**Chapter 1**

**PREAMBLE**

* 1. **Introduction**

The number of visually impaired people is growing over the past decades. As reported by the world health organization (WHO), about 285 million people worldwide are estimated to be visually impaired. People to commute from one place to other they have to take help of someone or the have to use the stick which is called as the white cane. The white cane stick senses any obstacle on the surface and gives a signal to the person holding it, by which the person gets to know that there is an obstacle. But technology advancement has changed the people deal with the problems.

There are smart glasses available in the market which can detect the obstacle in front of us and warn us, so we get alert. So, we are trying to come up with a project in which we can have all the necessary functionality and try to improve the life of visually impaired people.

The smart glasses available in the market are very costly, which every person cannot afford that is the reason we find even today people using those sticks for their daily commute in day to day life.

The current methods used are:

* The **white cane** helps people who are blind or severely visually impaired know when there are tripping hazards such as cracks, poles, etc. The cane is swept from side to side to clear one’s path from these and other obstacles. Other techniques allow us to know when we’ve reached a crosswalk or the entrance to a room. The white cane also signals to drivers that the pedestrian about to cross the street is visually impaired.
* **Guide dogs** are service animals that have received special and extensive training to guide blind and visually impaired individuals. These dogs guide their handlers around obstacles and can also help find things like entrances, escalators and elevators. It is up to the handler to tell the dog where to go – it is only there to lead the person and help him or her arrive safely to the desired destination.
* **A sighted (or human) guide** is probably the simplest of all the methods, and is the proper way of assisting someone who may need help getting somewhere. A blind person is guided by someone else by holding on to their arm. This method is preferred by some of us when in unfamiliar places or if there are large crowds.

To give a better solution to this problem our team have decided to come up with a device in which we have obstacle detection and identification and many other features which will help the user commute easily and the output to the user will be in the form of speech.

* 1. **Relevance of the Project**

There are over 285 million people who are suffering from visual problem and by coming up with this technology we can help this people by giving a chance to live the life to full and to add something to the society.

India is a country with a population of over 1.3 billion people. Among this, over 13million people are suffer from visual impairment, with almost 260,000 individuals residing in the state of Karnataka alone, according to the Karnataka Census of 2011 There are many such problems which are faced by them in daily routines of life like commuting from one place to other, reading, getting things done by themselves, finding independence, finding objects and obstacles.

There are some other companies in the market which are trying to come with a solution for this problem in the society like for an example we can see the Google lens which scans an object and can tell you what is that. Also, some companies have come with the product likes smart glasses where it detects the object or obstacle ahead and gives out a beep sound or warns the person and guides him/her. But we don’t have something where all these three things are combined like object detection, object identification and then output in the form of speech.

So, our team have decided to come with some technology where we can help this people in making their life a bit easier. Like by helping them out with guiding through roads and if any object or obstacle detected by the device will signal the voice out message and there by letting to know them by a voice output and they get aware about it.

By using this product, they will become independent and will not require to depend on any one else for their daily life activity which they required to be dependent all time.

* 1. **Purpose of Study**

India is the second most populated country in the world with nearly a fifth of the world's population. According to the 2017 revision of the World Population Prospects, the population stood at 1,324,171,354. During 1975–2010 the population doubled to 1.2 billion. The Indian population reached the billion mark in 1998. India is projected to be the world's most populous country by 2024, surpassing the population of China. In this vast growing population India has as many as 8.8 million people who were found to be blind in 2015 and another 47.7 million people had moderate and severe vision impairment, according to a study published online by The Lancet Global Health journal on August 2.

The state of Karnataka alone has a population of Approximate 6.11 Crore out of which 264,170 individuals are visually impaired according to the census of Karnataka 2011.So we are coming up with this technology where we can help this people in making their life a bit easier. Like by helping them out with guiding through roads and if any object or obstacle detected by the device will signal the voice out message and there by letting to know them by a voice output and they get aware about it.

By using this product, they will become independent and will not require to depend on any one else for their daily life activity which they required to be dependent all time. When it comes to blind people they are ignored and nothing much is done to them if we look at the society and that’s our main intention to come up with something where we can give them a hope of living normally like other people. This project is an attempt for inclusion of the individuals who are visually impaired when it comes to commuting from one place to other, this can be achieved by using the technology implement a product which is intuitive and user friendly for the Visually Impaired to use with the help of Speech for guidance.

* 1. **Scope of the Project**

In last some years we have seen that there are some technology and some companies which are trying to come with a solution for this problem in the society like for an example we can see the Google lens which scans an object and can tell you what is that.

Also, some companies have come with the product likes smart glasses where it detects the object or obstacle ahead and gives out a beep sound or warns the person and guides him/her. But we don’t have something where all these three things are combined like object detection, object identification and then output in the form of speech.

So, as we all know that India is the second most populated country in the world with nearly a fifth of the world's population. According to the 2017 revision of the World Population Prospects, the population stood at 1,324,171,354. During 1975–2010 the population doubled to 1.2 billion. The Indian population reached the billion mark in 1998. India is projected to be the world's most populous country by 2024, surpassing the population of China. In this vast growing population India has as many as 8.8 million people who were found to be blind in 2015 and another 47.7 million people had moderate and severe vision impairment, according to a study published online by The Lancet Global Health journal on August 2. So, our team have decided to come with a product where we can help this people in making their life a bit easier. Like by helping them out with guiding through roads and if any object or obstacle detected by the device will signal the voice out message and there by letting to know them by a voice output and they get aware about it. By using this product, they will become independent and will not require to depend on any one else for their daily life activity which they required to be dependent all time.

* 1. **Problem Definition**

The problem statement is to come up with a product which can be used by visually challenged people to commute and do their daily life activity without any hassle. Blind people face a lot of challenges in their daily lives. To overcome the difficulty of the visually impaired group this work presents a Smart Vision system which provides guidance to blind people efficiently and safely.

* 1. **Problem Explanation**

Blind people face lot of challenges in their daily lives. To overcome the difficulty of the visually impaired group this project presents a Smart Vision system which provides guidance to blind people efficiently and safely. The main objective of the present work is to develop a low cost, reliable, portable, user friendly solution for smooth navigation. It includes ultrasonic sensors to detect any obstacle and notify the user with a beep sound. It also includes a camera which provides various functionalities such as OCR (optical character recognition), voice out the top 10 news, current time, new emails, current temperature, current location etc. The experimental results show that the Smart Vision System can effectively improve the user’s travelling experience. Thus, it serves as a consumer device for helping the visually impaired people.

India is the second most populated country in the world with nearly a fifth of the world's population. The Indian population reached the billion mark in 1998. India is projected to be the world's most populous country by 2024, surpassing the population of China. In this vast growing population India has as many as 8.8 million people who were found to be blind in 2015 and another 47.7 million people had moderate and severe vision impairment, according to a study published online by The Lancet Global Health journal on August 2.

So, by looking at this statistic we can tell that it’s a very big no of people and there should be some solution to this problem. So, our team have decided to come with a product where we can help this people in making their life a bit easier. Like by helping them out with guiding through roads and if any object or obstacle detected by the device will signal the voice out message and there by letting to know them by a voice output and they get aware about it. By using this product, they will become independent and will not require to depend on any one else for their daily life activity which they required to be dependent all time.

* 1. **Objective of the Study**

The objective of the study is to understand the user problems faced by them in their daily life activity and in which they have to depend on someone else for each and every work they do, like moving from one place to other, difficult to recognize the current location, timing like this there are many problems faced by them and so we have decided to come up with technology product wherein we can make use of that and help the people who are in need of that.

According to WHO (World Health Organization), these estimated number of people visually impaired in the world is 285 million, out of which 39 million are blind and 246 million are having low vision. The visually impaired people face a lot of difficulty in perceiving and interacting with the surroundings but there are some navigation systems or tools available for visually impaired individuals. Traditionally, most of them rely on cane (walking stick) swaying in front while walking to avoid obstacle. However, they cannot perceive any information written on boards or any important indication. So, we are coming up with a product which can give much better results when compared to traditional methods used.

* 1. **Existing System**

The existing system includes:

**White cane** which helps people who are blind or severely visually impaired know when there are tripping hazards such as cracks, poles, etc. The cane is swept from side to side to clear one’s path from these and other obstacles. Other techniques allow us to know when we’ve reached a crosswalk or the entrance to a room. The white cane also signals to drivers that the pedestrian about to cross the street is visually impaired.

**Guide dogs** are service animals that have received special and extensive training to guide blind and visually impaired individuals. These dogs guide their handlers around obstacles and can also help find things like entrances, escalators and elevators. It is up to the handler to tell the dog where to go – it is only there to lead the person and help him or her arrive safely to the desired destination.

**A sighted (or human) guide** is probably the simplest of all the methods, and is the proper way of assisting someone who may need help getting somewhere. A blind person is guided by someone else by holding on to their arm. This method is preferred by some of us when in unfamiliar places or if there are large crowds.

* + 1. **Limitations**
* By using the white cane sticks we can only know the things which are on ground and things above our stomach level if there is any barrier above that it’s not possible to know and the person might end up hitting his head or something.
* Guide dogs can’t be taken to all the place as there are restriction to many public places where dogs are not allowed then the person might be in trouble and he may be not able to go to that place and do his work normally like other people.
* Human guides are very efficient but they are very expensive and can’t be afforded by everyone out there. So, we see that people using the white cane most of the times whenever we encounter a visually challenged person.
* An even smart glass available doesn’t provide all the three features in one device like our product does. Our product can detect the obstacle, identify the obstacle and then give the output in the form of speech.
  1. **Proposed System**

Smart vision glasses give the visually impaired person with the following capabilities:

1. ***Voice the text content present in a picture***

The webcam is used to take a picture of the document or any object containing text. The picture is taken and tesseract ocr module is used to extract the text from the image and the extracted text is stored into a text document. The gTTS is used to convert the text to speech format. The speech is then played back to the visually impaired person.

1. ***Voice out the current date and time***

The smart vision system uses the datetime module to get the current date and time and it is stored into a text document. The text document that is generated is later given as an input to the gTTS (google text to speech module) which converts the text to speech and the speech output is stored into a .mp3 file and the .mp3 file is played out as the output to the visually impaired person via an earphone.

1. ***Voice out the current location***

The smart vision system uses the ip address for knowing the current location, region and the country. The shell command curl ipinfo is used to get the current location, region and the country. The result is stored into a text document and the text document is given as an input to the gTTS which converts the text into .mp3 file. The .mp3 file is played back to the visually impaired person through the headphones or any media device attached to the processor.

1. ***Voice out the current temperature***

The smart vision system uses the OpenWeatherMap API to get the current temperature and the weather description for the day. The result is stored into a text document and this document is given to gTTS which converts the result into speech format. The speech result is then played to the visually impaired person.

1. ***Voice out the new emails***

The smart vision system has the capability to read out the new emails arrived to the person’s email. The vision system uses the imap module to connect the SMTP server over the SSL. Using already feed in user credentials we login to the mail server and get the unread messages and store it into a text file. Using gTTS the text file is converted into a speech format and the .mp3 file is played out to the visually impaired person.

