

免费模板~~~

# **ACM Standard Code Library**

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October, 2008

# ACM 算法模板集

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# 第一章 常用函数和 STL

## 一. 常用函数

```
#include <stdio.h>
int getchar( void );           //读取一个字符, 一般用来去掉无用字符
char *gets( char *str );      //读取一行字符串

#include <stdlib.h>
void * malloc( size_t size );  //动态内存分配, 开辟大小为 size 的空间
void qsort( void *buf, size_t num, size_t size, int (*compare)(const void *, const void *) ); //快速排序

Sample:
int compare_ints( const void* a, const void* b )
{
    int* arg1 = (int*) a;      int* arg2 = (int*) b;
    if( *arg1 < *arg2 ) return -1;
    else if( *arg1 == *arg2 ) return 0;
    else return 1;
}
int array[] = { -2, 99, 0, -743, 2, 3, 4 };   int array_size = 7;
qsort( array, array_size, sizeof(int), compare_ints );

#include <math.h>
//求反正弦, arg ∈ [-1, 1], 返回值 ∈ [-pi/2, +pi/2]
double asin( double arg );
//求正弦, arg 为弧度, 弧度=角度*Pi/180.0, 返回值 ∈ [-1, 1]
double sin( double arg );
//求 e 的 arg 次方
double exp( double arg );
//求 num 的对数, 基数为 e
double log( double num );
//求 num 的根
double sqrt( double num );
//求 base 的 exp 次方
double pow( double base, double exp );

#include <string.h>
//初始化内存, 常用来初始化数组
void* memset( void* buffer, int ch, size_t count );
memset( the_array, 0, sizeof(the_array) );
//printf 是它的变形, 常用来将数据格式化为字符串
int sprintf( char *buffer, const char *format, ... );
sprintf(s, "%d%d", 123, 4567); //s="1234567"
```

//scanf 是它的变形, 常用来从字符串中提取数据

```
int sscanf( const char *buffer, const char *format, ... );
```

Sample:

```
char result[100]="24 hello", str[100];          int num;
```

```
sprintf( result, "%d %s", num,str );//num=24;str="hello" ;
```

//字符串比较, 返回值<0 代表 str1<str2, =0 代表 str1=str2, >0 代表 str1>str2

```
int strcmp( const char *str1, const char *str2 );
```

## 二. 常用 STL

### [标准 container 概要]

vector<T>	大小可变的向量, 类似数组的用法, 容易实现删除
list<T>	双向链表
queue<T>	队列, empty(), front(), pop(), push()
stack<T>	栈, empty(), top(), pop(), push()
priority_queue<T>	优先队列, empty(), top(), pop(), push()
set<T>	集合
map<key,val>	关联数组, 常用来作 hash 映射

### [标准 algorithm 摘录]

for_each()	对每一个元素都唤起 (调用) 一个函数
find()	查找第一个能与引数匹配的元素
replace()	用新的值替换元素, O(N)
copy()	复制 (拷贝) 元素, O(N)
remove()	移除元素
reverse()	倒置元素
sort()	排序, O(N log(N))
partial_sort()	部分排序
binary_search()	二分查找
merge()	合并有序的序列, O(N)

### [C++ String 摘录]

copy()	从别的字符串拷贝
empty()	判断字符串是否为空
erase()	从字符串移除元素
find()	查找元素
insert()	插入元素
length()	字符串长度
replace()	替换元素
substr()	取子字符串
swap()	交换字符串

## 第二章 重要公式与定理

### 1. Fibonacci Number

0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144, 233, 377, 610 ...

**Formula:**

$$F_0 = 1$$

$$F_1 = 1$$

$$F_i = F_{i-1} + F_{i-2}$$

$$F_n = \frac{(1+\sqrt{5})^n - (1-\sqrt{5})^n}{2^n \sqrt{5}} = \left[ \frac{1}{\sqrt{5}} \left( \frac{1+\sqrt{5}}{2} \right)^n \right]$$

### 2. Lucas Number

1, 3, 4, 7, 11, 18, 29, 47, 76, 123...

**Formula:**

$$L_n = \left( \frac{1+\sqrt{5}}{2} \right)^n + \left( \frac{1-\sqrt{5}}{2} \right)^n$$

### 3. Catalan Number

1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, 208012...

**Formula:**

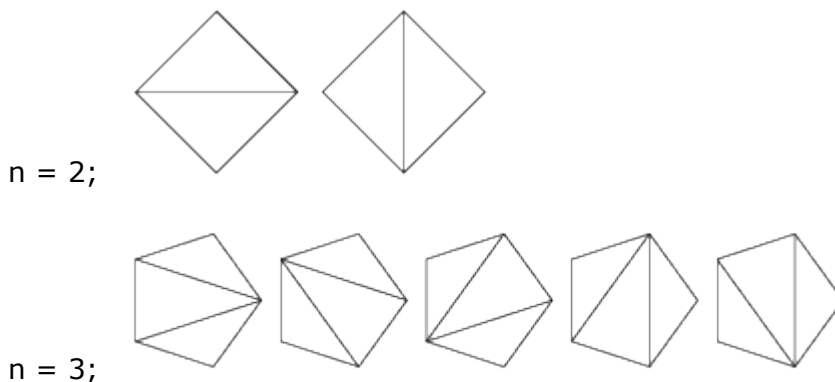
$$Cat_n = \frac{C(2n, n)}{n+1}$$

$$Cat_n = \sum_{i=0}^{n-1} Cat_i * Cat_{n-1-i}$$

**Application:**

1) 将  $n + 2$  边形沿弦切割成  $n$  个三角形的不同切割数

Sample:



2)  $n + 1$  个数相乘, 给每两个元素加上括号的不同方法数

Sample:

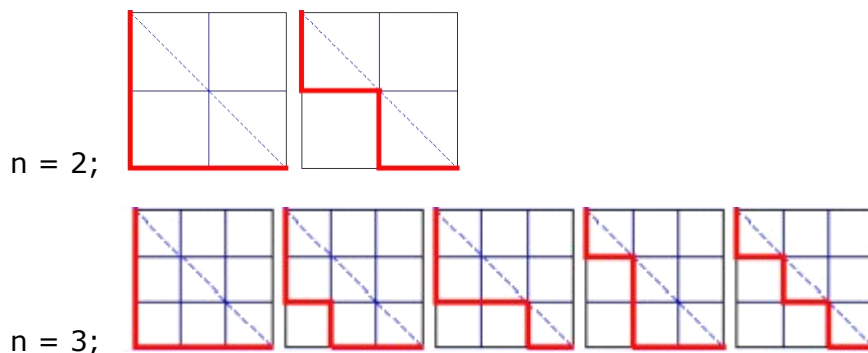
$n = 2$ ; (1 (2 3)), ((1 2) 3)

$n = 3$ ; (1 (2 (3 4))), (1 ((2 3) 4)), ((1 2) (3 4)), ((1 (2 3)) 4), (((1 2) 3) 4)

3)  $n$  个节点的不同形状的二叉树数(严《数据结构》P.155)

4) 从  $n * n$  方格的左上角移动到右下角不升路径数

Sample:



## 4. Stirling Number(Second Kind)

$S(n, m)$ 表示含  $n$  个元素的集合划分为  $m$  个集合的情况数

或者是  $n$  个有标号的球放到  $m$  个无标号的盒子中, 要求无一为空, 其不同的方案数

**Formula:**

$$S_{n,m} = \begin{cases} 0 & (m=0 \parallel n < m) \\ S_{n-1,m-1} + m \times S_{n-1,m} & (n > m \geq 1) \end{cases}$$

$$S_{n,m} = \frac{1}{m!} \sum_{i=0}^m (-1)^i \times C(m, i) \times (m-i)^n$$

**Special Cases:**

$$S_{n,0} = 0$$

$$S_{n,1} = 1$$

$$S_{n,2} = 2^{n-1} - 1$$

$$S_{n,3} = \frac{1}{6}(3^n - 3 \times 2^n + 3)$$

$$S_{n,n-1} = C(n, 2)$$

$$S_{n,n} = 1$$

## 5. Bell Number

$n$  个元素集合所有的划分数

**Formula:**

$$B_n = \sum_{i=0}^n S_{n,i}$$



## 6. Stirling's Approximation

$$n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n$$

## 7. Sum of Reciprocal Approximation

EulerGamma = 0.57721566490153286060651209;

$$\sum_{i=1}^n \frac{1}{i} = \ln(n) + \text{EulerGamma} \quad (n \rightarrow \infty)$$

## 8. Young Tableau

Young Tableau(杨式图表)是一个矩阵, 它满足条件:

如果格子[i, j]没有元素, 则[i+1, j]也一定没有元素

如果格子[i, j]有元素 a[i, j], 则[i+1, j]要么没有元素, 要么 a[i+1, j] > a[i, j]

Y[n]代表 n 个数所组成的杨式图表的个数

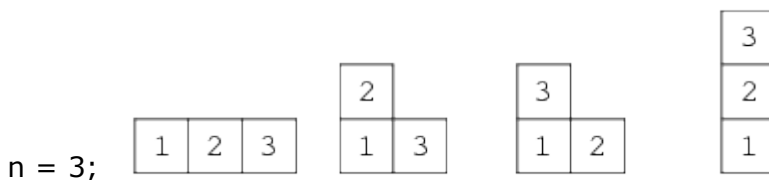
**Formula:**

$$Y_1 = 1$$

$$Y_2 = 2$$

$$Y_n = Y_{n-1} + (n-1) \times Y_{n-2} \quad (n > 2)$$

Sample:



## 9. 整数划分

将整数 n 分成 k 份, 且每份不能为空, 任意两种分法不能相同

1) 不考虑顺序

```
for(int p=1; p<=n ;p++)
    for(int i=p; i<=n ;i++)
        for(int j=k; j>=1 ;j--)
            dp[i][j] += dp[i-p][j-1];
cout<< dp[n][k] <<endl;
```

2) 考虑顺序

dp[i][j] = dp[i-k][j-1]; (k=1..i)

3) 若分解出来的每个数均有一个上限 m

dp[i][j] = dp[i-k][j-1]; (k=1..m)

## 10. 错排公式

$$D_1 = 0$$

$$D_2 = 1$$

$$D_n = (n-1) \times (D_{n-1} + D_{n-2})$$

## 11. 三角形内切圆半径公式

$$p = \frac{a+b+c}{2}$$

$$s = \sqrt{p(p-a)(p-b)(p-c)}$$

$$r = \frac{2s}{a+b+c}$$

## 12. 三角形外接圆半径公式

$$R = \frac{abc}{4s}$$

## 13. 圆内接四边形面积公式

$$p = \frac{a+b+c+d}{2}$$

$$s = \sqrt{(p-a)(p-b)(p-c)(p-d)}$$

## 14. 基础数论公式

### 1) 模取幂

$$a^n \% b = (((a \% b) * a) \% b) \dots) \% b$$

### 2) n 的约数的个数

若 n 满足  $n = p_1^{n_1} + p_2^{n_2} + \dots + p_m^{n_m}$ , 则 n 的约数的个数为

$$(n_1 + 1)(n_2 + 1) \dots (n_m + 1)$$

## 第三章 大数模板

```

typedef int hugeint;
//应不大于,以防乘法时溢出
const int Base = 1000;
const int Capacity = 1000;

struct xnum
{
    int Len;
    int Data[Capacity];
    xnum() : Len(0) {}
    xnum(const xnum& V) : Len(V.Len) {
        memcpy(Data, V.Data, Len * sizeof *Data);
    }
    xnum(int V) : Len(0) {
        for (; V > 0; V /= Base) Data[Len++] = V % Base;
    }
    xnum(char S[]);
    xnum& operator=(const xnum& V) {
        Len = V.Len;
        memcpy(Data, V.Data, Len * sizeof *Data);
        return *this;
    }
    int& operator[](int Index) { return Data[Index]; }
    int operator[](int Index) const { return Data[Index]; }

    void print(){
        printf("%d", Len==0?0:Data[Len-1]);
        for(int i=Len-2; i>=0; i--)
            for(int j=Base/10; j>0; j/=10)
                printf("%d", Data[i]/j%10);
    }
};

xnum::xnum(char S[])
{
    int I, J;
    Data[Len = 0] = 0;
    J = 1;
    for (I = strlen(S)-1; I>=0; I--) {
        Data[Len] += (S[I] - '0') * J;
        J *= 10;
        if (J >= Base) J = 1, Data[++Len] = 0;
    }
}

```

```

    }
    if (Data[Len] > 0) Len++;
}

int compare(const xnum& A, const xnum& B)
{
    int I;
    if (A.Len != B.Len) return A.Len > B.Len ? 1 : -1;
    for (I = A.Len - 1; I >= 0 && A[I] == B[I]; I--);
    if (I < 0) return 0;
    return A[I] > B[I] ? 1 : -1;
}

xnum operator+(const xnum& A, const xnum& B)
{
    xnum R;
    int I;
    int Carry = 0;
    for (I = 0; I < A.Len || I < B.Len || Carry > 0; I++)
    {
        if (I < A.Len) Carry += A[I];
        if (I < B.Len) Carry += B[I];
        R[I] = Carry % Base;
        Carry /= Base;
    }
    R.Len = I;
    return R;
}

xnum operator-(const xnum& A, const xnum& B)
{
    xnum R;
    int Carry = 0;
    R.Len = A.Len;
    int I;
    for (I = 0; I < R.Len; I++)
    {
        R[I] = A[I] - Carry;
        if (I < B.Len) R[I] -= B[I];
        if (R[I] < 0) Carry = 1, R[I] += Base;
        else Carry = 0;
    }
    while (R.Len > 0 && R[R.Len - 1] == 0) R.Len--;
    return R;
}

```

```
}
```

```
xnum operator*(const xnum& A, const int B)
{
    int I;
    if (B == 0) return 0;
    xnum R;
    hugeint Carry = 0;
    for (I = 0; I < A.Len || Carry > 0; I++)
    {
        if (I < A.Len) Carry += hugeint(A[I]) * B;
        R[I] = Carry % Base;
        Carry /= Base;
    }
    R.Len = I;
    return R;
}
```

```
xnum operator*(const xnum& A, const xnum& B)
{
    int I;
    if (B.Len == 0) return 0;
    xnum R;
    for (I = 0; I < A.Len; I++)
    {
        hugeint Carry = 0;
        for (int J = 0; J < B.Len || Carry > 0; J++)
        {
            if (J < B.Len) Carry += hugeint(A[I]) * B[J];
            if (I + J < R.Len) Carry += R[I + J];
            if (I + J >= R.Len) R[R.Len++] = Carry % Base;
            else R[I + J] = Carry % Base;
            Carry /= Base;
        }
    }
    return R;
}
```

```
xnum operator/(const xnum& A, const int B)
{
    xnum R;
    int I;
    hugeint C = 0;
    for (I = A.Len - 1; I >= 0; I--)
```

```

    {
        C = C * Base + A[I];
        R[I] = C / B;
        C %= B;
    }
    R.Len = A.Len;
    while (R.Len > 0 && R[R.Len - 1] == 0) R.Len--;
    return R;
}

//div
xnum operator/(const xnum& A, const xnum& B)
{
    int I;
    xnum R, Carry = 0;
    int Left, Right, Mid;
    for (I = A.Len - 1; I >= 0; I--)
    {
        Carry = Carry * Base + A[I];
        Left = 0;
        Right = Base - 1;
        while (Left < Right)
        {
            Mid = (Left + Right + 1) / 2;
            if (compare(B * Mid, Carry) <= 0) Left = Mid;
            else Right = Mid - 1;
        }
        R[I] = Left;
        Carry = Carry - B * Left;
    }
    R.Len = A.Len;
    while (R.Len > 0 && R[R.Len - 1] == 0) R.Len--;
    return R;
}

//mod
xnum operator%(const xnum& A, const xnum& B)
{
    int I;
    xnum R, Carry = 0;
    int Left, Right, Mid;
    for (I = A.Len - 1; I >= 0; I--)
    {
        Carry = Carry * Base + A[I];

```

```

    Left = 0;
    Right = Base - 1;
    while (Left < Right)
    {
        Mid = (Left + Right + 1) / 2;
        if (compare(B * Mid, Carry) <= 0) Left = Mid;
        else Right = Mid - 1;
    }
    R[I] = Left;
    Carry = Carry - B * Left;
}
R.Len = A.Len;
while (R.Len > 0 && R[R.Len - 1] == 0) R.Len--;
return Carry;
}

```

```

istream& operator>>(istream& In, xnum& V)
{
    char Ch;
    for (V = 0; In >> Ch;)
    {
        V = V * 10 + (Ch - '0');
        if (cin.peek() <= ' ') break;
    }
    return In;
}

```

```

ostream& operator<<(ostream& Out, const xnum& V)
{
    int I;
    Out << (V.Len == 0 ? 0 : V[V.Len - 1]);
    for (I = V.Len - 2; I >= 0; I--)
        for (int J = Base / 10; J > 0; J /= 10)
            Out << V[I] / J % 10;
    return Out;
}

```

```

xnum gcd(xnum a,xnum b)
{
    if(compare(b,0)==0) return a;
    else return gcd(b,a%b);
}

```

```

int div(char *A,int B)

```

```

{
    int I;
    int C = 0;
    int Alen=strlen(A);
    for (I = 0; I <Alen; I++)
    {
        C = C * Base + A[I]-'0';
        C %= B;
    }
    return C;
}

```

```

xnum C(int n,int m)
{
    int i;
    xnum sum = 1;

    for(i = n; i >= n-m+1; i --)
        sum = sum*i;
    for(i = 1; i <= m; i ++)
        sum = sum/i;

    return sum;
}

```

```

#define MAXN 9999
#define DLEN 4
class BigNum {
private:
    int a[1000]; //可以控制大数的位数
    int len; //大数长度
public:
    BigNum() {len = 1;memset(a,0,sizeof(a));}
    BigNum(const int);
    BigNum(const char*);
    BigNum(const BigNum &);
    BigNum &operator=(const BigNum &);
    BigNum operator+(const BigNum &) const;
    BigNum operator-(const BigNum &) const;
    BigNum operator*(const BigNum &) const;
    BigNum operator/(const int &) const;
    BigNum operator^(const int &) const;
    int operator%(const int &) const;
    bool operator>(const BigNum & T)const;
}

```



```

    void print();
};

BigNum::BigNum(const int b) {
    int c,d = b;
    len = 0;
    memset(a,0,sizeof(a));
    while(d > MAXN) {
        c = d - (d / (MAXN + 1)) * (MAXN + 1);
        d = d / (MAXN + 1);    a[len++] = c;
    }
    a[len++] = d;
}

BigNum::BigNum(const char*s) {
    int t,k,index,l,i;
    memset(a,0,sizeof(a));
    l=strlen(s);
    len=l/DLEN;
    if(l%DLEN)len++;
    index=0;
    for(i=l-1;i>=0;i-=DLEN) {
        t=0;k=i-DLEN+1;
        if(k<0)k=0;
        for(int j=k;j<=i;j++)
            t=t*10+s[j]-'0';
        a[index++]=t;
    }
}

BigNum::BigNum(const BigNum & T) : len(T.len) {
    int i;
    memset(a,0,sizeof(a));
    for(i = 0 ; i < len ; i++)a[i] = T.a[i];
}

BigNum & BigNum::operator=(const BigNum & n) {
    len = n.len;
    memset(a,0,sizeof(a));
    int i;
    for(i = 0 ; i < len ; i++)
        a[i] = n.a[i];
    return *this;
}

BigNum BigNum::operator+(const BigNum & T) const {
    BigNum t(*this);
    int i,big;//位数

```

```

        big = T.len > len ? T.len : len;
        for(i = 0 ; i < big ; i++) {
            t.a[i] +=T.a[i];
            if(t.a[i] > MAXN) {
                t.a[i + 1]++;
                t.a[i] -=MAXN+1;
            }
        }
        if(t.a[big] != 0) t.len = big + 1;
        else t.len = big;
        return t;
    }
}

BigNum BigNum::operator-(const BigNum & T) const {
    int i,j,big;
    bool flag;
    BigNum t1,t2;
    if(*this>T) {
        t1=*this;
        t2=T;
        flag=0;
    } else {
        t1=T;
        t2=*this;
        flag=1;
    }
    big=t1.len;
    for(i = 0 ; i < big ; i++) {
        if(t1.a[i] < t2.a[i]) {
            j = i + 1;
            while(t1.a[j] == 0) j++;
            t1.a[j--]--;
            while(j > i) t1.a[j--] += MAXN;
            t1.a[i] += MAXN + 1 - t2.a[i];
        } else t1.a[i] -= t2.a[i];
    }
    t1.len = big;
    while(t1.a[len - 1] == 0 && t1.len > 1) {
        t1.len--;
        big--;
    }
    if(flag)t1.a[big-1]=0-t1.a[big-1];
    return t1;
}

BigNum BigNum::operator*(const BigNum & T) const {

```

```

BigNum ret;
int i,j,up;
int temp,temp1;
for(i = 0 ; i < len ; i++) {
    up = 0;
    for(j = 0 ; j < T.len ; j++) {
        temp = a[i] * T.a[j] + ret.a[i + j] + up;
        if(temp > MAXN) {
            temp1 = temp - temp / (MAXN + 1) * (MAXN + 1);
            up = temp / (MAXN + 1);
            ret.a[i + j] = temp1;
        } else {
            up = 0;
            ret.a[i + j] = temp;
        }
    }
    if(up != 0)
        ret.a[i + j] = up;
}
ret.len = i + j;
while(ret.a[ret.len - 1] == 0 && ret.len > 1) ret.len--;
return ret;
}

BigNum BigNum::operator/(const int & b) const {
    BigNum ret;
    int i,down = 0;
    for(i = len - 1 ; i >= 0 ; i--) {
        ret.a[i] = (a[i] + down * (MAXN + 1)) / b;
        down = a[i] + down * (MAXN + 1) - ret.a[i] * b;
    }
    ret.len = len;
    while(ret.a[ret.len - 1] == 0 && ret.len > 1) ret.len--;
    return ret;
}

int BigNum::operator%(const int & b) const {
    int i,d=0;
    for (i = len-1; i>=0; i--) {
        d = ((d * (MAXN+1))% b + a[i])% b;
    }
    return d;
}

BigNum BigNum::operator^(const int & n) const {
    BigNum t,ret(1);
    if(n<0)exit(-1);

```

```

    if(n==0)return 1;
    if(n==1)return *this;
    int m=n;
    while(m>1) {
        t=*this;
        int i;
        for(i=1;i<=1<=m;i<=1) {
            t=t*t;
        }
        m-=i;
        ret=ret*t;
        if(m==1)ret=ret>(*this);
    }
    return ret;
}

bool BigNum::operator>(const BigNum & T) const {
    int ln;
    if(len > T.len) return true;
    else if(len == T.len) {
        ln = len - 1;
        while(a[ln] == T.a[ln] && ln >= 0) ln--;
        if(ln >= 0 && a[ln] > T.a[ln]) return true;
        else return false;
    } else return false;
}

void BigNum::print() {
    int i;
    cout << a[len - 1];
    for(i = len - 2 ; i >= 0 ; i--) {
        cout.width(DLEN);
        cout.fill('0');
        cout << a[i];
    }
}

//读取整数
const int ok = 1;
int get_val(int & ret) {
    ret = 0;
    char ch;
    while ((ch=getchar()) > '9' || ch < '0') ;
    do {
        ret = ret*10 + ch - '0';
    } while ((ch=getchar()) <= '9' && ch >= '0') ;
    return ok;
}

```

```
}
```

```
//带负数
```

```
int get_val(int & ret) {  
    ret = 0;  
    char ch;  
    bool neg = false;  
    while (((ch=getchar()) > '9' || ch < '0') && ch!='-') ;  
    if (ch == '-') {  
        neg = true;  
        while ((ch=getchar()) > '9' || ch < '0') ;  
    }  
    do {  
        ret = ret*10 + ch - '0';  
    } while ((ch=getchar()) <= '9' && ch >= '0') ;  
    ret = (neg? -ret : ret);  
    return ok;  
}
```

```
//读取整数,可判EOF和EOL
```

```
const int eof = -1;  
const int eol = -2;  
int get_val(int & ret) {  
    ret = 0;  
    char ch;  
    while (((ch=getchar()) > '9' || ch < '0') && ch!=EOF) ;  
    if (ch == EOF) return eof;  
    do {  
        ret = ret*10 + ch - '0';  
    } while ((ch=getchar()) <= '9' && ch >= '0') ;  
    if (ch == '\n') return eol;  
    return ok;  
}
```

```
//读取浮点数
```

```
int get_val(double & ret) {  
    ret = 0;  
    double base = 0.1;  
    char ch;  
    bool dot = false, neg = false;  
    while (((ch=getchar()) > '9' || ch < '0') && ch != '.' && ch != '-') ;  
    if (ch == '-') {  
        neg = true;  
        while (((ch=getchar()) > '9' || ch < '0') && ch != '.' && ch != '-') ;  
    }
```

```

    }
    do {
        if (ch == '.') {
            dot = true;
            continue;
        }
        if (dot) {
            ret += (ch-'0') * base;
            base *= 0.1;
        } else ret = ret*10 + (ch-'0');
    } while (((ch=getchar()) <= '9' && ch >= '0') || ch == '.');
    ret = (neg? -ret : ret);
    return ok;
}

typedef long long LL;
//LL MultiMod(LL a, LL b, LL c) {
// if (b)
// return (a * (b & 1) % c + (MultiMod(a, b >> 1, c) << 1)) % c;
// return 0;
//}

LL MultiMod(LL a, LL b, LL c) {
    LL ret = 0, d = a;
    for (; b; b >>= 1, d <= 1, d %= c)
        if ((b & 1))
            ret = (ret + d) % c;
    return ret;
}

// 128-bits integer's power with mod in O(64*LogN)
LL ModPower(LL base, LL exp, LL mod) {
    LL ret = 1;
    for (; exp; exp >>= 1, base = MultiMod(base, base, mod))
        if ((exp & 1))
            ret = MultiMod(ret, base, mod);
    return ret;
}

```

## 第四章 数论算法

### 1. Greatest Common Divisor 最大公约数

```
int GCD(int x, int y)
{
    int t;
    while(y > 0) {
        t = x % y;
        x = y;
        y = t;
    }
    return x;
}
```

### 2. Prime 素数判断

```
bool is_prime(int u)
{
    if(u == 0 || u == 1) return false;
    if(u == 2) return true;
    if(u%2 == 0) return false;
    for(int i=3; i <= sqrt(u) ;i+=2)
        if(u%i==0) return false;
    return true;
}
```

### 3. Sieve Prime 素数筛法

```
const int M = 1000; // M : size
bool mark[M]; // true : prime number
void sieve_prime()
{
    memset(mark, true, sizeof(mark));
    mark[0] = mark[1] = false;
    for(int i=2; i <= sqrt(M) ;i++) {
        if(mark[i]) {
            for(int j=i*i; j < M ;j+=i)
                mark[j] = false;
        }
    }
}
```

#### 4. Module Inverse 模逆元

```
//  $ax \equiv 1 \pmod{n}$ 
int Inv(int a, int n)
{
    int d, x, y;
    d = extended_euclid(a, n, x, y);
    if(d == 1) return (x%n + n) % n;
    else return -1; // no solution
}
```

#### 5. Extended Euclid 扩展欧几里德算法

```
//如果  $\text{GCD}(a,b) = d$ , 则存在  $x, y$ , 使  $d = ax + by$ 
//  $\text{extended\_euclid}(a, b) = ax + by$ 
int extended_euclid(int a, int b, int &x, int &y)
{
    int d;
    if(b == 0) {x = 1; y = 0; return a;}
    d = extended_euclid(b, a % b, y, x);
    y -= a / b * x;
    return d;
}
```

#### 6. Modular Linear Equation 模线性方程(同余方程)

```
//如果  $\text{GCD}(a, b)$  不能整除  $c$ , 则  $ax + by = c$  没有整数解
//  $ax \equiv b \pmod{n}$   $n > 0$ 
//上式等价于二元一次方程  $ax - ny = b$ 
void modular_linear_equation(int a, int b, int n)
{
    int d, x, y, x0, gcd;
    // 可以减少扩展欧几里德溢出的可能
    gcd = GCD(a, n);
    if (b%gcd != 0) {
        cout << "no solution" << endl;
        return ;
    }
    a /= gcd; b /= gcd; n /= gcd;
    d = extended_euclid(a, n, x, y);
    if( b%d == 0) {
        x0 = ( x*(b/d) ) % n; // x0 : basic solution
        int ans = n; // min x = (x0%(n/d) + (n/d)) % (n/d)
        for(int i=0; i < d ;i++) {
            ans = ( x0 + i*(n/d) ) % n;
            cout << ans << endl;
        }
    }
}
```



```

    }
}
else    cout << "no solution" << endl;
}

```

## 7. Chinese Remainder Theorem 中国余数定理

```

//  $x \equiv b[i] \pmod{w[i]}$ ,  $i \in [1, \text{len}-1]$ 
// 前提条件  $w[i] > 0$ , 且  $w[]$  中任意两个数互质
int chinese_remainder(int b[], int w[], int len)
{
    int i, d, x, y, m, n, ret;
    ret = 0;    n = 1;
    for(i=0; i < len ;i++)    n *= w[i];
    for(i=0; i < len ;i++) {
        m = n / w[i] ;
        d = extended_euclid(w[i], m, x, y);
        ret = (ret + y*m*b[i]) % n;
    }
    return (n + ret%n) % n;
}

//  $m \equiv r[i] \pmod{a[i]}$ 
//  $a[i]$  可以不互素
// -1表示无解
/*
Pku 2891 Strange Way to Express Integers
假设  $C \equiv A1 \pmod{B1}$ ,  $C \equiv A2 \pmod{B2}$ 。
令  $C = A1 + X1B1$ , 那么  $X1B1 \equiv A2 - A1 \pmod{B2}$ 。
用扩展欧几里德算法求出  $X1$ , 也就求出  $C$ 。
令  $B = \text{lcm}(B1, B2)$ , 那么上面两条方程就可以被  $C' \equiv C \pmod{B}$  代替。
迭代直到只剩下一条方程。
*/
LL chinese_remainder2()
{

```

```

    int i, j;

    if (n == 1)
        return r[0];

    LL m, x, apre;
    x = modular_linear_equation(a[0], r[1]-r[0], a[1]);
    if (x == -1)
        return -1;
    m = x*a[0] + r[0];
    apre = LCM(a[0], a[1]);

```

```

for (i=2; i<n; i++)
{
    x = modular_linear_equation(apre, r[i]-m, a[i]);
    if (x == -1)
        return -1;
    m = x*apre + m;
    apre = LCM(apre, a[i]);
}
return m;
}

```

## 8. Euler Function 欧拉函数

//求1..n-1中与n互质数的个数

```

int euler(int n)
{
    int ans = 1;
    int i;
    for(i=2; i*i<=n ;i++) {
        if(n%i == 0) {
            n /= i;
            ans *= i-1;
            while(n%i == 0) {
                n /= i;
                ans *= i;
            }
        }
    }
    if(n > 1) {
        ans *= n-1;
    }
    return ans;
}

```

## 9. Farey 总数

//求MAX以内所有Farey的总数

```

const int MAX = 1000100;
int n;
bool num[1100]; //sqrt(MAX)
int prime[1100], total;
__int64 f[MAX], inc[MAX];

```

```

void cal_prime() {
    int i,j;

```

```

    memset(num, false, sizeof(num));
    total = 0;
    for(i=2;i<1100;i++) {
        if(!num[i]) {
            prime[total++] = i;
            j = i+i;
            while(j < 1100) {
                num[j] = true;
                j += i;
            }
        }
    }
}

void cal_farey() {
    int i,j,k;
    inc[1] = 1;
    for(i=2;i<MAX;i++) {
        for(j=0;j<total;j++) {
            if(i%prime[j] == 0) {
                k = i / prime[j];
                if(k%prime[j] == 0) inc[i] = inc[k] * prime[j];
                else inc[i] = inc[k] * (prime[j] - 1);
                break;
            }
        }
        if(j == total) inc[i] = i - 1;
    }
    f[1] = 0;
    for(i=2;i<MAX;i++) f[i] = f[i-1] + inc[i];
}

int main() {
    cal_prime();
    cal_farey();
    while(scanf("%d", &n), n) {
        printf("%I64d\n", f[n]);
    }
}

```

## 10. Farey 序列构造

//构造5000以内的Farey序列

```

const int MAX = 8000000;
int total;

```

```

int n,k;
int farey[2][MAX];
void make_farey_seq(int x1,int y1,int x2, int y2)
{
    if(x1+x2 > n || y1+y2 > n) return;
    make_farey_seq(x1, y1,x1+x2, y1+y2);
    total ++;
    farey[0][total] = x1+x2;
    farey[1][total] = y1+y2;
    make_farey_seq(x1+x2, y1+y2,x2,y2);
}
int main() {
    int t;
    scanf("%d %d", &n, &t);
    total = 1;
    farey[0][1] = 0;
    farey[1][1] = 1;
    make_farey_seq(0,1,1,1);
    farey[0][total+1] = 1;
    farey[1][total+1] = 1;
    total ++;
    while(t --) {
        scanf("%d", &k);
        if(k > total) puts("No Solution");
        else printf("%d/%d\n", farey[0][k], farey[1][k]);
    }
}

```

## 11. Miller\_Rabbin 素数测试, Pollard\_rho 因式分解

```

typedef __int64 I64;
const char * pformat = "%I64d";
I64 big_rand(I64 m) {
    I64 x = rand();
    x *= rand();
    if(x < 0) x = -x;
    return x % m;
}
// x*y % n
I64 mod_mul(I64 x, I64 y, I64 n) {
    if(x == 0 || y == 0) return 0;
    return ( ((x&1)*y)%n + (mod_mul(x>>1,y,n)<<1)%n ) % n;
}
// x^y % n
I64 mod_exp(I64 x, I64 y, I64 n) {

```

```

    I64 ret = 1;
    while(y) {
        if(y&1) ret = mod_mul(ret,x,n);
        x = mod_mul(x,x,n);
        y >>= 1;
    }
    return ret;
}

bool Miller_Rabbin(I64 n) { // O(times * (log N)^3)
    I64 i,j,x,m,k;
    if(n == 2) return true;
    if(n < 2 || !(n&1)) return false;
    m = n - 1; k = 0;
    while(!(m&1)) m >>= 1, k++; // binary scan
    for(i=0;i<4;i++) { // test times
        x = big_rand(n-2) + 2;
        x = mod_exp(x,m,n);
        if(x == 1) continue;
        for(j=0;j<k;j++) {
            if(x == n-1) break;
            x = mod_mul(x,x,n);
        }
        if(j >= k) return false;
    }
    return true;
}

/*Irj P.218
for(i=0;i<20;i++) {
    x = big_rand(n-2) + 2;
    if(mod_exp(x,n-1,n) != 1) return false;
}
return true;
*/
}

I64 gcd(I64 x, I64 y) {
    if(x > y) std::swap(x,y);
    while(x) {
        I64 t = y % x;
        y = x;
        x = t;
    }
    return y;
}

I64 func(I64 x, I64 m) {
    return (mod_mul(x,x,m)+1) % m;
}

