Traffic Operation 2022-S

SKILLS SUMMARY

- Python
- Pytorch, Transformers
- LaTeX, Figma