1. ***Voice out the top 10 headlines for the day***

The smart vision system uses the News API to get the top 10 news headlines for the day. The result is stored into a text document and the text document is given as an input to the gTTS. The gTTS converts it into the .mp3 file which is played to the visually impaired person***.***

* + 1. **Advantages**
* Increased confidence to travel alone.
* Ease of interaction with public.
* Increased safety during travelling around.
* Being able to do the work without any hassle.
* Social and psychological benefits.

**Chapter 2**

**LITERATURE SURVEY**

**Case Study1: Survey on Smart Glasses for Visually Impaired People**

By Muhammad Shahbaz Khan, Sunil K A, Pramod Sencha N

**Abstract**

Blind people face lot of challenges in their daily lives. To overcome the difficulty of the visually impaired group this paper presents a Smart Glasses which provides guidance to blind people efficiently and safely. The main objective of the present work is to develop a low cost, reliable, portable, user friendly solution for smooth navigation. It includes ultrasonic sensors to detect any obstacle and notify the user with a beep sound. It also includes a camera which provides various functionalities such as OCR (optical character recognition), voice out the top 10 news, current time, new emails, current temperature, current location etc. The experimental results show that the Smart Vision System can effectively improve the user’s travelling experience. Thus it serves as a consumer device for helping the visually impaired people.

Keywords: Raspberry PI, OCR (Optical Character recognition), Obstacle detection, Current date and time, new emails, current location and temperature.

1. **Introduction**

According to WHO (World Health Organization), the estimated number of people visually impaired in the world is 285 million, out of which 39 million are blind and 246 million are having low vision. The visually impaired people face a lot of difficulty in perceiving and interacting with the surroundings but there are some navigation systems or tools available for visually impaired individuals. Traditionally, most of them rely on cane (walking stick) swaying in front while walking to avoid obstacle. However, they cannot perceive any information written on boards or any important indication.

The proposed prototype includes ultrasonic sensors, camera which is used for multiple functionalities. The ultrasonic sensors are placed on hat/glass which detects objects and notify the user with a beep sound through an earphone when the user is very close to the object. The camera is used for OCR (optical character recognition) which extracts text from images taken by the camera on the press of button on remote by the user. The processing unit used is Raspberry pi which processes the above functionalities. The other functionalities implemented on raspberry pi are news headlines, current date and time, current temperature, current location etc. The details of the above functionalities are discussed in the proposed system.

1. **Literature Survey**

The paper[1] presents an assistive system for visually impaired people. The system helps the visually impaired people while travelling. It is designed in the shape of eyeglasses for providing guidance efficiently and safely. It uses Ultrasonic sensors which are placed on glasses which are used to detect objects and alert the User. The model improves the traveling experience of users but still the user cannot perceive any written information.

The paper[2] identifies the personal, environmental, and transportation factors that have an effect on visually impaired people. It is designed to help the visually impaired people in indoor and outdoor mobility and navigation. The prototype can detect traffic situations such as street crossings, traffic lamps, cars, cyclists, other people and low and high obstacles. The user is alerted with a beep sound via an earphone.

The paper[3] consists of rangefinders that would take input from the ultrasonic sensors and output feedback to pulse vibration motors which are placed on the blind man's head. When the person gets closer to the object, the intensity and frequency of the vibration are increased. The main limitation is the use of vibration motor. The vibrations as an output feedback are far way irritating for any blind person.

In paper [4] it can be observed that it consists of a video camera on the frame itself as well as a computer processing unit precise enough to get fit in the pocket and the software that provides images of objects close by to transparent displays on the eyepieces. The major limitation of this device is that it is not at all suitable for completely blind people. It is recommended only for people with low vision or night blindness.

1. **Barriers**

The visually impaired people face a lot of difficulties in their daily tasks. A visually impaired person needs some help to move from one place to another either in the form of a tool such as cane(walking stick) or a person to guide them. The walking stick doesn’t detect potholes or small objects which is inefficient for the user. A human guidance is not available or cannot be given every time.

Some of the existing systems offer limited functionality such as detecting the objects and alerting the user through speaker but cannot assist the blind person to the fullest. Few models are not feasible because of weight or cost.

1. **Conclusion**

The paper introduces the need for a good model for the visually impaired. The performance of the proposed system has found to be effective. The ultrasonic sensors can detect the obstacle in the range 2cm to 400cm and alert the user with a beep sound via an earphone. With the press of a button, the user can perform various functionalities. The user can perceive any written information with a press of a button, voice out the current date and time, current temperature, current location etc. The proposed model is easy to wear and use and can be used as a portable model for visually impaired people.

**Case Study - 2: Implementation of Smart Glasses for Visually Impaired people.**

By Muhammad Shahbaz Khan, Sunil K A, Pramod Sencha N

**Abstract**

In today’s growing world where technology is advancing into every aspect of our lives, it has changed the way we go about our life. With all this technology in hand, improvements can be made in various ways to help the society. Blind people face lot of challenges in their daily lives. To overcome the difficulty of the visually impaired group this paper presents a Smart Glasses which provides guidance to blind people efficiently and safely. The main objective of the present work is to develop a low cost, reliable, portable, user friendly solution for smooth navigation. It includes ultrasonic sensors to detect any obstacle and notify the user with a beep sound. It also includes a camera which provides various functionalities such as OCR (optical character recognition), voice out the top 10 news, current time, new emails, current temperature, current location etc. The experimental results show that the Smart Vision System can effectively improve the user’s travelling experience. Thus it serves as a consumer device for helping the visually impaired people.

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The proposed prototype includes ultrasonic sensors, camera which is used for multiple functionalities. The ultrasonic sensors are placed on hat/glass which detects objects and notify the user with a beep sound through an earphone when the user is very close to the object. The camera is used for OCR (optical character recognition) which extracts text from images taken by the camera on the press of button on remote by the user. The processing unit used is Raspberry pi which processes the above functionalities. The other functionalities implemented on raspberry pi are news headlines, current date and time, current temperature, current location etc. The details of the above functionalities are discussed in the proposed system.

1. **Implementation**

The implementation of Smart Glasses for visually impaired People is done with the help of components such as Raspberry pi, ultrasonic sensors, webcam, earphone. All the components are placed in secure manner which is easy for the person to use it. The person can anytime wear or remove the model.

The raspberry pi is a low cost, credit card size computer which is used for running the programs(processing). The Ultrasonic sensors measure distance by using ultrasonic waves. The sensor head emits an ultrasonic wave and receives the wave reflected back from the target. Ultrasonic sensor measure the distance to the target by measuring the time between the emission and reception. It has a range to detect the objects in the range of 2cm to 400cm. The sensors are placed on the model which are used to detect any obstacle and alert the user with a beep sound.

The webcam is used to capture an image and is processed by Raspberry pi to extract text from the image using the OCR (optical character recognition) technology. It can also identify the dominant color present in the image.

The features such as voice out unread emails, current temperature, current location, current date and time, current weather details are programmed on the raspberry pi. All the above features can be executed with the press of a specific button on the handheld remote. The output of all the features is in speech format using gTTS library.

1. **Modules**
2. **Voice out results**

gTTS (google text to speech library): It is used to convert the text to speech format. It is vital for voice output for user.

1. **DateTime module**

It has methods to return information about the date and time object. Basically, it is used to fetch the current date and time.

1. **OpenWeatherMap API**

OpenWeatherMap API is used to get the current temperature and the weather description for the day and the result is stored in a text file.

1. **Imap module**

Internet Message Access Protocol. It is an Internet standard protocol used by email clients to retrieve email messages from a mail server over a TCP/IP connection.

1. **News API**

It is used to fetch the top headlines from news server and store the results in a text file. The text file is given as an input to gTTS module to voice out the top 10 headlines.

1. **Tesseract**

Python-tesseract is an optical character recognition (OCR) tool for python. That is, it will recognize and “read” the text embedded in images.

1. **Geocoder**

This module is used to find the current location of the user. Geocoding uses spatially explicit reference dataset (e.g., digital road network) to identify the location that best matches the input address, essentially by comparing and interpolating the address to the range of addresses for each segment of the reference dataset.

1. **Conclusion**

With the available improvements in technology it is imperative to provide a solution which will work towards the betterment of the society and make a change in our community. The paper introduces the need for a good model for the visually impaired. The performance of the proposed system has found to be effective. The ultrasonic sensors can detect the obstacle in the range 2cm to 400cm and alert the user with a beep sound via an earphone. With the press of a button, the user can perform various functionalities. The user can perceive any written information with a press of a button, voice out the current date and time, current temperature, current location etc. The proposed model is easy to wear and use and can be used as a portable model for visually impaired people.

**Chapter 3**

**SYSTEM REQUIREMENTS SPECIFICATION**

**3.1 General Description of the System**

Smart glasses for the visually impaired is an intuitive hardware pilus software combined product which would serve as a helping or assistive device for the visually impaired people or the people who have visual disability. The idea is to design a product by keeping in mind the limitations it would present when being used by a person who us visually disabled.

The developed product will be able to assist the visually impaired people with everyday simple tasks and voice out all the results or the outputs of the processes, to curb this we employ the use text to speech. The idea is the create a product which would voice out the current date and time, voice out the current location, voice out the current weather information with the description, voice out the unread emails, voice out the current top 10 news headlines, voice out the text in an image by using OCR ( optical character recognition ) technology, voice out the dominant color in an image and also provide obstacle detection using ultrasonic sensors hosted on the product. All these features would be available to the visually impaired person through the push of a button on the handheld remote corresponding to a particular feature. The processing and execution of the various features are performed the raspberry pi processor. All these features are possible by using machine learning models and the python programming language. Python is currently the most widely used multi-purpose, high-level programming language. The biggest strength of Python is huge collection of standard library which can be used for [Machine Learning](https://www.geeksforgeeks.org/machine-learning/), GUI Applications (like [Kivy](https://www.geeksforgeeks.org/kivy-tutorial/" \t "_blank), Tkinter, PyQt etc. ), Web frameworks like [Django](https://www.geeksforgeeks.org/django-tutorial/) (used by YouTube, Instagram, Dropbox), Image processing (like [OpenCV](https://www.geeksforgeeks.org/opencv-python-tutorial/), Pillow), Web scraping (like Scrapy etc..) Text processing and much more.

**3.1.1 Overview of Functional Requirements**

The functional requirements give the functionality of the system. For the system to work the mobile data or Wi-Fi with a good internet speed is required. This ensures that the device can work efficiently work with the various API’s used in the product. The current weather, current location, current news headlines, text to speech, email voice out features requires a stable internet connection for the efficient results.