```

```

}
I64 Pollard(I64 n) {
    if(Miller_Rabbin(n)) return n;
    if(!(n&1)) return 2;
    I64 i,x,y,ret;
    i = 1;
    while(true) {
        x = i ++;
        y = func(x,n);
        ret = gcd(y-x,n);
        while(ret == 1) {
            x = func(x,n);
            y = func(func(y,n),n);
            ret = gcd((y-x+n)%n,n) % n;
        }
        if(0 < ret && ret < n) return ret;
    }
}
I64 factor[100], nfac, minfac;
void cal_factor(I64 n) {
    I64 x = Pollard(n);
    if(x == n) {
        //factor[nfac++] = x;
        minfac = min(minfac,x);
        return;
    }
    cal_factor(x);
    cal_factor(n/x);
}
void print_factor(I64 n) {
    I64 i;
    nfac = 0;
    cal_factor(n);
    std::sort(factor,factor + nfac);
    for(i=0;i<nfac;i++) {
        if(i > 0) putchar(' ');
        printf(pformat,factor[i]);
    }
    puts("");
}
}
const I64 lim = 100000;
int main() {
    I64 n,t,i;
    srand((unsigned)time(NULL));

```

```

scanf(pformat,&t);
while(t --) {
    scanf(pformat, &n);
    if(Miller_Rabbin(n)) puts("Prime");
    else {
        if(!(n&1)) puts("2");
        else {
            for(minfac=3; minfac < lim && n % minfac ;minfac+=2) ;
            if(minfac >= lim) {
                I64 rn = sqrt(1.0*n);
                if(rn * rn == n) {
                    minfac = rn;
                    cal_factor(rn);
                }
                else {
                    minfac = n;
                    cal_factor(n);
                }
            }
            printf(pformat,minfac);
            puts("");
        }
    }
}
}
}

```

**12.**

## 第五章 图论算法

### 1. 最小生成树(Kruscal 算法)

```
/* **** */
*   Function Name :      最小生成树(Kruscal 算法)
*   Description :      ZJU 1203 Swordfish O(E*LogE)
* **** */
#include <iostream>
#include <algorithm>
#include <cstdio>
#include <cmath>
using namespace std;
struct struct_edges
{
    int bv, tv; //bv 起点 tv 终点
    double w; //权值
};
struct_edges edges[10100]; //边集
struct struct_a
{
    double x;
    double y;
};
struct_a arr_xy[101];
int point[101], n, e; //n 顶点数, e 边数(注意是无向网络)
double sum;

int kruscal_f1(int point[], int v)
{
    int i = v;
    while(point[i] > 0)    i = point[i];
    return i;
}

bool UDlessor(struct_edges a, struct_edges b)
```



```
{return a.w < b.w;}
```

```
void kruscal() //只需要准备好 n, e, 递增的边集 edges[]即可使用
```

```
{
    int v1,v2,i,j;
    for(i=0; i<n ;i++)    point[i]=0;
    i = j = 0;
    while(j<n-1 && i<e) {
        v1 = kruscal_f1(point, edges[i].bv);
        v2 = kruscal_f1(point, edges[i].tv);
        if(v1 != v2) {
            sum += edges[i].w; //注意 sum 初始为 0
            point[v1]=v2;
            j++;
        }
        i++;
    }
}
```

```
int main()
```

```
{
    int k,i,j;
    cin>>n;
    k=0;
    while(n != 0) {
        sum=0;
        k++;
        for(i=0; i<n ;i++)
            cin>>arr_xy[i].x>>arr_xy[i].y;
        e=0;
        for(i=0; i<n ;i++) //从 0 开始计数
            for(j=i+1; j<n ;j++) //注意是无向网络
            {
                if(i == j) continue;
                edges[e].bv=i;
                edges[e].tv=j;
                edges[e].w=sqrt((arr_xy[i].x-arr_xy[j].x)*(arr_xy[i].x-arr_xy[j].x)+(arr_xy[i].y-arr_xy[j].y)*(arr_xy[i].y-arr_xy[j].y));
                e++;
            }
        sort(edges,edges+e,UDlesser); //得到一个递增的边集，注意是从 0 开始计数
        kruscal();
    }
}
```

```

        printf("Case #%%d:\n",k); //cout<<"Case #"<<k<<":"<<endl;
        printf("The minimal distance is: %.2f\n",sum); //输出 sum
        cin>>n;
        if(n != 0) printf("\n");
    }
}

```

## 2. 最小生成树(Prim 算法)

```

/***** *****/
*   Function Name :      最小生成树(Prim 算法)
*   Description :       ZJU 1203 Swordfish O(N^2)
*****/
#include <iostream>
#include <cmath>
#include <cstdio>
using namespace std;
double sum, arr_list[101][101], min;
int i, j, k=0, n;

struct struct_a
{
    float x;
    float y;
};
struct_a arr_xy[101];
struct struct_b
{
    int point;
    float lowcost;
};
struct_b closedge[101];

void prim(int n) //prim 需要准备: n 顶点数 arr_list[][]顶点的邻接矩阵也是从 0 开始计数
{
    int i,j,k;
    k=0;
    for(j=0; j<n ;j++) {
        if(j != k) {
            closedge[j].point = k;
            closedge[j].lowcost = arr_list[k][j];
        }
    }
}

```

```

    }
    closedge[k].lowcost=0;
    for(i=0; i<n ;i++) {
        min=10000;
        for(j=0; j<n ;j++) {
            if (closedge[j].lowcost != 0 && closedge[j].lowcost < min) {
                k = j;
                min = closedge[j].lowcost;
            }
        }
        sum += closedge[k].lowcost; //不要改成 sum+=min; sum 即为所求值
        closedge[k].lowcost = 0;
        for(j=0; j<n ;j++) {
            if(arr_list[k][j] < closedge[j].lowcost) {
                closedge[j].point = k;
                closedge[j].lowcost = arr_list[k][j];
            }
        }
    }
}
/*
arr_list[][]= Wij 如果 Vi, Vj 有边
                0  如果 i=j
                无限大 如果没有边
*/
int main()
{
    cin>>n;
    while(n != 0) {
        sum=0;
        k++;
        for(i=0; i<n ;i++)
            cin>>arr_xy[i].x>>arr_xy[i].y;
        for(i=0; i<n ;i++)
            for(j=0; j<n ;j++) //得到邻接矩阵 arr_list[][]
                arr_list[i][j]=arr_list[j][i]=sqrt((arr_xy[i].x-arr_xy[j].x)*(arr_xy[i].x-arr_xy[j].x)+(arr_xy[i].y-arr_xy[j].y)*(arr_xy[i].y-arr_xy[j].y));
        prim(n);

        cout<<"Case #"<<k<<":"<<endl;
        printf("The minimal distance is: %.2f\n",sum);
        cin>>n;
        if(n!=0)    printf("\n");
    }
}

```

```
}
```

### 3. 单源最短路径(**Bellman-ford** 算法)

```
struct node {
    int e,v;
    node(int a = 0,int b = 0)
        : e(a), v(b) {}
};
vector< vector<node> > path;
int n,p,q;
int dist[1000100];
/*
 *   SPFA (Shortest Path Faster Algorithm)
 *   Bellman-Ford算法的一种队列实现，减少了不必要的冗余计算
 *   返回值为false，说明队列不为空，存在负权环
 */
bool SPFA()
{
    int i,j,k,now,l;
    node next;
    bitset <1000100> vis;
    queue< int > SQ;
    memset(dist,-1,sizeof(dist));
    SQ.push(1);
    vis[1] = true;
    dist[1] = 0;

    for (i=0;i<=n;i++) {
        l = SQ.size();
        if (l == 0) break;
        while (l--) {
            now = SQ.front();
            SQ.pop();
            vis[now] = false;
            for (j=path[now].size()-1;j>=0;j--) {
                next = path[now][j];
                if (dist[next.e]==-1 || dist[next.e] > dist[now]+next.v) {
                    dist[next.e] = dist[now]+next.v;
                    if(!vis[next.e]) {
                        SQ.push(next.e);
                        vis[next.e] = true;
                    }
                }
            }
        }
    }
}
```

```

    }
}
return SQ.empty();
}

```

#### 4. 单源最短路径(Dijkstra 算法)

```

/***** *****/
*   Function Name :      单源最短路径 (Dijkstra 算法)
*   Description :      贪心,  $O(N^2)$ , 不能有负权
*****/
int matrix[200][200],n;      //matrix[i][j], 30000 表示无限大,即无边.否则为有边,
其值为边的权值
void Dijkstra(int x,int y)    //起点 Vx 终点 Vy
{
    int i,j,k,path[40000],mark[40000];
    int min,dist[40000];
    for(i=1;i<=n;i++) {
        mark[i] = 0;
        dist[i] = matrix[x][i];
        path[i] = x;
    }
    mark[x] = 1;
    do {
        min=30000;
        k=0;
        for(i=1;i<=n;i++)
            if(mark[i]==0 && dist[i]<min) {
                min = dist[i];
                k = i;
            }
        if(k) {
            mark[k] = 1;
            for(i=1;i<=n;i++)
                if(matrix[k][i]<30000 && min+matrix[k][i]<dist[i]) {
                    dist[i] = min + matrix[k][i];
                    path[i] = k;
                }
        }
    }while(k);
    cout<<dist[y]<<endl;    //dist[y] 的值就是从 Vx 到 Vy 的最短路径值
    //如果希望得到路径, 加入如下代码:
    do {
        cout<<k<<"<--";
        k = path[k];
    }
}

```

```

    }while(k!=x);
    cout<<x<<endl;
}

```

## 5. 全源最短路径(Folyd 算法)

```

/***** *****/
*   Function Name :      全源最短路径(Folyd 算法)
*   Description :       DP, O(N^3)
*****/
//初始化
//path[i][j]=j;
void Floyd()
{
    int i,j,k;
    for(k=0;k<vertex_number;k++) {
        for(i=0;i<vertex_number;i++) {
            for(j=0;j<vertex_number;j++) {
                if((graph[i][k]==-1) || (graph[k][j]==-1)) continue;
                if((graph[i][j]==-1) || (graph[i][j] > graph[i][k]+graph[k][j]))
                {
                    graph[i][j] = graph[i][k]+graph[k][j];    /*最短路径值*/
                    path[i][j] = k;    /*最短路径*/
                }
            }
        }
    }
}

```

## 6. 拓扑排序

```

/***** *****/
*   Function Name :      拓扑排序
*****/
//degree[]    每个结点的入度
//f[]         每个结点所在的层
void Topological_sort()
{
    int i,j;
    bool p=true;
    top=0;
    while(p) {
        p=false;
        top++;
        for(i=1;i<=n;i++)

```

```

        if(degree[i]==0) {
            p=true;
            f[i]=top;
        }
        for(i=1;i<=n;i++)
            if(f[i]==top) {
                for(j=1;j<=n;j++)
                    if(map[i][j]) degree[j]--;
                degree[i]=-1;
            }
        }
        top--;
    }
}

```

## 7. 网络预流和最大流

/\*

网络中求最大流Edmonds\_Karp最短增广路算法 $O(VE^2)$

参数含义: n代表网络中节点数,第1节点为源点,第n节点为汇点

net[][]代表剩余网络,0表示无通路

path[]保存增广路径

neck[]代表瓶颈,保存增广路径最小容量

返回值: 最大流量

\*/

```
const int NMAX = 210;
```

```
int net[NMAX][NMAX];
```

```
int path[NMAX], n;
```

```
int bfs()
```

```
{
```

```
    queue<int> SQ;
```

```
    int neck[NMAX], i;
```

```
    memset(path,-1,sizeof(path));
```

```
    neck[1] = INT_MAX;
```

```
    SQ.push(1);
```

```
    while(!SQ.empty()) {
```

```
        int now = SQ.front();
```

```
        SQ.pop();
```

```
        if(now == n) break ;
```

```
        for(i=1;i<=n;i++) {
```

```
            if(net[now][i] > 0 && path[i] == -1) {
```

```
                path[i] = now;
```

```
                neck[i] = min(neck[now], net[now][i]);
```

```
                SQ.push(i);
```

```

    }
    }
}
if(path[n] == -1) return -1;
return neck[n];
}

```

```

int Edmonds_Karp()
{
    int now, step;
    int max_flow = 0;

    while( (step=bfs()) != -1 ) {
        max_flow += step;
        now = n;
        while(now != 1) {
            int pre = path[now];
            net[pre][now] -= step;
            net[now][pre] += step;
            now = pre;
        }
    }
    return max_flow;
}

```

/\*

网络中求最大流HLPP高度标号预流推进算法 $O(V^2 * E^{0.5})$

参数含义: n代表网络中节点数,第0节点为源点,第n节点为汇点

net[][]代表剩余网络,0表示无通路

earn[]代表各点的盈余

high[]代表各点的高度

返回值: 最大流量

\*/

```

const int NMAX = 110;
int earn[NMAX], net[NMAX][NMAX], high[NMAX];
int n, m;
queue<int> SQ;
void push(int u, int v) {
    int ex = min(earn[u], net[u][v]);
    earn[u] -= ex;
    net[u][v] -= ex;
    earn[v] += ex;
    net[v][u] += ex;
}
void relable(int u) {

```



```

    int i, mmin = INT_MAX;
    for(i=0;i<=n;i++) {
        if(net[u][i] > 0 && high[i] >= high[u]) {
            mmin = min(mmin, high[i]);
        }
    }
    high[u] = mmin + 1;
}

void discharge(int u) {
    int i, vn;
    while(earn[u] > 0) {
        vn = 0;
        for(i=0;i<=n && earn[u] > 0;i++) {
            if(net[u][i] > 0 && high[u] == high[i]+1) {
                push(u,i);
                vn ++;
                if(i != n) SQ.push(i);
            }
        }
        if(vn == 0) relable(u);
    }
}

void init_preflow() {
    int i;
    memset(high,0,sizeof(high));
    memset(earn,0,sizeof(earn));
    while(!SQ.empty()) SQ.pop();
    high[0] = n+1;
    for(i=1;i<=n;i++) {
        if(net[0][i] > 0) {
            earn[i] = net[0][i];
            earn[0] -= net[0][i];
            net[i][0] = net[0][i];
            net[0][i] = 0;
            if(i != n) SQ.push(i);
        }
    }
}

int high_label_preflow_push() {
    int i,j;
    init_preflow();
    while(!SQ.empty()) {
        int overp = SQ.front();
        SQ.pop();
    }
}

```

```

        discharge(overp);
    }
    return earn[n];
}
//带gap优化的高标预流
const int N = 128;
const int INF = 1 << 28;

class Edge {
public:
    int u, v, cuv, cvu, flow;
    Edge() {}
    Edge(int cu, int cv, int ccu, int ccv) : u(cu), v(cv), cuv(ccu), cvu(ccv), flow(0)
    {}
    int other(int p) const { return p == u ? v : u; }
    int cap(int p) const { return p == u ? cuv-flow : cvu+flow; }
    void addFlow(int p, int f) { flow += (p == u ? f : -f); }
};

class NodeList {
private:
    int level, next[N], index[2*N], v;
public:
    void clear(int cv) { v = cv; level = -1; memset(index, -1, sizeof(index)); }
    void insert(int n, int h) { next[n] = index[h]; index[h] = n; level >= h; }
    int remove();
    bool empty() const { return level < 0; }
};

int NodeList::remove() {
    int r = index[level]; index[level] = next[index[level]];
    while(level >= 0 && index[level] == -1) level--;
    return r;
}

class Network {
private:
    vector<Edge> eg;
    vector<Edge*> net[N];
    int v, s, t;
    NodeList list;
    int h[N], hn[2*N], e[N], cur[N];
    void initNet();
    void initFlow();
    void initHeight();
};

```

```

    void push(int);
    void relabel(int);
    void discharge(int);
    void gapHeuristic(int);
public:
    bool build();
    int maxFlow(int, int);
};

void Network::gapHeuristic(int k) {
    if(hn[k] != 0 || k >= v+1) return;
    for(int i = 0; i < v; i++)
        if(h[i] > k && h[i] <= v && i != s)
            { hn[h[i]]--; hn[v+1]++; h[i] = v+1; }
}

void Network::initNet() {
    for(int i = 0; i < v; i++) net[i].clear();
    for(int i = eg.size()-1; i >= 0; i--) {
        net[eg[i].u].push_back(&eg[i]);
        net[eg[i].v].push_back(&eg[i]);
    }
}

void Network::initHeight() {
    memset(h, 0, sizeof(h)); memset(hn, 0, sizeof(hn));
    memset(e, 0, sizeof(e)); e[s] = INF;
    for(int i = 0; i < v; i++) h[i] = v;
    queue<int> Q; Q.push(t); h[t] = 0;
    while(!Q.empty()) {
        int p = Q.front(); Q.pop();
        for(int i = net[p].size()-1; i >= 0; i--) {
            int u = net[p][i]->other(p), ec = net[p][i]->cap(u);
            if(ec != 0 && h[u] == v && u != s) { h[u] = h[p]+1; Q.push(u); }
        }
    }
    for(int i = 0; i < v; i++) hn[h[i]]++;
}

void Network::initFlow() {
    initNet(); initHeight();
    for(int i = 0; i < v; i++) cur[i] = net[i].size()-1;
    list.clear(v);
    for(; cur[s] >= 0; cur[s]--) push(s);
}

void Network::push(int u) {
    Edge* te = net[u][cur[u]];
    int ex = min(te->cap(u), e[u]), p = te->other(u);

```

```

        if(e[p] == 0 && p != t) list.insert(p, h[p]);
        te->addFlow(u, ex); e[u] -= ex; e[p] += ex;
    }
    void Network::relabel(int u) {
        int mh = 2*v, oh = h[u];
        for(int i = net[u].size()-1; i >= 0; i--) {
            int p = net[u][i]->other(u);
            if(net[u][i]->cap(u) != 0) mh <?= h[p]+1;
        }
        hn[h[u]]--; hn[mh]++; h[u] = mh; cur[u] = net[u].size()-1;
        gapHeuristic(oh);
    }
    void Network::discharge(int u) {
        while(e[u] > 0)
            if(cur[u] < 0) relabel(u);
            else if(net[u][cur[u]]->cap(u) > 0 && h[u] ==
h[net[u][cur[u]]->other(u)+1]) push(u);
            else cur[u]--;
    }
    bool Network::build() {
        int m, np, nc;
        int a, b, l, i;
        if(scanf("%d %d %d %d", &v, &np, &nc, &m) != 4) return false;
        v += 2; eg.clear();
        for(i = 0; i < m; i++) {
            scanf("\n(%d,%d)%d", &a, &b, &l);
            eg.push_back(Edge(a+2, b+2, l, 0));
        }
        for(i = 0; i < np; i++) {
            scanf("\n(%d)%d", &a, &l);
            eg.push_back(Edge(0, a+2, l, 0));
        }
        for(i = 0; i < nc; i++) {
            scanf("\n(%d)%d", &a, &l);
            eg.push_back(Edge(a+2, 1, l, 0));
        }
        return true;
    }
    int Network::maxFlow(int ss, int tt) {
        s = ss; t = tt; initFlow();
        while(!list.empty()) {
            int u = list.remove();
            discharge(u);
        }
    }

```

```

    return e[t];
}

int main()
{
    Network net;
    while(net.build()) printf("%d\n", net.maxFlow(0, 1));
    return 0;
}

/*
网络中求最大流Dinic算法 $O(V^2E)$ 
适用于稠密图，实际复杂度低于HLPP模板
参数含义：    n代表网络中节点数,第0节点为源点，第n节点为汇点
               net代表网络，使用前向星表示法存储边
               dis[]代表从源点出发的距离标号
               path[]代表模拟栈中的路径信息
               cur[]代表模拟栈的现场保存
返回值：      最大流量
*/
const int NMAX = 21000;
const int MMAX = 250000<<1;

struct EDGE {
    int u, v, cap, flow;
    int next;
    EDGE(int _u=0, int _v=0, int _c=0, int _f=0)
        : u(_u), v(_v), cap(_c), flow(_f) {}
};

const int ENDFLAG = -1;
struct EDGELIST {
    int start[NMAX];
    int last[NMAX];
    int tot;
    EDGE arc[MMAX];
    void clear() {
        tot = ENDFLAG + 1;
        memset(last, ENDFLAG, sizeof(last));
    }
    void push_back(EDGE edge) {
        edge.next = ENDFLAG;
        arc[tot] = edge;
        if (last[edge.u] != ENDFLAG) arc[ last[edge.u] ].next = tot;
        else start[edge.u] = tot;
    }
};

```

```

        last[edge.u] = tot;
        tot ++;
    }
    // 创建双向弧
    void add_arc(EDGE edge) {
        push_back(edge);
        push_back(EDGE(edge.v,edge.u,edge.cap));
    }
}net;

int que[2][NMAX];
int qf[2],qe[2],qnow;

#define push_que(a) (que[qnow][ qe[qnow]++ ] = (a))
#define pop_que2  (que[qnow^1][ qf[qnow^1]++ ])
#define switch_que qnow ^= 1; \
                    qf[qnow] = qe[qnow] = 0;
#define empty_que2  (qf[qnow^1] >= qe[qnow^1])
#define size_que2  (qe[qnow^1] - qf[qnow^1])

int n, m;
int dis[NMAX];
int path[NMAX], deep;
int cur[NMAX];
bool bfs() {
    int i, j;
    memset(dis,-1,sizeof(dis));
    dis[0] = 0;
    qnow = 0;
    switch_que;
    push_que(0);
    switch_que;
    while (!empty_que2) {
        int l = size_que2;
        while (l --) {
            int u = pop_que2;
            for (i=net.start[u];i!=ENDFLAG;i=net.arc[i].next) {
                int v = net.arc[i].v;
                if (dis[v]==-1 && net.arc[i].cap>net.arc[i].flow) {
                    push_que(v);
                    dis[v] = dis[u]+1;
                    if (v == n) return true;
                }
            }
        }
    }
}

```

```

    }
    switch_que;
}
return false;
}
int Dinic()
{
    int i, j;
    int u;
    int maxflow = 0;
    while (bfs()) {
        memcpy(cur, net.start, sizeof(cur));
        for (deep = u = 0; true;) {
            if (u == n) {
                int neck = INT_MAX, pos;
                for (i = 0; i < deep; i++) {
                    int res = net.arc[path[i]].cap - net.arc[path[i]].flow;
                    if (res < neck) {
                        neck = res;
                        pos = i;
                    }
                }
                maxflow += neck;
                for (i = 0; i < deep; i++) {
                    net.arc[path[i]].flow += neck;
                    net.arc[path[i]^1].flow -= neck;
                }
                deep = pos;
                u = net.arc[path[deep]].u;
            }
            for (i = cur[u]; i != ENDFLAG; i = net.arc[i].next) {
                if (net.arc[i].cap > net.arc[i].flow
                    && dis[u] + 1 == dis[net.arc[i].v]) break;
            }
            cur[u] = i;
            if (i != ENDFLAG) {
                path[deep++] = i;
                u = net.arc[i].v;
            }
            else {
                if (deep == 0) break;
                dis[u] = -1;
                u = net.arc[path[--deep]].u;
            }
        }
    }
}

```

```

    }
}
return maxflow;
}

```

## 8. 网络最小费用最大流

```

/***** *****/

```

网络中最小费用最大流  $O(V \cdot E^2)$

参数含义:  $n$ 代表网络中的总节点数,第0节点为源点,第 $n$ 节点为汇点

$net[][]$ 代表剩余网络

$cost[][]$ 代表单位费用

$path[]$ 保存增广路径

$ecost[]$ 源点到各点的最短路

算法:初始最小费用和最大流均为0,寻找单位费用最短路

在最短路中求出最大流,即为增广路,再修改剩余网络,直到无可增广路为止

返回值: 最小费用,最大流量

```

**** */

```

```

const int NMAX = 210;

```

```

int net[NMAX][NMAX], cost[NMAX][NMAX];

```

```

int path[NMAX], ecost[NMAX];

```

```

int n;

```

```

bool bellman_ford()

```

```

{

```

```

    int i,j;

```

```

    memset(path,-1,sizeof(path));

```

```

    fill(ecost, ecost+NMAX, INT_MAX);

```

```

    ecost[0] = 0;

```

```

    bool flag = true;

```

```

    while(flag) {

```

```

        flag = false;

```

```

        for(i=0;i<=n;i++) {

```

```

            if(ecost[i] == INT_MAX) continue ;

```

```

            for(j=0;j<=n;j++) {

```

```

                if(net[i][j] > 0 && ecost[i]+cost[i][j] < ecost[j]) {

```

```

                    flag = true;

```

```

                    ecost[j] = ecost[i]+cost[i][j];

```

```

                    path[j] = i;

```

```

                }

```

```

            }

```

```

        }

```

```

    }

```

```

    return ecost[n] != INT_MAX;

```

```

}

```



```

int min_cost_max_flow()
{
    int i,j;
    int mincost = 0, maxflow = 0;
    while( bellman_ford() ) {
        int now = n;
        int neck = INT_MAX;
        while(now != 0) {
            int pre = path[now];
            neck = min(neck, net[pre][now]);
            now = pre;
        }
        maxflow += neck;
        now = n;
        while(now != 0) {
            int pre = path[now];
            net[pre][now] -= neck;
            net[now][pre] += neck;
            cost[now][pre] = - cost[pre][now];
            mincost += cost[pre][now] * neck;
            now = pre;
        }
    }
    return mincost;
}

```

```

/***** ***/

```

网络中最小费用最大流 $O(V \cdot E^2)$  邻接表SPFA实现

参数含义:  $n$ 代表网络中的总节点数,第 $s$ 节点为源点, 第 $t$ 节点为汇点

$net$ 代表剩余网络

$path[]$ 保存增广路径

$ecost[]$ 源点到各点的最短路

返回值: 最小费用, 最大流量

```

*****/

```

```

// POJ 3422

```

```

const int NMAX = 5100; // 点数

```

```

const int MMAX = 30000; // 边数

```

```

const int INF = 0x7f7f7f7f;

```

```

int path[NMAX], ecost[NMAX];

```

```

int n;

```

```

int s, t;

```

```

struct EDGE {

```

```

    int u, v, cap, cost, flow;
    int next;
    EDGE(int _u=0, int _v=0, int _c=0, int _ct=0, int _f=0)
        : u(_u), v(_v), cap(_c), flow(_f), cost(_ct) {}
};

const int ENDFLAG = -1;
struct EDGELIST {
    int start[NMAX];
    int last[NMAX];
    int tot;
    EDGE arc[MMAX];
    void clear() {
        tot = ENDFLAG + 1;
        memset(last, ENDFLAG, sizeof(last));
    }
    void push_back(EDGE edge) {
        edge.next = ENDFLAG;
        arc[tot] = edge;
        if (last[edge.u] != ENDFLAG) arc[ last[edge.u] ].next = tot;
        else start[edge.u] = tot;
        last[edge.u] = tot;
        tot ++;
    }
    // 创建双向弧
    void add_arc(EDGE edge) {
        push_back(edge);
        push_back(EDGE(edge.v, edge.u, 0, INF));
    }
}net;

int que[2][NMAX];
int qf[2],qe[2],qnow;

#define push_que(a) (que[qnow][ qe[qnow]++ ] = (a))
#define pop_que2  (que[qnow^1][ qf[qnow^1]++ ])
#define switch_que qnow ^= 1; \
                    qf[qnow] = qe[qnow] = 0;
#define empty_que2  (qf[qnow^1] >= qe[qnow^1])
#define size_que2  (qe[qnow^1] - qf[qnow^1])

bool SPFA()
{
    int i,j;
    bitset <NMAX> vis;

```

```

memset(ecost, 0x7f, sizeof(ecost));
memset(path, -1, sizeof(path));

bool flag = true;
qnow = 1;
switch_que;
push_que(s);
vis[s] = 1;
ecost[s] = 0;

for (j=0; j<n && flag; j++)
{
    flag = false;
    switch_que;
    int l = size_que2;
    while (l --)
    {
        int now = pop_que2;
        vis[now] = 0;
        for (i=net.start[now]; i!=ENDFLAG; i=net.arc[i].next)
        {
            EDGE ed = net.arc[i];
            if (ed.cap>ed.flow && ecost[ed.v]>ecost[now]+ed.cost)
            {
                flag = true;
                ecost[ed.v] = ecost[now]+ed.cost;
                path[ed.v] = i;
                if (! vis[ed.v])
                {
                    vis[ed.v] = 1;
                    push_que(ed.v);
                }
            }
        }
    }
}

return ecost[t] != INF;
}

int min_cost_max_flow()
{
    int i,j;
    int mincost = 0, maxflow = 0;

```

```

while( SPFA() ) {
    int pre = path[t];
    int neck = INT_MAX;
    while(pre != -1) {
        int res = net.arc[pre].cap - net.arc[pre].flow;
        neck = min(neck, res);
        pre = path[net.arc[pre].u];
    }
    maxflow += neck;
    mincost += ecost[t] * neck;
    pre = path[t];
    while(pre != -1) {
        net.arc[pre].flow += neck;
        net.arc[pre^1].flow -= neck;
        net.arc[pre^1].cost = - net.arc[pre].cost;
        pre = path[net.arc[pre].u];
    }
}
return mincost;
}

```

## 9. 网络最大流(高度标号预流推进)

/\*

函数接口: `int Relabel_To_Front(int s,int d)`  $O(V^2 \cdot \sqrt{E})$

参数含义: `s` 为源点, `d` 为汇点

返回值 : 网络最大流

调用函数前的初始化工作:`ver` 置为网络中节点的个数, `c[i][j]`代表节点 `i` 到节点 `j` 的流量, `vl[i]`存放 `i` 与相邻的所有节点  
其它全局变量均初始化为零

\*/

`const int VEX = 405;` //网络中顶点数

`const int HMAX = 810;` //最大高度的定义,只要大于顶点的 2 倍就可以了

`int f[VEX][VEX];` //流量

`int c[VEX][VEX];` //边最大容量

`int h[VEX];` //节点高度

`int e[VEX];` //节点容量

`int ver;` //节点数目

`vector<int> vl[VEX];` //邻接表, `vl[i]`存放与 `i` 相邻的节点

`void Push(int u,int v)` //流推进, 由节点 `u` 推向 `v`

{

`int cf = c[u][v] - f[u][v];` //u,v 边的容量

```

    int d = e[u] < cf ? e[u] : cf;

    f[u][v] += d;
    f[v][u] = -f[u][v];
    e[u] -= d;
    e[v] += d;
}

void Relabel(int u) //对 u 重新标号
{
    int i,t,cf;
    int hmin = HMAX;

    for(i = 0 ; i < vl[u].size() ; i++){ //寻找相邻最低点
        t = vl[u][i];
        cf = c[u][t] - f[u][t];
        if(cf > 0 && h[u] <= h[t] && h[t] < hmin)
            hmin = h[t];
    }
    h[u] = hmin + 1;
}

void Init_Preflow(int s) //初始化网络流，s 为源点
{
    int i;
    int u;

    h[s] = ver; //初始化高度
    for(i = 0 ; i < vl[s].size() ; i++){
        u = vl[s][i];
        f[s][u] = c[s][u];
        f[u][s] = -c[s][u];
        e[u] = c[s][u];
        e[s] -= c[s][u];
    }
}

void Discharge(int u)
{
    int i = 0;
    int cf,v;

    if(vl[u].size() == 0) return;
    while(e[u] > 0){

```

```

        if(i < vl[u].size()) {
            v = vl[u][i];
            cf = c[u][v] - f[u][v];
        }
        if(i >= vl[u].size()){
            Relabel(u);
            i = 0;
        }
        else if(cf > 0 && h[u] == h[v] + 1)
            Push(u,v);
        else
            i++;
    }
}

int Relabel_To_Front(int s,int d) //s 为源点, d 为汇点
{
    int u,i,old_h;
    list<int> l;
    list<int>::iterator iter;

    Init_Preflow(s);

    iter = l.begin();
    for(i = 0 ; i < ver ; i++){
        if(i != s && i != d)
            l.insert(iter,i);
    }
    iter = l.begin();
    while(iter != l.end()){
        u = *iter;
        old_h = h[u];
        Discharge(u);
        if(h[u] > old_h){
            l.erase(iter);
            l.insert(l.begin(),u);
            iter = l.begin();
        }
        iter++;
    }
    return e[ver - 1];
}

```

## 10. 最大团

```

/**** ***/
*   Function Name :           最大独立集，最大团
*   Description :           PKU 1419 Graph Coloring
*   团：指G的一个完全子图，该子图不包含在任何其他的完全子图当中
*   最大独立集：补图的最大团
*   最大团：指其中包含顶点最多的团
**** ***/

#include <cstdio>
#include <string>
#define NMAX 110
bool path[NMAX][NMAX];
int n, mmax;
int dp[NMAX];
bool v[NMAX];
int seq[NMAX], seq_pos;
//seq记录最大团集合
bool dfs(int pos, int size)
{
    int i, j, unvis;
    bool tv[NMAX];

    unvis = 0;
    for (i=pos; i<n; i++) {
        if (!v[i]) {
            unvis ++;
        }
    }
    if (unvis == 0) { //|U| = 0
        if (size > mmax) {
            mmax = size;
            seq_pos = 0;
            seq[ seq_pos ++] = pos+1;
            return true;
        }
        return false;
    }

    for (i=pos; i < n && unvis > 0 ; i++) {
        if (!v[i]) {
            if (unvis + size <= mmax || dp[i] + size <= mmax) {
                return false;
            }
            v[i] = true; //U = U\{vi}
            unvis --;

```

```

        memcpy(tv, v, sizeof(v));
        for (j=0;j<n;j++) { //U ∩ N(vi);
            if (!path[i][j]) {
                v[j] = true;
            }
        }
        if ( dfs(i, size+1) ) {
            seq[ seq_pos ++ ] = pos+1;
            return true;
        }
        memcpy(v, tv, sizeof(v));
    }
} //while U is not empty
return false;
}

```

```

int max_clique()
{
    int i,j;
    mmax = 0;

    for (i=0;i<n;i++) {
        path[i][i] = false;
    }
    for (i=n-1;i>=0;i--) {
        for (j=0;j<n;j++) { //Si ∩ N(vi);
            v[j] = !path[i][j];
        }
        dfs(i, 1);
        dp[i] = mmax;
    }
    return mmax;
}

```

```

int main()
{
    int i,j,x,y,e;
    int m,tn;
    scanf("%d", &m);
    while (m --) {
        scanf("%d %d", &n, &e);
        memset(path,0,sizeof(path));
        for (i=0;i<e;i++) {
            scanf("%d %d", &x,&y);

```



```

        x--;y--;
        path[x][y] = path[y][x] = true;
    }
    //max independent set in original graph
    //max clique in inverse graph
    for (i=0;i<n;i++) {
        for (j=0;j<n;j++) {
            path[i][j] = !path[i][j];
        }
    }
    memset(dp,0,sizeof(dp));
    printf("%d\n", max_clique());

    printf("%d", seq[0]);
    for (i=1;i<seq_pos;i++) {
        printf(" %d", seq[i]);
    }
    printf("\n");
}
}

