#### Aim

To understand backpropagation by manually computing it for a simple computation graph

### Introduction

Backpropagation helps us compute the gradient of a composite function efficiently.

```
In [25]: # # Value Object Explained
         # ## What is a Value Object?
         # A Value object represents a variable in a computation and tracks two
         # 1. The current value of the variable
         # 2. How this variable affects the final output (its gradient)
         from graphviz import Digraph
         from graphviz import Digraph
         class Value:
             def __init__(self, data, label="", prev=[], op=""):
                 self.data = data
                 self.grad = 0
                 self.label = label
                 self.prev = prev
                 self.op = op
             def __add__(self, other):
                 other = other if isinstance(other, Value) else Value(other)
                 out = Value(self.data + other.data, prev=[self, other], op="+"
                 return out
             def __mul__(self, other):
                 other = other if isinstance(other, Value) else Value(other)
                 out = Value(self.data * other.data, prev=[self, other], op="*"
                 return out
             def __rmul__(self, other):
                 return self * other
             def __repr__(self):
                 return f"Value(label={self.label}, data={self.data}, grad={sel
```

```
def build(self):
    """builds a set of all nodes and edges in a graph"""
    nodes, edges = set(), set()
    def build(v):
        if v not in nodes:
            nodes.add(v)
            for child in v.prev:
                edges.add((child, v))
                build(child)
    build(self)
    return nodes, edges
def draw_dot(self):
    """Creates a visualization of the computation graph"""
    dot = Digraph(format='svg', graph_attr={'rankdir': 'LR'})
    nodes, edges = self._build()
    # Add all nodes to graph
    for n in nodes:
        uid = str(id(n))
        # Create a node label with data and optional label
        node label = f"data {n.data:.4f}"
        if n.label:
            node_label += f" | label {n.label}"
        if n.grad:
            node_label += f" | grad {n.grad}"
        # Add the node as a box
        dot.node(name=uid,
                label=node_label,
                shape='record')
        # If it's an operation result, add the operation node
        if n.op:
            op_id = uid + n.op
            dot.node(name=op_id, label=n.op, shape='circle')
            dot.edge(op_id, uid)
    # Add edges between nodes
    for n1, n2 in edges:
        dot.edge(str(id(n1)), str(id(n2)) + n2.op)
    return dot
```

### **Example Problem**

Consider a concrete example with following equations:

```
L = d * f

d = e + c

e = a * b

Where a=2, b=-3, c=10, f=-2
```

We aim to minimize the loss function L. To achieve this, we need to calculate the partial derivatives (gradients) with respect to each variable in our computation:

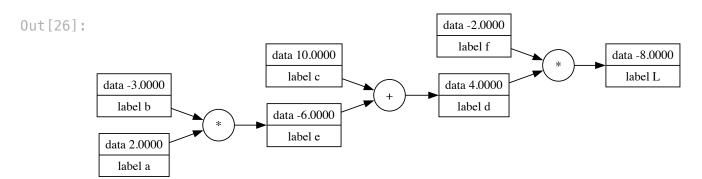
- $\partial L/\partial a$ : How L changes with respect to a
- $\partial L/\partial b$ : How L changes with respect to b
- ∂L/∂c: How L changes with respect to c
- ∂L/∂d: How L changes with respect to d
- ∂L/∂e: How L changes with respect to e
- ∂L/∂f: How L changes with respect to f

These gradients tell us how to adjust each variable to reduce L. While we could calculate these gradients manually, backpropagation provides an efficient algorithm to compute them automatically by leveraging the computational graph structure.

## The forward pass

The forward pass is the process of computing the final output (in this case, L) by evaluating each expression in our computation graph from inputs to outputs. It follows the natural order of calculations.

```
In [26]: a = Value(2.0, label='a')
b = Value(-3.0, label='b')
c = Value(10.0, label='c')
f = Value(-2.0, label = 'f')
e = a*b; e.label = 'e'
d = e + c; d.label = 'd'
L = d * f; L.label = 'L'
L.draw_dot()
```



# Gradient computation by backpropagation

The backward pass is where we compute all gradients by moving backwards through our computational graph. We start at the output (L) and move towards the inputs (a, b, c, f).