**3.1.2 Overview of Data Requirements**

Data requirements are the consensual agreements or prescribed directives that define the content and structure that consist of high-quality values and data instances. Data requirements can therefore be stated by the several different individuals or groups of individuals. The current date and time feature extracts the required data from the Linux OS, the current location feature extracts the data from the IP to which the system is connected, the current weather feature extracts the data from the open weather API, email voice out feature extracts the data from the email server, the news headlines feature extracts the current news data using the news API, the image to text to speech conversion feature requires an image from the user, the image is taken from the product hosted webcam on the push of a button form the hand held remote, the color detection feature also requires an image from the user, the image is taken from the product hosted webcam on the push of a button form the hand held remote. The ultrasonic sensor analyzes the environment for the obstacles and sets an alarm if an obstacle is too close to the user.

The data for executing a particular feature is taken from the user using the hand held remote. Each button In the remote corresponds to a particular feature on the product. The push a button activates the corresponding feature and the particular feature is executed automatically by the raspberry pi processor.

**3.2 Technical Requirements of the System**

This technical requirement specifies the requirements of the project. The information on technical design, development and procedures related to the requirements is outlined here. This section talks about the system requirement details, including functional, interface and design requirements.

**3.2.1 Hardware Requirements**

For the application to be built and used efficiently the hardware components required to run these below mentioned software resources on the computer. It gives a physical computer resource list accompanied by Hardware Compatibility List (HCL).

**Raspberry pi processor:**

The model of raspberry pi processor used in the project is “Raspberry PI 3 Model B+ ” which has the following specifications:

* SOC: Broadcom BCM2837B0, Cortex-A53 (ARMv8) 64-bit SoC
* CPU: 1.4GHz 64-bit quad-core ARM Cortex-A53 CPU
* RAM: 1GB LPDDR2 SDRAM
* WIFI: Dual-band 802.11ac wireless LAN (2.4GHz and 5 GHz) and Bluetooth 4.2
* Ethernet: Gigabit Ethernet over USB 2.0 (max 300 Mbps). Power-over-Ethernet support (with separate PoE HAT). Improved PXE network and USB mass-storage booting.
* Thermal management: Yes
* Video: Yes – Video Core IV 3D. Full-size HDMI, Audio: Yes
* USB 2.0: 4 ports
* GPIO: 40-pin
* Power: 5V/2.5A DC power input
* Operating system support: Linux and Unix

**External Webcam:**

The external webcam is used for capturing the images for OCR feature and the dominant color feature. The external webcam used in this project has the following configuration:

* HD video calling (1280 x 720 pixels) with recommended system, Video capture: Up to 1280 x 720 pixels
* Logitech Fluid Crystal Technology, Photos: Up to 3.0 megapixels (software enhanced)
* Built-in mic with noise reduction, Hi-Speed USB 2.0 certified (recommended)
* Universal clip fits laptops, LCD or CRT monitors
* Built-in microphone that reduces background noise.

**Compatibility**

**Basic Requirements**

* 1 GHz
* 512 MB RAM or more
* 200 MB hard drive space
* Internet connection
* USB 1.1 port (2.0 recommended)

**Ultrasonic sensors:**

The ultrasonic sensors are used for the obstacle avoidance feature. The ultrasonic sensor that is used in the project has the following configuration.

* High sensitivity ultrasonic range sensor
* Working Voltage - DC 5V, Working Current - 15mA
* Max Range - 4m, Min Range - 2cm, Measuring Angle - 15 degree

**Mini keyboard:**

The mini keyboard would act as a hand held remote through which the user can select a particular feature to execute and hear the result. The keyboard used in this project has the following configuration:

* 2.4GHz Mini Wireless QWERTY keyboard, Touchpad combo, multimedia control keys and PC gaming control keys with USB interface adapter.
* 92 keys Wireless QWERTY Keyboard, Touchpad which supports multi-finger functions, A single finger click as left mouse function, two-finger click as the right mouse function, double finger drags as the rolling screen.
* Built-in highly sensitive smart touchpad with 360-degree flip design. Innovative shape, portable, elegant. The Ergonomically handheld design is easy to carry and operate.
* Perfect for PC, Pad, Android TV Box, Google TV Box, Xbox 360, PS3, HTPC, IPTV.

**3.2.2 Software Requirements**

The software requirements deal with the prerequisites and software resource requirements that are needed to be installed on the computer to give optimal functioning of the application.

* Operating System – Raspbian Stretch
* Programming Language – Python2, Python3, Shell scripting
* IDE – Geany IDE
* Libraries – Pillow, OpenCV, datetime, Geocoder, numpy, scipy, tesseract, gTTS, IMAP protocol, playsound, News API, Open Weather API, email library.

**3.3 Input Requirements**

The features like voice out current date and time, voice out current location, voice out the current weather, voice out the top 10 news headlines just requires the push of corresponding button from the hand held remote.

The voice out the unread email requires the user to have a configured email address which would allow the IMAP call from the python code. The OCR feature and the dominant color feature requires an image to be taken by the user using the webcam hosted on the product. The obstacle detection feature takes the input feed from the ultrasonic sensor and sets an alarm to high if a particular object is too close to the user. The product must have a good internet connection for the various API’s work efficiently.

**3.4 Output Requirements**

The product must have a good internet connection for the various API’s work efficiently. The product must have an audio output connected to it which can be in the form of headphones or Bluetooth audio outputs. The voice output results for all the features are played to the user or the visually impaired person through the audio output devices. The volume needs to be high in order for the user to hear the results given from the device.

**3.5 Language Specification**

The language specification is used during system analysis, system design and requirement analysis to describe the system at a higher level than the programming language, and hence used to the executable code for the system. These area unit are usually in a roundabout way dead. they're meant to explain the what, not the however. Indeed, it's thought-about as a slip-up if a demand specification is untidy with inessential implementation detail.

A common elementary assumption of the many specification approaches is that programs area unit modelled as pure mathematics or model-theoretic structures that embrace a set of sets of knowledge values at the side of functions over those sets. This level of abstraction coincides with the read that the correctness of the input/output behavior of a program takes precedence over all its alternative properties.

**3.5.1 Python**

Python is a multi paradigm programming language. Object-oriented programming and structured programming are fully supported, and many of its features support functional programming and aspect-oriented programming (including by metaprogramming and metaobjects (magic methods)). Many other paradigms are supported via extensions, including design by contract and logic programming.

Python uses dynamic typing and a combination of reference counting and a cycle-detecting garbage collector for memory management. It also features dynamic name resolution (late binding), which binds method and variable names during program execution. Python’s design offers some support for functional programming in the Lisp tradition. It has filter, map, and reduce functions; list comprehensions, dictionaries, sets, and generator expressions. The standard library has two modules (itertools and functools) that implement functional tools borrowed from Haskell and Standard ML.

Rather than having all of its functionality built into its core, Python was designed to be highly extensible. This compact modularity has made it particularly popular as a means of adding programmable interfaces to existing applications. Van Rossum's vision of a small core language with a large standard library and easily extensible interpreter stemmed from his frustrations with ABC, which espoused the opposite approach.

Python strives for a simpler, less-cluttered syntax and grammar while giving developers a choice in their coding methodology. In contrast to Perl's "there is more than one way to do it" motto, Python embraces a "there should be one—and preferably only one—obvious way to do it" design philosophy. Alex Martelli, a Fellow at the Python Software Foundation and Python book author, writes that "To describe something as 'clever' is not considered a compliment in the Python culture."

Python's developers strive to avoid premature optimization, and reject patches to non-critical parts of the CPython reference implementation that would offer marginal increases in speed at the cost of clarity. When speed is important, a Python programmer can move time-critical functions to extension modules written in languages such as C, or use PyPy, a just-in-time compiler. Cython is also available, which translates a Python script into C and makes direct C-level API calls into the Python interpreter.

An important goal of Python's developers is keeping it fun to use. This is reflected in the language's name—a tribute to the British comedy group Monty Python—and in occasionally playful approaches to tutorials and reference materials, such as examples that refer to spam and eggs (from a famous Monty Python sketch) instead of the standard foo and bar.

A common neologism in the Python community is pythonic, which can have a wide range of meanings related to program style. To say that code is pythonic is to say that it uses Python idioms well, that it is natural or shows fluency in the language, that it conforms with Python's minimalist philosophy and emphasis on readability. In contrast, code that is difficult to understand or reads like a rough transcription from another programming language is called unpythonic. Users and admirers of Python, especially those considered knowledgeable or experienced, are often referred to as Pythonistas.

**3.5.2 Shell Scripting**

A shell script is a computer program designed to be run by the Unix shell, a command-line interpreter.The various dialects of shell scripts are considered to be scripting languages. Typical operations performed by shell scripts include file manipulation, program execution, and printing text. A script which sets up the environment, runs the program, and does any necessary cleanup, logging, etc. is called a wrapper. The term is also used more generally to mean the automated mode of running an operating system shell; in specific operating systems they are called other things such as batch files (MSDos-Win95 stream, OS/2), command procedures (VMS), and shell scripts (Windows NT stream and third-party derivatives like 4NT—article is at cmd.exe), and mainframe operating systems are associated with a number of terms.

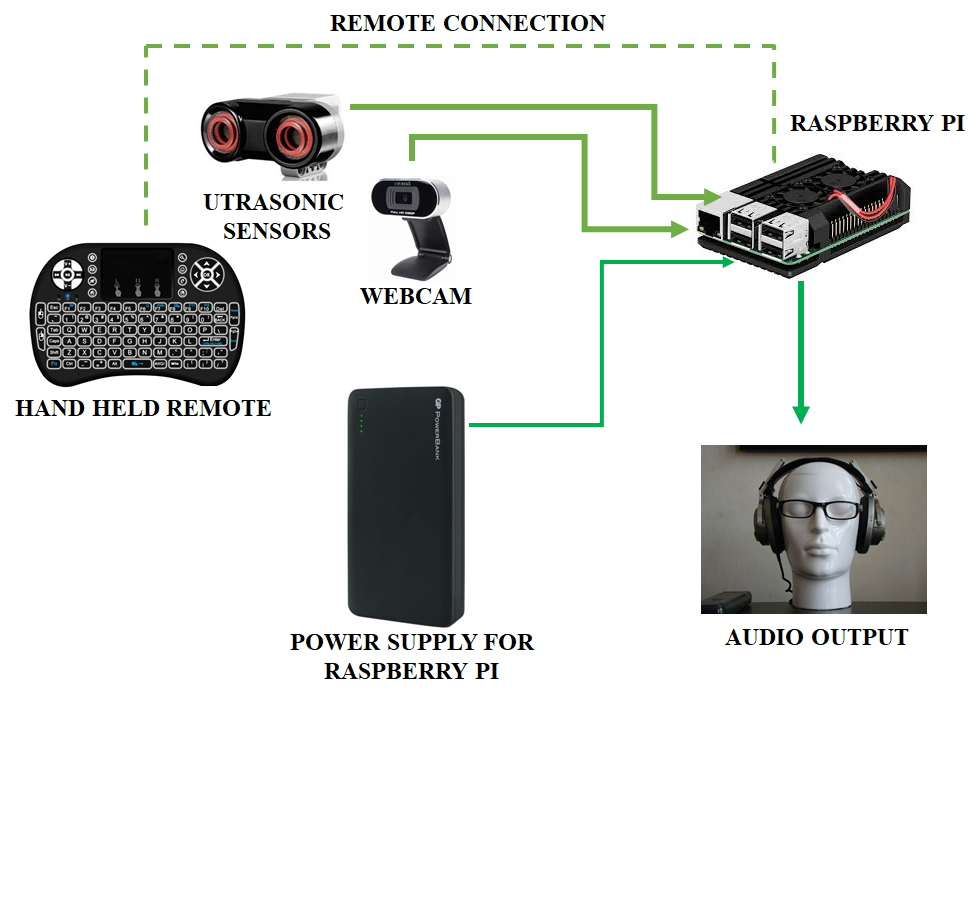
The typical Unix/Linux/POSIX-compliant installation includes the KornShell (ksh) in several possible versions such as ksh88, Korn Shell '93 and others. The oldest shell still in common use is the Bourne shell (sh); Unix systems invariably also include the C shell (csh), Bash (bash), a Remote Shell (rsh), a Secure Shell (ssh) for SSL telnet connections, and a shell which is a main component of the Tcl/Tk installation usually called tclsh; wish is a GUI-based Tcl/Tk shell. The C and Tcl shells have syntax quite similar to that of said programming languages, and the Korn shells and Bash are developments of the Bourne shell, which is based on the ALGOL language with elements of a number of others added as well. On the other hand, the various shells plus tools like awk, sed, grep, and BASIC, Lisp, C and so forth contributed to the Perl programming language.