```

## 11. 最大二分图匹配(匈牙利算法)

```

/***** *****/
*   Function Name :    最大二分图匹配(匈牙利算法)
*   Description :    HDOJ 2063 过山车
*   二分图: 指所有顶点分成集合 M 和 N, M 或 N 中任意两个在同一集合中的点互不相连
*   匹配: 一组边顶点分别在两个集合中, 并且任意两条边都没有相同顶点
*   最大匹配: 所能得到的最大的边的个数
*****/
#include<cstdio>
#include<memory>
#include<vector>
using namespace std;
const int Max=1100;
vector< vector<int> > Bmap;
int n, m, k, nm;
int mark[Max];
bool flag[Max];

bool dfs(int pos)
{
    int i, pre, tp;
    for(i=0; i < Bmap[pos].size() ;i++) {
        tp = Bmap[pos][i];
    }
}

```

```

        if( !flag[tp] ) {
            flag[tp] = true;
            pre = mark[tp];
            mark[tp] = pos;
            if(pre==-1 || dfs(pre))    return true;
            mark[tp] = pre;
        }
    }
    return false;
}

inline int Max_Match()
{
    int mmax = 0, i;
    for(i=1; i <= m ;i++) {
        memset(flag,0,sizeof(flag));
        if( dfs(i) )    mmax++;
    }
    return mmax;
}

int main()
{
    int i, j, id, id2;
    while(scanf("%d", &k)==1 && k) {
        scanf("%d%d",&m, &n);
        nm = n + m;
        Bmap.clear();    Bmap.resize(nm+10);
        memset(mark,-1,sizeof(mark));
        for(j=0; j < k ;j++) {
            scanf("%d %d", &id, &id2);
            id2 += m;
            Bmap[id].push_back(id2);
        }
        printf("%d\n", Max_Match());
    }
}

// 二分匹配HopcroftKarp算法O(sqrt(V)*E)
// 贪心一个初始匹配可以加速
#include <iostream>
#include <queue>
using namespace std;

const int MAXN = 3002;

```

```
const int INF = 1<<30;

struct node{
    int x, y;
}G[MAXN], U[MAXN];

int n, m, t, nx, ny, dis;
int x[MAXN], y[MAXN], vs[MAXN];
int Isf[MAXN];
bool adj[MAXN][MAXN];
int ds[MAXN], dt[MAXN];

void input(){
    scanf("%d %d", &t, &m);
    for(int i = 0; i < m; i++){
        scanf("%d %d %d", &G[i].x, &G[i].y, &vs[i]);
        vs[i] *= vs[i];
    }
    scanf("%d", &n);
    for(int i = 0; i < n; i++){
        scanf("%d %d", &U[i].x, &U[i].y);
    }
    memset(adj, 0, sizeof(adj));
    if(m < n){
        nx = m, ny = n;
        for(int i = 0; i < m; i++){
            for(int j = 0; j < n; j++){
                int a = G[i].x - U[j].x, b = G[i].y - U[j].y;
                if( (a*a + b*b) < vs[i]*t*t)
                    adj[i][j] = 1;
            }
        }
    }else{
        nx = n, ny = m;
        for(int i = 0; i < n; i++){
            for(int j = 0; j < m; j++){
                int a = G[j].x - U[i].x, b = G[j].y - U[i].y;
                if( (a*a + b*b) <= vs[j]*t*t)
                    adj[i][j] = 1;
            }
        }
    }
}

bool Search() {
    memset(ds, -1, sizeof(ds));
    memset(dt, -1, sizeof(dt));
}
```

```

queue<int> Q; dis = INF;
for(int i = 0; i < nx; i++)
    if(x[i] == -1){
        Q.push(i);
        ds[i] = 0;
    }
while(!Q.empty()) {
    int u = Q.front(); Q.pop();
    if(ds[u] > dis) break;
    for(int v = 0; v < ny; v++){
        if(adj[u][v]){
            if(dt[v] != -1) continue;
            dt[v] = ds[u]+1;
            if(y[v] == -1) dis = dt[v];
            else{
                ds[y[v]] = dt[v]+1;
                Q.push(y[v]);
            }
        }
    }
}
return (dis != INF);
}

bool DFS(int u) {
    for(int v = 0; v < ny; v++){
        if(!Isf[v] && adj[u][v] && dt[v] == ds[u] + 1){
            Isf[v] = true;
            if(y[v] != -1 && dt[v] == dis) continue;
            if(y[v] == -1 || DFS(y[v])){
                y[v] = u; x[u] = v;
                return 1;
            }
        }
    }
    return 0;
}

int HopcroftKarp() {
    int cnt = 0;
    for(int i = 0; i < nx; i++) x[i] = -1;
    for(int i = 0; i < ny; i++) y[i] = -1;
    while(Search()){
        memset(Isf, 0, sizeof(Isf));
    }
}

```

```

        for(int i = 0; i < nx; i++)
            if(ds[i] == 0 && DFS(i))
                cnt++;
    }
    return cnt;
}

int main(){
    int test;
    scanf("%d", &test);
    for(int k = 1; k <= test; k++){
        input();
        printf("Scenario #%d:\n%d\n\n", k, HopcroftKarp());
    }
    return 0;
}

```

## 12. 带权二分图最优匹配(KM 算法)

//二分图带权匹配 $O(N^3)$

```
const int MAXN = 509;
```

```
const int INF = 0x1fffffff;
```

```

int bpCostMatch(int c[][MAXN], int nx, int ny) {
    static int lx[MAXN], ly[MAXN], slack[MAXN];
    static int open[MAXN], prev[MAXN], pnt[MAXN], x[MAXN], y[MAXN];
    int i, j, k, s, head, tail;
    int d, ans = 0;

    if (nx > ny) ny = nx;
    for (i = 0; i < nx; i++) lx[i] = -INF;
    for (i = 0; i < ny; i++) ly[i] = 0;
    for (i = 0; i < nx; i++)
        for (j = 0; j < ny; j++)
            if ((lx[i] - c[i][j]) < 0)
                lx[i] = c[i][j];
    memset(x, -1, sizeof(x)); memset(y, -1, sizeof(y));
    for (i = 0; i < nx; i++) {
        memset(prev, -1, sizeof(prev));
        for (j = 0; j < ny; j++) slack[j] = INF;
        open[0] = i; head = 0; tail = 1;
        while (x[i] < 0) {
            for (; head < tail && x[i] < 0; head++)
                for (s = open[head], j = 0; j < ny && x[i] < 0; j++)
                    if (prev[j] < 0) {

```

```

        if ((d = lx[s] + ly[j] - c[s][j]) > 0) {
            if ((slack[j] - d) > 0) {
                slack[j] = d; pnt[j] = s;
            }
            continue;
        }
        open[tail++] = y[j]; prev[j] = s;
        if (y[j] >= 0) continue;
        while (j >= 0) {
            s = prev[j]; y[j] = s; k = x[s]; x[s] = j; j = k;
        }
    }
    if (x[i] >= 0) break;
    for (d = INF, j = 0; j < ny; j++)
        if (prev[j] < 0 && (d - slack[j]) > 0)
            d = slack[j];
    for (j = 0; j < tail; j++) lx[open[j]] -= d;
    for (j = 0; j < ny; j++)
        if (prev[j] >= 0)
            ly[j] += d;
        else if (slack[j] < INF)
            slack[j] -= d;
    for (j = 0; j < ny; j++)
        if (prev[j] < 0 && slack[j] == 0) {
            open[tail++] = y[j]; prev[j] = pnt[j];
            if (y[j] >= 0) continue;
            while (j >= 0) {
                s = prev[j]; y[j] = s; k = x[s]; x[s] = j; j = k;
            }
            break;
        }
    }
}

for (i = 0; i < nx; i++)
    if (c[i][x[i]] > -INF) {
        if (c[i][x[i]] < 0)
            return -1;
        ans += c[i][x[i]];
    } else return -1;
return ans;
}

int N, M, E;
int c[MAXN][MAXN];

```

```

int cas;

int main() {
    int i, j, a, b, w, ans;
    while (scanf("%d%d%d", &N, &M, &E) != EOF) {
        for (i = 0; i < N; i++)
            for (j = 0; j < M; j++)
                c[i][j] = -INF;
        for (i = 0; i < E; i++) {
            scanf("%d%d%d", &a, &b, &w);
            if (w < 0) continue;
            if (c[a][b] < w)
                c[a][b] = w;
        }
        if (N > M) ans = -1;
        else ans = bpCostMatch(c, N, M);
        printf("Case %d: %d\n", ++cas, ans);
    }
    return 0;
}

```

/\*  
wywcgs 的KM  $O(n^3)$   
只需要把Graph里的n(顶点数)和edge[x][y](边权)赋值，第一维为x点，第二维为y点。  
然后调用KMMatch()函数即可，返回值为最大权完美匹配。  
最小权匹配可将每条边权取反，然后类似求最大权匹配即可。  
匹配信息保存在xmate[]和ymate[]中。其中xmate[i]为x[i]的匹配点，ymate[i]为y[i]的匹配点。

```

*/
#include <cstdio>
#include <queue>
#include <algorithm>
using namespace std;

const int N = 310;
const int INF = 1 << 28;

class Graph {
private:
    bool xckd[N], yckd[N];
    int n, edge[N][N], xmate[N], ymate[N];
    int lx[N], ly[N], slack[N], prev[N];
    queue<int> Q;
    bool bfs();

```

```

    void agument(int);
public:
    bool make();
    int KMMatch();
};

bool Graph::bfs() {
    while(!Q.empty()) {
        int p = Q.front(), u = p>>1; Q.pop();
        if(p&1) {
            if(ymate[u] == -1) { agument(u); return true; }
            else { xckd[ymate[u]] = true; Q.push(ymate[u]<<1); }
        } else {
            for(int i = 0; i < n; i++)
                if(yckd[i]) continue;
            else if(lx[u]+ly[i] != edge[u][i]) {
                int ex = lx[u]+ly[i]-edge[u][i];
                if(slack[i] > ex) { slack[i] = ex; prev[i] = u; }
            } else {
                yckd[i] = true; prev[i] = u;
                Q.push((i<<1)|1);
            }
        }
    }
    return false;
}

void Graph::agument(int u) {
    while(u != -1) {
        int pv = xmate[prev[u]];
        ymate[u] = prev[u]; xmate[prev[u]] = u;
        u = pv;
    }
}

int Graph::KMMatch() {
    memset(ly, 0, sizeof(ly));
    for(int i = 0; i < n; i++) {
        lx[i] = -INF;
        for(int j = 0; j < n; j++) lx[i] >?= edge[i][j];
    }
    memset(xmate, -1, sizeof(xmate)); memset(ymate, -1, sizeof(ymate));
    bool agu = true;
    for(int mn = 0; mn < n; mn++) {
        if(agu) {
            memset(xckd, false, sizeof(xckd));
            memset(yckd, false, sizeof(yckd));

```



```

        for(int i = 0; i < n; i++) slack[i] = INF;
        while(!Q.empty()) Q.pop();
        xckd[mn] = true; Q.push(mn<<1);
    }
    if(bfs()) { agu = true; continue; }
    int ex = INF; mn--; agu = false;
    for(int i = 0; i < n; i++)
        if(!yckd[i]) ex <= slack[i];
    for(int i = 0; i < n; i++) {
        if(xckd[i]) lx[i] -= ex;
        if(yckd[i]) ly[i] += ex;
        slack[i] -= ex;
    }
    for(int i = 0; i < n; i++)
        if(!yckd[i] && slack[i] == 0) { yckd[i] = true; Q.push((i<<1)|1); }
    }
    int cost = 0;
    for(int i = 0; i < n; i++) cost += edge[i][xmate[i]];
    return cost;
}

bool Graph::make()
{
    int i, j;
    while (scanf("%d", &n) == 1)
    {
        for (i = 0; i < n; i++)
            for (j = 0; j < n; j++)
                scanf("%d", &edge[i][j]);
        return true;
    }
    return false;
}

int main()
{
    Graph g;

    while(g.make()) printf("%d\n", g.KMMatch());

    return 0;
}

```

### 13. 强连通分量(Kosaraju 算法)

```

/*
有向图的强连通分量Kosaraju算法O(E)
参数含义：    使用邻接表来保存图
               path原图，npath逆图
               scc强连通个数
               id[x]=y表示第x个顶点属于y强连通
*/
#define NMAX 11000
vector< vector< int > > path;
vector< vector< int > > npath;
int n,m, scc;
int order[NMAX], order_pos, id[NMAX];
bool vis[NMAX];

void dfs(int pos)
{
    int i,j,l;
    vis[pos] = true;
    l = path[pos].size();
    for (i=0;i<l;i++) {
        j = path[pos][i];
        if (!vis[j]) {
            dfs(j);
        }
    }
    order[ order_pos ++ ] = pos;//make order
}

void ndfs(int pos)
{
    int i,j,l;
    vis[pos] = true;
    id[pos] = scc;
    l = npath[pos].size();
    for (i=0;i<l;i++) {
        j = npath[pos][i];
        if (!vis[j]) {
            ndfs(j);
        }
    }
}

void Kosaraju()
{

```

```

int i,j;
//dfs in original graph
memset(vis, 0, sizeof(vis));
order_pos = 0;
for (i=1; i<=n ;i++) {
    if (!vis[i]) {
        dfs(i);
    }
}
//dfs in inverse graph
memset(vis, 0, sizeof(vis));
memset(id, 0, sizeof(id));
scc = 1;
for (i=order_pos-1; i>=0 ;i--) {
    if (!vis[ order[i] ]) {
        ndfs(order[i]);
        scc ++;
    }
}
scc --;
}

```

## 14. 强连通分量(**Gabow** 算法)

```

/*
有向图的强连通分量Gabow算法O (E)
参数含义：    使用邻接表来保存图
               path原图
               scc强连通个数
               id[x]=y表示第x个顶点属于y强连通
*/

```

```

#define NMAX 11000
vector< vector< int > > path;
int n,m, scc, step;
int order[NMAX], order_pos, id[NMAX];
int order2[NMAX], order2_pos;
int vis[NMAX];

void dfs(int pos)
{
    int i,j,next,l,pre;
    vis[pos] = step ++;
    order[ order_pos ++ ] = pos;
    order2[ order2_pos ++ ] = pos;
    l = path[pos].size();

```

```

for (i=0;i<l;i++) {
    next = path[pos][i];
    if (vis[next] == 0) {
        dfs(next);
    }
    else if (id[next] == 0) {//have a circle and belong to nothing
        while (vis[ order2[order2_pos -1] ] > vis[next]) {
            order2_pos --;
        }
    }
} //for i
if (order2[order2_pos -1] == pos) {//if pos back to begin of scc
    order2_pos --;
}
else {
    return ;
}
do {//record scc
    pre = order[order_pos -1];
    id[pre] = scc;
    order_pos --;
} while(pre != pos);
scc ++;
}

void Gabow()
{
    int i,j,l;
    //dfs in original graph
    memset(id, 0, sizeof(id));
    memset(vis, 0, sizeof(vis));
    scc = step = 1;
    order_pos = order2_pos = 0;
    for (i=1; i<=n ;i++) {
        if (vis[i] == 0) {
            dfs(i);
        }
    }
    scc --;
}

```

## 15. 无向图割边割点和双连通分量

```

#define mclear(x) memset((x), 0, sizeof((x)))
const int MAX = 5100;

```

```

int n,m,deep;
vector<int> path[MAX];
int vis[MAX], low[MAX];
vector<int> cutpoint;//割点
vector< pair<int,int> > bridge;//割边,桥
int nbcc;//双连通分量数
stack< pair<int,int> > order;
vector<int> bcc[MAX];//双连通分量

void dfs(int pos, int father) {
    int i,j, total = 0;
    bool cut = false;
    int reback = 0;//处理平行边
    vis[pos] = low[pos] = deep ++;
    int ls = path[pos].size();
    for(j=0;j<ls;j++) {
        i = path[pos][j];
        if(i == father) reback ++;
        if(vis[i] == 0) {
            pair<int,int> e(pos, i);
            order.push(e);
            dfs(i, pos);
            if(low[i] >= vis[pos]) {
                nbcc ++;
                bcc[nbcc].clear();
                pair<int,int> r;
                do {
                    r = order.top();
                    order.pop();
                    bcc[nbcc].push_back(r.second);
                }while(e != r);
                bcc[nbcc].push_back(r.first);
            }
            total ++;
            low[pos] = min(low[i], low[pos]);
            if((vis[pos] == 1 && total > 1) ||
                (vis[pos] != 1 && low[i] >= vis[pos])) cut = true;
            if(low[i] > vis[pos]) bridge.push_back(e);
        }
        else if(i != father) {
            low[pos] = min(vis[i], low[pos]);
        }
    }
    if(reback > 1) low[pos] = min(low[pos], vis[father]);
}

```

```

        if(cut) cutpoint.push_back(pos);
    }

    void find_cut() {
        int i;
        mclear(vis); mclear(low);
        cutpoint.clear(); bridge.clear();
        nbcc = 0;
        while(!order.empty()) order.pop();
        for(i=1;i<=n;i++) {
            if(vis[i] == 0) {
                deep = 1;
                dfs(i, i);
            }
        }
    }
}

```

/\*\*\*\*\*\*

图的DFS信息构建by oyjpArt

g矩阵: g[i][j] -> 0 : 无边

1 : 可重复访问边

-1: 非可重复访问边

说明:以为在无向图中u->v访问之后就不能再从v->u访问了

故{u, v}访问了之后{v, u}要置-1

如果有向图则没有这个规则

gc矩阵:gc[i][j]-> 0 : 无边

1 : 树枝边

2 : 反向边

3 : 正向边

4 : 交叉边

d数组: 顶点的开始访问时间表

f数组: 顶点的结束访问时间表

c数组: 顶点颜色表0白色-1灰色1黑色

p数组: 顶点的前驱表

l数组: 顶点的L值(最顶层的祖先层数)

b数组: 顶点的度数表

关于标号函数LOW()

LOW(U)代表的是与U以及U的子孙直接相连的结点的最高辈分(深度)

d[U] U首次被访问时

LOW[U] = min(LOW[U], d[W]) 访问边{U,W}

min(LOW[U], LOW[S]) U的儿子S的关联边全部被访问时

/\*\*\*\*\*\*

```
const int maxn = 100;
```

```
int n, g[maxn][maxn], gc[maxn][maxn];
```

```

int d[maxn], f[maxn], l[maxn], p[maxn], c[maxn], b[maxn];
int time;

void dfs_visit(int u) { //递归搜索以U为根的深度优先树
    int v;
    c[u] = -1;          //置顶点为灰色//去掉这句之后适用于有向图(后面设置不可访问亦同)
    time++; d[u] = time, l[u] = time;
    for(v = 1; v <= n; v++)
        if(g[u][v] > 0)
            if(c[v] == 0) { //如果v是白色节点
                g[v][u] = -1; //不可再访问
                gc[u][v] = 1; //树枝边
                b[u]++;        //度数
                p[v] = u;      //记录父亲节点
                dist_visit(v); //递归搜索以v为根的深度优先树
                if(l[v] < l[u]) //v是u的后代
                    l[u] = l[v]; //u的儿子v的关联边搜索完后计算父亲的low值
                g[v][u] = 1;    //恢复可访问标志
            } else {
                if(c[v] < 0) { //若顶点为灰色
                    if(l[v] < l[u]) //u与v相连
                        l[u] = l[v];
                    gc[u][v] = 2; //反向边
                } else { //黑色
                    if(d[v] > d[u])
                        gc[u][v] = 3; //正向边
                    else
                        gc[u][v] = 4; //交叉边
                }
            }
    c[u] = 1; //DFS完毕置黑色吧
    time++; f[u] = time;
}

void dfs() {
    int u;
    memset(gc, 0, sizeof(gc));
    memset(c, 0, sizeof(c));
    memset(b, 0, sizeof(b));
    time = 0;
    for(u = 1; u <= n; u++)
        if(c[u] == 0) {
            p[u] = 0;

```

```

        dfs_visit(u);
    }
}

```

## 16. 最小树形图 $O(N^3)$

/\*

最小树形图  $O(N^3)$

参数含义: 使用邻接矩阵来保存图, 邻接表  $O(VE)$

path原图

pre保存最小入弧的权

del表示被缩去的点

fpre保存最小树形图的逆路径

例题: TJU 2248 Channel Design

\*/

```

const int NMAX = 110;
const int INF = 0x7f7f7f7f;
int n;
int path[NMAX][NMAX];
int pre[NMAX];
bool vis[NMAX], del[NMAX];
int min_cost;
int fold[NMAX], fpre[NMAX];
void dfs(int pos) {
    int i;
    vis[pos] = true;
    for(i=1; i<=n; i++) {
        if(path[pos][i] != INF && !vis[i]) dfs(i);
    }
}
bool is_connect(int root) {
    int i;
    memset(vis, 0, sizeof(vis));
    dfs(root);
    for(i=1; i<=n; i++) {
        if(!vis[i]) return false;
    }
    return true;
}
//O(N^3)
bool min_tree_graph(int root) {
    int i, j, k;
    //make sure every node(except root) have in-arc
    if(!is_connect(root)) return false;
}

```



```

memset(del, 0, sizeof(del));
min_cost = 0;
for(i=0;i<=n;i++) fold[i] = fpre[i] = i;
while(true) {
    for(i=1;i<=n;i++) {
        if(del[i] || i == root) continue;
        pre[i] = i;
        path[i][i] = INF;//delete self-cycle
        for(j=1;j<=n;j++) {
            if(del[j]) continue;
            if(path[j][i] < path[ pre[i] ][i]) pre[i] = fpre[fold[i]] = j;
        }
    }//find min in-arc
    for(i=1;i<=n;i++) {
        if(del[i] || i == root) continue;
        j = i;
        memset(vis, 0, sizeof(vis));
        while(!vis[j] && j != root) {
            vis[j] = true;
            j = pre[j];
        }
        if(j == root) continue;//no cycle
        i = j;//cycle begin node
        min_cost += path[ pre[i] ][i];
        for(j=pre[i]; j != i ;j=pre[j]) {
            del[j] = true;//fold cycle
            min_cost += path[ pre[j] ][j];//add cycle cost
        }
        for(j=1;j<=n;j++) {
            if(del[j]) continue;
            if(path[j][i] != INF) path[j][i] -= path[ pre[i] ][i];
        }//i is new fold node
        for(j=pre[i]; j != i ;j=pre[j]) {
            for(k=1;k<=n;k++) {
                if(del[k]) continue;
                path[i][k] = min(path[i][k], path[j][k]);
                if(path[k][j] != INF && path[k][i] > path[k][j] -
path[ pre[j] ][j]) {
                    path[k][i] = path[k][j] - path[ pre[j] ][j];
                    fold[i] = j;//record fold node
                    fpre[i] = j;
                }
            }
        }
    }//make new graph
}

```

```

        break;
    }
    if(i > n) {
        for(i=1;i<=n;i++) {
            if(del[i] || i == root) continue;
            min_cost += path[ pre[i] ][i];
        }
        break;
    } //graph no cycle
} //while have cycle
return true;
}
//print path in min tree graph
void print_mtg(int root) {
    int i, total = n;
    memset(vis, 0, sizeof(vis));
    for(i=1;i<=n;i++) vis[fpre[i]] = true;
    for(i=1;i<=n;i++) {
        if(!vis[i]) {
            int pos = i;
            while(pos != root) {
                printf("%d <- ", pos);
                pos = fpre[pos];
            }
            printf("%d\n", root);
        }
    }
}
}
int main() {
    int i,m;
    while(scanf("%d %d", &n,&m), !(n==0 && m==0)) {
        memset(path, 0x7f, sizeof(path));
        while(m--) {
            int x,y,z;
            scanf("%d %d %d", &x,&y,&z);
            path[x][y] = min(path[x][y], z);
        }
        if( !min_tree_graph(1) ) puts("impossible");
        else printf("%d\n", min_cost);
    }
}

```

## 17. 最小树形图 **O(VE)**

```
const int NMAX = 1500;
```

```

const int INF = 0x7f7f7f7f;
struct LINKT {
    int ls;
    int adj[NMAX];
    void clear() {ls = 0;}
    int operator [] (const int pos) {return adj[pos];}
    int size() {return ls;}
    void push_back(const int pos) {adj[ls++] = pos;}
};
int n;
int path[NMAX][NMAX];
LINKT epath[NMAX], npath[NMAX];
int pre[NMAX];
bool vis[NMAX], del[NMAX];
int min_cost;
int fold[NMAX], fpre[NMAX];
void dfs(int pos) {
    int i;
    vis[pos] = true;
    for(i=0;i<epath[pos].ls;i++) {
        if(!vis[epath[pos].adj[i]]) dfs(epath[pos].adj[i]);
    }
}
bool is_connect(int root) {
    int i;
    memset(vis, 0, sizeof(vis));
    dfs(root);
    for(i=1;i<=n;i++) {
        if(!vis[i]) return false;
    }
    return true;
}
//O(VE)
bool min_tree_graph(int root) {
    int i,j,k;
    //make sure every node(except root) have in-arc
    if(!is_connect(root)) return false;
    memset(del, 0, sizeof(del));
    min_cost = 0;
    for(i=0;i<=n;i++) fold[i] = fpre[i] = i;
    while(true) {
        for(i=1;i<=n;i++) {
            if(del[i] || i == root) continue;
            pre[i] = i;

```

```

    path[i][i] = INF;//delete self-cycle
    for(j=0;j<nepath[i].ls;j++) {
        int t = nepath[i].adj[j];
        if(del[t]) continue;
        if(path[t][i] < path[ pre[i] ][i]) pre[i] = fpre[fold[i]] = t;
    }
} //find min in-arc
for(i=1;i<=n;i++) {
    if(del[i] || i == root) continue;
    j = i;
    memset(vis, 0, sizeof(vis));
    while(!vis[j] && j != root) {
        vis[j] = true;
        j = pre[j];
    }
    if(j == root) continue;//no cycle
    i = j;//cycle begin node
    min_cost += path[ pre[i] ][i];
    for(j=pre[i]; j != i ;j=pre[j]) {
        del[j] = true;//fold cycle
        min_cost += path[ pre[j] ][j];//add cycle cost
    }
    for(j=0;j<nepath[i].ls;j++) {
        int t = nepath[i].adj[j];
        if(del[t]) continue;
        path[t][i] -= path[ pre[i] ][i];
    } //i is new fold node
    for(j=pre[i]; j != i ;j=pre[j]) {
        for(k=0;k<epath[j].ls;k++) {
            int t = epath[j].adj[k];
            if(del[t]) continue;
            if(path[i][t] == INF) {
                epath[i].push_back(t);
                nepath[t].push_back(i);
            }
            path[i][t] = min(path[i][t], path[j][t]);
        }
        for(k=0;k<nepath[j].ls;k++) {
            int t = nepath[j].adj[k];
            if(del[t]) continue;
            if(path[t][i] == INF) {
                epath[t].push_back(i);
                nepath[i].push_back(t);
            }
        }
    }
}

```

```

        if(path[t][i] > path[t][j] - path[ pre[j] ][j]) {
            path[t][i] = path[t][j] - path[ pre[j] ][j];
            fold[i] = j;//record fold node
            fpre[i] = j;
        }
    }
}
} //make new graph
break;
}
if(i > n) {
    for(i=1;i<=n;i++) {
        if(del[i] || i == root) continue;
        min_cost += path[ pre[i] ][i];
    }
    break;
} //graph no cycle
} //while have cycle
return true;
}

```

**18.**

## 第六章 几何算法

```

/*****
* COMPUTATIONAL GEOMETRY ROUTINES
* WRITTEN BY : LIU Yu (C) 2003
*****/

// 叉乘
// 两个点的距离
// 点到直线距离
// 返回直线  $Ax + By + C = 0$  的系数
// 线段
// 圆
// 两个圆的公共面积
// 矩形
// 根据下标返回多边形的边
// 两个矩形的公共面积
// 多边形 ,逆时针或顺时针给出 x,y
// 多边形顶点
// 多边形的边
// 多边形的周长

```

```

// 判断点是否在线段上
// 判断两条线断是否相交，端点重合算相交
// 判断两条线断是否平行
// 判断两条直线断是否相交
// 直线相交的交点
// 判断是否简单多边形
// 求多边形面积
// 判断是否在多边形上
// 判断是否在多边形内部
// 点阵的凸包，返回一个多边形
// 最近点对的距离

#include <cmath>
#include <cstdio>
#include <memory>
#include <algorithm>
#include <iostream>
using namespace std;

typedef double TYPE;

#define Abs(x) (((x)>0)?(x):(-(x)))
#define Sgn(x) (((x)<0)?(-1):(1))
#define Max(a,b) (((a)>(b))?(a):(b))
#define Min(a,b) (((a)<(b))?(a):(b))

#define Epsilon 1e-10
#define Infinity 1e+10
#define Pi 3.14159265358979323846

TYPE Deg2Rad(TYPE deg)
{return (deg * Pi / 180.0);}

TYPE Rad2Deg(TYPE rad)
{return (rad * 180.0 / Pi);}

TYPE Sin(TYPE deg)
{return sin(Deg2Rad(deg));}

TYPE Cos(TYPE deg)
{return cos(Deg2Rad(deg));}

TYPE ArcSin(TYPE val)
{return Rad2Deg(asin(val));}

```

```
TYPE ArcCos(TYPE val)
{ return Rad2Deg(acos(val));}
```

```
TYPE Sqrt(TYPE val)
{ return sqrt(val);}
```

```
struct POINT
{
    TYPE x;
    TYPE y;
    TYPE z;
    POINT() : x(0), y(0), z(0) {};
    POINT(TYPE _x_, TYPE _y_, TYPE _z_ = 0) : x(_x_), y(_y_), z(_z_) {};
};
```

```
// cross product of (o->a) and (o->b)
```

```
// 叉乘
```

```
TYPE Cross(const POINT & a, const POINT & b, const POINT & o)
{return (a.x - o.x) * (b.y - o.y) - (b.x - o.x) * (a.y - o.y);}
```

```
// planar points' distance
```

```
// 两个点的距离
```

```
TYPE Distance(const POINT & a, const POINT & b)
{return Sqrt((a.x - b.x) * (a.x - b.x) + (a.y - b.y) * (a.y - b.y) + (a.z - b.z) * (a.z - b.z));}
```

```
struct LINE
```

```
{
    POINT a;
    POINT b;
    LINE() {};
    LINE(POINT _a_, POINT _b_) : a(_a_), b(_b_) {};
};
```

```
//点到直线距离
```

```
double PointToLine(POINT p0 ,POINT p1 ,POINT p2 ,POINT &cp)
{
    double d = Distance(p1 ,p2);
    double s = Cross(p1 ,p2 ,p0) / d;
    cp.x = p0.x + s*( p2.y-p1.y) / d;
    cp.y = p0.y - s*( p2.x-p1.x) / d;
    return Abs(s);
}
```

// 返回直线  $Ax + By + C = 0$  的系数

```
void Coefficient(const LINE & L, TYPE & A, TYPE & B, TYPE & C)
{
    A = L.b.y - L.a.y;
    B = L.a.x - L.b.x;
    C = L.b.x * L.a.y - L.a.x * L.b.y;
}
```

```
void Coefficient(const POINT & p, const TYPE a, TYPE & A, TYPE & B, TYPE & C)
{
    A = Cos(a);
    B = Sin(a);
    C = - (p.y * B + p.x * A);
}
```

// 线段

```
struct SEG
{
    POINT a;
    POINT b;
    SEG() {}
    SEG(POINT _a_, POINT _b_):a(_a_),b(_b_) {}
};
```

// 圆

```
struct CIRCLE
{
    TYPE x;
    TYPE y;
    TYPE r;
    CIRCLE() {}
    CIRCLE(TYPE _x_, TYPE _y_, TYPE _r_) : x(_x_), y(_y_), r(_r_) {}
};
```

```
POINT Center(const CIRCLE & circle)
{ return POINT(circle.x, circle.y);}
```

```
TYPE Area(const CIRCLE & circle)
{ return Pi * circle.r * circle.r;}
```

//两个圆的公共面积

```
TYPE CommonArea(const CIRCLE & A, const CIRCLE & B)
{
    TYPE area = 0.0;
```



```

const CIRCLE & M = (A.r > B.r) ? A : B;
const CIRCLE & N = (A.r > B.r) ? B : A;

TYPE D = Distance(Center(M), Center(N));

if ((D < M.r + N.r) && (D > M.r - N.r))
{
    TYPE cosM = (M.r * M.r + D * D - N.r * N.r) / (2.0 * M.r * D);
    TYPE cosN = (N.r * N.r + D * D - M.r * M.r) / (2.0 * N.r * D);

    TYPE alpha = 2.0 * ArcCos(cosM);
    TYPE beta = 2.0 * ArcCos(cosN);

    TYPE TM = 0.5 * M.r * M.r * Sin(alpha);
    TYPE TN = 0.5 * N.r * N.r * Sin(beta);

    TYPE FM = (alpha / 360.0) * Area(M);
    TYPE FN = (beta / 360.0) * Area(N);

    area = FM + FN - TM - TN;
}
else if (D <= M.r - N.r)
{
    area = Area(N);
}
return area;
}

// 矩形
// 矩形的线段
//      2
//  ----- b
//  |           |
//  3 |           | 1
//  a -----
//      0

struct RECT
{
    POINT a;                // 左下点
    POINT b;                // 右上点
    RECT() {}
    RECT(const POINT & _a_, const POINT & _b_)

```

```
{a = _a_; b = _b_;}
};
```

//根据下标返回多边形的边

```
SEG Edge(const RECT & rect, int idx)
{
    SEG edge;
    while (idx < 0) idx += 4;
    switch (idx % 4)
    {
    case 0:
        edge.a = rect.a;
        edge.b = POINT(rect.b.x, rect.a.y);
        break;
    case 1:
        edge.a = POINT(rect.b.x, rect.a.y);
        edge.b = rect.b;
        break;
    case 2:
        edge.a = rect.b;
        edge.b = POINT(rect.a.x, rect.b.y);
        break;
    case 3:
        edge.a = POINT(rect.a.x, rect.b.y);
        edge.b = rect.a;
        break;
    default:
        break;
    }
    return edge;
}
```

```
TYPE Area(const RECT & rect)
{return (rect.b.x - rect.a.x) * (rect.b.y - rect.a.y);}
```

// 两个矩形的公共面积

```
TYPE CommonArea(const RECT & A, const RECT & B)
{
    TYPE area = 0.0;

    POINT LL(Max(A.a.x, B.a.x), Max(A.a.y, B.a.y));
    POINT UR(Min(A.b.x, B.b.x), Min(A.b.y, B.b.y));

    if ((LL.x <= UR.x) && (LL.y <= UR.y))
```

```

    {
        area = Area(RECT(LL, UR));
    }
    return area;
}

// 多边形 ,逆时针或顺时针给出 x,y
struct POLY
{
    int n;    //n 个点
    TYPE * x;    //x,y 为点的指针, 首尾必须重合
    TYPE * y;
    POLY() : n(0), x(NULL), y(NULL) {};
    POLY(int _n_, const TYPE * _x_, const TYPE * _y_)
    {
        n = _n_;
        x = new TYPE[n + 1];
        memcpy(x, _x_, n*sizeof(TYPE));
        x[n] = _x_[0];

        y = new TYPE[n + 1];
        memcpy(y, _y_, n*sizeof(TYPE));
        y[n] = _y_[0];
    }
};

//多边形顶点
POINT Vertex(const POLY & poly, int idx)
{
    idx %= poly.n;
    return POINT(poly.x[idx], poly.y[idx]);
}

//多边形的边
SEG Edge(const POLY & poly, int idx)
{
    idx %= poly.n;
    return SEG(POINT(poly.x[idx], poly.y[idx]),
        POINT(poly.x[idx + 1], poly.y[idx + 1]));
}

//多边形的周长
TYPE Perimeter(const POLY & poly)
{