#### Our equations

```
L = d * f

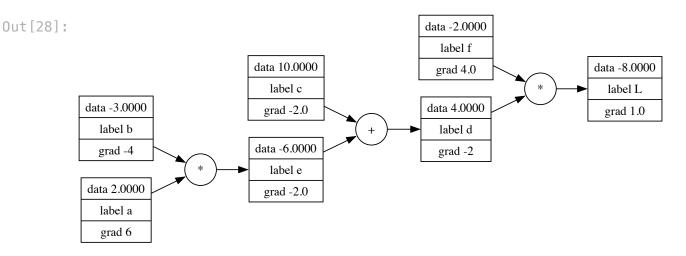
d = e + c

e = a * b
```

- 1. Start at L  $(\partial L/\partial L = 1)$ :
- By definition,  $\partial L/\partial L = 1.0$
- This serves as our starting point
- 2. Compute  $\partial L/\partial d$  and  $\partial L/\partial f$ :
- For equation L = d \* f:
- $\partial L/\partial d = f = -2.0$
- $\partial L/\partial f = d = 4.0$
- 3. Compute  $\partial L/\partial e$  and  $\partial L/\partial c$ :
- For equation d = e + c:
- $\partial L/\partial c = \partial L/\partial d * \partial d/\partial c = -2.0 * 1 = -2.0$
- $\partial L/\partial e = \partial L/\partial d * \partial d/\partial e = -2.0 * 1 = -2.0$
- 4. Compute  $\partial L/\partial a$  and  $\partial L/\partial b$ :
- For equation e = a \* b:
- $\partial L/\partial a = \partial L/\partial e * \partial e/\partial a = -2.0 * b = -2.0 * (-3) = 6.0$
- $\partial L/\partial b = \partial L/\partial e * \partial e/\partial b = -2.0 * a = -2.0 * 2 = -4.0$

Once we have these gradients, we can use them to update our variables:

```
In [27]: L.grad = 1.0; f.grad = 4.0; c.grad = -2.0; d.grad = -2; e.grad = -2.0
In [28]: L.draw_dot()
```



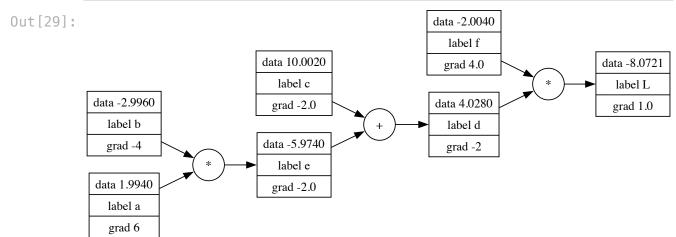
# Minimize L using gradient / Gradient Descent Update

```
In [29]: # Set learning rate
lr = 0.001

# Update parameters
a.data -= lr * a.grad # 2.0 - 0.001 * 6.0 = 1.994
b.data -= lr * b.grad # -3.0 - 0.001 * (-4.0) = -2.996
c.data -= lr * c.grad # 10.0 - 0.001 * (-2.0) = 10.002
f.data -= lr * f.grad # -2.0 - 0.001 * 4.0 = -2.004

# Recompute forward pass
e.data = a.data * b.data
d.data = e.data + c.data
L.data = d.data * f.data

L.draw_dot()
```



The loss value has decreased from -8.0 to -8.0721, showing our updates moved in the right direction. This happened because:

- 1. Each variable was adjusted in proportion to its gradient
- 2. The learning rate (0.001) ensured small, controlled updates
- 3. The negative change in L indicates we're successfully minimizing the loss function

If we continued this process iteratively, L would continue to decrease until reaching a local minimum. This is the core principle behind how neural networks learn from data.