Other shells available on a machine or available for download and/or purchase include Almquist shell (ash), PowerShell (msh), Z shell (zsh, a particularly common enhanced KornShell), the Tenex C Shell (tcsh), a Perl-like shell (psh). Related programs such as shells based on Python, Ruby, C, Java, Perl, Pascal, Rexx &c in various forms are also widely available. Another somewhat common shell is osh, whose manual page states it "is an enhanced, backward-compatible port of the standard command interpreter from Sixth Edition UNIX." Windows-Unix interoperability software such as the MKS Toolkit, Cygwin, UWIN, Interix and others make the above shells and Unix programming available on Windows systems, providing functionality all the way down to signals and other inter-process communication, system calls and APIs. Microsoft distributes Windows Services for UNIX for use with its NT-based operating systems in particular, which have a POSIX environmental subsystem.

**Chapter 4**

**SYSTEM DESIGN AND ANALYSIS**

**4.1 Preliminary Design**



**Fig. Design outline of the product**

The hand held remote is the remote that is held by the visually impaired user for providing the input for a certain feature to execute by the raspberry pi processor. The webcam and the ultrasonic sensors are mounted over the glasses which would be worn by the visually impaired user. The ultrasonic sensors are used to analyze the environment for the obstacles and alert the user when an object is too close to the user. The webcam is used too take images for the OCR and color detection features that are provided by the product. The power bank is used to power the raspberry pi processor. The raspberry pi processor is the central processing using where all the features processing occurs. The results of all the features are provided to the visually impaired person using the audio output which can be in the form of a headphones.

**4.2 System Architecture**

1. **Voice out the current date and time**

The smart vision system uses the datetime module to get the current date and time and it is stored into a text document. The text document that is generated is later given as an input to the gTTS (google text to speech module) which converts the text to speech and the speech output is stored into a .mp3 file and the .mp3 file is played out as the output to the visually impaired person using the speakers.

1. **Voice out the current location**

The smart vision system uses the ip address for knowing the current location, region and the country. The shell command curl ipinfo is used to get the current location, region and the country. The result is stored into a text document and the text document is given as an input to the gTTS which converts the text into .mp3 file. The .mp3 file is played back to the visually impaired person.

1. **Voice out the current temperature**

The smart vision system uses the OpenWeatherMap API to get the current temperature and the weather description for the day. The result is stored into a text document and this document is given to gTTS which converts the result into speech format. The speech result is then played to the visually impaired person.

1. **Voice out the new emails**

The smart vision system has the capability to read out the new emails arrived to the person’s email. The vision system uses the the imap module to connect the SMTP server over the SSL. Using already feed in user credentials we login to the mail server and get the unread messages and store it into a text file. Using gTTS the text file is converted into a speech format and the .mp3 file is played out to the visually impaired person.

1. **Voice out the top 10 headlines for the day**

The smart vision system uses the News API to get the top 10 news headlines for the day. The result is stored into a text document and the text document is given as an input to the gTTS. The gTTS converts it into the .mp3 file which is played to the visually impaired person.

1. **Voice the text content present in a picture**

The webcam is used to take a picture of the document or any text containing object. The picture is taken and tesseract ocr module is used to extract the text from the image and the extracted text is stored into a text document. The gTTS is used to convert the text to speech format. The speech is then played back to the visually impaired person.

**7. Voice out the dominant color in a picture.**

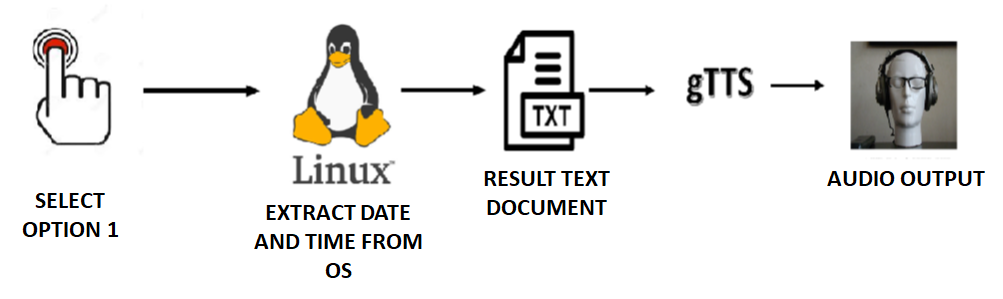
For the dominant color feature an image is captured form the webcam and this image is given to the python code which detects the dominant color in the image. The result is stored into a text document and this text document is given as an input to the gTTS program which converts the text results into a .mp3 file which is played to the visually impaired person via the audio output device which here is headphones.

**8. Obstacle detection**

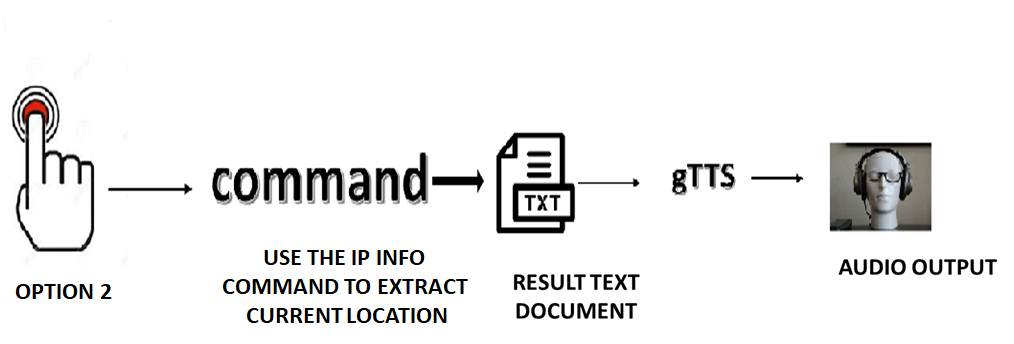
The ultrasonic sensors are used to analyze the environment for the obstacles and alert the user when an object is too close to the user.

**SYSTEM ARCHITECTURE FOR EACH FEATURE**

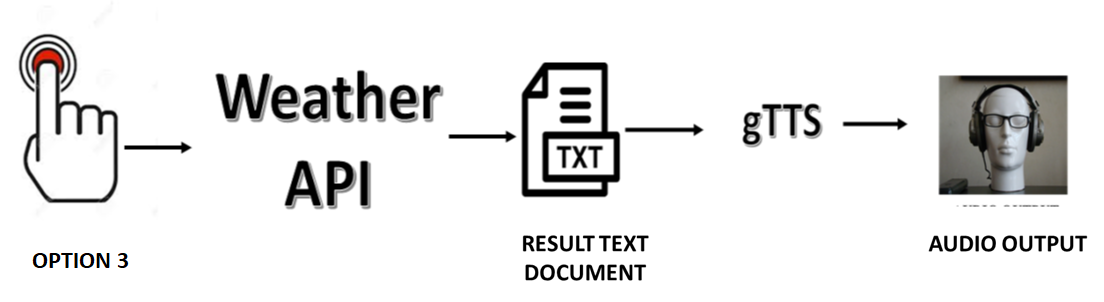
1. Option 1: Voice out the current date and time

****

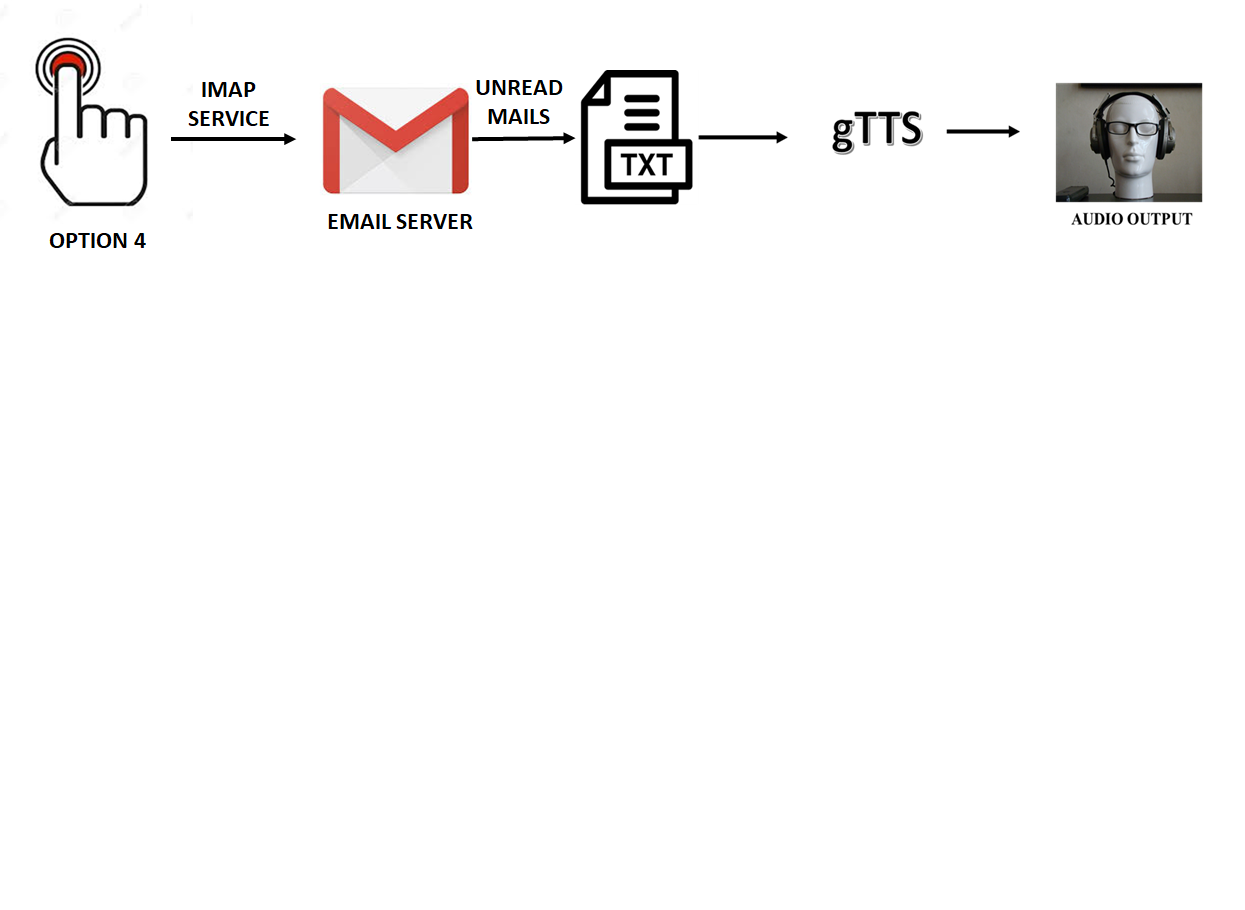
1. Option 2: Voice out the current location