```

```

    TYPE p = 0.0;
    for (int i = 0; i < poly.n; i++)
        p = p + Distance(Vertex(poly, i), Vertex(poly, i + 1));
    return p;
}

bool IsEqual(TYPE a, TYPE b)
{return (Abs(a - b) < Epsilon);}

bool IsEqual(const POINT & a, const POINT & b)
{return (IsEqual(a.x, b.x) && IsEqual(a.y, b.y));}

bool IsEqual(const LINE & A, const LINE & B)
{
    TYPE A1, B1, C1;
    TYPE A2, B2, C2;

    Coefficient(A, A1, B1, C1);
    Coefficient(B, A2, B2, C2);

    return IsEqual(A1 * B2, A2 * B1) &&
        IsEqual(A1 * C2, A2 * C1) &&
        IsEqual(B1 * C2, B2 * C1);
}

// 判断点是否在线段上
bool IsOnSeg(const SEG & seg, const POINT & p)
{
    return (IsEqual(p, seg.a) || IsEqual(p, seg.b)) ||
        (((p.x - seg.a.x) * (p.x - seg.b.x) < 0 ||
        (p.y - seg.a.y) * (p.y - seg.b.y) < 0) &&
        (IsEqual(Cross(seg.b, p, seg.a), 0)));
}

//判断两条线断是否相交，端点重合算相交
bool IsIntersect(const SEG & u, const SEG & v)
{
    return (Cross(v.a, u.b, u.a) * Cross(u.b, v.b, u.a) >= 0) &&
        (Cross(u.a, v.b, v.a) * Cross(v.b, u.b, v.a) >= 0) &&
        (Max(u.a.x, u.b.x) >= Min(v.a.x, v.b.x)) &&
        (Max(v.a.x, v.b.x) >= Min(u.a.x, u.b.x)) &&
        (Max(u.a.y, u.b.y) >= Min(v.a.y, v.b.y)) &&
        (Max(v.a.y, v.b.y) >= Min(u.a.y, u.b.y));
}

```

//判断两条线断是否平行

```
bool IsParallel(const LINE & A, const LINE & B)
{
    TYPE A1, B1, C1;
    TYPE A2, B2, C2;

    Coefficient(A, A1, B1, C1);
    Coefficient(B, A2, B2, C2);

    return (A1 * B2 == A2 * B1) &&
        ((A1 * C2 != A2 * C1) || (B1 * C2 != B2 * C1));
}
```

//判断两条直线断是否相交

```
bool IsIntersect(const LINE & A, const LINE & B)
{return !IsParallel(A, B);}
```

//直线相交的交点

```
POINT Intersection(const LINE & A, const LINE & B)
{
    TYPE A1, B1, C1;
    TYPE A2, B2, C2;

    Coefficient(A, A1, B1, C1);
    Coefficient(B, A2, B2, C2);

    POINT I(0, 0);
    I.x = - (B2 * C1 - B1 * C2) / (A1 * B2 - A2 * B1);
    I.y = (A2 * C1 - A1 * C2) / (A1 * B2 - A2 * B1);
    return I;
}
```

```
bool IsInCircle(const CIRCLE & circle, const RECT & rect)
{
    return (circle.x - circle.r >= rect.a.x) &&
        (circle.x + circle.r <= rect.b.x) &&
        (circle.y - circle.r >= rect.a.y) &&
        (circle.y + circle.r <= rect.b.y);
}
```

//判断是否简单多边形

```
bool IsSimple(const POLY & poly)
{
```

```

    if (poly.n < 3)
        return false;
    SEG L1, L2;
    for (int i = 0; i < poly.n - 1; i++)
    {
        L1 = Edge(poly, i);
        for (int j = i + 1; j < poly.n; j++)
        {
            L2 = Edge(poly, j);
            if (j == i + 1)
            {
                if (IsOnSeg(L1, L2.b) || IsOnSeg(L2, L1.a))
                    return false;
            }
            else if (j == poly.n - i - 1)
            {
                if (IsOnSeg(L1, L2.a) || IsOnSeg(L2, L1.b))
                    return false;
            }
            else
            {
                if (IsIntersect(L1, L2)) return false;
            }
        } // for j
    } // for i
    return true;
}

```

//求多边形面积

```

TYPE Area(const POLY & poly)
{
    if (poly.n < 3) return TYPE(0);
    double s = poly.y[0] * (poly.x[poly.n - 1] - poly.x[1]);
    for (int i = 1; i < poly.n; i++)
    {
        s += poly.y[i] * (poly.x[i - 1] - poly.x[(i + 1) % poly.n]);
    }
    return s/2;
}

```

//判断是否在多边形上

```

bool IsOnPoly(const POLY & poly, const POINT & p)
{
    for (int i = 0; i < poly.n; i++)

```

```

{
    if (IsOnSeg(Edge(poly, i), p)) return true;
}
return false;
}

```

//判断是否在多边形内部

bool IsInPoly(const POLY & poly, const POINT & p)

```

{
    SEG L(p, POINT(Infinity, p.y));
    int count = 0;
    for (int i = 0; i < poly.n; i++)
    {
        SEG S = Edge(poly, i);
        if (IsOnSeg(S, p))
        {
            return false; //如果想让 在 poly 上则返回 true,则改为 true
        }
        if (!IsEqual(S.a.y, S.b.y))
        {
            POINT & q = (S.a.y > S.b.y)?(S.a):(S.b);
            if (IsOnSeg(L, q))
            {
                ++count;
            }
            else if (!IsOnSeg(L, S.a) && !IsOnSeg(L, S.b) && IsIntersect(S, L))
            {
                ++count;
            }
        }
    }
    return (count % 2 != 0);
}

```

// 点阵的凸包, 返回一个多边形

POLY ConvexHull(const POINT \* set, int n)

// 不适用于点少于三个的情况

```

{
    POINT * points = new POINT[n];
    memcpy(points, set, n * sizeof(POINT));

    TYPE * X = new TYPE[n];
    TYPE * Y = new TYPE[n];

    int i, j, k = 0, top = 2;

```

```

for(i = 1; i < n; i++)
{
    if ((points[i].y < points[k].y) ||
        ((points[i].y == points[k].y) &&
         (points[i].x < points[k].x)))
    {
        k = i;
    }
}

std::swap(points[0], points[k]);

for (i = 1; i < n - 1; i++)
{
    k = i;
    for (j = i + 1; j < n; j++)
    {
        if ((Cross(points[j], points[k], points[0]) > 0) ||
            ((Cross(points[j], points[k], points[0]) == 0) &&
             (Distance(points[0], points[j]) < Distance(points[0], points[k]))))
        {
            k = j;
        }
    }
    std::swap(points[i], points[k]);
}

X[0] = points[0].x; Y[0] = points[0].y;
X[1] = points[1].x; Y[1] = points[1].y;
X[2] = points[2].x; Y[2] = points[2].y;

for (i = 3; i < n; i++)
{
    while (Cross(points[i], POINT(X[top], Y[top]),
        POINT(X[top - 1], Y[top - 1])) >= 0 && top>0)
    {
        top--;
    }
    ++top;
    X[top] = points[i].x;
    Y[top] = points[i].y;
}

delete [] points;

```



```

    POLY poly(++top, X, Y);
    delete [] X;
    delete [] Y;
    return poly;
}

//最近点对的距离, Written By PrincessSnow
#define MAXN 100000
POINT pt[MAXN];

bool cmp(POINT n1, POINT n2)
{return (n1.x<n2.x || n1.x==n2.x && n1.y<n2.y);}

double Get(double dis, int mid, int start, int end)
{
    int s=mid, e=mid, i, j;
    double t;
    while(s > start && pt[mid].x - pt[s].x <= dis)    s--;
    while(e < end && pt[e].x - pt[mid].x <= dis)    e++;
    for(i=s; i <= e; i++)
        for(j=i+1; j <= e && j <= i+7; j++) {
            t = Distance(pt[i], pt[j]);
            if(t < dis)    dis=t;
        }
    return dis;
}

double ClosestPairDistance(int start, int end)
{
    int m = end-start+1, mid, i;
    double t1, t2, dis=-1, t;
    if(m <= 3) {
        for(i=start; i < end; i++) {
            t = Distance(pt[i], pt[i+1]);
            if(t < dis || dis == -1)    dis = t;
        }
        t = Distance(pt[start], pt[end]);
        if(t < dis) dis=t;
        return dis;
    }

    if(m%2 == 0)    mid = start + m/2 - 1;
    else            mid = start + m/2;
    if(m%2 == 0) {

```

```

    t1 = ClosestPairDistance(start, mid);
    t2 = ClosestPairDistance(mid+1, end);
}
else {
    t1 = ClosestPairDistance(start, mid);
    t2 = ClosestPairDistance(mid+1, end);
}
if(t1 < t2)    dis = t1;
else          dis = t2;
dis = Get(dis, mid, start, end);
return dis;
}

```

## 1. 球面上两点最短距离

```

// 计算圆心角 lat 表示纬度, -90 <= w <= 90, lng 表示经度
// 返回两点所在大圆劣弧对应圆心角, 0 <= angle <= pi
double angle(double lng1, double lat1, double lng2, double lat2)
{
    double dlng = fabs(lng1 - lng2) * pi / 180;
    while(dlng >= pi+pi)    dlng -= pi+pi;
    if(dlng > pi)    dlng = pi + pi - dlng;
    lat1 *= pi / 180,    lat2 *= pi / 180;
    return acos( cos(lat1)*cos(lat2)*cos(dlng) + sin(lat1)*sin(lat2) );
}

// 计算距离, r 为球半径
double line_dist(double r, double lng1, double lat1, double lng2, double lat2)
{
    double dlng = fabs(lng1 - lng2) * pi / 180;
    while(dlng >= pi+pi)    dlng -= pi+pi;
    if(dlng > pi)    dlng = pi + pi - dlng;
    lat1 *= pi / 180,    lat2 *= pi / 180;
    return r * sqrt( 2 - 2*( cos(lat1)*cos(lat2)*cos(dlng) + sin(lat1)*sin(lat2) )
);
}

// 计算球面距离, r 为球半径
double sphere_dist(double r, double lng1, double lat1, double lng2, double lat2)
{
    return r * angle(lng1, lat1, lng2, lat2);
}

```

## 2. 三点求圆心坐标

```

double GetRadiusBy3Points(double x1, double y1,
                           double x2, double y2,
                           double x3, double y3,
                           double &x, double &y)
{
    // 由  $(x - x1)^2 + (y - y1)^2 = (x - x2)^2 + (y - y2)^2$  得
    //  $2*(x2 - x1)*x + 2*(y2 - y1)*y = x2^2 - x1^2 + y2^2 - y1^2$ 
    // 同理得
    //  $2*(x3 - x2)*x + 2*(y3 - y2)*y = x3^2 - x2^2 + y3^2 - y2^2$ 
    // 由行列式解方程得  $x, y$ 
    double a11, a12, a21, a22, b1, b2;
    double d, d1, d2;
    a11 = 2 * (x3 - x2);
    a12 = 2 * (y3 - y2);
    a21 = 2 * (x2 - x1);
    a22 = 2 * (y2 - y1);

    b1 = x3*x3 - x2*x2 + y3*y3 - y2*y2;
    b2 = x2*x2 - x1*x1 + y2*y2 - y1*y1;

    d = a11*a22 - a12*a21;
    d1 = b1*a22 - a12*b2;
    d2 = a11*b2 - b1*a21;
    //  $x, y$  是圆心坐标
    x = d1 / d;
    y = d2 / d;
    return (x1 - x)*(x1 - x) + (y1 - y)*(y1 - y);
}

```

### 3. 三角形几个重要的点

设三角形的三条边为  $a, b, c$ ，且不妨假设  $a \leq b \leq c$

三角形的面积可以根据海伦公式算得，如下：

$$s = \sqrt{p * (p - a) * (p - b) * (p - c)}, p = (a + b + c) / 2$$

1. 费马点(该点到三角形三个顶点的距离之和最小)

有个有趣的结论：若三角形的三个内角均小于  $120^\circ$ ，

那么该点连接三个顶点形成的三个角均为  $120^\circ$ ；若三角形存在一个内角大于  $120^\circ$ ，则该顶点就是费马点)

计算公式如下：

若有一个内角大于  $120^\circ$  (这里假设为角  $C$ )，则距离为  $a + b$

若三个内角均小于  $120^\circ$ ，则距离为

$$\sqrt{(a^2 + b^2 + c^2 + 4 * \sqrt{3.0} * s) / 2}, \text{其中}$$

2. 内心----角平分线的交点

令  $x = (a + b - c) / 2$ ,  $y = (a - b + c) / 2$ ,  $z = (-a + b + c) / 2$ ,  $h = s / p$   
 计算公式为  $\text{sqrt}(x * x + h * h) + \text{sqrt}(y * y + h * h) + \text{sqrt}(z * z + h * h)$

### 3. 重心----中线的交点

计算公式如下:

$$2.0 / 3 * (\text{sqrt}((2 * (a * a + b * b) - c * c) / 4) \\ + \text{sqrt}((2 * (a * a + c * c) - b * b) / 4) \\ + \text{sqrt}((2 * (b * b + c * c) - a * a) / 4))$$

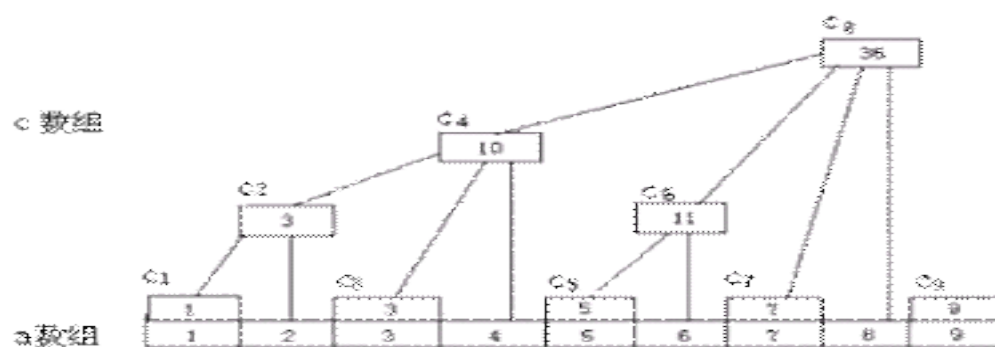
### 4. 垂心----垂线的交点

计算公式如下:

$$3 * (c / 2 / \text{sqrt}(1 - \cos C * \cos C))$$

## 4.

# 第七章 专题讨论



## 1. 树状数组

```

/**** **** **** **** **** ****
*   Function Name :       树状数组
*   Description :       HDOJ 1166 敌兵布阵
*                           减少冗余统计, 是线段树的一种变化
**** **** **** **** **** ****/

#include<cstdio>
int data[50001], s[50001], T[50001];

inline int lowbit(int t)
{return t & (-t);}

inline int sum(int end)

```

```
{
    int sum = 0;
    while(end > 0) {
        sum += T[end];
        end -= lowbit(end);
    }
    return sum;
}

inline void plus(int pos, int num, int count)
{
    while(pos <= count) {
        T[pos] += num;
        pos += lowbit(pos);
    }
}

int main()
{
    char buffer[10];
    int i, j, t, n, a, b;
    scanf("%d", &t);
    for(i=1; i <= t ;i++) {
        scanf("%d", &n);
        T[0] = s[0] = data[0] = 0;
        for(j=1; j <= n ;j++) {
            scanf("%d", &data[j]);
            s[j] = s[j - 1] + data[j];
            T[j] = s[j] - s[j - lowbit(j)];
        }
        printf("Case %d:\n", i);
        while(scanf("%s", buffer) == 1 && buffer[0] != 'E') {
            scanf("%d%d", &a, &b);
            switch(buffer[0]) {
                case 'Q':
                    printf("%d\n", sum(b) - sum(a) + data[a]); break;
                case 'A':
                    plus(a, b, n); break;
                case 'S':
                    plus(a, -b, n); data[a] -= b; break;
            }
        }
    }
}
```

## 2. 字典树

```

/***** *****/
*   Function Name :      字典树(多路查找树)
*   Description :       HDOJ 1075 What Are You Talking About
*                       易于字符保存, 插入和查找, 时间复杂度都是线性
*****/

#include <cstdio>
#include <string>
using namespace std;

struct trie
{
    trie * next[26];
    int index;
};
trie *thead;
char dic[1000000][20];

inline trie * newnode()
{
    int i;
    trie *t;
    t=(trie*)malloc(sizeof(trie));
    memset(t,0,sizeof(trie));
    return t;
}

void insert(trie * s,char x[],int pos)
{
    int i;
    trie *t;
    for(i=0; x[i] ; i++) {
        if( s->next[ x[i]-'a' ] )    s=s->next[ x[i]-'a' ];
        else {
            t=newnode();
            s->next[ x[i]-'a' ]=t;
            s=t;
        }
    }
    s->index=pos;
}

void deltrie(trie * s)

```

```

{
    int i;
    for(i=0; i < 26 ;i++) {
        if( s->next[i] )
            deltrie(s->next[i]);
    }
    free(s);
    s=NULL;
}

int find(trie *s, char x[])
{
    int i;
    if(x[0] == 0)    return -1;
    for(i=0; x[i] ; i++) {
        if( s->next[ x[i]-'a' ] )    s=s->next[ x[i]-'a' ];
        else                        break;
    }
    if(x[i]==0)    return s->index;
    else          return -1;
}

int main()
{
    int t,n,i,j,all;
    char word[20],mars[20],ch;

    thead=newnode();
    while(scanf("%s",word)==1)
        if(word[0]=='S')    break;
    i=1;
    while(scanf("%s",dic[i])==1 && dic[i][0]!='E') {
        scanf("%s",mars);
        insert(thead,mars,i);
        i++;
    }
    all=i;
    while(scanf("%s",word)==1)
        if(word[0]=='S')    break;
    getchar();    j=0;
    while(scanf("%c",&ch)==1 && ch!='E') {
        if(ch>='a' && ch<='z') {
            mars[j]=ch;    j++;
        }
    }
}

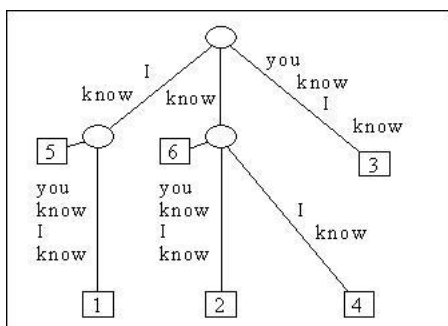
```

```

else {
    mars[j]=0;
    t=find( thead , mars );
    j=0;
    if(t>0)    printf("%s",dic[t]);
    else if(mars[0]!=0)    printf("%s",mars);
    printf("%c",ch);
}
} //while
deltrie(thead);
}

```

### 3. 后缀树



```

/***** *****/
*   Function Name :      后缀树
*   Description :      PKU 2774 Long Long Message
*                       有效的支持字符串匹配和查询
**** */

```

```
#include<stdio>
```

```
#include<string>
```

```
#define NUM          27
```

```
#define STARTCHAR    'a'
```

```
#define SPECIALCHAR  '{'
```

```
#define ERROR        -1
```

```
#define TYPE1        1
```

```
#define TYPE2        2
```

```
#define LEAF         1
```

```
#define NOTLEAF      2
```

```
struct SuffixTrie {
```

```
    int Start, End;
```

```
    SuffixTrie * Next[NUM];
```

```
    SuffixTrie * Link;
```

```
    SuffixTrie * Father;
```

```
    int Flag;
```



```

    int Length;
};

char str[100010], buf[100010];
SuffixTrie head;
SuffixTrie*P, *G, *U, *V, *q;
int W[3], len, len2;

void CreateNode(SuffixTrie * & Node) {
    int i;
    Node = (SuffixTrie * ) malloc(sizeof(SuffixTrie));
    Node -> Start = Node -> End = Node -> Length = ERROR;
    for (i = 0; i < NUM; i++) Node -> Next[i] = NULL;
    Node -> Link = Node -> Father = NULL;
    Node -> Flag = LEAF;
}

void Init(SuffixTrie & h, char s[]) {
    int i;
    h.Start = h.End = ERROR;
    for (i = 0; i < NUM; i++) h.Next[i] = NULL;
    h.Link = & h;
    h.Father = NULL;
    h.Flag = LEAF;
    h.Length = 0;

    len = strlen(s);
    s[len] = SPECIALCHAR;
    s[len + 1] = '\0';
    len++;
}

int FindV(char s[]) {
    int old;
    SuffixTrie * t, * newt;
    t = U -> Next[s[W[0]] - STARTCHAR];

    old = 0;
    while (W[2] > (t -> End) - (t -> Start) + 1 + old) {
        old += (t -> End - t -> Start + 1);
        t = t -> Next[s[W[0] + old] - STARTCHAR];
    }
    if (W[2] == (t -> End) - (t -> Start) + 1 + old) {
        V = t;
    }
}

```

```

    P -> Link = V;
    return TYPE1;
} else {
    CreateNode(newt);
    newt -> Start = t -> Start;
    newt -> End = t -> Start + W[2] - old - 1;
    newt -> Father = t -> Father;
    newt ->
        Length = newt -> Father -> Length + newt -> End - newt ->
            Start + 1;
    t -> Father -> Next[s[t -> Start] - STARTCHAR] = newt;
    t -> Start = newt -> End + 1;
    newt -> Next[s[t -> Start] - STARTCHAR] = t;
    t -> Father = newt;
    V = newt;
    P -> Link = V;
    return TYPE2;
}
}

int Insert(SuffixTrie * Node, int start, char s[]) {
    int i, posbegin, posend;
    SuffixTrie * t;
    if (Node -> Next[s[start] - STARTCHAR] == NULL) {
        CreateNode(Node -> Next[s[start] - STARTCHAR]);
        Node -> Next[s[start] - STARTCHAR] -> Start = start;
        Node -> Next[s[start] - STARTCHAR] -> End = len - 1;
        Node -> Next[s[start] - STARTCHAR] -> Father = Node;
        Node -> Next[s[start] - STARTCHAR] ->
            Length = Node -> Length + len - start;
        Node -> Flag = NOTLEAF;
        P = Node;
        return TYPE1;
    } else {
        posbegin = Node -> Next[s[start] - STARTCHAR] -> Start;
        posend = Node -> Next[s[start] - STARTCHAR] -> End;
        for (i = posbegin; i <= posend; i++) {
            if (s[i] != s[start + i - posbegin]) break;
        }
        if (i == posend + 1) {
            return Insert(Node -> Next[s[start] - STARTCHAR], start + i - posbe
gin, s);
        } else {
            CreateNode(t);

```

```

    t -> Start = posbegin;
    t -> End = i - 1;
    t -> Flag = NOTLEAF;
    Node -> Next[s[start] - STARTCHAR] -> Start = i;
    t -> Next[s[i] - STARTCHAR] = Node -> Next[s[start] - STARTCHAR];
    t -> Next[s[i] - STARTCHAR] -> Father = t;
    Node -> Next[s[start] - STARTCHAR] = t;
    t -> Father = Node;
    t -> Length = Node -> Length + t -> End - t -> Start + 1;
    Insert(t, start + i - posbegin, s);
    G = Node;
    P = t;
    return TYPE2;
}
}
}

```

```

int Select(int start, char s[], int type) {
    int result1, result2, result;
    if (type == TYPE1) {
        U = P -> Link;
        result = Insert(U, start + U -> Length, s);
    } else {
        U = G -> Link;
        if (G -> Link == G) {
            W[0] = P -> Start + 1;
            W[1] = P -> End;
            W[2] = P -> End - P -> Start;
        } else {
            W[0] = P -> Start;
            W[1] = P -> End;
            W[2] = P -> End - P -> Start + 1;
        }
        if (W[2] == 0) {
            V = G;
            P -> Link = V;
            result = Insert(V, start, s);
        } else {
            result1 = FindV(s);
            result2 = Insert(V, start + V -> Length, s);
            if (result1 == TYPE2) {
                G = P -> Father;
                result = result1;
            } else result = result2;
        }
    }
}

```

```

    }
}
return result;
}

void BuildSuffixTrie(SuffixTrie & h, char s[]) {
    int i;
    int type;

    len = strlen(s);
    CreateNode(h.Next[s[0] - STARTCHAR]);
    h.Next[s[0] - STARTCHAR] -> Start = 0;
    h.Next[s[0] - STARTCHAR] -> End = len - 1;
    h.Next[s[0] - STARTCHAR] -> Father = & h;
    h.Next[s[0] - STARTCHAR] -> Length = h.Length + h.Next[s[0] - STARTC
HAR] -> End - h.Next[s[0] - STARTCHAR] -> Start + 1;
    h.Flag = NOTLEAF;
    type = TYPE1;
    P = & h;

    for (i = 1; i < len; i++) type = Select(i, s, type);
}

void DeleteSuffixTrie(SuffixTrie * & Node) {
    int i;
    for (i = 0; i < NUM; i++) {
        if (Node -> Next[i] != NULL) {
            DeleteSuffixTrie(Node -> Next[i]);
            Node -> Next[i] = NULL;
        }
    }
    free(Node);
}

int FindString(int start, char s[]) {
    int result;
    int i;
    int temp;
    SuffixTrie * x;
    x = P -> Next[s[start] - STARTCHAR];
    result = P -> Length;
    if (x == NULL) {
        P = P -> Link;
        return result;
    }
}

```

```

    }
    temp = 0;
    for (i = start; i < len2; i++) {
        if (x -> Start + i - start - temp > x -> End) {
            temp = i - start;
            P = x;
            x = x -> Next[s[start + temp] - STARTCHAR];
            if (x == NULL) break;
        }
        if (s[i] != str[x -> Start + i - start - temp]) break;
        result++;
    }
    P = P -> Link;
    return result;
}

```

```

int Search(SuffixTrie & h, char s[]) {
    int result;
    int i;
    int temp;
    len2 = strlen(s);
    result = 0;
    P = & head;
    for (i = 0; i < len2; i++) {
        temp = FindString(i + P -> Length, s);
        if (result < temp) result = temp;
        if (result >= len2 - i) break;
    }
    return result;
}

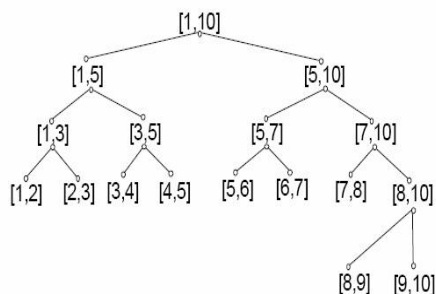
```

```

int main() {
    int result;
    while (scanf("%s", str) != EOF) {
        Init(head, str);
        BuildSuffixTrie(head, str);
        scanf("%s", buf);
        result = Search(head, buf);
        printf("%d\n", result);
    }
}

```

#### 4. 线段树



```

/***** *****/

```

```

*   Function Name :      线段树

```

```

*   Description :      HDOJ 1542 Atlantis

```

```

*           用于表示区间线段

```

```

*****/

```

```

#include<cstdio>

```

```

#include<algorithm>

```

```

using namespace std;

```

```

typedef struct ITREE_NODE {

```

```

    ITREE_NODE * pLChild, * pRChild;

```

```

    double left, right;      // 左端点, 右端点

```

```

    double measure;         // 测度

```

```

    int count;              // 覆盖计数器

```

```

    int lines;              // 独立线段数

```

```

    int lbound, rbound;     // 覆盖左、右顶点的线段数目

```

```

}*PITREE_NODE;

```

```

inline void safe_add(int & v, int value) {

```

```

    v += value;

```

```

    if (v < 0) v = 0;

```

```

}

```

```

void itree_splite(const double * pList, PITREE_NODE pParent, const int iLeft,
const int iRight) {

```

```

    if (iRight - iLeft <= 1) return;

```

```

    int iMid = (iLeft + iRight) >> 1;

```

```

    pParent -> pLChild = new ITREE_NODE;

```

```

    pParent -> pRChild = new ITREE_NODE;

```

```

    memset(pParent -> pLChild, 0, sizeof(ITREE_NODE));

```

```

    memset(pParent -> pRChild, 0, sizeof(ITREE_NODE));

```

```

    pParent -> pLChild -> left = pList[iLeft];

```

```

    pParent -> pLChild -> right = pList[iMid];

```

```

    pParent -> pRChild -> left = pList[iMid];

```

```

    pParent -> pRChild -> right = pList[iRight];

```

```

    itree_splite(pList, pParent -> pLChild, iLeft, iMid);

```

```

    itree_splite(pList, pParent -> pRChild, iMid, iRight);
}

PITREE_NODE itree_generate(const double * pList, const int iListCount) {
    PITREE_NODE pRoot = new ITREE_NODE;
    memset(pRoot, 0, sizeof(ITREE_NODE));
    pRoot -> left = pList[0];
    pRoot -> right = pList[iListCount - 1];
    itree_splite(pList, pRoot, 0, iListCount - 1);
    return pRoot;
}

void itree_destroy(PITREE_NODE pParent) {
    if (pParent == NULL) return;
    if (pParent -> pLChild) itree_destroy(pParent -> pLChild);
    if (pParent -> pRChild) itree_destroy(pParent -> pRChild);
    delete pParent;
}

inline void itree_measure(PITREE_NODE pNode) {
    if (pNode -> count > 0)
        pNode -> measure = pNode -> right - pNode -> left;
    else if (pNode -> pLChild && pNode -> pRChild)
        pNode -> measure = pNode -> pLChild -> measure + pNode -> pRChild -> measure;
    else
        pNode -> measure = 0;
}

inline void itree_lines(PITREE_NODE pNode) {
    if (pNode -> count > 0) {
        pNode -> lines = 1;
    } else if (pNode -> pLChild && pNode -> pRChild) {
        if (pNode -> pLChild -> rbound && pNode -> pRChild -> lbound) {
            pNode -> lines = pNode -> pLChild -> lines + pNode -> pRChild -> lines - 1;
        } else {
            pNode -> lines = pNode -> pLChild -> lines + pNode -> pRChild -> lines;
        }
    } else {
        pNode -> lines = 0;
    }
}

// 插入的时候 value = 1, 删除的时候 value = -1

```

```

void itree_update(PITREE_NODE pParent, const double left, const double right,
int value) {
    if (pParent -> left == left && pParent -> right == right) {
        safe_add(pParent -> count, value);
        safe_add(pParent -> lbound, value);
        safe_add(pParent -> rbound, value);
        itree_measure(pParent);
        itree_lines(pParent);
    } else {
        if (pParent -> pLChild -> right > left) {
            if (pParent -> pLChild -> right >= right) {
                itree_update(pParent -> pLChild, left, right, value);
            } else {
                itree_update(pParent -> pLChild, left,
                    pParent -> pLChild -> right, value);
                itree_update(pParent -> pRChild, pParent -> pRChild -> left,
                    right, value);
            }
        } else {
            itree_update(pParent -> pRChild, left, right, value);
        }
        itree_measure(pParent);
        itree_lines(pParent);
        if (left == pParent -> left) safe_add(pParent -> lbound, value);
        if (right == pParent -> right) {
            safe_add(pParent -> rbound, value);
        }
    }
}

void itree_insert(PITREE_NODE pParent, const double left, const double right)
{itree_update(pParent, left, right, 1); }

void itree_delete(PITREE_NODE pParent, const double left, const double right)
{itree_update(pParent, left, right, -1); }

struct EVENT {
    double x, y1, y2;
    int type;
};

bool cmp(const EVENT & a, const EVENT & b)
{ return a.x < b.x; }

```



```

PITREE_NODE pRoot;
EVENT env[200];
double Y[200];
double tsize = 0.0;

int main() {
    double x1, x2, y1, y2;
    int i, n, n2, cas = 0;
    while (scanf("%d", &n) == 1 && n) {
        cas++;
        n2 = n << 1;
        for (i = 0; i < n2; i += 2) {
            scanf("%lf%lf%lf%lf", &x1, &y1, &x2, &y2);
            env[i].x = x1;
            env[i].y1 = y1;
            env[i].y2 = y2;
            env[i].type = 1;
            env[i + 1].x = x2;
            env[i + 1].y1 = y1;
            env[i + 1].y2 = y2;
            env[i + 1].type = -1;
            Y[i] = y1;
            Y[i + 1] = y2;
        }
        sort(env, env + n2, cmp);
        sort(Y, Y + n2);
        pRoot = itree_generate(Y, n2);
        for (i = 0; i < n2; ++i) {
            if (i > 0) tsize += pRoot->measure * (env[i].x - env[i - 1].x);
            else tsize = 0.0;
            itree_update(pRoot, env[i].y1, env[i].y2, env[i].type);
        }
        itree_destroy(pRoot);
        printf("Test case #%d\nTotal explored area: %.2lf\n\n", cas, tsize);
    }
    return 0;
}

```

## 5. 并查集

```

/***** *****/
*   Function Name :      并查集
*   Description :      集合操作, 并, 除, 判断
*****/

```

```

const int Max=1000;
typedef int ElemType;

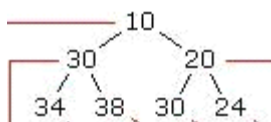
int Parent[Max],Rank[Max];

int Find(int x)
{
    int temp = x, root, w;
    //搜寻根节点
    while(Parent[x]!=0)    x=Parent[x];
    root=x;
    x=temp;
    //压缩路径
    while(Parent[x]!=0) {
        w=Parent[x];
        Parent[x]=root;
        x=w;
    }
    return root;
}

int Union(int x,int y)
{
    int u, v, root;
    u=Find(x);
    v=Find(y);
    if(Rank[u] <= Rank[v]) {
        root = Parent[u] = v;
        if(Rank[u] == Rank[v])    Rank[v]++;
    }
    else    root=Parent[v]=u;
    return root;
}

```

## 6. 二叉堆



```

/***** *****/
*   Function Name :    二叉堆
*   Description :      父结点的键值总是大於或等於任何一个子节点的键值
*                       便於寻找父节点和子节点
*****/

```

```
const int Max=1000;
typedef int ElemType;

ElemType Heap[Max];

int Sift_Up(int i)    //上移
{
    ElemType temp;
    bool flag;
    flag = true;
    if(i == 1)    return 0;
    do {
        if(Heap[i] > Heap[i/2])
            {temp=Heap[i];    Heap[i]=Heap[i/2];    Heap[i/2]=temp;}
        else    flag = false;
        i /= 2;
    }while(i>1 || flag);
    return 1;
}

int Sift_Down(int i,int n)    //下移
{
    bool flag;
    ElemType temp;
    flag = false;
    if(2*i > n)    return 0;
    do {
        i*=2;
        if(i+1 <= n && Heap[i+1] > Heap[i])    i++;
        if(Heap[i/2] < Heap[i])
            {temp=Heap[i];    Heap[i]=Heap[i/2];    Heap[i/2]=temp;}
        else    flag = false;
    }while(2*i<=n || flag);
    return 1;
}

int Insert(int &n,ElemType x)    //插入元素
{
    Heap[++n] = x;
    if( Sift_Up(n) )    return n;
}

int Delete(int &n,int i)    //输出元素
{

```

```

    ElemType x,y;
    x = Heap[i];    y = Heap[n];
    n--;
    if(i == n+1)    return x;
    Heap[i] = y;
    if(y >= x)    Sift_Up(i);
    else        Sift_Down(i,n);
    return x;
}

int Delete_Max(int &n)    //输出最大值
{
    ElemType x;
    x = Heap[1];
    Delete(n,1);
    return x;
}

int Make_Heap(int n)    //转换为大顶堆
{
    int i;
    for(i=n/2; i >= 1 ;i--)    Sift_Down(i,n);
    return n;
}

int HeapSort(int n)    //非降序排序
{
    int i;
    ElemType temp;
    Make_Heap(n);
    for(i=n; i >= 2 ;i--) {
        temp=Heap[i];    Heap[i]=Heap[1];    Heap[1]=temp;
        Sift_Down(1,i-1);
    }
    return 1;
}

```

## 7. 逆序数(归并排序)

```

/***** *****/
*   Function Name :    逆序数(归并排序)
*   Description :    N*Log(N)
*****/
//逆序数值存放在 anti 中
int p[MAX], t[MAX], anti = 0;

```

```

void merge(int first, int last)
{
    int mid = (first+last)/2;
    int i1 = 0, i2 = first, i3 = mid+1;
    while(i2 <= mid && i3 <= last) {
        if(p[i2] > p[i3]) {
            t[i1++] = p[i3++];
            anti += mid-i2+1;
        }
        else t[i1++] = p[i2++];
    }
    while(i2 <= mid)    t[i1++] = p[i2++];
    while(i3 <= last)   t[i1++] = p[i3++];
    i1 = first;    i2 = 0;
    while(i2 < last-first+1)    p[i1++] = t[i2++];
}

```

```

void merge_sort(int first, int last)
{
    int mid;
    if(first<last) {
        mid = (first+last)/2;
        merge_sort(first, mid);
        merge_sort(mid+1, last);
        merge(first, last);
    }
}

```

## 8. 树状 DP

```

/***** *****/
*   Function Name :      树状 DP
*   Description :       HDOJ 1561 The more, The Better
*****/
#include<stdio>
#include<memory>
#include<queue>
using namespace std;
#define Max 210
int n,m,a[Max][Max];
struct inf
{
    int l,r,p;
    int v;
}tree[Max];

```

```

int tp,now;
queue<int> SQ;
char v[Max];

int main()
{
    int i,j;
    int root,pt,tv;
    while(scanf("%d%d",&n,&m)) {
        if(n==0 && m==0 ) break;
        memset(tree,0,sizeof(tree));
        memset(a,0,sizeof(a));
        memset(v,3,sizeof(v));
        while(!SQ.empty()) SQ.pop();
        for(i=1; i <= n ;i++) {
            scanf("%d%d", &root, &tree[i].v);
            if(tree[root].l == 0) {
                tree[root].l = i;
                v[root]--;
                tree[i].p = root;
            }
            else {
                pt = tree[root].l;
                while(tree[pt].r != 0) pt = tree[pt].r;
                tree[pt].r = i;
                v[pt] -= 2;
                tree[i].p = pt;
            }
        }
        for(i=1;i<=n;i++)
            if(v[i]==3) SQ.push(i);
        while(!SQ.empty()) {
            now = SQ.front();
            SQ.pop();

            a[now][1] = tree[now].v;
            for(i=1; i <= m ;i++)
                a[now][i] = a[now][i] < a[ tree[now].r ][i] ? a[ tree[now].r ][i]
: a[now][i];
            for(i=2; i <= m ;i++)
                for(j=1; j <= i ;j++) {
                    tv = a[ tree[now].l ][j-1] + tree[now].v + a[ tree[now].r ][i
-j];

                    a[now][i] = a[now][i] < tv ? tv : a[now][i];
                }
        }
    }
}

```

```

    }
    if(tree[ tree[now].p ].l == now)    v[ tree[now].p ]++;
    else                                v[ tree[now].p ] += 2;
    if(v[ tree[now].p ] == 3) SQ.push(tree[now].p);
}
printf("%d\n",a[ tree[0].l ][m]);
}
}

```

## 9. 欧拉路

```

/***** *****/
*   Function Name :      欧拉路
*   Description :       ZJU 2730 Necklace
*   欧拉路的构造方法:
*   若图连同且度为奇数的节点不超过 2 个,则该图可以构造出欧拉路
*   先选一个度为奇数的节点(若没有就任选一个度为偶数的节点)
*   再以该节点为起点,用 dfs 遍历所有的弧(每条弧只遍历一次),遇到死胡同就回溯
*   在每次回溯时将所在弧按顺序记录下来,这组弧的排列就组成了一条欧拉路
*****/
#include<stdio.h>
#define MAXN 50
void find_path_euler(int n, int mat[][MAXN], int now, int& step, int* path)
{
    int i;
    for(i=n-1; i >= 0 ;i--)
        while(mat[now][i]) {
            mat[now][i]--, mat[i][now]--;
            find_path_u(n, mat, i, step, path);
        }
    path[ step++ ]=now;
}

int main()
{
    int n;
    int a[MAXN][MAXN];
    int i, j, cnt, mmin;
    int b[10000],c[10000];
    while(scanf("%d",&n)!=EOF) {
        for(i=0; i<n ;i++)
            for(j=0; j<n ;j++)
                if(j == i)    a[i][j] = 0;
                else          a[i][j] = a[j][i] = 1;
    }
}

```

```

    cnt = 0;
    mmin = 2000000000;
    for(i=0; i<n ;i++) {
        find_path_u(n, a, i, cnt, b);
        if(cnt < mmin) {
            mmin = cnt;
            for(j=0; j<mmin ;j++)
                c[j] = b[j];
            break;
        }
    }
    printf("%d\n", mmin-1);
    for(i=0; i<mmin-2 ;i++)
        printf("%d ",c[i]);
    printf("%d",c[i]);
    printf("\n");
}
}

```

## 10. 八数码

```

/**** **** **** **** **** ****
*   Function Name :      八数码 Eight(Special Judge)
*   Description :      搜索 + 状态 hash
*   PKU(1077)      HDOJ(1043)      ZOJ(1217)
*   BFS          广搜      PKU(312ms)  HDOJ(TLE)      ZOJ(TLE)
*   BFS2        双向广搜  PKU(31ms)  HDOJ(1325ms)  ZOJ(TLE)
*   以上均是每次计算的运行耗时，ZOJ 的可以全部计算后保存状态
**** **** **** **** **** ****/

#include<cstdio>
#include<string>
#include<memory>
#include<queue>
using namespace std;
char input[100];
int state[10], s_num, e10[10], fac_n[10];
char hash_T[400000], step[10000], hash_T2[400000];
struct inf
{
    int pos;
    char mode;
};
queue<int> SQ;
queue<inf> SQ2;

```



```
int num_pos(int num,int x,int y)
{
    int temp=(x-1)*3+y;
    if(temp == num%10)    return 9;
    if(temp > num%10)    return (num / e10[9-temp+1]) %10;
    else    return (num / e10[9-temp] )%10;
}
```

```
int state_pos(int num,int x,int y)
{
    int temp=(x-1)*3+y;
    if(temp == state[9])    return 9;
    if(temp > state[9])    return state[temp-1];
    else    return state[temp];
}
```

```
inline int move(int num,char op)
{
    int t0,t1,t2;
    switch(op)
    {
        case 'r':
            if(num%10%3 == 0)    return 0;
            return num+1;
        case 'l':
            if((num-1)%10%3 ==0)    return 0;
            return num-1;
        case 'u':
            if(num%10 -3 <= 0)    return 0;
            t0 = 9-num%10 + 1;
            t1 = num / e10[t0];
            t2 = t1%1000;
            t1= t1- t2 + (t2 % 100) * 10 + t2 / 100;
            t1*= e10[t0];
            return (t1 + ( (num % e10[t0]) - 3));
        case 'd':
            if(num%10 +3 > 9)    return 0;
            t0 = 9-num%10 + 1 -3;
            t1 = num / e10[t0];
            t2 = t1%1000;
            t1= t1- t2 + (t2 % 10) * 100 + t2 / 10;
            t1*= e10[t0];
            return (t1 + ( (num % e10[t0]) + 3));
    }
}
```

```

}

bool be_solved()
{
    int i,j,anti=0;
    for(i=1;i<=8;i++)
        for(j=1;j<i;j++)
            if( state[i] < state[j] )
                anti++;
    if(anti%2)    return false;
    else        return true;
}

inline int hash(int num)
{
    int dig[10],i=9,j,sum,anti;
    if(num==0)    return -1;
    while(num)    dig[i]=num%10 , num/=10 , i-- ;
    sum=(9-dig[9])*fac_n[8];
    for(i=1;i<9;i++) {
        for(anti=0,j=1;j<i;j++)
            if(dig[i] < dig[j])
                anti++;
        sum += anti*fac_n[i-1];
    }
    return sum;
}

void BFS()
{
    int k,to_num,to_hash,i;
    memset(hash_T,0,sizeof(hash_T));
    while(!SQ.empty())    SQ.pop();
    SQ.push(123456789);
    hash_T[ hash(123456789) ]='e';
    while(!SQ.empty())
    {
        k=SQ.front();
        SQ.pop();

        to_num=move(k,'r');    to_hash=hash(to_num);
        if(to_hash>=0 && hash_T[ to_hash ]==0)
            hash_T[ to_hash ]='r' , SQ.push(to_num);
        to_num=move(k,'l');    to_hash=hash(to_num);
    }
}

```

```

        if(to_hash>=0 && hash_T[ to_hash ]==0)
            hash_T[ to_hash ]='l' , SQ.push(to_num);
        to_num=move(k,'u');    to_hash=hash(to_num);
        if(to_hash>=0 && hash_T[ to_hash ]==0)
            hash_T[ to_hash ]='u' , SQ.push(to_num);
        to_num=move(k,'d');    to_hash=hash(to_num);
        if(to_hash>=0 && hash_T[ to_hash ]==0)
            hash_T[ to_hash ]='d' , SQ.push(to_num);
    }
}

void BFS2()
{
    int to_num,to_hash,i;
    char *phash,*phash2;
    char op;
    inf k,t;
    memset(hash_T,0,sizeof(hash_T));
    memset(hash_T2,0,sizeof(hash_T2));
    while(!SQ2.empty())    SQ2.pop();
    k.pos=s_num;    k.mode=1;
    SQ2.push(k);
    k.pos=123456789;    k.mode=2;
    SQ2.push(k);
    hash_T[ hash(s_num) ]='s';
    hash_T2[ hash(123456789) ]='e';
    while(!SQ2.empty()) {
        k=SQ2.front();
        SQ2.pop();
        to_hash=hash(k.pos);
        if(k.mode==1)
            if(hash_T2[ to_hash ]!=0)    break;
        else    phash=hash_T,phash2=hash_T2;
        if(k.mode==2)
            if(hash_T[ to_hash ]!=0)    break;
        else    phash=hash_T2,phash2=hash_T;
        t=k;
        t.pos=move(k.pos,'r');    to_hash=hash(t.pos);
        if(to_hash>=0 && phash[ to_hash ]==0)
            phash[ to_hash ]='r' , SQ2.push(t);
        t.pos=move(k.pos,'l');    to_hash=hash(t.pos);
        if(to_hash>=0 && phash[ to_hash ]==0)
            phash[ to_hash ]='l' , SQ2.push(t);
        t.pos=move(k.pos,'u');    to_hash=hash(t.pos);
    }
}

```

```

        if(to_hash>=0 && phash[ to_hash ]==0)
            phash[ to_hash ]='u' , SQ2.push(t);
        t.pos=move(k.pos,'d');    to_hash=hash(t.pos);
        if(to_hash>=0 && phash[ to_hash ]==0)
            phash[ to_hash ]='d' , SQ2.push(t);
    }
    i=0;
    to_hash = hash(k.pos);
    to_num = k.pos;
    while( hash_T[ to_hash ] != 's' ) {
        switch( step[i++]=hash_T[ to_hash ] ) {
            case 'r':    op='l';break;
            case 'l':    op='r';break;
            case 'u':    op='d';break;
            case 'd':    op='u';break;
        }
        to_num=move(to_num,op);
        to_hash=hash(to_num);
    }
    while(i>0)    printf("%c",step[--i]);
    to_hash=hash(k.pos);
    to_num=k.pos;
    while( hash_T2[ to_hash ]!='e' ) {
        switch( hash_T2[ to_hash ] ) {
            case 'r':    op='l';break;
            case 'l':    op='r';break;
            case 'u':    op='d';break;
            case 'd':    op='u';break;
        }
        printf("%c",op);
        to_num=move(to_num, op );
        to_hash=hash(to_num);
    }
}

int main()
{
    int i,j;
    for(e10[0]=1,i=1;i<=9;i++)
        e10[i] =e10[i-1]*10;
    for(fac_n[0]=0,fac_n[1]=1,i=2;i<=9;i++)
        fac_n[i] =fac_n[i-1]*i;
    while( gets(input) ) {
        for(i=strlen(input)-1,j=8;i>=0;i--) {

```

```

        if(input[i]!=' ') {
            if(input[i]=='x')
                state[9]=j+1;
            else state[j--]=input[i]-'0';
        }
    }
    for(s_num=0,i=9,j=1;i>0;i--,j*=10)
        s_num += state[i]*j;
    if( !be_solved() )
        printf("unsolvable\n");
    else {
        BFS2();
        printf("\n");
    }
}
}

```

## 11. 高斯消元法

```

/***** *****/
*   Function Name :      高斯消元法
*   Description :      求解线性方程组
*
*   void exchange_col(int p1,int p2,int n)
*   交换 p1 行和 p2 行的所有数据
*
*   bool gauss(int n)
*   求解系数矩阵为 n 的线性方程组，方程组无解返回 false，否则 true
*
*    $x_1 = x_0 - f(x_0)/f'(x_0)$  牛顿迭代法
*****/
const int num = 100;
double matrix[num][num + 1]; //系数矩阵，从 0 开始
double ans[num];             //结果数组

void exchange_col(int p1,int p2,int n) //交换 p1 行和 p2 行的所有数据
{
    double t;
    int i;

    for(i = 0 ; i <= n ; i++)
        t = matrix[p1][i],matrix[p1][i] = matrix[p2][i],matrix[p2][i] = t;
}

bool gauss(int n) //求解系数矩阵为 n 的线性方程组

```

```

{
    int i,j,k;
    int p;
    double r;

    for(i = 0 ; i < n - 1 ; i++) {
        p = i;
        for(j = i + 1 ; j < n ; j++) { //寻找 i 列绝对值最大值位置
            if(abs(matrix[j][i]) > abs(matrix[p][i]))
                p = j;
        }
        if(p != i)    exchange_col(i,p,n);
        if(matrix[i][i] == 0) return false;
        for(j = i + 1 ; j < n ; j++) { //剩余列进行消元
            r = matrix[j][i] / matrix[i][i];
            for(k = i ; k <= n ; k++)
                matrix[j][k] -= r * matrix[i][k];
        }
    }
    for(i = n - 1 ; i >= 0 ; i--) { //获得结果
        ans[i] = matrix[i][n];
        for(j = n - 1 ; j > i ; j--)
            ans[i] -= matrix[i][j] * ans[j];
        if(matrix[i][i] == 0) return false;
        ans[i] /= matrix[i][i];
    }
    return true;
}

```

## 12. 字符串匹配(KMP 算法)

```

/***** *****/
*   Function Name :      字符串匹配(KMP 算法)
*   Description :      O(N+M)
*****/
void get_nextval(const string & s, int * p)
{
    int i = 0,j = -1;
    p[0] = -1;
    while(i < s.size()) {
        if(j == -1 || s[i] == s[j]) {
            ++i,++j;
            if(s[i] != s[j]) p[i] = j;
            else p[i] = p[j];
        }
    }
}

```

```

        else j = p[j];
    }
}
int Index_KMP(const string & s, const string & s1, int pos)
{
    int i = pos - 1, j = 0;
    int * next = new int[s1.size()];

    get_nextval(s1, next);
    while(i <= s.size() && j <= s1.size()) {
        if(j == -1 || s[i] == s1[j]) ++i, ++j;
        else j = next[j];
    }
    if(j > s1.size()) return i - s1.size();
    else return -1;
}

```

### 13. 全排列,全组合

```

/***** *****/
*   Function Name :      全排列,全组合
*****/
void createper(int n) //全排列
{
    int total, i, j, k, t, *a = new int[n], top;
    total = 1;
    for(i = 1; i <= n; i++) {
        a[i] = i;
        total *= i;
    }
    for(i = 1; i < n; i++) printf("%d ", a[i]);
    printf("%d\n", a[n]);
    for(i = 1; i < total; i++) {
        j = n;
        while(a[j] < a[j-1]) j--;
        k = n;
        while(a[j-1] > a[k]) k--;
        t = a[j-1];
        a[j-1] = a[k];
        a[k] = t;
        top = (j + n - 1) / 2;
        for(k = j; k <= top; k++) {
            t = a[k];
            a[k] = a[n - k + j];
            a[n - k + j] = t;
        }
    }
}

```

```

    }
    for(j=1;j<n;j++) printf("%d ",a[j]);
    printf("%d\n",a[n]);
}
}

void createfab(int m,int n) //全组合
{
    int i,j,lcount,*a=new int[n+2];
    for(i=1;i<=n;i++) a[i]=i;
    a[n+1]=m+1;
    for(j=1;j<n;j++) printf("%d ",a[j]);
    printf("%d\n",a[n]);
    lcount=1;
    while(a[1]<m-n+1) {
        for(i=n;i>0;i--) {
            if(a[i]<a[i+1]-1) {
                a[i]++;
                for(j=i;j<n;j++) a[j+1]=a[j]+1;
                for(j=1;j<n;j++) printf("%d ",a[j]);
                printf("%d\n",a[n]);
                lcount++;
                break;
            }
        }
    }
}
}

```

## 14. 二维线段树

```

/***** ***/
*   Function Name :   二维线段树RMQ
*   Description :     HDOJ 1823 Luck and Love
*****/
#include <cstdio>
#include <string>
#include <algorithm>
using namespace std;
#define NMAX 500000
#define MQ(x,y) ((x)>(y)?(x):(y))
struct node {
    node * pleft, * pright;
    node * ytree;
    int left, right;
    int M;
}

```



```

}mem[NMAX];
int mem_pos;

node * new_node()
{
    node * pt = &mem[mem_pos ++];
    memset(pt,0,sizeof(node));
    pt ->M = -1;//maximum or minimum
    return pt;
}

node * create_tree(int x1, int y1, int x2, int y2, bool flag)
{
    node * root = new_node();
    if(flag) { // first dimension
        root ->left = x1;
        root ->right = y1;
        root ->ytree = create_tree(x1, y1, x2, y2, false);
        if(x1 != y1) {
            int mid = (x1+y1)/2;
            root ->pleft = create_tree(x1, mid, x2, y2, true);
            root ->pright = create_tree(mid+1, y1, x2, y2, true);
        }
    }
    else { // second dimension
        root ->left = x2;
        root ->right = y2;
        if(x2 != y2) {
            int mid = (x2+y2)/2;
            root ->pleft = create_tree(x1, y1, x2, mid, false);
            root ->pright = create_tree(x1, y1, mid+1, y2, false);
        }
    }
    return root;
}

void update(node * root, int d1, int d2, int v, bool flag)
{
    int mid = (root ->left + root ->right)/2;
    if(flag) { // first dimension
        update(root ->ytree, d1, d2, v, false);
        if(root ->left < root ->right) {
            if(d1 <= mid) {
                update(root ->pleft, d1, d2, v, true);
            }
        }
    }
}

```

```

    }
    else {
        update(root ->pright, d1, d2, v, true);
    }
}
}
else { // second dimension
    if(root ->left == root ->right) {
        root ->M = MQ(root ->M, v);
    }
    else {
        if(d2 <= mid) {
            update(root ->pleft, d1, d2, v, false);
        }
        else {
            update(root ->pright, d1, d2, v, false);
        }
        root ->M = MQ(root ->pleft ->M, root ->pright ->M);
    }
}
}
}

```

```

int query(node * root, int x1, int y1, int x2, int y2, bool flag)
{
    int lmq, rmq;
    int mid = (root ->left + root ->right)/2;
    if(flag) { // first dimension
        if(root ->left == x1 && root ->right == y1) {
            return query(root ->ytree, x1, y1, x2, y2, false);
        }
        else {
            if(y1 <= mid) {
                return query(root ->pleft, x1, y1, x2, y2, true);
            }
            if(x1 > mid) {
                return query(root ->pright, x1, y1, x2, y2, true);
            }
            lmq = query(root ->pleft, x1, mid, x2, y2, true);
            rmq = query(root ->pright, mid+1, y1, x2, y2, true);
        }
    }
    else { // second dimension
        if(root ->left == x2 && root ->right == y2) {
            return root ->M;
        }
    }
}

```

```

    }
    else {
        if(y2 <= mid) {
            return query(root ->pleft, x1, y1, x2, y2, false);
        }
        if(x2 > mid) {
            return query(root ->pright, x1, y1, x2, y2, false);
        }
        lmq = query(root ->pleft, x1, y1, x2, mid, false);
        rmq = query(root ->pright, x1, y1, mid+1, y2, false);
    }
}
return MQ(lmq, rmq);
}

```

```

int main()
{
    int m;
    char cmd;
    while(scanf("%d", &m), m) {
        mem_pos = 0;
        node * root = create_tree(100,200,0,1000,true);
        while(m --) {
            getchar();
            cmd = getchar();
            if(cmd == 'I') {
                int h, ia, il;
                double a,l;
                scanf("%d %d %lf %lf", &h, &a, &l);
                ia = 10*(a+0.05);
                il = 10*(l+0.05);
                update(root, h, ia, il, true);
            }
            else {
                int h1, h2, ia1, ia2;
                double a1, a2;
                scanf("%d %d %lf %lf", &h1, &h2, &a1, &a2);
                ia1 = 10*(a1+0.05);
                ia2 = 10*(a2+0.05);
                if(h1 > h2) {
                    swap(h1, h2);
                }
                if(ia1 > ia2) {
                    swap(ia1, ia2);
                }
            }
        }
    }
}

```

```

    }
    int t = query(root, h1, h2, ia1, ia2, true);
    if(t == -1) {
        puts("-1");
    }
    else {
        printf("%.1lf\n", t / 10.0);
    }
}
}
}

```

## 15. 稳定婚姻匹配

```

/***** ***** *****/
*   Function Name :   稳定婚姻匹配gale_shapley算法
*   Description :     HDOJ 1522 Marriage is Stable
*****/
//rmw[i][j]代表i男对女生的喜欢排名
//lwm[i][j]代表i女对j男的喜欢程度
const int MAX = 510;
int w,m,n;
int rmw[MAX][MAX];
int lmw[MAX][MAX], lwm[MAX][MAX];
int couple[MAX];
char sman[MAX][110], swoman[MAX][110];

queue<int> SQ;
void gale_shapley()
{
    int i,man,woman;
    while(!SQ.empty()) {
        SQ.pop();
    }
    memset(couple,-1,sizeof(couple));
    for(i=1;i<=n;i++) {
        SQ.push(i);
    }
    while(!SQ.empty()) {
        man = SQ.front();
        for(i=1;i<=n;i++) {
            if(rmw[man][i] != -1) {
                //选择为被拒绝且最喜欢的女生
                woman = rmw[man][i];
                rmw[man][i] = -1;
            }
        }
    }
}

```

```
int pre = couple[woman];  
if(pre == -1) {  
    couple[woman] = man;  
    SQ.pop();  
    break;  
}  
else {  
    if(lwm[woman][man] > lwm[woman][pre]) {  
        SQ.pop();  
        SQ.push(pre);  
        couple[woman] = man;  
        break;  
    }  
}  
}  
}  
} //while  
}
```

## 16. 后缀数组

```

/***** *****/
*      Function Name :   后缀数组O(NLogN)
*      Description :     PKU 2774 Long Long Message
*****/

#include <stdio>
#include <string>
using namespace std;
const int MAX = 250000;
char txt[MAX];
int mem[3][MAX], c[MAX], height[MAX];
int * SA, * nSA, * Rank, * nRank;
int len, l1, l2;
//O(NLogN)
//SA[ rank ] = who;
//Suffix(SA[i]) < Suffix(SA[i+1]) , 1≤i<n
//Rank[ who ] = rank;
//k-Rank[i]代表加上满足Suffix(j) < k Suffix(i)的j的个数
void init()
{
    l1 = strlen(txt);
    txt[l1] = 1;//特殊结尾
    gets(txt + l1+1);
    l2 = strlen(txt + l1+1);
    len = l1 + l2+1;
}

```

```

    txt[len++] = 1; //特殊结尾
}
//性质.1 对 $k \geq n$ ,  $\text{Suffix}(i) < k \text{ Suffix}(j)$  等价于  $\text{Suffix}(i) < \text{Suffix}(j)$ 
//性质.2  $\text{Suffix}(i) = 2k \text{ Suffix}(j)$  等价于
// $\text{Suffix}(i) = k \text{ Suffix}(j)$  且  $\text{Suffix}(i+k) = k \text{ Suffix}(j+k)$ 
//性质.3  $\text{Suffix}(i) < 2k \text{ Suffix}(j)$  等价于
// $\text{Suffix}(i) < k \text{ Suffix}(j)$  或  $(\text{Suffix}(i) = k \text{ Suffix}(j) \text{ 且 } \text{Suffix}(i+k) < k \text{ Suffix}(j+k))$ 
void suffix_array()
{
    int i, j, k;
    SA = mem[0]; nSA = mem[1]; Rank = mem[2];
    memset(c, 0, sizeof(c));
    for(i=0; i<len; i++) {
        c[txt[i]]++;
    }
    for(i=0; i<128; i++) {
        c[i+1] += c[i];
    }
    for(i=0; i<len; i++) {
        SA[--c[txt[i]]] = i;
    }
    Rank[SA[0]] = 0;
    for(i=1; i<len; i++) {
        Rank[SA[i]] = Rank[SA[i-1]];
        if(txt[SA[i]] != txt[SA[i-1]]) {
            Rank[SA[i]]++;
        }
    }
    for(k=1; k<len && Rank[SA[len-1]]<len-1; k*=2) {
        memset(c, 0, sizeof(c));
        for(i=0; i<len; i++) {
            c[Rank[SA[i]]]++;
        }
        for(i=1; i<len; i++) {
            c[i] += c[i-1];
        }
        for(i=len-1; i>=0; i--) {
            if(SA[i] >= k) {
                nSA[--c[Rank[SA[i]-k]]] = SA[i] - k;
            }
        }
        for(i=len-k; i<len; i++) {
            nSA[--c[Rank[i]]] = i;
        }
    }
}

```

```

        nRank = SA;
        nRank[ nSA[0] ] = 0;
        for(i=1;i<len;i++) {
            nRank[ nSA[i] ] = nRank[ nSA[i-1] ];
            if(Rank[nSA[i]] != Rank[nSA[i-1]] || Rank[nSA[i]+k] !=
Rank[nSA[i-1]+k]) {
                nRank[nSA[i]] ++;
            }
        }
        SA = nSA;
        nSA = Rank;
        Rank = nRank;
    }
}
//LCP(i,j)=lcp(Suffix(SA[i]),Suffix(SA[j]))
//height[i]=LCP(i,i+1), ≤i<n
int getlcp()
{
    int i, j, k, rs;
    for (i = 0, k = 0; i < len; i++) {
        if (Rank[i] == len - 1) {
            height[Rank[i]] = k = 0;
        }
        else {
            if (k > 0) {
                k --;
            }
            j = SA[Rank[i] + 1];
            while(txt[i + k] == txt[j + k]) {
                k ++;
            }
            height[Rank[i]] = k;
        }
    }
    for (i = 0, rs = 0; i < len - 1; i++) {
        if (rs < height[i] && (SA[i] < l1) != (SA[i+1] < l1)) {
            rs = height[i];
        }
    }
    int t = min(l1,l2);
    return min(t, rs);
}

int main()

```

```
{
    gets(txt);
    init();
    suffix_array();
    printf("%d\n", getlcp());
    return 0;
}
```

## 17. 左偏树

```
/* **** * **** * **** * **** * **** */
*   Function Name :   左偏树
*   Description :     HDOJ 1512 Monkey King
*                       二叉堆的变形，方便堆的合并
* **** * **** * **** * **** * **** */

#include <stdio>
#include <string>
#include <queue>
#include <algorithm>
using namespace std;
const int MAX = 101000;
struct node {
    int v, dis; //键值，距离
    node * pl, * pr; //左右子树
    node * pf; //父节点
} mem[MAX];
int mem_pos;
int value[MAX], n;

node * new_node() {
    node * pt = mem + (mem_pos ++);
    memset(pt, 0, sizeof(node));
    return pt;
}
//清除节点休息
inline void clear(node * pos) {
    if(pos == NULL) return;
    pos->pl = pos->pr = pos->pf = NULL;
    pos->dis = 0;
}
//合并堆O(log N)
node * merge(node * pa, node * pb) {
    if(pa == NULL) return pb;
    if(pb == NULL) return pa;
    //maximum vertex heap
```



```

    if(pb->v > pa->v) std::swap(pa, pb);
    pa->pr = merge(pa->pr, pb);
    if(pa->pr) {
        if(pa->pl == NULL || pa->pr->dis > pa->pl->dis) {
            std::swap(pa->pl, pa->pr);
        }
    }
    if(pa->pr == NULL) pa->dis = 0;
    else pa->dis = pa->pr->dis + 1;
    if(pa->pl) pa->pl->pf = pa;
    if(pa->pr) pa->pr->pf = pa;
    return pa;
}

//插入节点
inline node * insert(node * root, node * val) {
    return merge(root, val);
}

//删除最大顶
inline node * delete_max(node * root) {
    node * pt = root;
    root = merge(root->pl, root->pr);
    if(root) root->pf = NULL;
    clear(pt);
    return root;
}

//取得最大值
inline int get_max(node * root) {
    return root->v;
}

//构建左偏树O(N)
inline node * make_leftist_tree() {
    queue<node *> SQ;
    node * ptemp;
    int i;
    ptemp = new_node();
    for(i=0;i<n;i++) {
        ptemp->v = value[i];
        SQ.push(ptemp);
    }
    while(!SQ.empty()) {
        int l = SQ.size();
        if(l == 1) return SQ.front();
        while(l --) {
            node * pa = SQ.front();

```

```

        SQ.pop();
        node * pb = SQ.front();
        SQ.pop();
        SQ.push(merge(pa, pb));
    }
}

//删除已知任意点 $O(\log N)$ 
inline void delete_any(node * pos) {
    node * ppre = pos->pf;
    node * pnnew = delete_max(pos);
    if(pnnew) pnnew->pf = ppre;
    if(ppre) {
        if(ppre->pl == pos) ppre->pl = pnnew;
        else ppre->pr = pnnew;
    }
    while(ppre) {
        int vl = -1, vr = -1;
        if(ppre->pl) vl = ppre->pl->dis;
        if(ppre->pr) vr = ppre->pr->dis;
        if(vl < vr) std::swap(ppre->pl, ppre->pr);
        if(vr + 1 == ppre->dis) return;
        ppre->dis = vr + 1;
        pnnew = ppre;
        ppre = ppre->pf;
    }
}

node ltree[MAX];
int main() {
    int i,j;
    int m,t;
    while(scanf("%d", &n)==1) {
        for(i=0;i<n;i++) {
            scanf("%d", &t);
            ltree[i].v = t;
            ltree[i].dis = 0;
            ltree[i].pl = ltree[i].pr = ltree[i].pf = NULL;
        }
        scanf("%d", &m);
        int a,b;
        while(m--) {
            scanf("%d %d", &a,&b);
            a--; b--;

```

```

        node * pa, * pb;
        pa = ltree + a;
        pb = ltree + b;
        while(pa->pf) pa = pa->pf;
        while(pb->pf) pb = pb->pf;
        if(pa == pb)    puts("-1");
        else {
            node * p1 = delete_max(pa);
            node * p2 = delete_max(pb);
            pa->v /= 2;
            pb->v /= 2;
            p1 = insert(p1, pa);
            p1 = insert(p1, pb);
            p1 = merge(p1, p2);
            printf("%d\n", get_max(p1));
        }
    }
}
}

```

## 18. 标准 RMQ-ST

```

/***** *****/
*   Function Name :   标准RMQ-ST
*   Description :     PKU 3264 Balanced Lineup
*****/

#include <cstdio>
#include <string>
#include <algorithm>
using namespace std;

const int MAX = 51000;
const int LOGMAX = 16;
int n,q;
int st_max[LOGMAX][MAX], st_min[LOGMAX][MAX];

void make_st()
{
    int i,j,k;
    for(j=1; (1<=j) <= n ;j++) {
        k = 1<=(j-1);
        for(i=0; i+k < n ;i++) {
            st_max[j][i] = max(st_max[j-1][i], st_max[j-1][i+k]);
            st_min[j][i] = min(st_min[j-1][i], st_min[j-1][i+k]);
        }
    }
}

```

```

    }
}

int rmq(int a,int b,int flag)
{
    int dis = abs(b-a) +1;
    int k;
    for(k=0; (1<<k) <= dis ;k++) ;
    k --;
    if(flag > 0) {
        return max(st_max[k][a], st_max[k][b-(1<<k)+1]);
    }
    else {
        return min(st_min[k][a], st_min[k][b-(1<<k)+1]);
    }
}

int main()
{
    while(scanf("%d %d", &n,&q)==2) {
        int i;
        for(i=0;i<n;i++) {
            scanf("%d", &st_max[0][i]);
            st_min[0][i] = st_max[0][i];
        }
        make_st();
        for(i=0;i<q;i++) {
            int a,b;
            scanf("%d %d", &a,&b);
            printf("%d\n", rmq(a-1,b-1,1) - rmq(a-1,b-1,-1));
        }
    }
}

```

## 19. 度限制最小生成树

```

/***** *****/
*   Function Name :   度限制最小生成树
*   Description :     PKU 1639 Picnic Planning
*                   有一个顶点有度限制，如果所有点都有限制，当限制>4时是NP
*****/
#include <cstdio>
#include <string>
#include <queue>
#include <vector>

```

```

#include <map>
#include <algorithm>
using namespace std;
const int MAX = 50;
int t,n,m;
map<string , int> names;
int path[MAX][MAX];
//dmax[i]: vi->park, 不与park相连的边的最大权值
int dmax[MAX];
struct node {
    int s,t;
    int dis;
    bool operator < (const node & tt) const {
        return dis > tt.dis;
    }
};
bool vis[MAX];
//block[i]: vi所属连通分量
//bs: 连通分量数目
//v0min[i][2]: park与第i个连通分量的最小权值[0], 连接顶点[1]
int block[MAX], v0min[MAX][2], bs;
//mst: 度限制生成树
vector<int> mst[MAX];
queue<int> sq;
//最小花费, park下标, 限制度数
int cost, park, deg;
//O(NlogN) prime求所有连通分量mst
void prime_all_mst() {
    int i,j;
    priority_queue<node> pq;
    node now, next;
    memset(vis, 0, sizeof(vis));
    for(i=0; i<=n; i++) mst[i].clear();
    vis[park] = true;
    block[park] = 1; bs = 1; //park为第个连通分量
    cost = 0;
    for(i=1; i<=n; i++) {
        if(!vis[i]) {
            bs++;
            while(!pq.empty()) pq.pop();
            now.s = i; now.t = i; now.dis = 0;
            pq.push(now);
            while(!pq.empty()) {
                now = pq.top();
            }
        }
    }
}