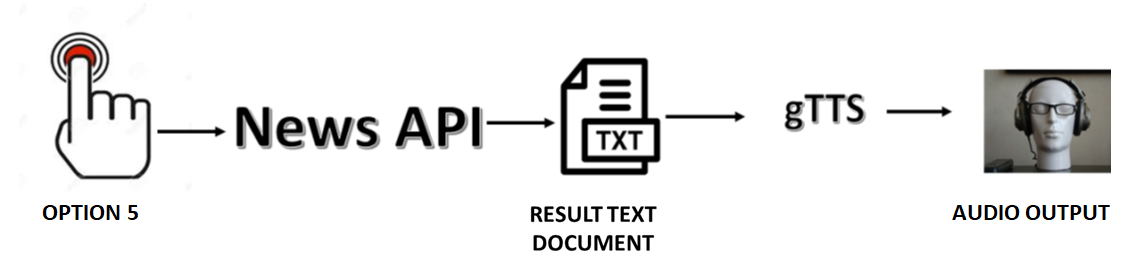
1. Option 3: Voice out the current weather



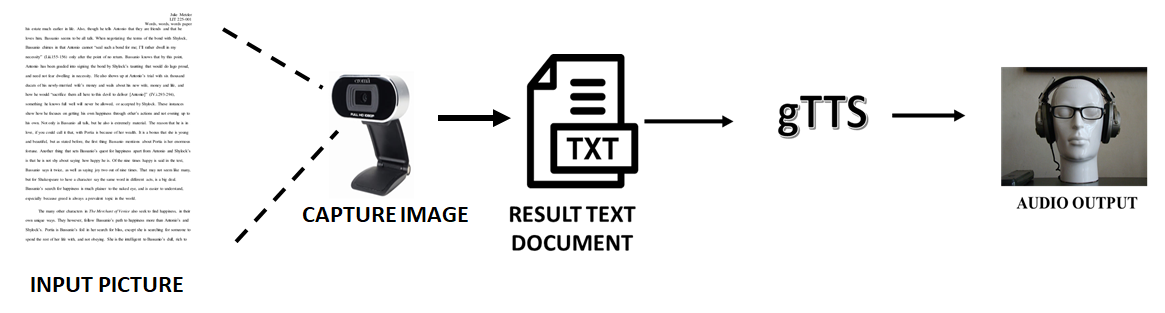
1. Option 4: Voice out the unread emails



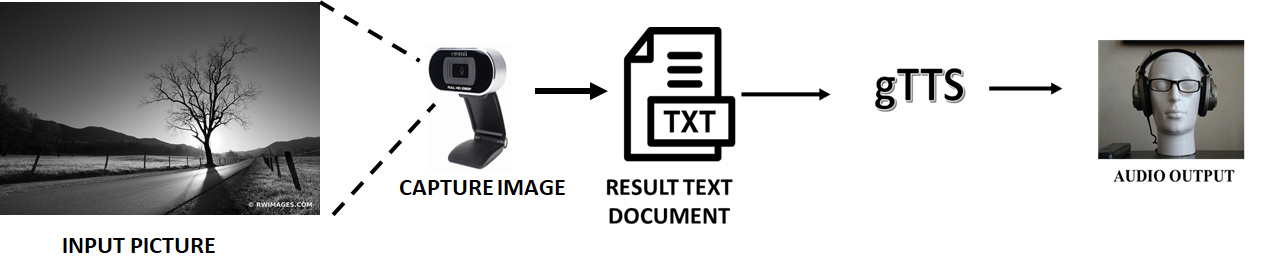
1. Option 5: Voice out the top 10 news headlines



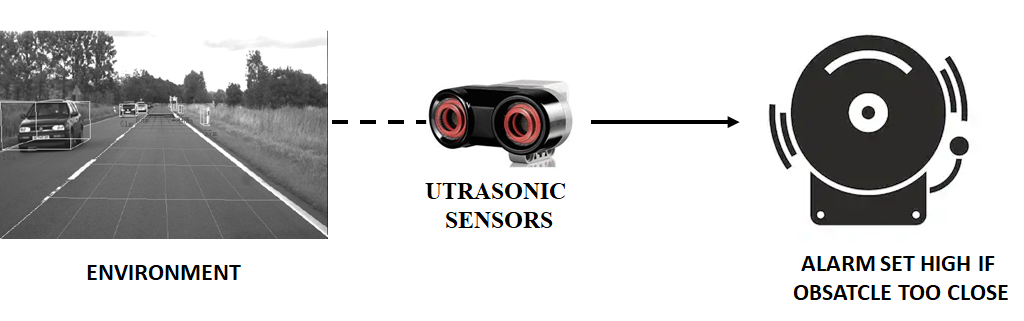
1. Option 6: Voice out the text in an image



1. Option 7 : Voice out the dominant color in an image



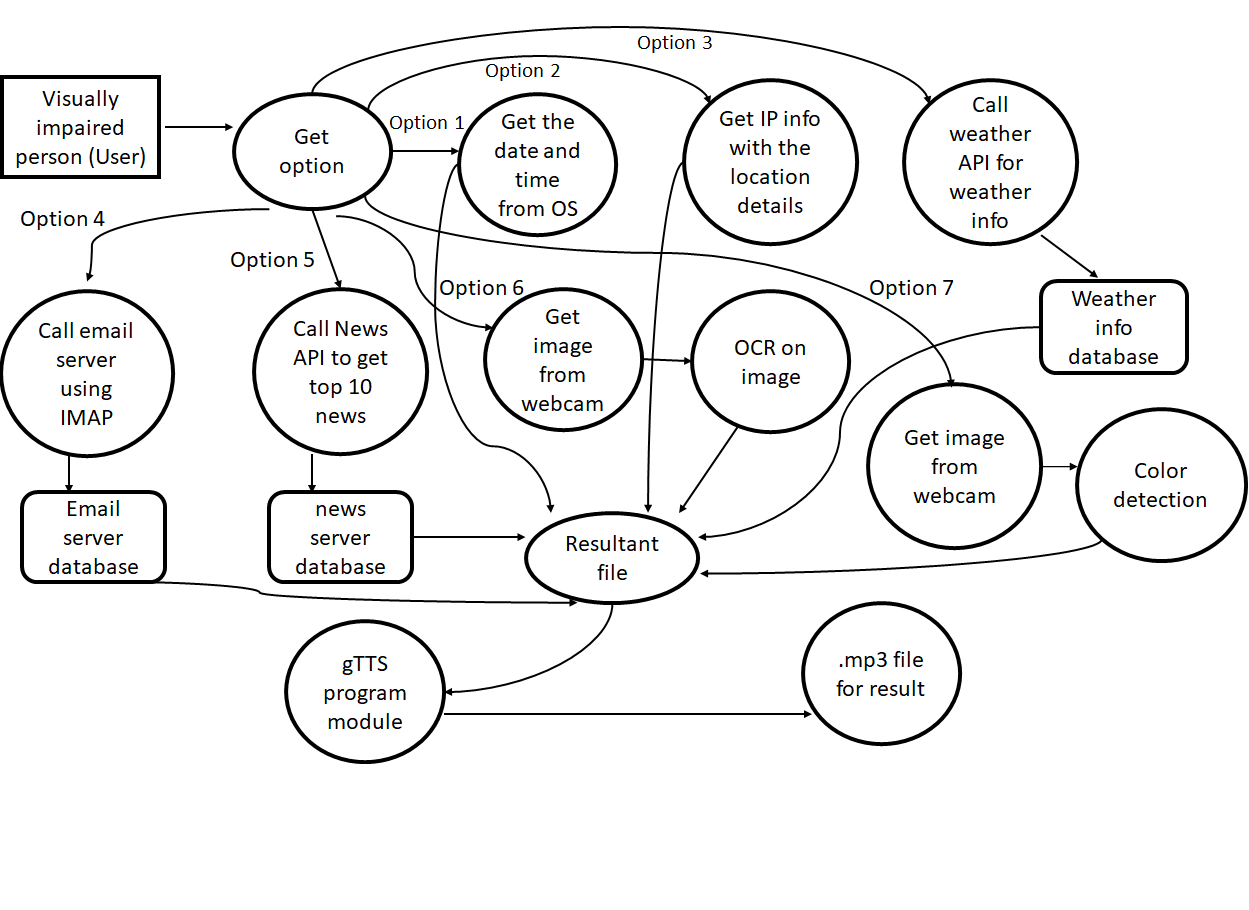
1. Obstacle detection



**4.3 Data Flow Diagram**

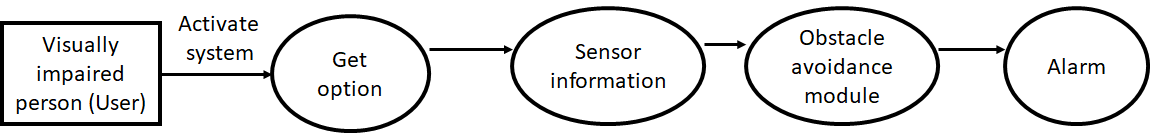
**4.3.1 System DFD**

This diagram represents the entire systems flow of data and how each module communicates with the other. The data flow diagram for the smart glasses for the visually impaired people starts by taking the input option from the remote keypad and then the particular feature is processed by the raspberry pi processor. The data flow diagram for the developed project is as shown below:

**Fig: DFD design 1**

The above diagram shows the data flow diagram for the features voice out the current data and time, voice out the current weather information, voice out the current location, voice out the unread emails, voice out the top 10 news headlines, voice out the text in an image and voice out the dominant color In the image.