```

```

        pq.pop();
        if(vis[now.t]) continue;
        vis[now.t] = true;
        mst[now.s].push_back(now.t);
        mst[now.t].push_back(now.s);
        block[now.t] = bs;
        cost += now.dis;
        next.s = now.t;
        for(j=1;j<=n;j++) {
            if(!vis[j] && path[next.s][j] != -1) {
                next.t = j;
                next.dis = path[next.s][j];
                pq.push(next);
            }
        }
    }
}

//O(N) park连接各连通分量
bool connect_block() {
    int i,j,k;
    //选取连接相邻连通分量的最小边
    for(i=2;i<=bs;i++) v0min[i][0] = INT_MAX;
    while(!sq.empty()) sq.pop();
    for(i=1;i<=n;i++) {
        if(path[park][i] != -1 && v0min[block[i]][0] > path[park][i]) {
            v0min[block[i]][0] = path[park][i];
            v0min[block[i]][1] = i;
        }
    }
    k = 0;
    for(i=2;i<=bs;i++) {
        if(v0min[i][0] != INT_MAX) {
            cost += v0min[i][0];
            path[park][ v0min[i][1] ] = -1;
            dmax[ v0min[i][1] ] = INT_MIN;
            sq.push(v0min[i][1]); //用来初始化dmax
            k ++; //能连通的分量数
        }
    }
    //图连通，且限制度数大于等于连通分量数
    deg -= bs-1;
    return k >= bs-1 && deg >= 0;
}

```

```

}
//O(N) 计算dmax
void cal_dmax() {
    int i;
    memset(vis, 0, sizeof(vis));
    while(!sq.empty()) {
        int now = sq.front();
        sq.pop();
        vis[now] = true;
        for(i=0;i<mst[now].size();i++) {
            int next = mst[now][i];
            if(!vis[next]) {
                dmax[next] = max(dmax[now], path[now][next]);
                sq.push(next);
                vis[next] = true;
            }
        }
    }
}

//O(N) 差额最小删除操作
void del_path(int pos, int val) {
    int i;
    queue<int> sq2;
    memset(vis, 0, sizeof(vis));
    sq2.push(pos);
    vis[pos] = true;
    while(!sq2.empty()) {
        int now = sq2.front();
        sq2.pop();
        for(i=0;i<mst[now].size();i++) {
            int next = mst[now][i];
            if(!vis[next]) {
                if(val == path[now][next]) {
                    mst[now].erase(mst[now].begin() + i);
                    return;
                }
                sq2.push(next);
                vis[next] = true;
            }
        }
    }
}

//O(deg*N)
bool deg_limit_mst() {

```

```

int i,j,v;
int minv,minp;
cal_dmax();
for(i=0;i<deg;i++) {
    minv = INT_MAX; minp = -1;
    for(j=1;j<=n;j++) {
        if(path[park][j] != -1) { //差额最小选择操作
            if(minv > path[park][j] - dmax[j]) {
                minv = path[park][j] - dmax[j];
                minp = j;
            }
        }
    }
    v = cost + minv;
    if(minp == -1 || v >= cost) return false;
    cost = v;
    path[park][minp] = -1; //差额最小添加删除操作
    del_path(minp, dmax[minp]);
    mst[park].push_back(minp);
    while(!sq.empty()) sq.pop();
    sq.push(minp);
    dmax[minp] = INT_MIN;
    cal_dmax();
}
for(i=0;i<mst[park].size();i++) mst[ mst[park][i] ].push_back(park);
return true;
}

int main() {
    int i,j;
    char n1[20], n2[20];
    names.clear();
    scanf("%d", &m);
    memset(path, -1, sizeof(path));
    n = 1;
    for(i=0;i<m;i++) {
        int x,y,z;
        scanf("%s %s %d", n1,n2,&z);
        x = names[string(n1)];
        y = names[string(n2)];
        if(x == 0) names[string(n1)] = x = n ++;
        if(y == 0) names[string(n2)] = y = n ++;
        if(strcmp(n1,"Park") == 0) park = x;
        else if(strcmp(n2,"Park") == 0) park = y;
    }
}

```



```

        path[x][y] = path[y][x] = z;
    }
    n--;
    scanf("%d", &deg);
    prime_all_mst();
    connect_block();
    deg_limit_mst();
    printf("Total miles driven: %d\n", cost);
}

```

## 20. 最优比率生成树

```

/***** *****/
*   Function Name :   最优比率生成树(迭代法)
*   Description :     PKU 2728 Desert King
*****/

#include <cstdio>
#include <string>
#include <cmath>
#include <algorithm>
using namespace std;

const int MAX = 1100;
int n;
struct point {
    int x,y,z;
}vi[MAX];
struct node {
    int s, t;
    double dis;
    bool operator < (const node & tt) const {
        return dis > tt.dis;
    }
};

double dist[MAX][MAX];
bool vis[MAX];
double rate;

double prime() {
    double cost = 0;
    double len = 0;
    double d[MAX],v;
    int pre[MAX];
    int i,j;
    memset(vis, 0, sizeof(vis));

```

```

vis[0] = true;
for(i=1;i<n;i++) {
    d[i] = abs(vi[0].z-vi[i].z) - rate*dist[0][i];
    pre[i] = 0;
}
for(i=1;i<n;i++) {
    double minv = INT_MAX;
    int minp = -1;
    for(j=1;j<n;j++) {
        if(!vis[j] && minv > d[j]) {
            minv = d[j];
            minp = j;
        }
    }
    vis[minp] = true;
    cost += abs(vi[pre[minp]].z - vi[minp].z);
    len += dist[pre[minp]][minp];
    for(j=1;j<n;j++) {
        if(!vis[j] && d[j] > (v=abs(vi[minp].z-vi[j].z) - rate*dist[minp][j])) {
            d[j] = v;
            pre[j] = minp;
        }
    }
}
return cost / len;
}

int main() {
    int i,j;
    while(scanf("%d", &n), n) {
        for(i=0;i<n;i++) {
            scanf("%d %d %d", &vi[i].x, &vi[i].y, &vi[i].z);
        }
        for(i=0;i<n;i++) {
            dist[i][i] = 0;
            for(j=i+1;j<n;j++) {
                dist[i][j] = dist[j][i] = sqrt(1.0*(vi[i].x-vi[j].x)*(vi[i].x-vi[j].x) +
                (vi[i].y-vi[j].y)*(vi[i].y-vi[j].y));
            }
        }
        rate = 0;
        while(true) {
            double pre = rate;
            rate = prime();

```

```

        if(fabs(rate - pre) < 0.001) break;
    }
    printf("%.3lf\n", rate);
}
}

```

## 21. 最小花费置换

//Cow Sorting

//对一个轮换进行处理的时候，应该考虑在轮换内进行交换，或与轮换外的元素交换之后，使代价值更小

```

#include <cstdio>
#include <string>
#include <functional>
#include <algorithm>
using namespace std;
int g[10100],n;
bool vis[10100];
int pos[101000];
struct node {
    int v,p;
    bool operator < (const node & t) const {
        return v < t.v;
    }
}g2[10100];
int main() {
    int i,j;
    int sum, mmin;
    while(scanf("%d", &n)==1) {
        sum = 0;
        mmin = INT_MAX;
        for(i=1;i<=n;i++) {
            scanf("%d", g+i);
            sum += g[i];
            g2[i].v = g[i];
            g2[i].p = i;
            mmin = min(mmin, g[i]);
            vis[i] = false;
        }
        sort(g2+1,g2+n+1);
        for(i=1;i<=n;i++) {
            pos[ g2[i].v ] = g2[i].p;
        }
        for(i=1;i<=n;i++) {
            if(!vis[i]) {

```

```

        int tpos = i;
        int len = 0;
        int tmin = INT_MAX;
        do {
            tmin = min(tmin, g[tpos]);
            vis[tpos] = true;
            tpos = pos[ g2[tpos].v ];
            len ++;
        } while(tpos != i);
        //选择两种方案中的最优方案
        sum += min( (len-2)*tmin, (len+1)*mmin +tmin);
    }
    }
    printf("%d\n", sum);
}
}

```

## 22. 区间 K 大数

```

//POJ 2104
#include <cstdio>
#include <string>
#include <vector>
#include <algorithm>
using namespace std;
const int NMAX = 100000;
const int LOGNMAX = 17 +1;
int sortseq[LOGNMAX][NMAX];
int num[NMAX];
struct node {
    int l,r,d;
    node * pl,* pr;
}mem[(NMAX<<1)+100];
int mempos,n,m;
node * root;
node * make_tree(int l,int r,int d) {
    node * rt = mem+(mempos ++);
    rt->l = l; rt->r = r; rt->d = d;
    if (l == r) {
        sortseq[d][l] = num[l];
        return rt;
    }
    int mid = (l+r) >> 1;
    rt->pl = make_tree(l,mid,d+1);
    rt->pr = make_tree(mid+1,r,d+1);
}

```

```

    int i=l,j=mid+1,k=l;
    while (i<=mid && j<=r) {
        if (sortseq[d+1][i] < sortseq[d+1][j]) sortseq[d][k++] =
sortseq[d+1][i++];
        else sortseq[d][k++] = sortseq[d+1][j++];
    }
    while (i<=mid) sortseq[d][k++] = sortseq[d+1][i++];
    while (j<=r) sortseq[d][k++] = sortseq[d+1][j++];
    return rt;
}
int s,t,rank;
int query(node * rt,int val) {
    int i,mid,ret;
    if (s <= rt->l && rt->r <= t) {
        if (val <= sortseq[rt->d][rt->l]) return 0;
        else if (sortseq[rt->d][rt->r] < val) return rt->r - rt->l + 1;
        else if (sortseq[rt->d][rt->r] == val) return rt->r - rt->l;
        int l = rt->l, r = rt->r, mid;
        while (l <= r) {
            mid = (l+r) >> 1;
            if (val <= sortseq[rt->d][mid]) r = mid-1;
            else l = mid+1;
        }
        return l - rt->l;
    }
    else {
        ret = 0;
        mid = (rt->l+rt->r) >> 1;
        if (s <= mid) ret += query(rt->pl,val);
        if (mid+1 <= t) ret += query(rt->pr,val);
        return ret;
    }
}
// 二分查找时遇到相同值的处理非常重要
int main() {
    int i,j,l,r;
    scanf("%d %d",&n,&m);
    for (i=0;i<n;i++) scanf("%d",num+i);
    mempos = 0;
    root = make_tree(0,n-1,0);
    while (m --) {
        s = get_val()-1; t = get_val()-1; rank = get_val()-1;
        l = 0, r = n-1;
        while (l <= r) {

```

```

        int mid = (l+r) >> 1;
        // 二分查找sortseq[0][mid]在区间[s,t]中的排名
        int pos = query(root,sortseq[0][mid]);
        if (rank < pos) r = mid-1;
        else l = mid+1;
    }
    printf("%d\n",sortseq[0][r]);
}
}

```

## 23. LCA – RMQ-ST

```

//POJ 3417
//online O(nlogn)-O(1)
#include <cstdio>
#include <string>
#include <queue>
#include <algorithm>
using namespace std;
typedef __int64 bigint;
const int MAX = 100010;
const int STMAX = 200010;
const int LOGMAX = 18;

int n,m;
const int ENDFLAG = 0;
struct EDGELIST {
    int start[MAX];
    int last[MAX];
    int edge[MAX<<1][2]; //pos,listnext
    int tot;

    void clear() {
        tot = ENDFLAG + 1;
        memset(last,ENDFLAG,sizeof(last));
        memset(start,ENDFLAG,sizeof(start));
    }
    void push_back(int s,int t) {
        edge[tot][0] = t;
        edge[tot][1] = ENDFLAG;
        if (last[s] != ENDFLAG) {
            edge[ last[s] ][1] = tot;
        }
        else {
            start[s] = tot;
        }
    }
}

```

```

    }
    last[s] = tot;
    tot ++;
    //swap
    if (s == t) return;
    edge[tot][0] = s;
    edge[tot][1] = ENDFLAG;
    if (last[t] != ENDFLAG) {
        edge[ last[t] ][1] = tot;
    }
    else {
        start[t] = tot;
    }
    last[t] = tot;
    tot ++;
}
}tree;
int cov[MAX];
bool vis[MAX];
bigint cnt[2];

int root[MAX],son[MAX];
int stn;
int st_min[LOGMAX][STMAX];
int order[STMAX],first[MAX],deep[STMAX];

void make_st() {
    int i,j,k;
    for (i=0;i<stn;i++) st_min[0][i] = i;
    for(j=1; 1<=j <= stn ;j++) {
        k = 1<<(j-1);
        for(i=0; i+k < stn ;i++) {
            if (deep[st_min[j-1][i]] < deep[st_min[j-1][i+k]])
                st_min[j][i] = st_min[j-1][i];
            else
                st_min[j][i] = st_min[j-1][i+k];
        }
    }
}

int rmq(int a,int b) {
    int dis = abs(b-a) +1;
    int k;
    for(k=0; (1<=k) <= dis ;k++) ;

```

```

    k--;
    int ret = st_min[k][a];
    if (deep[ret] > deep[st_min[k][b-(1<<k)+1]])
        ret = st_min[k][b-(1<<k)+1];
    return ret;
}

int lca(int a,int b) {
    int x = first[a],y = first[b];
    if (x > y) swap(x,y);
    return order[rmq(x,y)];
}

int ordcnt;
int sq[MAX];
int qf,qe;
void dfs(int pos,int d) {
    int i,j;
    vis[pos] = true;
    first[pos] = ordcnt;
    deep[ordcnt] = d;
    order[ordcnt++] = pos;
    for (i=tree.start[pos]; i != ENDFLAG ;i=tree.edge[i][1]) {
        int next = tree.edge[i][0];
        if (vis[next]) continue;
        son[pos]++;
        root[next] = pos;
        dfs(next,d+1);
        deep[ordcnt] = d;
        order[ordcnt++] = pos;
    }
    if (son[pos] == 0) sq[qe++] = pos;
}

void treedp() {
    son[0] = -1;
    while (qf < qe) {
        int now = sq[qf++];
        if (cov[now] <= 1) cnt[ cov[now] ]++;
        son[ root[now] ]--;
        cov[ root[now] ] += cov[now];
        if (son[ root[now] ] == 0) sq[qe++] = root[now];
    }
}

```



```
int get_val() {
    int ret = 0;
    char ch;
    while ((ch=getchar()) > '9' || ch < '0') ;
    do {
        ret = ret*10 + ch - '0';
    } while ((ch=getchar()) <= '9' && ch >= '0') ;
    return ret;
}
```

```
int main() {
    int i,j,a,b,rt;
    n = get_val();
    m = get_val();
    if (n == 1) {
        puts("0");
        return 0;
    }

    tree.tot = ENDFLAG + 1;
    qf = qe = 0;
    for (i=0;i<n-1;i++) {
        a = get_val();
        b = get_val();
        tree.push_back(a,b);
        rt = a;
    }
```

```
    ordcnt = 0;
    dfs(rt,0);
    stn = ordcnt;
    make_st();
```

```
    for (i=0;i<m;i++) {
        a = get_val();
        b = get_val();
        cov[a] ++;
        cov[b] ++;
        cov[lca(a,b)] -= 2;
    }
```

```
    treedp();
    cnt[0] --;
```

```

    printf("%I64d\n",cnt[0]*m + cnt[1]);
}

```

## 24. LCA – Tarjan

```

//POJ 3417
//offline O(na(n))
#include <cstdio>
#include <string>
#include <vector>
#include <algorithm>
using namespace std;
typedef __int64 bigint;
const int MAX = 100010;

int n,m;
const int ENDFLAG = 0;
struct EDGELIST {
    int start[MAX];
    int last[MAX];
    int edge[MAX<<1][2]; //pos,listnext
    int tot;

    void clear() {
        tot = ENDFLAG + 1;
        memset(last,ENDFLAG,sizeof(last));
        memset(start,ENDFLAG,sizeof(start));
    }
    void push_back(int s,int t) {
        edge[tot][0] = t;
        edge[tot][1] = ENDFLAG;
        if (last[s] != ENDFLAG) {
            edge[ last[s] ][1] = tot;
        }
        else {
            start[s] = tot;
        }
        last[s] = tot;
        tot ++;
        //swap
        if (s == t) return;
        edge[tot][0] = s;
        edge[tot][1] = ENDFLAG;
    }
}

```

```

        if (last[t] != ENDFLAG) {
            edge[ last[t] ][1] = tot;
        }
        else {
            start[t] = tot;
        }
        last[t] = tot;
        tot ++;
    }
}tree,newed;
int cov[MAX];
bool vis[MAX];
bigint cnt[2];

int father[MAX];
int ancestor[MAX];

int find_set(int x) {
    if (father[x] == x) return x;
    return father[x] = find_set(father[x]);
}

void union_set(int x,int y) {
    father[ find_set(y) ] = x;
}

void tarjan(int pos,int pre) {
    int i,j;

    father[pos] = pos;
    ancestor[pos] = pos;

    for (i=tree.start[pos]; i != ENDFLAG ;i=tree.edge[i][1]) {
        int next = tree.edge[i][0];
        if (next == pre) continue;
        tarjan(next,pos);
        union_set(pos,next);
        cov[pos] += cov[next];
    }

    vis[pos] = true;
    for (j=newed.start[pos]; j != ENDFLAG ;j=newed.edge[j][1]) {
        int next = newed.edge[j][0];
        if (vis[next]) cov[ ancestor[ find_set(next) ] ] -= 2;
    }
}

```

```

    }

    if (cov[pos] <= 1) cnt[ cov[pos] ] ++;
}

int get_val() {
    int ret = 0;
    char ch;
    while ((ch=getchar()) > '9' || ch < '0') ;
    do {
        ret = ret*10 + ch - '0';
    } while ((ch=getchar()) <= '9' && ch >= '0') ;
    return ret;
}

int main() {
    int i,j,a,b,rt;
    n = get_val();
    m = get_val();
    if (n == 1) {
        puts("0");
        return 0;
    }

    tree.tot = newed.tot = ENDFLAG +1;
    for (i=0;i<n-1;i++) {
        a = get_val();
        b = get_val();
        tree.push_back(a,b);
        rt = a;
    }

    for (i=0;i<m;i++) {
        a = get_val();
        b = get_val();
        newed.push_back(a,b);
        cov[a] ++;
        cov[b] ++;
    }

    tarjan(rt,rt);
    cnt[0] --;
    printf("%I64d\n",cnt[0]*m + cnt[1]);
}

```

## 25. 指数型母函数

/\*

HDOJ 1521 排列组合

有n种物品，并且知道每种物品的数量。要求从中选出m件物品的排列数。 $\leq m, n \leq 10$

数量较少时，直接用除法

\*/

#include <stdio>

#include <string>

#define MAX 100

double cal[2][MAX];

double \*pre,\*now,\*pt;

int n,m;

int a[11];

double fac[100];

int main()

{

int i,j,k,sum;

fac[0] = fac[1] = 1;

for (i=2;i<=20;i++) {

fac[i] = fac[i-1] \* i;

}

while (scanf("%d %d",&n,&m)==2) {

memset(cal,0,sizeof(cal));

for (i=0;i<n;i++) {

scanf("%d",&a[i]);

}

pre = cal[0];

now = cal[1];

pre[0] = 1;

for (i=1;i<=a[0];i++) {

pre[i] = 1.0 / fac[i];

}

for (i=1;i<n;i++) {

for (j=0;j<MAX;j++) {

if (pre[j] > 0) {

for (k=0;k<=a[i];k++) {

now[k+j] += pre[j] / fac[k];

}

}

}

```

        pt = now;
        now = pre;
        pre = pt;
        memset(now,0,sizeof(cal[0]));
        pre[0] = 1;
    }
    printf("%.0lf\n",fac[m] * pre[m]);
}
}

```

## 26. 指数型母函数（大数据）

```

#include<iostream>
using namespace std;
int mm[1000][100];
__int64 a[1000], b[1000];

inline __int64 gcd(__int64 x, __int64 y) //求公约数
{
    __int64 temp;
    while (x % y) {
        temp = x % y;
        x = y;
        y = temp;
    }
    return y;
}

int main() {
    int n, m, i, j, k;
    __int64 tmp, tmp1;
    while (scanf("%d %d", &n, &m) != EOF) {
        for (i = 0; i < n; i++) {
            scanf("%d", &mm[i][0]);
            for (j = 1; j <= mm[i][0]; j++)
                scanf("%d", &mm[i][j]);
        }
        memset(a, 0, sizeof(__int64)*(m + 1));
        for (i = 1; i <= mm[0][0]; i++)
            a[mm[0][i]] = 1;
        for (i = 1; i < n; i++) {
            memset(b, 0, sizeof(__int64)*(m + 1));
            for (j = 0; j <= m; j++)
                for (k = 1; j + mm[i][k] <= m && k <= mm[i][0]; k++) {
                    if (mm[i][k] != 0) {

```

```

        tmp = 1; tmp1 = 1;
        int w = j + mm[i][k];
        int x = mm[i][k] < j ? mm[i][k] : j; //x是较小的数
        int y = w - x;

        __int64 z;
        while (w > y) {
            tmp *= w;
            tmp1 *= x;
            z = gcd(tmp, tmp1);
            if (z > 1) {
                tmp /= z;
                tmp1 /= z;
            }
            w--;
            x--;
        }

        b[j + mm[i][k]] += tmp * a[j];
    }
}
for (j = 0; j <= m; j++)
    a[j] += b[j];
}
printf("%I64d\n", a[m]);
}
return 0;
}

```

## 27. AC 自动机（字典树+KMP）

```

const int NMAX = 10000;
const int LMAX = 1000001;
const int MMAX = 51;
const int MEMMAX = 500000;

```

```

char s[LMAX];
char p[MMAX];
int n, m;

```

```

struct NODE
{
    int nsuffix;
    char chword;
    NODE * next, * father;
}

```

```
    NODE * son[26];
}mem[MEMMAX];
int total;
NODE * root;

NODE * new_node()
{
    NODE * ret = &mem[total ++];
    memset(ret, 0, sizeof(NODE));
    return ret;
}

// O(n MMAX)
void insert(NODE * rt, char * p)
{
    //puts(p);
    if (*p == 0)
    {
        rt->nsuffix ++;
        return;
    }
    if (rt->son[*p - 'a'] == NULL)
    {
        rt->son[*p - 'a'] = new_node();
        rt->son[*p - 'a']->father = rt;
        rt->son[*p - 'a']->chword = *p;
    }
    insert(rt->son[*p - 'a'], p+1);
}

// O(n MMAX)
void bfs()
{
    int i, j;
    queue <NODE *> sq;
    sq.push(root);

    while (!sq.empty())
    {
        NODE * now = sq.front();
        sq.pop();

        if (now->father == root)
            now->next = root;
    }
}
```



```

else
{
    NODE * shift = (now->father)->next;
    while (shift != root && shift->son[now->chword - 'a'] == NULL)
        shift = shift->next;
    now->next = shift->son[now->chword - 'a'];
    if (now->next == NULL)
        now->next = root;
}

for (i=0; i<26; i++)
{
    if (now->son[i] != NULL)
        sq.push(now->son[i]);
}
}
}

// O(LMAX)
int solve()
{
    int i,j;
    int ret = 0;
    NODE * now = root;
    NODE * psuffix;

    root->father = root;
    bfs();

    for (i=0; s[i]; i++)
    {
        while (now != root && now->son[ s[i] - 'a' ] == NULL)
            now = now->next;
        now = now->son[ s[i] - 'a' ];
        if (now == NULL)
            now = root;
        // add same suffix
        psuffix = now;
        while (psuffix != root && psuffix->nsuffix != -1)
        {
            ret += psuffix->nsuffix;
            psuffix->nsuffix = -1;
            psuffix = psuffix->next;
        }
    }
}

```

```
    }  
    return ret;  
}
```

## 28. FFT (大数乘法)

```
const int BASE = 100000;  
const int N_DIGIT = 5;  
const int N = 32768;  
const double PI = acos(-1.0);
```

```
struct Complex  
{  
    double real, imag;  
};
```

```
Complex omega[N >> 1];  
Complex a[N];  
Complex b[N];
```

```
char s[1000003];  
int d[N], len;
```

```
void bitReverse(Complex a[])  
{  
    int i, j = 1, k;  
    Complex t;  
    for (i = 1; i < len; ++ i)  
    {  
        if (i < j)  
        {  
            t.real = a[j - 1].real;  
            t.imag = a[j - 1].imag;  
            a[j - 1].real = a[i - 1].real;  
            a[j - 1].imag = a[i - 1].imag;  
            a[i - 1].real = t.real;  
            a[i - 1].imag = t.imag;  
        }  
        k = len >> 1;  
        while (k < j)  
        {  
            j -= k;  
            k >>= 1;  
        }  
        j += k;  
    }
```

```

    }
}

void calOmega()
{
    double unit = 2 * PI / len;
    int n = len >> 1;
    for (int i = 0; i < n; ++ i)
    {
        double t = unit * i;
        omega[i].real = cos( t );
        omega[i].imag = sin( t );
    }
}

void fft(Complex a[], bool inverse = false)
{
    bitReverse( a );

    int s = len >> 1;
    int m, k, j;
    int up, t, step;
    int i1, i2;
    Complex tmp;

    if ( inverse )
    {
        for (j = 0; j < s; ++ j)
            omega[j].imag = - omega[j].imag;
    }
    s = 1;
    for (m = 2; m <= len; m <= 1)
    {
        up = m >> 1, t = len >> s;           // 2^(log2(n) - s) != n - 2^s  !!!!!!!
        for (k = 0; k < len; k += m)
        {
            step = 0;
            for (j = 0; j < up; ++ j)
            {
                i1 = k + j;
                i2 = i1 + up;
                tmp.real = omega[step].real * a[i2].real - omega[step].imag *
a[i2].imag;
                tmp.imag = omega[step].real * a[i2].imag + omega[step].imag *

```

```

a[i2].real;
        a[i2].real = a[i1].real - tmp.real;
        a[i2].imag = a[i1].imag - tmp.imag;
        a[i1].real += tmp.real;
        a[i1].imag += tmp.imag;
        step += t;
    }
}
++ s;
}
if ( inverse )
{
    double t = 1.0 / len;
    for (j = 0; j < len; ++ j)
        a[j].real *= t;
}
}

int convert(int d[], char s[])
{
    int sLen = strlen( s );
    int dLen = ((sLen - 1) / N_DIGIT) + 1, i = 0, n;
    char *pRight = s + sLen - 1, *pLeft = pRight - (N_DIGIT - 1);
    memset(d, 0, sizeof(int) * dLen);

    while (i < dLen && pRight >= s)
    {
        if (pLeft < s)    pLeft = s;
        n = 0;
        while (pLeft <= pRight)
        {
            n = n * 10 + (*pLeft & 15);
            ++ pLeft;
        }
        d[i++] = n;
        pRight -= N_DIGIT;
        pLeft = pRight - (N_DIGIT - 1);
    }
    return dLen;
}

bool init()
{
    int i, j;

```

```
//read a
if (scanf("%s", s) != 1)
    return false;
int aLen = convert(d, s);           //length of a
for (i = 0; i < aLen; ++ i)
{
    a[i].real = d[i];
    a[i].imag = 0;
}

//read b
scanf("%s", s);
int bLen = convert(d, s);           //length of b
for (j = 0; j < bLen; ++ j)
{
    b[j].real = d[j];
    b[j].imag = 0;
}

len = 1;                             //length of product who uses int
while (len < aLen + bLen)    len <<= 1;

memset(a + i, 0, sizeof(Complex) * (len - i));
memset(b + j, 0, sizeof(Complex) * (len - j));

calOmega();
return true;
}

void mul()
{
    for (int i = 0; i < len; ++ i)
    {
        double real = a[i].real * b[i].real - a[i].imag * b[i].imag;
        double imag = a[i].real * b[i].imag + a[i].imag * b[i].real;
        a[i].real = real;
        a[i].imag = imag;
    }
}

void print()
{
    double carry = 0, t;
```

```

static char format[10];
int i;

for (i = 0; i < len; ++ i)
{
    t = carry + a[i].real;
    carry = floor((t + 0.5) / BASE);
    d[i] = int(t - carry * BASE + 0.5);
}
for (i = len - 1; i > 0 && d[i] == 0; -- i);
sprintf(format, "%%.%dd", N_DIGIT);
printf("%d", d[i]);
for (-- i; i >= 0; -- i)
    printf(format, d[i]);
printf("\n");
}

int main()
{
    while ( init() )
    {
        fft( a );
        fft( b );
        mul();
        fft(a, true);
        print();
    }

    return 0;
}

```

## 29. 二分图网络最大流最小割

```

// PKU 2125 Destroying The Graph
// 二分图最小点权覆盖集，求割集
// 1. 设置一个集合A，最开始A={s},按如下方法不断扩张A:
// 2. 若存在一条边(u,v)，其流量小于容量，且u属于A,则v加入A
// 3. 若存在(v,u)，其流量大于0，且u属于A,则v加入A
// 4. A计算完毕，设B=V-A，最小割集E={ (u,v) | u∈A,v∈B }
// Character '+' means that Bob removes all arcs incoming into the specified vertex
// and '-' that Bob removes all arcs outgoing from the specified vertex.
bool S[MAX];
void dfs(int pos) {
    int i;
    S[pos] = 1;

```

```

    for(i=1;i<=m;i++) {
        if(!S[i] && net[pos][i]) dfs(i);
    }
}

struct node {
    int num;
    char sign;
}cs[MAX];
void find_cut() {
    int i,ps = 0;
    memset(S, 0, sizeof(S));
    dfs(1);
    for(i=2;i<=n+1;i++) {
        if(!S[i] && net[1][i] == 0) {
            //printf("%d -\n", i-1);
            cs[ps].num = i-1;
            cs[ps].sign = '-';
            ps ++;
        }
    }
    for(i=n+2;i<=2*n+1;i++) {
        if(S[i] && net[i][m] == 0) {
            //printf("%d +\n", i-n-1);
            cs[ps].num = i-n-1;
            cs[ps].sign = '+';
            ps ++;
        }
    }
    printf("%d\n", ps);
    for(i=0;i<ps;i++) printf("%d %c\n", cs[i].num, cs[i].sign);
    //puts("-----");
    //for(i=1;i<=m;i++) if(S[i]) printf("%d ",i);
    //puts("\n-----");
}

int win[MAX], wout[MAX];
int main() {
    int i,j;
    while(scanf("%d %d", &n,&m)==2) {
        memset(net, 0, sizeof(net));
        for(i=2;i<=n+1;i++) scanf("%d", win+i);
        for(i=2;i<=n+1;i++) scanf("%d", wout+i);
        while(m --) {

```

```

        int x,y;
        scanf("%d %d", &x,&y);
        x ++; y += n+1;
        net[x][y] = INT_MAX;
    }
    for(i=2;i<=n+1;i++) {
        net[1][i] = wout[i];
    }
    for(i=n+2;i<=2*n+1;i++) {
        net[i][2*n+2] = win[i-n];
    }
    m = 2*n + 2;
    printf("%d\n", Edmonds_Karp());
    find_cut();
}
}

```

### 30. 混合图欧拉回路

```

// 1637 PKU
bool solve()
{
    int i, j;
    for (i=2; i<n; i++)
    {
        x[i] = indeg[i] - outdeg[i];
        if (x[i] % 2)
            return false;
        if (x[i] > 0)
            net[i][m] += x[i] >> 1;
        else if (x[i] < 0)
            net[1][i] += (-x[i]) >> 1;
    }
    int cap = 0;
    for (i=2; i<n; i++)
        cap += net[1][i];
    int flow = Edmonds_Karp();
    // when flow==cap, say it exist euler circuit
    /*
    // print the undirected edge's direction
    for (i=2; i<m; i++)
        for (j=2; j<m; j++)
            if (net[i][j] != 0)
                printf("%d -> %d\n", i-1,j-1);
    */
}

```



```

    return (flow == cap);
}

int main()
{
    int i, j, cas;
    scanf("%d", &cas);
    while (cas --)
    {
        memset(indeg, 0, sizeof(indeg));
        memset(outdeg, 0, sizeof(outdeg));
        memset(net, 0, sizeof(net));
        scanf("%d %d", &m, &s);
        for (i=0; i<s; i++)
        {
            int x, y, d;
            scanf("%d %d %d", &x, &y, &d);
            x ++; y ++;
            // if d=0, make x->y
            indeg[y] ++;
            outdeg[x] ++;
            if (d == 0)
                net[x][y] ++;
        }
        n = m + 2;
        puts(solve() ? "possible" : "impossible");
    }
}

```

### 31. 无源汇上下界网络流

```

/*
* 2314 ZJU Reactor Cooling
* 无源汇上下界网络流
* (1) 新建S, T
* (2)  $D(u) = \sum B(i,u) - \sum B(u,i)$ 
*       $D(u) > 0$ , 建弧(S,u), 权值为D(u)
*       $D(u) < 0$ , 建弧(u,T), 权值为-D(u)
* (3) 求最大流, 判定是否满流
*/
struct NODE
{
    int x, y;
    int b, c;
    NODE (int _x = 0, int _y = 0, int _b = 0, int _c = 0)

```

```

        : x(_x), y(_y), b(_b), c(_c) {}
};
vector <NODE> nodes;
int make_net()
{
    int i, j;
    int D[NMAX] = {0};
    memset(net, 0, sizeof(net));
    n += 2;
    vector <NODE>::iterator iter;
    foreach (iter,nodes)
    {
        i = iter->x;
        j = iter->y;
        net[i][j] = iter->c - iter->b;
        D[j] += iter->b;
        D[i] -= iter->b;
    }
    int ret = 0;
    for (i=2; i<n; i++)
    {
        if (D[i] > 0)
            net[1][i] = D[i];
        else if (D[i] < 0)
            net[i][n] = - D[i];
        ret += net[1][i];
    }
    return ret;
}

void solve()
{
    int i, j;
    int cap = make_net();
    int flow = Edmonds_Karp();
    if (flow != cap)
        puts("NO\n");
    else
    {
        puts("YES");
        vector <NODE>::iterator iter;
        foreach (iter,nodes)
            printf("%d\n", iter->c - net[iter->x][iter->y]);
    }
}

```

```

}

int main()
{
    int i, j, cas;
    scanf("%d", &cas);
    while (cas --)
    {
        scanf("%d %d", &n, &m);
        nodes.clear();
        for (i=0; i<m; i++)
        {
            int x, y, l, cap;
            scanf("%d %d %d %d", &x, &y, &l, &cap);
            x ++; y ++;
            nodes.push_back(NODE(x,y,l,cap));
        }
        solve();
    }
}