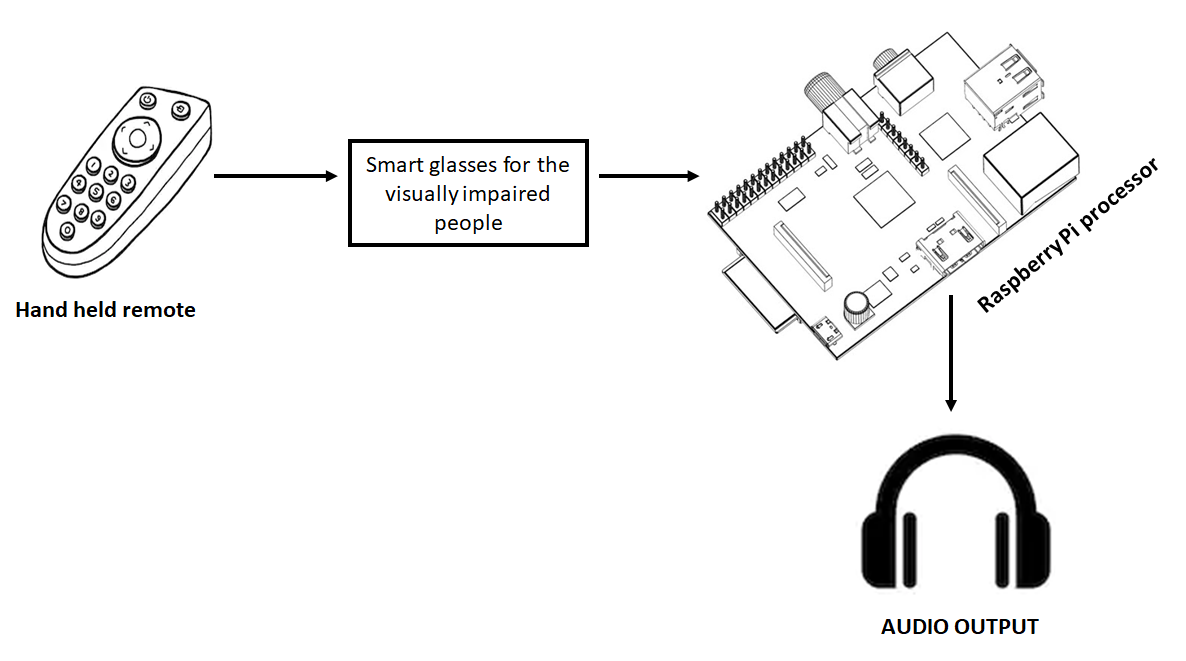
The data flow diagram for the obstacle avoidance is as shown below:



**Fig: DFD design 2**

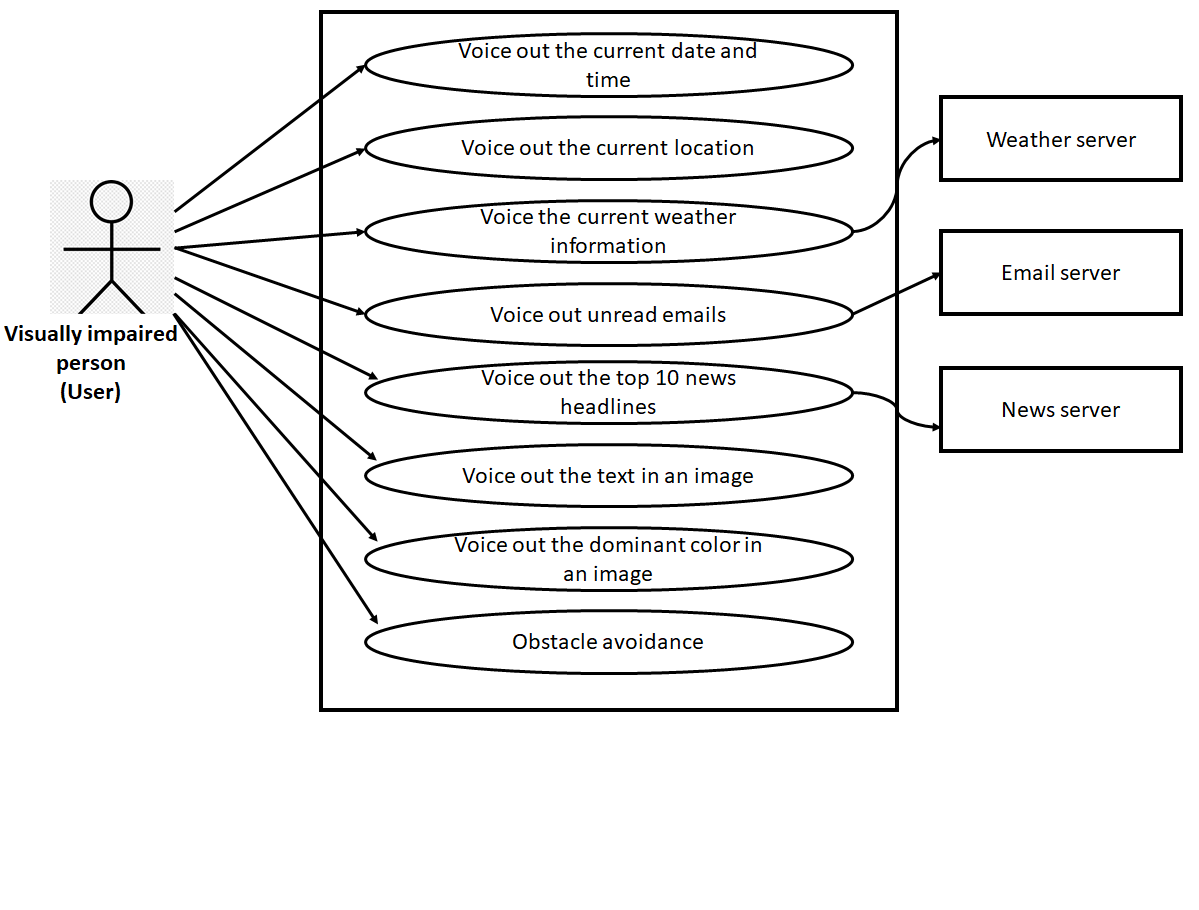
**4.3.2 Input DFD**

The input DFD depicts the ways the app accepts input from the user to carry out the execution of various features in the product. The only input that is required from the visually impaired person or the user of the product is the press of the button in the hand held remote which corresponds to a particular feature. Each and every button on the hand held remote corresponds to different feature. When a particular button is pressed the corresponding feature is executed by the raspberry pi and the output or the result of the execution is given out in the form an audio output which is heard by the visually impaired person through the audio output device.

****

**4.4 Use Case Diagram**

In the following diagram, various use cases of “Smart glasses for the visually impaired people” is depicted. The first use case of the system is voicing out the current date and the time for the user. The second use case is voicing out the current location to the user. The third use case of the system is voicing out the current weather information for the user. The fifth use case of the system is voicing out the unread emails to the user. The sixth use case is to voice out the top ten news headlines for the day. The seventh use case of the system is to voice out the text in a image using OCR. The eighth use case of the system is to voice out the dominant color in an image. The ninth use case of the system is providing the obstacle avoidance system using the sensors.



**Fig: Use case diagram of the system**

**Chapter 5**

**Implementation**

**5.1 Different Modules of the project**

The various modules present in the project along with the code implemented for the particular feature are given below:

1. **Date and time module**

import time

import os

import pytesseract

import pyttsx3

from PIL import Image

from googletrans import Translator

from gtts import gTTS

from playsound import playsound

from datetime import datetime

from datetime import date

from datetime import date

f = open("/home/pi/Desktop/final\_year\_project/date\_and\_time/date\_time\_text.txt",'w')

today = date.today()

d2 = today.strftime("%B %d, %Y")

print("d2 =", d2)

f.write("Today's date is : ")

f.write(d2)

f.write("\n")

t = time.localtime()

current\_time = time.strftime("%H:%M:%S",t)

print(current\_time)

f.write("Current time is : ")

f.write(current\_time)

f.write("\n")

print("Have a nice day")

f.write("Have a nice day")

f.close()

1. **Current location module**

#!/usr/bash

rm /home/pi/Desktop/final\_year\_project/current\_location/location.txt

printf "current city is : " >> /home/pi/Desktop/final\_year\_project/current\_location/location.txt

curl ipinfo.io/city >> /home/pi/Desktop/final\_year\_project/current\_location/location.txt

printf "\n"

printf "current region is : " >> /home/pi/Desktop/final\_year\_project/current\_location/location.txt

curl ipinfo.io/region >> /home/pi/Desktop/final\_year\_project/current\_location/location.txt

printf "\n"

printf "Current country is : " >> /home/pi/Desktop/final\_year\_project/current\_location/location.txt

curl ipinfo.io/country >> /home/pi/Desktop/final\_year\_project/current\_location/location.txt

printf "\n"

echo "Program complete ,done" >> /home/pi/Desktop/final\_year\_project/current\_location/location.txt

1. **Current weather information**

import requests, json

api\_key = "f28e654cf78a932a10e58b89e87bb4aa"

base\_url = "http://api.openweathermap.org/data/2.5/weather?"

city\_name = "Bangalore"

complete\_url = base\_url + "appid=" + api\_key + "&q=" + city\_name

response = requests.get(complete\_url)

x = response.json()

if x["cod"] != "404":

y = x["main"]

current\_temperature = y["temp"]

current\_pressure = y["pressure"]

current\_humidiy = y["humidity"]

z = x["weather"]

weather\_description = z[0]["description"]

# print following values

print(" Temperature (in kelvin unit) = " +

str(current\_temperature) +

"\n atmospheric pressure (in hPa unit) = " +

str(current\_pressure) +

"\n humidity (in percentage) = " +

str(current\_humidiy) +

"\n description = " +

str(weather\_description))

f = open("/home/pi/Desktop/final\_year\_project/weather/weather\_text.txt","w")

f.write("Today's temperature : "+str(current\_temperature))

f.write("\nHumidity : "+str(current\_humidiy))

f.write("\nDescription : "+str(weather\_description))

f.write("\nProgram complete ,done")

f.close()

else:

print(" City Not Found ")

1. **Unread emails module**

import email

import imaplib

import os

mail = imaplib.IMAP4\_SSL('imap.gmail.com')

(retcode, capabilities) = mail.login('wingsoffirew@gmail.com','wingswings')

mail.list()

mail.select('inbox')

n=0

(retcode, messages) = mail.search(None, '(UNSEEN)')

if retcode == 'OK':

for num in messages[0].split() :

os.remove('/home/pi/Desktop/final\_year\_project/email/emailemail\_text.txt')

print ('Processing ')

n=n+1

typ, data = mail.fetch(num,'(RFC822)')

for response\_part in data:

if isinstance(response\_part, tuple):

original = email.message\_from\_bytes(response\_part[1])

# print (original['From'])

# print (original['Subject'])

raw\_email = data[0][1]

raw\_email\_string = raw\_email.decode('utf-8')

email\_message = email.message\_from\_string(raw\_email\_string)

for part in email\_message.walk():

if (part.get\_content\_type() == "text/plain"): # ignore attachments/html

body = part.get\_payload(decode=True)

#save\_string = str(r"/home/pi/Desktop/final\_year\_project/email" + str('email\_text') + ".txt" )

save\_string='/home/pi/Desktop/final\_year\_project/email/emailemail\_text.txt'

myfile = open(save\_string, 'a')

myfile.write("email from : ")

myfile.write(original['From']+'\n')

myfile.write("email subject: ")

myfile.write(original['Subject']+'\n')

myfile.write("email is :\n ")

myfile.write(body.decode('utf-8')+"\n Program complete, done")

myfile.close()

else:

continue

typ, data = mail.store(num,'+FLAGS','\\Seen')

print (n)

if(n==0):

#os.remove('/home/pi/Desktop/final\_year\_project/email/emailemail\_text.txt')

save\_string='/home/pi/Desktop/final\_year\_project/email/emailemail\_text.txt'

myfile = open(save\_string, 'w')

myfile.write("No new emails arrived,done")

myfile.close()

print("No new emails arrived")

1. **Top 10 news headlines module**

import requests

import os

from gtts import gTTS

import time

def NewsFromBBC():

# BBC news api

main\_url = " https://newsapi.org/v1/articles?source=bbc-news&sortBy=top&apiKey=dc8e4f0486b84d01bf7c18d5d8f06e72"

# fetching data in json format

open\_bbc\_page = requests.get(main\_url).json()

# getting all articles in a string article

article = open\_bbc\_page["articles"]

# empty list which will

# contain all trending news

results = []

for ar in article:

results.append(ar["title"])

f= open("/home/pi/Desktop/final\_year\_project/news\_headlines/news\_text.txt","w+")

for i in range(len(results)):

# printing all trending news

s = "headline "+str(i + 1)+": "+ results[i]

print(s)

f.write(s+"\n")

time.sleep(1)

f.write("Program complete, complete \n")

f.close()

# Driver Code

if \_\_name\_\_ == '\_\_main\_\_':

# function call

NewsFromBBC()

1. **OCR module**

import cv2

import pytesseract

import os

try:

f = open("//home//pi//Desktop//final\_year\_project//ocr//saved\_img.jpg")

f2 = open("//home//pi//Desktop//final\_year\_project//ocr//saved\_img-final.jpg")

f3 = open("//home//pi//Desktop//final\_year\_project//ocr//ocr\_text.txt")

# Do something with the file

print("file exists")

os.remove("//home//pi//Desktop//final\_year\_project//ocr//saved\_img.jpg")

os.remove("//home//pi//Desktop//final\_year\_project//ocr//saved\_img-final.jpg")

os.remove("//home//pi//Desktop//final\_year\_project//ocr//ocr\_text.txt")

#os.remove("ocr\_voice.mp3")

except IOError:

print("Files no found")

finally:

print("complete")

key = cv2. waitKey(1)

webcam = cv2.VideoCapture(0)

while True:

try:

check, frame = webcam.read()

print(check) #prints true as long as the webcam is running

print(frame) #prints matrix values of each framecd

cv2.imshow("Capturing", frame)

key = cv2.waitKey(1)

if key == ord('s'):

cv2.imwrite(filename='//home//pi//Desktop//final\_year\_project//ocr//saved\_img.jpg', img=frame)

webcam.release()

img\_new = cv2.imread('//home//pi//Desktop//final\_year\_project//ocr//saved\_img.jpg', cv2.IMREAD\_GRAYSCALE)

img\_new = cv2.imshow("Captured Image", img\_new)

cv2.waitKey(1650)

cv2.destroyAllWindows()

print("Processing image...")

img\_ = cv2.imread('//home//pi//Desktop//final\_year\_project//ocr//saved\_img.jpg', cv2.IMREAD\_ANYCOLOR)

print("Converting RGB image to grayscale...")

gray = cv2.cvtColor(img\_, cv2.COLOR\_BGR2GRAY)

print("Converted RGB image to grayscale...")

print("Resizing image to 28x28 scale...")

img\_ = cv2.resize(gray,(999,999))

print("Resized...")

img\_resized = cv2.imwrite(filename='//home//pi//Desktop//final\_year\_project//ocr//saved\_img-final.jpg', img=img\_)

print("Image saved!")

print("Hello we are printing here")

text = pytesseract.image\_to\_string('//home//pi//Desktop//final\_year\_project//ocr//saved\_img.jpg').encode('utf-8').strip()

print(text)

text\_file = open("//home//pi//Desktop//final\_year\_project//ocr//ocr\_text.txt","w")

n = text\_file.write(text)

text\_file.write("Program complete, complete")

text\_file.close()

#execfile('he4.py')

break

elif key == ord('q'):

print("Turning off camera.")

webcam.release()

print("Camera off.")

print("Program ended.")

cv2.destroyAllWindows()

break

except(KeyboardInterrupt):

print("Turning off camera.")

webcam.release()

print("Camera off.")

print("Program ended.")

cv2.destroyAllWindows()

break

1. **Dominant color feature**

from colorthief import ColorThief

import numpy as np

from scipy import spatial

color\_thief = ColorThief('/home/pi/Desktop/final\_year\_project/color/img.jpg')

# get the dominant color

dominant\_color = color\_thief.get\_color(quality=1)

palette = color\_thief.get\_palette(color\_count=6)

a = dominant\_color[0]

b = dominant\_color[1]

c = dominant\_color[2]

print(a)

print(b)

print(c)

#!/usr/bin/env python

# rgb2colorname.py

# by wilsonmar@gmail.com, ayush.original@gmail.com, https://github.com/paarthneekhara

# Usage: python rgb2colorname.py

# To ensure this program has no external dependencies,

# an array and dictionary is used in place of I/O from input reference files.

# Explained in https://github.com/jetbloom/rgb2colorname/blob/master/README.md

# import Algorithmia

# TODO: define function for use in Algorithmia.com or other API:

#def find\_nearest\_vector(array, value):

# # http://docs.scipy.org/doc/numpy/reference/generated/numpy.linalg.norm.html

# idx = np.array([np.linalg.norm(x+y) for (x,y,z) in array-value]).argmin()

# return array[idx]

# NO import importlib & import\_module('rgbcsv2rgbarray.py.txt') to avoid external dependencies.

#moduleName='rgbcsv2rgbarray.py.txt'

# mport\_module(moduleName)

#### Paste in contents of rgb\_combined\_v01.csv.txt below: ###

# 2016-08-31-07:53 (local time) rgbcsv2rgbarray.py START: outrowcount=570.

RGB = np.array([ \

[0,0,0] \

,[0,0,128] \

,[0,0,139] \

,[0,0,139] \

,[0,0,205] \

,[0,0,205] \

,[0,0,238] \

,[0,0,255] \

,[0,0,255] \

,[0,100,0] \

,[0,104,139] \

,[0,128,0] \

,[0,128,0] \

,[0,128,128] \

,[0,134,139] \

,[0,139,0] \

,[0,139,69] \

,[0,139,139] \

### End of paste ###

# Dictionary of colornames indexed by key \_Hex:

# See https://bdhacker.wordpress.com/2010/02/27/python-tutorial-dictionaries-key-value-pair-maps-basics/

HexNameDict = { \

,"#006400":"DarkGreen" \

,"#00688B":"DeepSkyBlue4" \

,"#008000":"WebGreen" \

,"#008000":"green" \

,"#008080":"teal" \

,"#00868B":"turquoise4" \

,"#008B00":"green4" \

,"#FFFFFF":"white" \

,"#FFFFFF":"gray100" \

}

# TODO: Test calls using variety of RGB input values

# TODO: Change to call argument with the point to find

# pt = [221,183,134] # approximate to

#pt = [0,0,0] # example needing zerofill

pt = [a,b,c] # = "burlywood","#DEB887"]

# pt = [222,184,135] # = "burlywood","#DEB887"]

# pt = [154,205,50] # = OliveDrab

# Lookup color name using Hex:ColorName dictionary:

NearestRGB = (RGB[spatial.KDTree(RGB).query(pt)[1]])

# TODO: Calculate Hex from pt. (upper case letters)

# Instead of str(hex(pt[0])[2:]) in Python2, this is Python3 compatible:

s = '#' \

+ format(NearestRGB[0],'x').zfill(2) \

+ format(NearestRGB[1],'x').zfill(2) \

+ format(NearestRGB[2],'x').zfill(2)

ColorHex = s.upper() # "#8B7355" # "#8B7355"

ColorDiff = \

'('+'{0:+d}'.format(NearestRGB[0]-pt[0]) \

+','+'{0:+d}'.format(NearestRGB[1]-pt[1]) \

+','+'{0:+d}'.format(NearestRGB[2]-pt[2]) \

+')'

try: ## TODO: try catch block per https://wiki.python.org/moin/HandlingExceptions

ColorName=HexNameDict[ColorHex]

except:

ColorName="not found"

print ('Nearest color name to input RGB ' \

+ str(pt) \

+ ' is "'+ ColorName +'"' \

+' '+ ColorHex \

+' '+ str(NearestRGB) \

+', '+ ColorDiff \

+'.')

f = open('/home/pi/Desktop/final\_year\_project/color/color\_text.txt',"w")

f.write("Dominant color in the image is : \n")

f.write(ColorName)

f.close()

1. **Shell script – Controller program**

#!/usr/bash

play /home/pi/Desktop/final\_year\_project/extravoices/welcome\_speech.mp3

while $1

do

sleep 1

echo "Please enter your option"

play /home/pi/Desktop/final\_year\_project/extravoices/get\_option.mp3

read option

case ${option} in

1) echo "option 1 choosen : funtion date and time"

play /home/pi/Desktop/final\_year\_project/extravoices/option1.mp3

python3 /home/pi/Desktop/final\_year\_project/date\_and\_time/date\_time.py &&

python3 /home/pi/Desktop/final\_year\_project/date\_and\_time/date\_time\_gtts.py &&

play /home/pi/Desktop/final\_year\_project/date\_and\_time/date\_time\_voice.mp3 &&

play /home/pi/Desktop/final\_year\_project/extravoices/program\_complete.mp3

sleep 1.5

;;

2) echo "option 2 choosen : function current location"

play /home/pi/Desktop/final\_year\_project/extravoices/option2.mp3

sh /home/pi/Desktop/final\_year\_project/current\_location/current\_loc.sh &&

python3 /home/pi/Desktop/final\_year\_project/current\_location/location\_gtts.py &&

play /home/pi/Desktop/final\_year\_project/current\_location/cur\_loc.mp3 &&

play /home/pi/Desktop/final\_year\_project/extravoices/program\_complete.mp3

sleep 1.5

;;

7) echo "option 7 choosen : function current weather"

play /home/pi/Desktop/final\_year\_project/extravoices/temperature.mp3

python3 /home/pi/Desktop/final\_year\_project/weather/weather\_code.py &&

python3 /home/pi/Desktop/final\_year\_project/weather/weather\_gtts.py &&

play /home/pi/Desktop/final\_year\_project/weather/weather\_voice.mp3 &&

play /home/pi/Desktop/final\_year\_project/extravoices/program\_complete.mp3

sleep 1.5

;;