```

## 32. 二分图最小点权覆盖

```

// 3308 PKU Paratroopers
// 2874 ZJU
double R[MAX], C[MAX];
// 二分图最小点权覆盖-> 网络最大流
void make_net()
{
    int i, j;
    memset(net, 0, sizeof(net));
    // C(S,x) = W[x]
    for (i=0; i<n; i++)
        net[0][i+1] = log(R[i]);
    // C(y,T) = W[y]
    for (i=0; i<m; i++)
        net[n+i+1][n+m+1] = log(C[i]);
    // C(x,y) = inf
    for (i=0; i<l; i++)
    {
        int x, y;
        scanf("%d %d", &x, &y);
        net[x][y+n] = 1e99;
    }
    n = n + m + 1;
}

```

```
}

```

```
double solve()
{
    int i, j;
    double ret;
    make_net();
    ret = Edmonds_Karp();
    return exp(ret);
}
```

### 33. 带约束的轨道计数(**Burnside** 引理)

```
// PKU 2888
#include <stdio.h>
#include <math.h>

const int MOD = 9973;
bool A[32000];
int prim[3500], T[10][10];
int total, n, m;

void init()
{
    int i, j;
    total = 0;
    for(i = 2; i < 32000; i++)
        if(!A[i])
        {
            prim[total++] = i;
            for(j = 2*i; j < 32000; j += i)
                A[j] = true;
        }
}

int phi(int x)
{
    int temp, i, num;
    if(x == 1) return 1;
    temp = 1;
    for(i = 0; i < total; i++)
    {
        num = prim[i];
        if(x % num == 0)
        {

```

```
        temp *= num-1;
        temp %= MOD;
        x /= num;
        while(x % num == 0)
        {
            x /= num;
            temp *= num;
            temp %= MOD;
        }
        if(x == 1) break;
    }
}
if(x != 1)
{
    temp *= x - 1;
    temp %= MOD;
}
return temp;
}

void GT(int TT[][10],int p)
{
    int i,j,sum,k;
    if(p == 1)
    {
        for(i = 0;i < m;i++)
            for(j = 0;j < m;j++)
                TT[i][j] = T[i][j];
        return;
    }
    int t2[10][10];
    GT(t2,p/2);
    for(i = 0;i < m;i++)
        for(j = 0;j < m;j++)
        {
            sum = 0;
            for(k = 0;k < m;k++)
                sum += t2[i][k]*t2[k][j];
            TT[i][j] = sum % MOD;
        }
    if(p % 2 == 0) return;
    int t[10][10];
    for(i = 0;i < m;i++)
        for(j = 0;j < m;j++)
```

```

        {
            sum = 0;
            for(k = 0;k < m;k++)
                sum += TT[i][k]*T[k][j];
            t[i][j] = sum % MOD;
        }
        for(i = 0;i < m;i++)
            for(j = 0;j < m;j++)
                TT[i][j] = t[i][j];
    }

int Tr(int p)
{
    int sum = 0,i;
    int TT[10][10];
    GT(TT,p);
    for(i = 0;i < m;i++)
        sum += TT[i][i];
    return sum % MOD;
}

int gn()
{
    int temp,sum = 0,i,all;
    temp = (int)(sqrt(1.0*n)+0.4) + 1;
    sum = (phi(1)*Tr(n)%MOD + phi(n)*Tr(1)%MOD) % MOD;
    for(i = 2;i < temp;i++)
    {
        if(n % i == 0)
        {
            if(i*i == n)
            {
                sum += phi(i)*Tr(i)%MOD;
                sum %= MOD;
            }
            else
            {
                sum += phi(i)*Tr(n/i)%MOD + phi(n/i)*Tr(i)%MOD;
                sum %= MOD;
            }
        }
    }
    all = sum / n;
    sum %= n;
}

```

```

while(sum)
{
    all++;
    sum = n - sum;
    sum %= MOD;
    if(sum == 0) break;
    sum = MOD - sum;
}
return all;
}

int main()
{
    int cas,k,x,y,i,j;
    scanf("%d",&cas);
    init();
    while(cas--)
    {
        scanf("%d %d %d",&n,&m,&k);
        for(i = 0;i < m;i++)
            for(j = 0;j < m;j++)
                T[i][j] = 1;
        while(k--)
        {
            scanf("%d %d",&x,&y);
            x--;
            y--;
            T[x][y] = 0;
            T[y][x] = 0;
        }
        printf("%d\n",gn());
    }
    return 0;
}

```

### 34. 三分法求函数波峰

// linle专场考研路茫茫——早起看书

```

const int MMAX = 11000;
const double EPS = 1e-4;
int x[MMAX], y[MMAX];
int n, m;

#define f(dt) k*(dt-x[p-1]) + y[p-1] + 1.0*n*dt/dt;

```

```
double triple_search(int p)
{
    double mmin = 1e99;
    double k = 1.0 * (y[p]-y[p-1]) / (x[p]-x[p-1]);
    double xl = x[p-1], xr = x[p];
    double lm, rm, flm, frm;

    while (fabs(xr-xl) > EPS)
    {
        lm = (2.0*xl + xr) / 3.0;
        rm = (2.0*xr + xl) / 3.0;
        flm = f(lm);
        frm = f(rm);
        if (frm > flm)
            xr = rm, mmin = min(mmin, flm);
        else
            xl = lm, mmin = min(mmin, frm);
    }
    return mmin;
}

double solve()
{
    int i, j, k;
    double mmin = 1e99;
    for (i=1; i<m; i++)
    {
        double ret = triple_search(i);
        mmin = min(mmin, ret);
    }
    return mmin;
}

int main()
{
    int i, j;
    while (scanf("%d %d", &m, &n) == 2)
    {
        for (i=0; i<m; i++)
            scanf("%d %d", &x[i], &y[i]);
        printf("%.3lf\n", solve());
    }
}
```

### 35. 单词计数, **DFA** 自动机, **Trie** 图



```

// linle专场考研路茫茫——单词情结
// 由正则表达式构造NFA, NFA转DFA, 最小化DFA
// 构造状态转移矩阵, 矩阵乘法
typedef unsigned long long ULL;
#define foreach(it,c) for (it=(c).begin(); it!=(c).end(); it++)
#define forsize(it,c) for (it=0; it<(c).size(); it++)

const int NMAX = 6;
int n, l;
char rt[NMAX][6];

const int SMAX = 80;

#define ADD(a,x) ((a)=((a)+(x)))

struct MATRIX
{
    ULL mat[SMAX][SMAX];
    int n;

    MATRIX (int _n = SMAX)
    {
        n = _n;
        memset(mat, 0, sizeof(mat));
    }
    void to_E(int nn)
    {
        int i;
        n = nn;
        memset(mat, 0, sizeof(mat));
        for (i=0; i<n; i++)
            mat[i][i] = 1;
    }
    void fill(const MATRIX & mt, int x, int y)
    {
        int i, j;
        for (i=0; i<mt.n; i++)
            for (j=0; j<mt.n; j++)
                mat[i+x][j+y] = mt.mat[i][j];
    }
    MATRIX operator * (const MATRIX & mt)
    {
        MATRIX ret;
        int i, j, k;

```

```

        for (i=0; i<n; i++)
            for (j=0; j<n; j++)
            {
                ret.mat[i][j] = 0;
                for (k=0; k<n; k++)
                    ADD(ret.mat[i][j], mat[i][k] * mt.mat[k][j]);
            }
        ret.n = n;
        return ret;
    }
    MATRIX operator ^ (int ex)
    {
        int i;
        MATRIX ret, tmp;
        ret = *this;
        tmp.to_E(this->n);
        while (ex > 1)
        {
            if (ex & 1)
                tmp = tmp * ret;
            ret = ret * ret;
            ex >>= 1;
        }
        ret = ret * tmp;
        return ret;
    }
};

const int NFAMAX = 60;
struct EDGE
{
    char ch;
    int next;
    EDGE (char _c = 0, int _n = 0)
        : ch(_c), next(_n) {}
};

vector <EDGE> nfa[NFAMAX];
vector <EDGE> dfa[NFAMAX];
vector <EDGE> mindfa[NFAMAX];
int nfact;
int dfaasn;
int mindfaasn;
vector <int> dfact;
vector <int> mindfact;

```

```

#define BADD(x,p) ((x) |= ((ULL)1<<(p)))
#define BSUB(x,p) ((x) &= ~((ULL)1<<(p)))
#define BGET(x,p) ((x) & ((ULL)1<<(p)))

void make_nfa()
{
    int i, j, k;
    for (i=0; i<NFAMAX; i++)
        nfa[i].clear();

    for (i='a'; i<='z'; i++)
        nfa[0].push_back(EDGE(i,0));

    nfact = 1;
    int lend[NMAX];
    for (i=0; i<n; i++)
    {
        nfa[0].push_back(EDGE('$',nfact++));
        for (j=0; rt[i][j]; j++)
        {
            nfa[nfact-1].push_back(EDGE(rt[i][j],nfact));
            nfact ++;
        }
        lend[i] = nfact - 1;
    }

    for (i=0; i<n; i++)
        nfa[ lend[i] ].push_back(EDGE('$',nfact));
    for (i='a'; i<='z'; i++)
        nfa[nfact].push_back(EDGE(i,nfact));
    nfact ++;
}

bitset <NFAMAX> vis;
ULL e_closure(int now)
{
    int i, j;
    ULL ret = 0;
    vector <EDGE>::iterator iter;

    BADD(ret, now);
    if (vis[now])
        return ret;

```

```

    vis[now] = true;

    foreach (iter, nfa[now])
        if (iter->ch == '$')
            ret |= e_closure(iter->next);
    return ret;
}

ULL e_closure2(ULL now)
{
    int i, j;
    ULL ret = now;

    vis.reset();
    for (i=0; i<nfact; i++)
        if (BGET(now, i))
            ret |= e_closure(i);
    return ret;
}

map < ULL, int > hash;

void dfs(ULL now)
{
    int i, j;
    vector <EDGE>::iterator iter;
    vector <int>::iterator iter2;
    vector <int> nxt[30];

    for (i=0; i<nfact; i++)
    {
        if (BGET(now,i))
        {
            foreach (iter, nfa[i])
            {
                if (iter->ch == '$')
                    continue;
                nxt[iter->ch - 'a'].push_back(iter->next);
            }
        }
    }

    int stag = hash[now];
    for (i='a'; i<='z'; i++)

```

```

{
    if (nxt[i-'a'].empty())
        continue;
    ULL next = 0;
    foreach (iter2, nxt[i-'a'])
        BADD(next, *iter2);
    next = e_closure2(next);
    bool flag = false;
    int ntag = hash[next];
    if (ntag == 0)
        ntag = hash[next] = dfasn ++, flag = true;
    dfa[stag-1].push_back(EDGE(i,ntag-1));
    if (flag)
    {
        if (BGET(next, nfact-1))
            dfact.push_back(ntag-1);
        dfs(next);
    }
}
}

void nfa_dfa()
{
    int i, j, k;

    dfasn = 1;
    vis.reset();
    hash.clear();
    dfact.clear();
    for (i=0; i<NFAMAX; i++)
        dfa[i].clear();

    ULL bs = e_closure(0);
    hash[bs] = dfasn ++;
    dfs(bs);
}

void min_dfa()
{
    int i, j, k;
    vector < vector <int> > split;
    vector <EDGE>::iterator iter;
    int belg[NFAMAX];

```

```
for (i=0; i<dfasn; i++)
{
    vector <int> newi;
    newi.push_back(i);
    split.push_back(newi);
    belg[i] = i;
}

bool flag = true;
while (flag)
{
    flag = false;
    for (i=0; i<split.size(); i++)
    {
        for (j=i+1; j<split.size(); j++)
        {
            vector < pair <char, int> > ibel, jbel;
            for (k=0; k<split[i].size(); k++)
                foreach (iter, dfa[ split[i][k] ])
                    ibel.push_back(make_pair(iter->ch, belg[iter->next]));
            for (k=0; k<split[j].size(); k++)
                foreach (iter, dfa[ split[j][k] ])
                    jbel.push_back(make_pair(iter->ch, belg[iter->next]));
            sort(ibel.begin(), ibel.end());
            sort(jbel.begin(), jbel.end());
            if (ibel == jbel)
            {
                flag = true;
                break;
            }
        }
        if (flag)
            break;
    }
    if (flag)
    {
        int s1 = belg[ split[i][0] ], s2 = belg[ split[j][0] ];
        for (k=0; k<dfasn; k++)
            if (belg[k] == s2)
                belg[k] = s1;
        split[i].insert(split[i].end(), split[j].begin(), split[j].end());
        split.erase(split.begin() + j);
    }
}
```

```

    for (i=0; i<split.size(); i++)
        for (j=0; j<split[i].size(); j++)
            belg[ split[i][j] ] = i;

    bitset <NFAMAX> acts;
    for (i=0; i<dfact.size(); i++)
        acts[ dfact[i] ] = true;
    mindfact.clear();

    mindfasn = split.size();
    for (i=0; i<mindfasn; i++)
    {
        int go[30];
        memset(go, -1, sizeof(go));
        mindfa[i].clear();
        flag = false;

        for (j=0; j<split[i].size(); j++)
        {
            if (acts[ split[i][j] ])
                flag = true;
            foreach (iter, dfa[ split[i][j] ])
                go[iter->ch - 'a'] = belg[iter->next];
        }
        for (j='a'; j<='z'; j++)
            if (go[j-'a'] != -1)
                mindfa[i].push_back(EDGE(j,go[j-'a']));
        if (flag)
            mindfact.push_back(i);
    }
}

MATRIX T;
MATRIX TT;
MATRIX BT;
MATRIX E;

void make_matrix()
{
    int i, j;
    vector <EDGE>::iterator iter;

    E.to_E(mindfasn);

```

```

    T.n = mindfasn;
    memset(T.mat, 0, sizeof(T.mat));
    for (i=0; i<mindfasn; i++)
    {
        foreach (iter, mindfa[i])
            T.mat[i][iter->next] ++;
    }
    // 构造等比矩阵
    BT.n = mindfasn<<1;
    memset(BT.mat, 0, sizeof(BT.mat));
    BT.fill(T, 0, 0);
    BT.fill(E, 0, mindfasn);
    BT.fill(E, mindfasn, mindfasn);
}

ULL solve()
{
    int i, j;
    ULL ret = 0;
    vector <EDGE>::iterator iter;

    make_nfa();
    nfa_dfa();
    dfasn = hash.size();
    min_dfa();
    make_matrix();

    BT = BT ^ I;
    TT.n = mindfasn;
    for (i=0; i<mindfasn; i++)
        for (j=0; j<mindfasn; j++)
            TT.mat[i][j] = BT.mat[i][j+mindfasn];
    T = T * TT;
    for (i=0; i<mindfact.size(); i++)
        ret += T.mat[0][ mindfact[i] ];
    return ret;
}

int main()
{
    int i, j;
    while (scanf("%d %d", &n, &l) == 2)
    {
        for (i=0; i<n; i++)

```



```
        scanf("%s", rt[i]);
        printf("%I64u\n", solve());
    }
}

// HDU 2471 History of Languages
// DFA同构判断
#include <iostream>
#include <string>
#include <algorithm>
using namespace std;

const int NMAX = 2010;
const int TMAX = 26;
const int FAIL = -1;

int sigma; // 字符集大小
bool dis[NMAX][NMAX];
int lx[NMAX*NMAX], ly[NMAX*NMAX];

struct DFA {
    int X[NMAX][TMAX];
    bool F[NMAX];
    int n;

    void read() {
        int i, j, k;
        scanf("%d", &n);
        for (i = 0; i < n; i++) {
            scanf("%d", &k);
            F[i] = (k == 1);
            for (j = 0; j < sigma; j++) {
                scanf("%d", &X[i][j]);
                if (X[i][j] == -1) X[i][j] = n;
            }
        }
        // 虚拟一个非接受态节点，再补边
        F[n] = false;
        for (i = 0; i < sigma; i++)
            X[n][i] = n;
        //n++;
    }

    void Minization(DFA &dst) {
        memset(dst.X, -1, sizeof(dst.X));
    }
};
```

```
int i, j, ch;
int p, q;

bool vis[NMAX] = {false};
vis[0] = true;
fill(vis, vis + n, true);
fill(dis[0], dis[n], false);

int Q[NMAX], Qf, Qr;
Qf = Qr = 0;
Q[Qr++] = 0;
while (Qf < Qr) {
    p = Q[Qf++];
    for (ch = 0; ch < sigma; ch++) {
        q = X[p][ch];
        if (q != -1 && !vis[q]) {
            vis[q] = true;
            Q[Qr++] = q;
        }
    }
}

for (i = 0; i < n; i++) {
    if (!vis[i]) continue;
    for (j = i + 1; j < n; j++) {
        if (!vis[j]) continue;
        if (F[i] != F[j]) dis[i][j] = dis[j][i] = true;
    }
}

while (1) {
    bool update = false;
    for (i = 0; i < n; i++) {
        if (!vis[i]) continue;
        for (j = i + 1; j < n; j++) {
            if (!vis[j]) continue;
            if (dis[i][j] == true) continue;

            for (ch = 0; ch < sigma; ch++) {
                p = X[i][ch];
                q = X[j][ch];

                if (p == -1 && q == -1) continue;
                if (p == -1 || q == -1 || dis[p][q]) {
```

```

        dis[i][j] = dis[j][i] = true;
        update = true;
        break;
    }
} //update
} //for j
} //for i
if (!update) break;
} //while

int id[NMAX], cnt = 0;
fill(id, id + n, -1);
for (i = 0; i < n; i++) {
    if (!vis[i]) continue;
    if (id[i] != -1) continue;

    for (j = 0; j < n; j++) {
        if (!vis[j]) continue;
        if (dis[i][j] == false) id[j] = cnt;
    }
    cnt++;
}
dst.n = cnt;

for (i = 0; i < n; i++) {
    if (!vis[i]) continue;
    if (id[i] != -1) continue;

    p = id[i];
    dst.F[p] = F[i];
    for (ch = 0; ch < sigma; ch++) {
        q = X[i][ch];
        if (q != FAIL) q = id[q];
        dst.X[p][ch] = q;
    }
}

}

void show() {
    int i, j;
    for (i = 0; i < n; i++) {
        cout << F[i] << " ";
        for (j = 0; j < sigma; j++)
            cout << X[i][j] << " ";
    }
}

```

```

        cout << endl;
    }
    cout << endl;
}

bool equals(DFA &dfa2) {
    memset(dis, 0, sizeof(dis));
    int p, q;

    p = q = 0;
    lx[q] = 0;
    ly[q] = 0;

    dis[0][0] = true;
    q++;
    while (p < q) {
        if (F[lx[p]] != dfa2.F[ly[p]]) break;

        for (int k = 0; k < sigma; k++)
            if (!dis[X[lx[p]][k]][dfa2.X[ly[p]][k]]) {
                dis[X[lx[p]][k]][dfa2.X[ly[p]][k]] = true;
                lx[q] = X[lx[p]][k];
                ly[q] = dfa2.X[ly[p]][k];
                q++;
            }
        p++;
    }
    return p == q;
}

};

DFA a, b;
int main() {
    int cas = 1;
    while (scanf("%d", &sigma), sigma) {
        a.read();
        b.read();
        printf("Case #%d: ", cas++);
        if (a.equals(b)) puts("Yes");
        else puts("No");
    }
    return 0;
}
/*

```

## Trie图

在Trie树的基础上补边（类似AC自动机）

可用于多字符串匹配和自动机的构造

图可转换为矩阵，或拓扑排序，用作统计或动态规划之用

\*/

```
typedef pair <int, int> PII;
typedef vector <PII> TRANS;
const int VMAX = 200;
const int SIGMAX = 50;
char d2c[110] = "ACGT"; // 字符集
struct TrieGraph
{
    struct NODE
    {
        int suffix; // 后缀节点指针
        int father; // 父节点指针
        int next[SIGMAX]; // 儿子节点指针
        bool mark; // 标记是否出现过
        char ch; // 入边信息
    };
    NODE mem[VMAX];
    int vn, root;
    char c2d[300]; // 字符集hash表
    int siglen; // 字符集大小

    int new_node(char ch, int fat) {
        memset(mem+vn, 0, sizeof(NODE));
        mem[vn].ch = ch;
        mem[vn].father = fat;
        return vn++;
    }
    // 初始化(字符集)
    void init(char * pstr) {
        vn = 0;
        siglen = strlen(pstr);
        for (int i=0; pstr[i]; i++)
            c2d[pstr[i]] = i;
        // 初始化节点，用作安全转移
        root = new_node('$', 0);
        for (int i=0; i<siglen; i++)
            mem[root].next[i] = new_node(pstr[i], root);
    }
    // 构造Trie
    void insert(char * pstr) {
```

```

    int i;
    for (i=root; *pstr; pstr++) {
        int x = c2d[*pstr];
        if (mem[i].next[x] == 0)
            mem[i].next[x] = new_node(*pstr, i);
        i = mem[i].next[x];
    }
    mem[i].mark = true;
}

int get_suffix(int idx) {
    int fat = mem[idx].father;
    if (fat == root) return root;
    int ich = c2d[mem[idx].ch];
    for (fat=mem[fat].suffix; fat!=root && mem[fat].next[ich]==0;
fat=mem[fat].suffix) ;
    if (mem[fat].next[ich] == 0) return root;
    return mem[fat].next[ich];
}

// 构造Trie Graph
void construct() {
    queue<int> sq;
    for (int i=0; i<siglen; i++) {
        if (mem[root].next[i] == 0) continue;
        NODE & son = mem[ mem[root].next[i] ];
        son.suffix = get_suffix(mem[root].next[i]);
        sq.push(mem[root].next[i]);
    }
    while (!sq.empty()) {
        int idx = sq.front(); sq.pop();
        NODE & now = mem[idx];
        for (int i=0; i<siglen; i++) {
            int sonidx = now.next[i];
            NODE & son = mem[sonidx];
            if (sonidx == 0) continue;
            sq.push(sonidx);
            son.suffix = get_suffix(sonidx);
            son.mark = son.mark || mem[son.suffix].mark;
        }
        for (int i=0; i<siglen; i++) {
            if (now.next[i] != 0) continue;
            now.next[i] = mem[now.suffix].next[i];
        }
    }
}

```

```

// 构造安全图
TRANS make_safe_graph() {
    queue <int> sq;
    bitset <VMAX> vis;
    TRANS ret;
    sq.push(root);
    vis[root] = true;
    while (! sq.empty()) {
        int idx = sq.front(); sq.pop();
        NODE & now = mem[idx];
        for (int i=0; i<siglen; i++) {
            int sonidx = now.next[i];
            if (sonidx==0 || mem[sonidx].mark) {
                now.next[i] = 0; // 更新Trie Graph
                continue;
            }
            ret.push_back(PII(idx, sonidx));
            if (vis[sonidx]) continue;
            sq.push(sonidx);
            vis[sonidx] = true;
        }
    }
    return ret;
}

void print() {
    printf("%6s%6s%6s%6s...\n", "Node", "Suff", "Mark", "Son");
    for (int i=0; i<vn; i++) {
        printf("%6d%6d%6d", i, mem[i].suffix, mem[i].mark);
        for (int j=0; j<siglen; j++)
            printf("%6d", mem[i].next[j]);
        puts("");
    }
}

};
/*
PKU 1625 Censored!
求长度为m，字符集为n且不含p个不良单词的字符串的数目，
就是求在安全图中从根结点出发走m步有多少种走法。
用count[step,x]表示从根结点出发走step步到结点x的走法数。
fillchar(count,sizeof(count),0);
count[0,根]=1;
for step:=1 to m do
    for 安全图中每条边(i,j) do
        inc(count[step,j],count[step-1,i]);

```

```

ans:=0;
for 安全图中每个结点x do
    inc(ans,count[m,x]);
*/
/*
PKU 2778 DNA Sequence
用矩阵做状态转移，矩阵二分求答案
*/
int n, m, p;
xnum dp[2][VMAX];
TrieGraph tg;

void solve()
{
    int i, j;
    xnum ret = 0;

    TRANS tr = tg.make_safe_graph();
    for (i=0; i<tg.vn; i++) dp[0][i] = dp[1][i] = 0;
    dp[0][0] = 1;
    for (i=1; i<=m; i++)
    {
        for (j=0; j<tr.size(); j++)
            dp[i&1][tr[j].second] = dp[i&1][tr[j].second] +
dp[(i&1)^1][tr[j].first];
        for (j=0; j<tg.vn; j++) dp[(i&1)^1][j] = 0;
    }

    for (i=0; i<tg.vn; i++)
        ret = ret + dp[m&1][i];
    ret.print();puts("");
}

int main()
{
    int i, j;
    char str[110];
    while (scanf("%d %d %d", &n, &m, &p) == 3)
    {
        scanf("%s", d2c);
        tg.init(d2c);
        for (i=0; i<p; i++)
        {
            scanf("%s", str);

```



```

        tg.insert(str);
    }
    tg.construct();
    //tg.print();
    solve();
}
}

```

### 36. 字符串和数值 hash

```

// 整数hash
// 104729, 224737, 350377, 479909, 611953, 882377
// 1020379, 1299709, 1583539, 1870667, 2015177
// 4256233, 5800079, 7368787, 10570841, 15485863
const int MOD = 20023;
bool bhash[MOD];
int vhash[MOD];
int cnt[MOD];

bool find_hash(int & pos) {
    int val = pos;
    pos %= MOD;
    for (; bhash[pos]; pos=(pos+1)%MOD) {
        if (vhash[pos] == val)
            return true;
    }
    return false;
}

int make_hash(int val) {
    int pos = val;
    if (! find_hash(pos)) {
        bhash[pos] = true;
        vhash[pos] = val;
        cnt[pos] = 0;
    }
    cnt[pos] ++;
    return pos;
}

//字符串hash
const int MOD = 20023;
bool bhash[MOD];
char vhash[MOD][45];
char str[45];

```

```

int cal_str() {
    int i, j, pos;
    for (i=pos=0,j=1; str[i]; i++,j=(j*27)&INT_MAX,pos&=INT_MAX) {
        int num = str[i] - 'a';
        if (str[i] == ' ')
            num = 26;
        pos += j*num;
    }
    return pos % MOD;
}

bool find_hash(int & pos) {
    pos = cal_str();
    for (; bhash[pos]; pos=(pos+1)%MOD) {
        if (strcmp(vhash[pos], str) == 0)
            return true;
    }
    return false;
}

int make_hash() {
    int pos;
    if (! find_hash(pos)) {
        bhash[pos] = true;
        strcpy(vhash[pos], str);
    }
    return pos;
}

```

### 37. 滚动队列，前向星表示法

```

int que[2][2000];
int qf[2],qe[2],qnow;

#define push_que(a) (que[qnow][ qe[qnow]++ ] = (a))
#define pop_que2  (que[qnow^1][ qf[qnow^1]++ ])
#define switch_que qnow ^= 1; \
                    qf[qnow] = qe[qnow] = 0;
#define empty_que2  (qf[qnow^1] >= qe[qnow^1])
#define size_que2  (qe[qnow^1] - qf[qnow^1])
/*
前向星表示法
空间O(E+N)
存储所有边，并用链表来实现读取s为起点的有向边

```

方便插入和遍历所有边,删除是 $O(E)$

```

*/
const int ENDFLAG = -1;
struct EDGELIST {
    int start[NMAX];
    int last[NMAX];
    int edge[MMAX][2]; //pos,listnext
    int tot;

    void clear() {
        tot = ENDFLAG + 1;
        memset(last, ENDFLAG, sizeof(last));
    }
    void push_back(int s, int t) {
        edge[tot][0] = t;
        edge[tot][1] = ENDFLAG;
        if (last[s] != ENDFLAG) edge[last[s]][1] = tot;
        else start[s] = tot;
        last[s] = tot;
        tot++;
    }
    int get_start(int s) {
        return start[s];
    }
    int get_next(int & p) {
        p = edge[p][1];
        return edge[p][0];
    }
    void erase(int s, int t) {
        int i, pre = ENDFLAG;
        int p, v;
        for (p = start[s]; p != ENDFLAG; p = edge[p][1]) {
            v = edge[p][0];
            if (v == t) {
                if (pre == ENDFLAG) start[s] = edge[p][1];
                else edge[pre][1] = edge[p][1];
            }
            else pre = p;
        }
        last[s] = pre;
    }
};

```

### 38. 最小点基, 最小权点基

// HDOJ 1827 Summer Holiday

// 点基：通过点基的点，能够到达有向图全部点

// 最小权点基：有向图顶点有权值

void Gabow()

```
{
    int i,j,l;
    //dfs in original graph
    memset(id, 0, sizeof(id));
    memset(vis, 0, sizeof(vis));
    scc = step = 1;
    order_pos = order2_pos = 0;
    for (i=1; i<=n ;i++) {
        if (vis[i] == 0) {
            dfs(i);
        }
    }
    scc --;
}
```

void top\_sort()

```
{
    int i,j,k,l,m = 0;
    memset(out_degree,0,sizeof(out_degree));
    memset(sel, 0x7f,sizeof(sel));
    l = SQ.size();
    while (l --) {
        SQ.pop();
    }
    for (i=1;i<=n;i++) {
        int id1 = id[i];
        l = path[i].size();
        for (j=0;j<l;j++) {
            int id2 = id[ path[i][j] ];
            if (id1 != id2) {
                out_degree[id2] ++;
                dag[id1].push_back(id2);
            }
        }
    }
    for (i=1;i<=scc;i++) {
        if (out_degree[i] == 0) {
            SQ.push(i);
        }
    }
}
```

```

while (!SQ.empty()) {
    int now = SQ.front();
    SQ.pop();
    l = dag[now].size();
    for (i=0;i<l;i++) {
        int next = dag[now][i];
        out_degree[next]--;
        if (out_degree[next] == 0) {
            SQ.push(next);
            m--; //find non-highest scc
            sel[next] = -1;
        }
    }
}
for (i=1;i<=n;i++) {
    if (sel[ id[i] ] != -1) { //selection minimum cost in the highest scc
        sel[ id[i] ] = sel[ id[i] ] > cost[i] ? cost[i] : sel[ id[i] ];
    }
}
min_cost = 0;
for (i=1;i<=scc;i++) {
    if (sel[i] != -1) {
        min_cost += sel[i];
    }
}
min_num = scc+m;
}

int main()
{
    int i,x,y;
    path.resize(NMAX);
    dag.resize(NMAX);
    while (scanf("%d %d",&n, &m)==2) {
        for (i=0;i<=n;i++) {
            path[i].clear();
            dag[i].clear();
        }
        for (i=1;i<=n;i++) {
            scanf("%d", cost+i);
        }
        for (i=1;i<=m;i++) {
            scanf("%d %d", &x,&y);
            path[x].push_back(y);
        }
    }
}

```

```

    }
    Gabow();
    top_sort();
    //min_num : minimum vertex number
    //min_cost : minimum cost
    printf("%d %d\n", min_num, min_cost);
}
}

```

### 39. LCSubsequence $O(N^2/\log N)$

```

// 1210 WHU
/*
 *   LCSubsequence  $O(N^2/\log N)$ 
 *   这个解法是在字符集不大的情况下，先预处理，再用位运算做状态转移。
 */
typedef UL data_type; // 变量存储类型
const int NMAX = 31000; // 字符串长度
const int BITLEN = sizeof(data_type)*8; // 变量存储位长度
const int BINLEN = 5; //  $2^{\text{BINLEN}} = \text{BITLEN}$ 
const int MMAX = (NMAX/BITLEN) + 1; // 申请空间长度

// ((x)/BITLEN)
#define GETBLOCK(x) ((x)>>BINLEN)

char str1[NMAX];
char str2[NMAX];

struct BITSET
{
    data_type dat[MMAX];
    int len;
    int bs;

    BITSET (int l = 0) {
        len = l;
        bs = GETBLOCK(l+BITLEN-1);
        memset(dat, 0, sizeof(dat));
    }
    bool operator [] (int p) {
        return (dat[GETBLOCK(p)] & ((data_type)1<<(p%BITLEN)));
    }
    void set(int p, bool flag) {
        if (!flag)
            dat[GETBLOCK(p)] &= ~((data_type)1<<(p%BITLEN));
    }
}

```

```

        else
            dat[GETBLOCK(p)] |= ((data_type)1<<(p%BITLEN));
    }
    void reset(int l) {
        len = l;
        bs = GETBLOCK(l+BITLEN-1);
        memset(dat, 0, sizeof(dat));
    }
    BITSET operator ~ () {
        BITSET ret = *this;
        int i;
        for (i=0; i<bs; i++)
            ret.dat[i] = ~ret.dat[i];
        return ret;
    }
    BITSET operator & (const BITSET & a) {
        BITSET ret = *this;
        int i;
        for (i=0; i<bs; i++)
            ret.dat[i] &= a.dat[i];
        return ret;
    }
    BITSET operator | (const BITSET & a) {
        BITSET ret = *this;
        int i;
        for (i=0; i<bs; i++)
            ret.dat[i] |= a.dat[i];
        return ret;
    }
    BITSET operator ^ (const BITSET & a) {
        BITSET ret = *this;
        int i;
        for (i=0; i<bs; i++)
            ret.dat[i] ^= a.dat[i];
        return ret;
    }
    BITSET & operator <<= (int l) {
        int i, j;
        int ll = l % BITLEN;
        l /= BITLEN;
        for (i=bs-l; l && i>=0; i--)
            dat[i] = dat[i-l];
        for (i=bs-l; ll && i>0; i--)
            dat[i] = (dat[i]<<ll) | (dat[i-1]>>(BITLEN-ll));
    }

```

```

        dat[0] <= ll;
        return *this;
    }
    BITSET operator - (const BITSET & a) {
        BITSET ret = *this;
        int i, borw = 0, tborw;
        for (i=0; i<bs; i++) {
            if (ret.dat[i] < a.dat[i] + borw)
                tborw = 1;
            else
                tborw = 0;
            ret.dat[i] -= a.dat[i] + borw;
            borw = tborw;
        }
        return ret;
    }
    int count(int l = 0) {
        int i, j, ret = 0;
        l = (l==0) ? len : l;
        for (i=0; i<bs && l>0; i++, l-=BITLEN) {
            data_type tmp = dat[i];
            int tl = l;
            for (; tmp && tl; tmp>>=1, tl--)
                ret += (tmp & 1);
        }
        return ret;
    }
};

```

```

BITSET ext[300];
BITSET row, X;

```

```

int BitLCS(char * s1, char * s2)
{
    int i, j;
    int len1 = strlen(s1);
    int len2 = strlen(s2);

    for (i=0; i<300; i++)
        ext[i].reset(len1);
    row.reset(len1);
    X.reset(len1);

    for (i=0; i<len1; i++)

```



```

        ext[ s1[i] ].set(i, 1);

    for (i=0; i<len2; i++)
    {
        X = row | ext[ s2[i] ];
        row <<= 1;
        row.set(0, 1);
        row = X & ((X-row) ^ X);
    }
    return row.count(len1);
}
int main()
{
    while (scanf("%s %s", str1, str2) == 2)
        printf("%d\n", BitLCS(str1, str2));
}

```

## 40. 伸展树

```

/*
伸展树
二叉查找树的改进，平摊复杂度都是 $O(\log n)$ 
维护序列，适用于统计对象次序发生大规模变化
有翻转和移动时，线段树不适用，且效率高于块状链表
HDOJ 1890 Robotic Sort
*/
const int MMAX = 101000;
struct NODE
{
    int key, cnt; // 键值, 重复次数
    NODE * pl, * pr;
    NODE * pf;
};
NODE mem[MMAX];
int mempos;
NODE * root;

inline NODE * new_node()
{
    NODE * pt = &mem[mempos ++];
    memset(pt, 0, sizeof(NODE));
    return pt;
}

// x = L[y]

```

```
inline void Zig(NODE * y)
{
    NODE * x = y->pl;
    NODE * z = y->pf;
    y->pl = x->pr;
    if (y->pl) y->pl->pf = y;
    x->pr = y; y->pf = x;

    if (! z)
    {
        x->pf = NULL;
        return;
    }
    if (z->pl == y) z->pl = x;
    else z->pr = x;
    x->pf = z;
}
```

```
// x = R[y]
```

```
inline void Zag(NODE * y)
{
    NODE * x = y->pr;
    NODE * z = y->pf;
    y->pr = x->pl;
    if (y->pr) y->pr->pf = y;
    x->pl = y; y->pf = x;

    if (! z)
    {
        x->pf = NULL;
        return;
    }
    if (z->pl == y) z->pl = x;
    else z->pr = x;
    x->pf = z;
}
```

```
// y = L[z], x = L[y]
```

```
inline void ZigZig(NODE * z)
{
    NODE * y = z->pl;
    NODE * x = y->pl;
    NODE * gz = z->pf;
    y->pl = x->pr;
```

```

    if (y->pl) y->pl->pf = y;
    z->pl = y->pr;
    if (z->pl) z->pl->pf = z;
    x->pr = y; y->pf = x;
    y->pr = z; z->pf = y;

    if (! gz)
    {
        x->pf = NULL;
        return;
    }
    if (gz->pl == z) gz->pl = x;
    else gz->pr = x;
    x->pf = gz;
}

```

```

// y = R[z], x = L[y]

```

```

inline void ZigZag(NODE * z)
{
    NODE * y = z->pr;
    NODE * x = y->pl;
    NODE * gz = z->pf;
    y->pl = x->pr;
    if (y->pl) y->pl->pf = y;
    z->pr = x->pl;
    if (z->pr) z->pr->pf = z;
    x->pl = z; z->pf = x;
    x->pr = y; y->pf = x;

    if (! gz)
    {
        x->pf = NULL;
        return;
    }
    if (gz->pl == z) gz->pl = x;
    else gz->pr = x;
    x->pf = gz;
}

```

```

// y = R[z], x = R[y]

```

```

inline void ZagZag(NODE * z)
{
    NODE * y = z->pr;
    NODE * x = y->pr;
}

```

```

    NODE * gz = z->pf;
    y->pr = x->pl;
    if (y->pr) y->pr->pf = y;
    z->pr = y->pl;
    if (z->pr) z->pr->pf = z;
    x->pl = y; y->pf = x;
    y->pl = z; z->pf = y;

    if (! gz)
    {
        x->pf = NULL;
        return;
    }
    if (gz->pl == z) gz->pl = x;
    else gz->pr = x;
    x->pf = gz;
}

```

```
// y = L[z], x = R[y]
```

```

inline void ZagZig(NODE * z)
{
    NODE * y = z->pl;
    NODE * x = y->pr;
    NODE * gz = z->pf;
    y->pr = x->pl;
    if (y->pr) y->pr->pf = y;
    z->pl = x->pr;
    if (z->pl) z->pl->pf = z;
    x->pl = y; y->pf = x;
    x->pr = z; z->pf = x;

    if (! gz)
    {
        x->pf = NULL;
        return;
    }
    if (gz->pl == z) gz->pl = x;
    else gz->pr = x;
    x->pf = gz;
}

```

```

NODE * splay_slow(NODE * x)
{

```

```
    if (! x) return NULL;
    while (x->pf)
    {
        NODE * y = x->pf;
        if (y->pl == x) Zig(y);
        else Zag(y);
    }
    return x;
}

NODE * splay(NODE * x)
{
    if (! x) return NULL;
    while (x->pf)
    {
        NODE * y = x->pf;
        NODE * z = y->pf;
        if (z)
        {
            if (z->pl == y)
            {
                if (y->pl == x) ZigZig(z);
                else ZagZig(z);
            }
            else
            {
                if (y->pr == x) ZagZag(z);
                else ZigZag(z);
            }
        }
        else
        {
            if (y->pl == x) Zig(y);
            else Zag(y);
        }
    }
    return x;
}

NODE * find(int val, NODE * rt)
{
    NODE * x = rt;
    NODE * pre = rt;
    while (x)
```

```

    {
        if (x->key == val) return x;
        pre = x;
        if (val < x->key) x = x->pl;
        else x = x->pr;
    }
    return pre;
}

// make sure all_elem(rt1) <= all_elem(rt2)
NODE * join(NODE * rt1, NODE * rt2)
{
    if (rt1) rt1->pf = NULL;
    if (rt2) rt2->pf = NULL;
    if (! rt1) return rt2;
    if (! rt2) return rt1;
    NODE * x = find(INT_MAX, rt1);
    rt1 = splay(x);
    rt1->pr = rt2;
    rt2->pf = rt1;
    return rt1;
}

NODE * split(int val)
{
    NODE * x = find(val, root);
    if (x == NULL || x->key != val) return NULL;
    root = splay(x);
    NODE * newroot = root->pr;
    newroot->pf = NULL;
    root = root->pl;
    root->pf = NULL;
    return newroot;
}

void insert(int val)
{
    if (root == NULL)
    {
        root = new_node();
        root->key = val;
        root->cnt = 1;
        return;
    }

```

```
}
NODE * x = find(val, root);
if (x->key == val) x->cnt ++;
else
{
    NODE * pnew = new_node();
    pnew->key = val;
    pnew->cnt = 1;
    pnew->pf = x;
    if (val < x->key) x->pl = pnew;
    else x->pr = pnew;
}
}

void remove(int val)
{
    NODE * x = find(val, root);
    root = splay(x);
    if (root && root->key == val)
    {
        root->cnt --;
        if (root->cnt == 0)
            root = join(root->pl, root->pr);
    }
}

void print_tree(NODE * rt)
{
    if (rt == NULL) return;
    printf(" (");
    print_tree(rt->pl);
    if (rt->pf == NULL)
        printf(" [%d] ", rt->key);
    else
        printf(" %d ", rt->key);
    print_tree(rt->pr);
    printf(")");
}

void test_tree()
{
    int v;
    char cmd[2];
    root = NULL;
```

```

    mempos = 0;
    while (scanf("%s %d", cmd, &v) == 2)
    {
        if (cmd[0] == 'i')
            insert(v);
        else if (cmd[0] == 'r')
            remove(v);
        else if (cmd[0] == 's')
            root = splay(find(v, root));
        print_tree(root);
        puts("");
    }
}

int main()
{
    test_tree();
    return 0;
}

```

## 41. Treap

```

/*
Treap
是有随机数满足堆的性质的二叉搜索树
其结构相当于以随机顺序插入的二叉搜索树
其基本操作的期望复杂度为 $O(\log n)$ 
其特点是实现简单，效率高于伸展树并且支持大部分基本功能，性价比很高
*/
#define MAX 100
typedef struct
{
    int l,r,key,fix;
}node;

class treap
{
public:
    node p[MAX];
    int size,root;
    treap()
    {
        srand(time(0));
        size=-1;
        root=-1;
    }

```



```
}

void rot_l(int &x)
{
    int y=p[x].r;
    p[x].r=p[y].l;
    p[y].l=x;
    x=y;
}

void rot_r(int &x)
{
    int y=p[x].l;
    p[x].l=p[y].r;
    p[y].r=x;
    x=y;
}

void insert(int &k,int tkey)
{
    if (k==-1)
    {
        k=++size;
        p[k].l=p[k].r=-1;
        p[k].key=tkey;
        p[k].fix=rand();
    }
    else
        if (tkey<p[k].key)
        {
            insert(p[k].l,tkey);
            if (p[ p[k].l ].fix>p[k].fix)
                rot_r(k);
        }
        else
        {
            insert(p[k].r,tkey);
            if (p[ p[k].r ].fix>p[k].fix)
                rot_l(k);
        }
}

void remove(int &k,int tkey)
```

```

{
    if (k==-1) return;
    if (tkey<p[k].key)
        remove(p[k].l,tkey);
    else if (tkey>p[k].key)
        remove(p[k].r,tkey);
    else
    {
        if (p[k].l==-1 && p[k].r==-1)
            k=-1;
        else if (p[k].l==-1)
            k=p[k].r;
        else if (p[k].r==-1)
            k=p[k].l;
        else
            if (p[ p[k].l ].fix < p[ p[k].r ].fix)
            {
                rot_l(k);
                remove(p[k].l,tkey);
            }
            else
            {
                rot_r(k);
                remove(p[k].r,tkey);
            }
    }
}

int find(int k,int r)
{
    if (r<=p[p[k].l].size)
        return find(p[k].l,r);
    else if (r> p[p[k].l].size+p[k].cnt)
        return find(p[k].r,r-(p[p[k].l].size+p[k].cnt));
    return p[k].key;
}

void print(int k)
{
    if (p[k].l!=-1)
        print(p[k].l);
    cout << p[k].key << " : " << p[k].fix << endl;
    if (p[k].r!=-1)
        print(p[k].r);
}

```

```

    }
};

treap T;

int main()
{
    int i;
    for (i=3;i>=1;i--)
        T.insert(T.root,i);
    T.print(T.root);
    for (i=3;i>=1;i--)
    {
        cout << endl;
        T.remove(T.root,i);
        T.print(T.root);
    }
    return 0;
}

```

## 42. 0/1 分数规划 **K** 约束

```

// 2976 PKU Dropping tests
// 0-1 Fractional Programing with K drop limit
/*
 $(\sum a_i) / (\sum b_i) \geq x$ 
 $\Leftrightarrow \sum a_i \geq \sum (x * b_i)$ 
 $\Leftrightarrow \sum (a_i - x * b_i) \geq 0.$ 

let  $w_i = a_i - x * b_i.$ 
max  $Q(x) = \max (\sum w_i).$ 
so drop K smallest  $w_i$  is ok.
*/
const int NMAX = 1100;
int n, k;
int A[NMAX], B[NMAX];
struct NODE
{
    double w;
    int a, b;
    bool operator < (const NODE & nt) const
    {
        return w < nt.w;
    }
}

```

```
}W[NMAX];

#define EQ(a,b) (fabs((a)-(b))<1e-4)
// Dinkelbach iterative algorithm
int solve()
{
    int i, j;
    double x = 1.0;
    for (i=0; i<100; i++)
    {
        for (j=0; j<n; j++)
        {
            W[j].w = 1.0*A[j] - x*B[j];
            W[j].a = A[j];
            W[j].b = B[j];
        }
        sort(W, W+n);
        double sum = 0;
        double sa, sb;
        sa = sb = 0;
        for (j=k; j<n; j++)
        {
            sum += W[j].w;
            sa += W[j].a;
            sb += W[j].b;
        }
        if (EQ(sum, 0)) break;
        x = 1.0 * sa / sb;
    }
    return (x*100+0.5);
}
```

```
// binary enum
int solve2()
{
    int i, j;
    double lb = 0, ub = 1;
    double x = 1, prex;
    for (i=0; i<100; i++)
    {
        prex = x;
        x = (lb+ub) / 2;
        if (EQ(x, prex)) break;
        for (j=0; j<n; j++)
```

```

        W[j].w = 1.0*A[j] - x*B[j];
    sort(W, W+n);
    double sum = 0;
    for (j=k; j<n; j++)
        sum += W[j].w;
    if (sum >= 0) lb = x;
    else ub = x;
}
return (x*100+0.5);
}

int main()
{
    int i, j;
    while (scanf("%d %d", &n, &k), n|k)
    {
        for (i=0; i<n; i++)
            scanf("%d", A+i);
        for (i=0; i<n; i++)
            scanf("%d", B+i);
        printf("%d\n", solve());
    }
}

```

### 43. 表达式求值

```

// HDU 2127 Polish notation
#include <cstdio>
#include <string>
#include <algorithm>
using namespace std;
typedef __int64 int64;

const int MAX = 1100;
char exp[MAX];
int priority[MAX];
int len;
bool output;

int64 dfs(int spos, int epos) {
    int i;
    int64 op1, op2, ans;
    char opr;
    int minv, minp = -1;
    if (spos > epos || spos >= len || epos < 0) {

```

```

        return 0;
    }
    for (i=epos;i>=spos;i--) {
        if (priority[i] != 0) {
            if (minp == -1) {
                minp = i;
                minv = priority[i];
            }
            else if (minv > priority[i]) {
                minv = priority[i];
                minp = i;
            }
        }
    }
    ans = 0;
    if (minp == -1) {
        for (i=spos;i<=epos;i++) {
            ans = ans * 10 + exp[i] - '0';
        }
        if (output) putchar(' ');
        printf("%d",ans);
        output = true;
    }
    else {
        opr = exp[minp];
        if (opr != '(' && opr != ')') {
            if (output) putchar(' ');
            putchar(opr);
            output = true;

            op1 = dfs(spos,minp-1);
            op2 = dfs(minp+1,epos);
            switch(opr) {
                case '+':
                    ans = op1 + op2;
                    break;
                case '-':
                    ans = op1 - op2;
                    break;
                case '*':
                    ans = op1 * op2;
                    break;
            }
        }
    }
}

```

```

        else {
            ans = dfs(spos,minp-1) + dfs(minp+1,epos);
        }
    }
    return ans;
}

int main() {
    int i,pre,t = 1;
    while(gets(exp)) {
        len = strlen(exp);
        pre = 0;
        // +,- 1
        // *,/ 2
        // - 3
        // () 4
        for (i=0;i<len;i++) {
            if (exp[i] == '*' || exp[i] == '/') priority[i] = pre + 2;
            else if (exp[i] == '+') priority[i] = pre + 1;
            else if (exp[i] == '(') priority[i] = pre = pre + 4;
            else if (exp[i] == ')') priority[i] = pre, pre -= 4;
            else if (exp[i] == '-') {
                if (exp[i-1]>='a' && exp[i-1]<='z' || exp[i-1]=='') priority[i] =
pre + 1;
                else priority[i] = pre + 3;
            }
            else priority[i] = 0;
        }
        printf("Case %d:\n", t ++);
        output = false;
        printf("\n%I64d\n", dfs(0,len-1));
    }
}

```

#### 44. 乘除法博弈,Wythoff 博弈

```

/*
PKU 2633 Funny Games
给定f[1..n]和x
两人轮流选择一个f[i],使得x=x*f[i]
当x<=1.0时胜利
普通的博弈搜索难于x过大,又是浮点数
*/
typedef pair <double, double> pdd;
typedef pair <double, double> * ppdd;

```

```

#define EQ(a,b) (fabs((a)-(b)) <= 1e-8)
#define LES(a,b) ((a) < (b))
#define LEQ(a,b) ((a)+1e-8 <= (b))
pdd win[10000];

ppdd interval_union(ppdd begin, ppdd end, ppdd dest)
{
    sort(begin, end);
    for (; begin != end; dest++)
    {
        *dest = *begin;
        for (begin++; begin != end; begin++)
        {
            if (LEQ(dest->second, begin->first))
                break;
            dest->second = max(dest->second, begin->second);
        }
    }
    return dest;
}

char * solve2()
{
    int i, j;
    pdd lose;
    double maxf;
    lose.second = maxf = 0;

    for (i=0; i<k; i++)
    {
        win[i] = make_pair(1, 1.0/f[i]);
        maxf = max(maxf, f[i]);
    }
    int nwin;
    for (i=0, nwin=k; LES(lose.second, x); i++)
    {
        // union the interval
        nwin = interval_union(win+i, win+nwin, win+i) - win;
        // lose <- win
        lose.first = win[i].second;
        lose.second = win[i].second / maxf; // it's min, and must
        // if the win have many interval
        if (i < nwin-1)
            lose.second = min(lose.second, win[i+1].first);
    }
}

```



```

        // win <- lose
        for (j=0; j<k; j++)
            win[nwin++] = make_pair(lose.first/f[j], lose.second/f[j]);
    }
    if (LES(x, lose.first)) return "Nils";
    return "Mikael";
}
// 有 2 堆石子，一次可以取任意个在一堆中或者任意个在两堆中取相同数目，取完者胜利
int swap(int &x,int &y)
{
    int t;
    t=x;
    x=y;
    y=t;
}
int main()
{
    double alpha = (1.0 + sqrt(5.0)) / 2.0;
    double beta  = (3.0 + sqrt(5.0)) / 2.0;
    int big, small, n, temp1, temp2;
    while(cin>>big>>small)
    {
        if(big < small)
            swap(big, small);
        n = ceil(big / beta);
        temp1 = alpha * n;
        temp2 = beta * n;
        if(small == temp1 && big == temp2)
            cout<<0<<endl;
        else cout<<1<<endl;
    }
    return 0;
}

```

## 45. 状态压缩的积木型 DP

```

// 1038 PKU Bugs Integrated, Inc.
// DP with state compression
#define MAX(a,b) ((a)>(b)?(a):(b))
int bad[160];
int n, m, k;
int e3[] = {
    1, 3, 9, 27, 81, 243, 729, 2187, 6561, 19683, 59049, 177147
};
short dp[2][60000];

```

```

/*
-->X(N)
|
↓Y(M)
0: [ ][ ]
1: [#][ ]
2: [#][#]
当维数扩展时,可以相应的扩展进制数.
此题积木可分解为1*3影响列,则记为3进制数.
当M小时,也可用进制直接保存列.
基于状态压缩的积木填充型DP, 有种实现方法:
1)直接构造fm和gn状态,如此题.
2)for(fm)再构造gn状态.
3)预处理,保存<fm,gn>为边.
优劣:
1)2)易实现,但状态量大时会比较耗时
3)保存边信息后,状态转移的时间消耗少
但边分布不均,需要动态数组或链表,且要处理去重操作
*/
void dfs(int x, int y, int fm, int gn, short v)
{
    if (y > m) return;
    if (y == m)
    {
        dp[(x&1)^1][gn] = MAX(v + dp[(x&1)][fm], dp[(x&1)^1][gn]);
        return;
    }

    int mask23 = 7 << y;
    int mask32 = 3 << y;
    if (x+1 < n)
    {
        if (!(bad[x]&mask23) && !(bad[x+1]&mask23))
            dfs(x, y+3, fm, gn+13*e3[y], v+1); // 2*3
        if (x+2 < n)
        {
            if (!(bad[x]&mask32) && !(bad[x+1]&mask32)
&& !(bad[x+2]&mask32))
                dfs(x, y+2, fm, gn+8*e3[y], v+1); // 3*2
        }
    }

    dfs(x, y+1, fm, gn, v); // 0->0
    if (!(bad[x]&(1<<y)))

```

```

    {
        dfs(x, y+1, fm+1*e3[y], gn, v); // 1->0
        if (!(bad[x+1]&(1<<y)))
            dfs(x, y+1, fm+2*e3[y], gn+1*e3[y], v); // 2->1
    }
}

int solve()
{
    int i, j;
    memset(dp, 0, sizeof(dp));
    for (i=0; i<n; i++)
    {
        dfs(i, 0, 0, 0, 0);
        memset(dp[i&1], 0, sizeof(dp[0]));
    }
    return dp[i&1][0];
}

int main()
{
    int i, j;
    int cas;
    for (scanf("%d", &cas); cas; cas--)
    {
        scanf("%d %d %d", &n, &m, &k);
        memset(bad, 0, sizeof(bad));
        for (i=0; i<k; i++)
        {
            int x, y;
            scanf("%d %d", &x, &y);
            x--; y--;
            bad[x] |= 1 << y;
        }
        printf("%d\n", solve());
    }
}

```

#### 46. 解一般线性方程组(消元法)

```

typedef int INT;
INT gcd(INT a, INT b) {
    return (b == 0)?a:gcd(b, a % b);
}
struct Fraction {

```

```

    INT up, down;
    Fraction():up(0), down(1) {};
    Fraction(INT a, INT b = 1):up(a), down(b) {};
    Fraction(const Fraction& a) {
        up = a.up;
        down = a.down;
    }
    Fraction operator - () const {
        return Fraction(-up, down);
    }
    Fraction& operator = (const Fraction& a) {
        up = a.up;
        down = a.down;
        return *this;
    }
    void reduce() {
        INT g = gcd(abs(up), abs(down));
        up /= g; down /= g;
    }
};

Fraction abs(const Fraction& a) {
    return Fraction(abs(a.up), abs(a.down));
}

Fraction operator + (Fraction a, Fraction b) {
    INT u1 = a.up * b.down + a.down * b.up;
    INT u2 = a.down * b.down;
    INT g = gcd(abs(u1), abs(u2));
    return Fraction(u1 / g, u2 / g);
}

Fraction operator - (Fraction a, Fraction b) {
    return a + (-b);
}

Fraction operator * (Fraction a, Fraction b) {
    INT u1 = a.up * b.up;
    INT u2 = a.down * b.down;
    INT g = gcd(abs(u1), abs(u2));
    return Fraction(u1 / g, u2 / g);
}

Fraction operator / (Fraction a, Fraction b) {
    INT u1 = a.up * b.down;
    INT u2 = a.down * b.up;
    if (u2 < 0) u1 = -u1, u2 = -u2;
    int g = gcd(abs(u1), abs(u2));

```

```

        return Fraction(u1 / g, u2 / g);
    }
    bool operator > (const Fraction& a, const Fraction& b) {
        return (a - b).up > 0;
    }
    bool operator == (const Fraction& a, const Fraction& b) {
        return (a - b).up == 0;
    }
    bool operator != (const Fraction& a, const Fraction& b) {
        return !(a == b);
    }
    bool operator < (const Fraction& a, const Fraction& b) {
        return (b - a).up > 0;
    }
    ostream& operator << (ostream& out, const Fraction& a) {
        if (a.down == 1) out << a.up;
        else out << a.up << '/' << a.down;
        return out;
    }
}

const int nSize = 101;
const int mSize = 26;
typedef Fraction fEquation[nSize];
typedef fEquation fMatrix[mSize];
/*
解一般形式的线性方程组(只输出其中一组解)
neqn个方程, nvar个变量
矩阵表示如下

$$B_0 = A_{0,0} * X_0 + A_{0,1} * X_1 + \dots + A_{0,n-1} * X_{n-1}$$


$$B_1 = A_{1,0} * X_0 + A_{1,1} * X_1 + \dots + A_{1,n-1} * X_{n-1}$$

... ..

$$B_m = A_{m,0} * X_0 + A_{m,1} * X_1 + \dots + A_{m,n-1} * X_{n-1}$$

*/
struct EqnGauss {
    int neqn, nvar;
    fMatrix f;
    Fraction avail[nSize];

    EqnGauss(): neqn(0), nvar(0) {}
    EqnGauss(const EqnGauss& a): neqn(a.neqn), nvar(a.nvar) {
        memcpy(f, a.f, sizeof(fMatrix));
    }
    void build() {
        for (int i = 0; i < neqn; ++ i)

```

```

        for (int j = 0; j <= nvar; ++ j) {
            int x;
            cin >> x;
            f[i][j] = Fraction(x);
        }
    }
    bool rebuild() {
        int cur = 0;
        for(int i = 1; i <= nvar; ++ i) {
            bool found = false;
            for(int j = cur; j < neqn; ++ j)
                if (f[j][i] != 0) {
                    found = true;
                    fEquation tmp;
                    memcpy(tmp, f[cur], sizeof(fEquation));
                    memcpy(f[cur], f[j], sizeof(fEquation));
                    memcpy(f[j], tmp, sizeof(fEquation));
                }
            if (!found) continue;
            f[cur][0] = f[cur][0] / f[cur][i];
            for(int j = i + 1; j <= nvar; ++ j)
                f[cur][j] = f[cur][j] / f[cur][i];
            f[cur][i] = 1;
            for(int j = 0; j < neqn; ++ j)
                if (j != cur && f[j][i] != 0) {
                    f[j][0] = f[j][0] - f[j][i] * f[cur][0];
                    for(int k = i + 1; k <= nvar; ++ k)
                        f[j][k] = f[j][k] - f[j][i] * f[cur][k];
                    f[j][i] = 0;
                }
            ++ cur;
        }
        return (cur != nvar);
    }
    void solve() {
        int cur = 0;
        for(int i = 1; i <= nvar; ++ i)
            if (f[cur][i] == 0) {
                INT ulcm = 1;
                for(int j = 0; j < cur; ++ j)
                    ulcm = ulcm / gcd(ulcm, f[j][i].down) * f[j][i].down;
                avail[i] = ulcm;
            } else ++ cur;
        cur = 0;
    }

```

```

        for(int i = 1; i <= nvar; ++ i)
            if (f[cur][i] == 1) {
                avail[i] = f[cur][0];
                for(int j = i + 1; j <= nvar; ++ j)
                    avail[i] = avail[i] - f[cur][j] * avail[j];
                ++ cur;
            }
    }
};

ostream& operator << (ostream& out, const EqnGauss& a) {
    for (int i = 1; i <= a.nvar; ++ i)
        out << a.avail[i] << endl;
    return out;
}

```

```

EqnGauss eqns;
int main() {
    while (true) {
        cin >> eqns.nvar >> eqns.neqn;
        eqns.build();
        if (eqns.rebuild()) {
            eqns.solve();
            cout << eqns;
        }
        else
            cout << "no solution" << endl;
    }
    return 0;
}

/*
4 2
10 1 1 1 1
3 1 1 0 0
4 2
10 1 1 0 0
3 1 1 0 0
*/

```

## 47. 块状链表

```

//块状链表
#include<iostream>
#include<cmath>
#define MAX 2900
struct block { //Type of block

```

```

    int nos;//Number of elements in this block
    char em[MAX];//elements
    block *be,*su;//previous&successor
}
*first;
struct cursor { //Type of cursor
    int n;//The position of cursor(in one block)
    block *ll;//The block the cursor in
}
cur;
int tot,n;//tot:the total number of elements,n:the number of operations
inline void clean(block *op) { //Clean a new block
    op->nos=0;
    memset(op->em,0,sizeof op->em);
    op->be=NULL;
    op->su=NULL;
}
inline void Spilt(block *a,int newsiz) { //Break a block into two blocks,one's size
equal to 'newsiz',and another's equal to 'a->nos-newsiz'
    if(!newsiz)return;
    int tmp=a->nos;
    a->nos=newsiz;
    block *tps=a->su;
    a->su=new(block);
    clean(a->su);
    a->su->be=a;
    if(tps) {
        a->su->su=tps;
        a->su->su->be=a->su;
    }
    a->su->nos=tmp-newsiz;
    block *tt=a->su;
    for(int i=newsiz+1;i<=tmp;i++)tt->em[i-newsiz]=a->em[i];
}
inline void Merge(block *a) { //Merge a & a->su
    if(a->su==NULL)return ;
    int tmp=a->nos;
    for(int i=1;i<=a->su->nos;i++)a->em[a->nos+i]=a->su->em[i];
    a->nos+=a->su->nos;
    block *oo=a->su;
    if(cur.ll==oo) {
        cur.ll=cur.ll->be;
        cur.n+=tmp;
    }
}

```



```

    a->su=a->su->su;
    delete(oo);
    if(a->su)a->su->be=a;
}
inline void Balance() { //Make these blocks' size balance
    block *k=first;
    int kk=(int)sqrt(tot);
    for(;k!=NULL;) {
        for(;k->nos < kk/2 || k->nos > 2*kk;) {
            if(k->nos<kk/2) { //the block is too small?
                if(k->su)Merge(k);
                else break;
            } else if(k->nos>kk*2) { //the block is too big?
                Spilt(k,(k->nos)>>1);
                if((cur.ll==k)&&(cur.n>k->nos)) {
                    cur.ll=k->su;
                    cur.n-=k->nos;
                }
                k=k->su;
            }
        }
        k=k->su;
    }
}
inline void Insert(block *lk,int x,int k) { //Insert text behind the cursor
    block *oo=new(block);
    clean(oo);
    block *gg=oo;
    int rr=k;
    tot+=rr;
    int bt=(int)sqrt(tot);
    for(int i=0;i<rr;i++) {
        char gg;
        scanf("%c",&gg);
        for(;(gg>126)|| (gg<32);scanf("%c",&gg));
        oo->em[++oo->nos]=gg;
        if((oo->nos>=bt)&&(i<rr-1)) {
            oo->su=new(block);
            clean(oo->su);
            oo->su->be=oo;
            oo=oo->su;
        }
    }
}
if(x) {

```

```

        Spilt(lk,x);
    } else {
        if(!cur.ll->be) {
            block *jj;
            jj=first;
            first=new(block);
            clean(first);
            first->su=jj;
            jj->be=first;
        }
        cur.ll=cur.ll->be;
        cur.n=cur.ll->nos;
        lk=lk->be;
    }
    block *tmp=lk->su;
    lk->su=gg;
    oo->su=tmp;
    if(oo->su)oo->su->be=oo;
    lk->su->be=lk;
    cur.ll=lk->su;
    cur.n=0;
    Balance();
}
inline void Remove(block *lk,int x,int num) { //Delete 'num' elements behind the
cursor
    if(x) {
        Spilt(lk,x);
        lk=lk->su;
    } else {
        if(!cur.ll->be) {
            block *jj;
            jj=first;
            first=new(block);
            clean(first);
            first->su=jj;
            jj->be=first;
        }
        cur.ll=cur.ll->be;
        cur.n=cur.ll->nos;
    }
    tot-=num;
    int ttt=num;
    block *tmp;
    block *ij;

```

```

    for(tmp=lk;tmp&&((num-tmp->nos)>=0);tmp=ii) {
        ii=tmp->su;
        num-=tmp->nos;
        delete(tmp);
    }
    if(num&&tmp) {
        Spilt(tmp,num);
        cur.ll->su=tmp->su;
        cur.ll->su->be=cur.ll;
        if(cur.ll->be)cur.ll->be->su=cur.ll;
    } else {
        cur.ll->su=tmp;
        if(cur.ll->be)cur.ll->be->su=cur.ll;
        if(cur.ll->su)cur.ll->su->be=cur.ll;
    }
    Balance();
}

inline void Print(block *lk,int x,int num) { //print 'num' elements behind the cursor
    block *cp=lk;
    for(;num-(cp->nos-x)>0;cp=cp->su) {
        for(int i=x+1;i<=cp->nos;i++)printf("%c",cp->em[i]);
        num-=(cp->nos-x);
        x=0;
    }
    for(int i=1;i<=num;i++)printf("%c",cp->em[i+x]);
    printf("\n");
}

inline void prev() { //cursor move forward
    cur.n--;
    if(cur.n<0) {
        cur.ll=cur.ll->be;
        cur.n=cur.ll->nos-1;
    }
}

inline void next() { //cursor move backward
    cur.n++;
    if((cur.n>=cur.ll->nos)&&(cur.ll->su)) {
        cur.ll=cur.ll->su;
        cur.n-=cur.ll->be->nos;
    }
}

inline void move(int k) { //move the cursor to the postion 'k'
    cur.ll=first;
    for(;(cur.ll)&&(k-cur.ll->nos>0);cur.ll=cur.ll->su)

```

```

        k-=cur.ll->nos;
    cur.n=k;
}
/*
NOI2003 editor O(sqrt(n))
MOVE(k)    Move k    将光标移动到第k个字符之后，如果k=0，将光标移到文本开头
INSERT(n, s)  Insert n S 在光标处插入长度为n的字符串s，光标位置不变，n >= 1
DELETE(n)  Delete n    删除光标后的n个字符，光标位置不变，n >= 1
GET(n)      Get n      输出光标后的n个字符，光标位置不变，n >= 1
PREV()      Prev      光标前移一个字符
NEXT()      Next      光标后移一个字符
*/
int main() {
    freopen("editor.in", "r", stdin);
    freopen("editor.out", "w", stdout);
    first=new(block);
    clean(first);
    char str[100];
    cur.ll=first;
    cur.n=0;
    scanf("%d\n", &n);
    int k;
    for (int i=0;i<n;i++) {
        scanf("%s", str);
        switch (str[0]) { //deal with operations
            case 'M' : scanf("%d", &k); move(k); break;
            case 'I' : scanf("%d", &k); Insert(cur.ll,cur.n,k); break;
            case 'D' : scanf("%d", &k); Remove(cur.ll,cur.n,k); break;
            case 'G' : scanf("%d", &k); Print(cur.ll,cur.n,k); break;
            case 'P' : prev(); break;
            case 'N' : next(); break;
        }
    }
    fclose(stdin);
    fclose(stdout);
}

```

## 48. Factor Oracle

```

/*
Factor Oracle
后缀自动机构造过于复杂
可利用Factor Oracle实现基于子串搜索
实现两个串公共最长子串/单串最长重复子串的O(n)算法
(1)能在O(|u|)识别p的子串u

```

(2)可以识别p的所有子串,可能会误识别长度小于|p|的子串!!

(3)在O(|p|)时间内构造

\*/

/\*

abaaabbabaa

abab

Find, it's wrong. (2)

\*/

const int INIT = 1;

const int FAIL = 0;

const int MMAX = 201000;

const int SIGMAX = 30;

/\*

2774 PKU Long Long Message

求出lrs和S以后, 问题就好解决了

对于公共子串, 扫描后半部分的lrs, 加上S的限制, 防止重复串在同一个串中

若是单串, 直接取lrs中的最大值

\*/

char str[MMAX];

struct ORACLE

{

int T[MMAX][SIGMAX];

int S[MMAX];

int LRS[MMAX];

int SN;

int c2d[256];

void init() {

SN = INIT + 1;

S[INIT] = FAIL;

LRS[INIT] = 0;

// memset(T, FAIL, sizeof(T)); // 节省清空的时间开销

// memset(c2d, FAIL, sizeof(c2d));

}

void add(char ch) {

int m = SN - 1;

SN ++;

ch = c2d[ch];

T[m][ch] = m + 1;

int k = S[m];

int pre = m;

while (k != FAIL && T[k][ch] == FAIL) {

T[k][ch] = m + 1;

pre = k;

```

        k = S[k];
    }
    int shift;
    if (k == FAIL) shift = INIT;
    else shift = T[k][ch];
    S[m+1] = shift;
    LRS[m+1] = len_repeat_suffix(pre, S[m+1]);
}
void construct(char * p) {
    for (int i=0,j=FAIL+1; p[i]; i++) {
        if (c2d[ p[i] ] == FAIL)
            c2d[ p[i] ] = j ++;
        add(p[i]);
    }
}
int len_common_suffix(int p1, int p2) {
    if (S[p1] == p2) return LRS[p1];
    while (S[p1] != S[p2]) p2 = S[p2];
    return min(LRS[p1], LRS[p2]);
}
int len_repeat_suffix(int p1, int m) {
    if (m == INIT) return 0;
    return len_common_suffix(p1, m-1) + 1;
}
};
ORACLE fo;

int main()
{
    gets(str);
    int len = strlen(str);
    str[len] = '$';
    gets(str+len+1);

    fo.init();
    fo.construct(str);
    int ans = 0;
    for (int i=len+INIT+2; i<fo.SN; i++)
    {
        if (fo.S[i] >= len+INIT+2) continue;
        ans = max(ans, fo.LRS[i]);
    }
    printf("%d\n", ans);
}

```

**49.**