3) echo "option 3 choosen : function email reading"

play /home/pi/Desktop/final\_year\_project/extravoices/option3.mp3

python3 /home/pi/Desktop/final\_year\_project/email/email\_code.py &&

python3 /home/pi/Desktop/final\_year\_project/email/email\_gtts.py &&

play /home/pi/Desktop/final\_year\_project/email/email\_voice.mp3 &&

play /home/pi/Desktop/final\_year\_project/extravoices/program\_complete.mp3

sleep 1.5

;;

4) echo "option 4 choosen : newsheadlines"

play /home/pi/Desktop/final\_year\_project/extravoices/option4.mp3

python3 /home/pi/Desktop/final\_year\_project/news\_headlines/news.py &&

python3 /home/pi/Desktop/final\_year\_project/news\_headlines/news\_gtts.py &&

play /home/pi/Desktop/final\_year\_project/news\_headlines/news\_voice.mp3 &&

play /home/pi/Desktop/final\_year\_project/extravoices/program\_complete.mp3

sleep 1.5

;;

5) echo "option 5 choosen : ocr"

play /home/pi/Desktop/final\_year\_project/extravoices/option5.mp3

python /home/pi/Desktop/final\_year\_project/ocr/ocr\_img\_to\_text.py &&

python3 /home/pi/Desktop/final\_year\_project/ocr/ocr\_gtts.py &&

play /home/pi/Desktop/final\_year\_project/ocr/ocr\_voice.mp3 &&

play /home/pi/Desktop/final\_year\_project/extravoices/program\_complete.mp3

sleep 1.5

;;

6) play /home/pi/Desktop/final\_year\_project/extravoices/help\_welcome.mp3

play /home/pi/Desktop/final\_year\_project/extravoices/help\_info.mp3

play /home/pi/Desktop/final\_year\_project/extravoices/help\_again.mp3

sleep 1.5

;;

8) play /home/pi/Desktop/final\_year\_project/extravoices/color\_welcome.mp3

python /home/pi/Desktop/final\_year\_project/color/capture\_image.py

play /home/pi/Desktop/final\_year\_project/extravoices/color2.mp3

python3 /home/pi/Desktop/final\_year\_project/color/color\_detect.py

python3 /home/pi/Desktop/final\_year\_project/color/color\_gtts.py

play /home/pi/Desktop/final\_year\_project/color/color\_voice.mp3

sleep 1.5

;;

9) echo "Program complete"

play /home/pi/Desktop/final\_year\_project/extravoices/exit.mp3

exit 1

;;

\*) echo "improper button please choosen again"

play /home/pi/Desktop/final\_year\_project/extravoices/improper\_button.mp3

sleep 1.5

;;

esac

done

1. **gTTS module**

from gtts import gTTS

import os

file = open("//home//pi//Desktop//final\_year\_project//color//color\_text.txt","r").read().replace("\n"," ")

speech = gTTS(text = str(file),lang = 'en',slow = False)

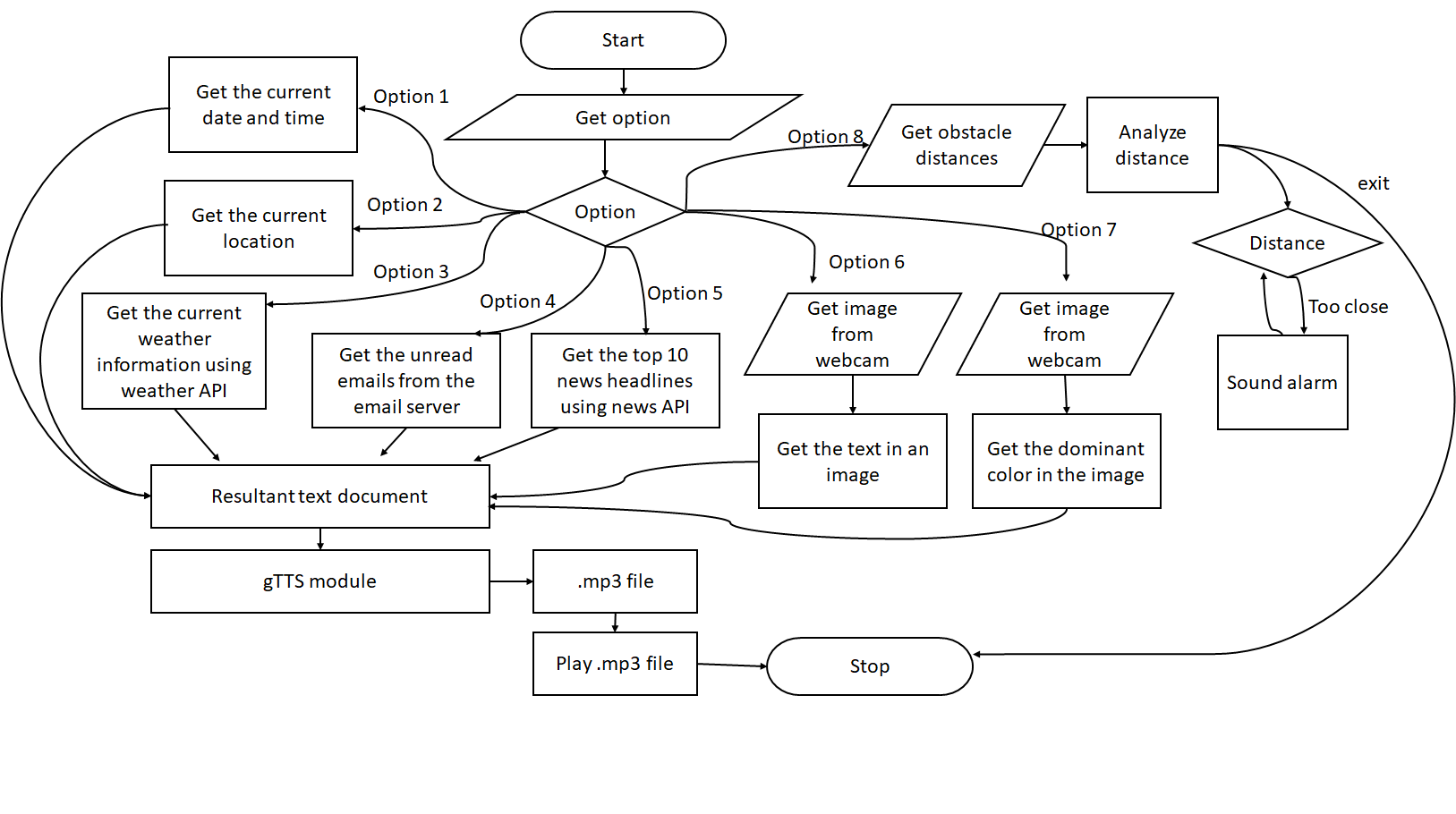
speech.save("//home//pi//Desktop//final\_year\_project//color//color\_voice.mp3")

**5.2 Dependencies**

The various dependencies for the opencv library used for implementing system is shown below:

* sudo apt install build-essential cmake git pkg-config libgtk-3-dev "libcanberra-gtk\*"
* sudo apt install libavcodec-dev libavformat-dev libswscale-dev libv4l-dev libxvidcore-dev libx264-dev
* sudo apt install libjpeg-dev libpng-dev libtiff-dev gfortran openexr libatlas-base-dev opencl-headers
* sudo apt install python3-dev python3-numpy libtbb2 libtbb-dev libdc1394-22-d

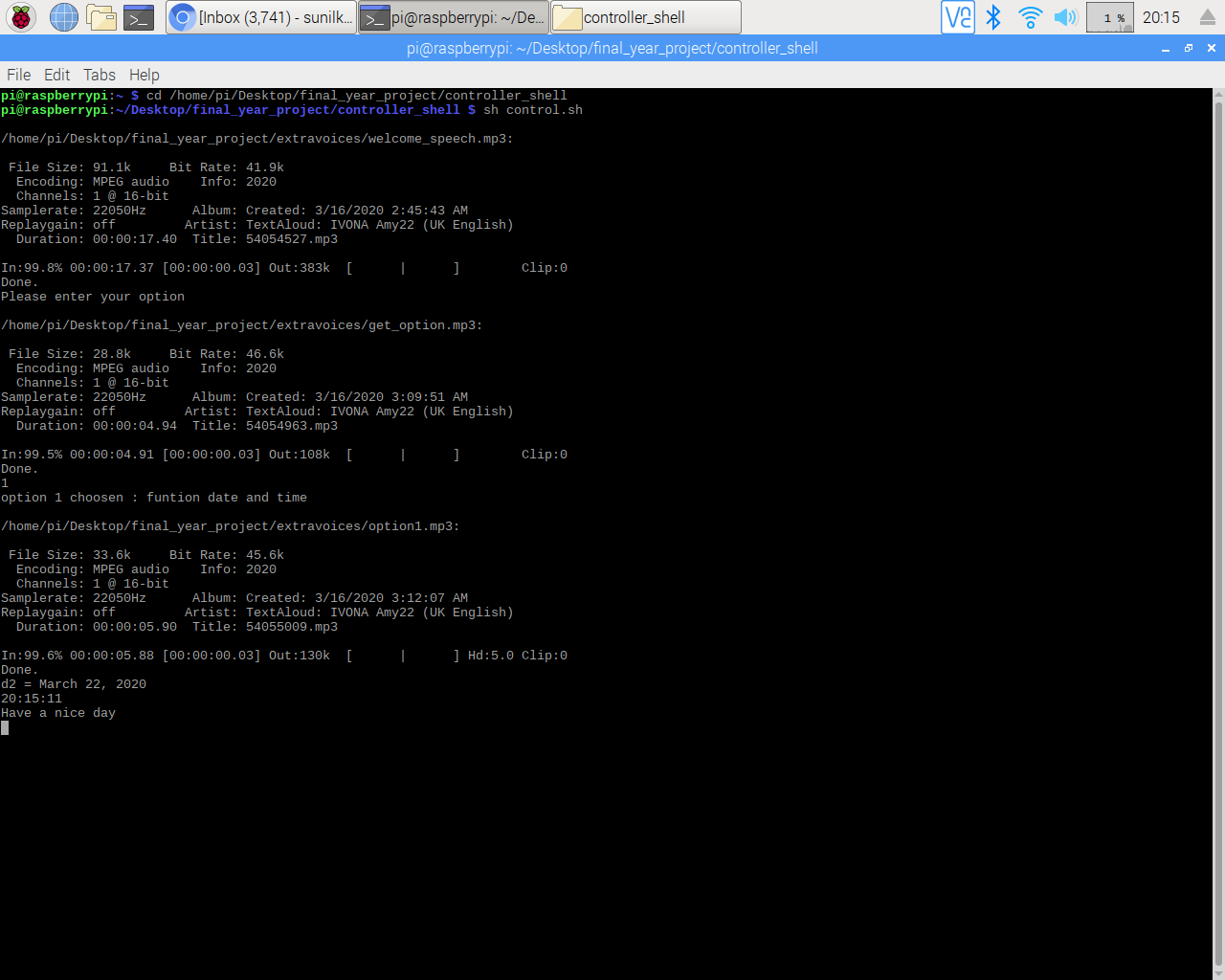
**5.3 Flow Chart of Proposed system**

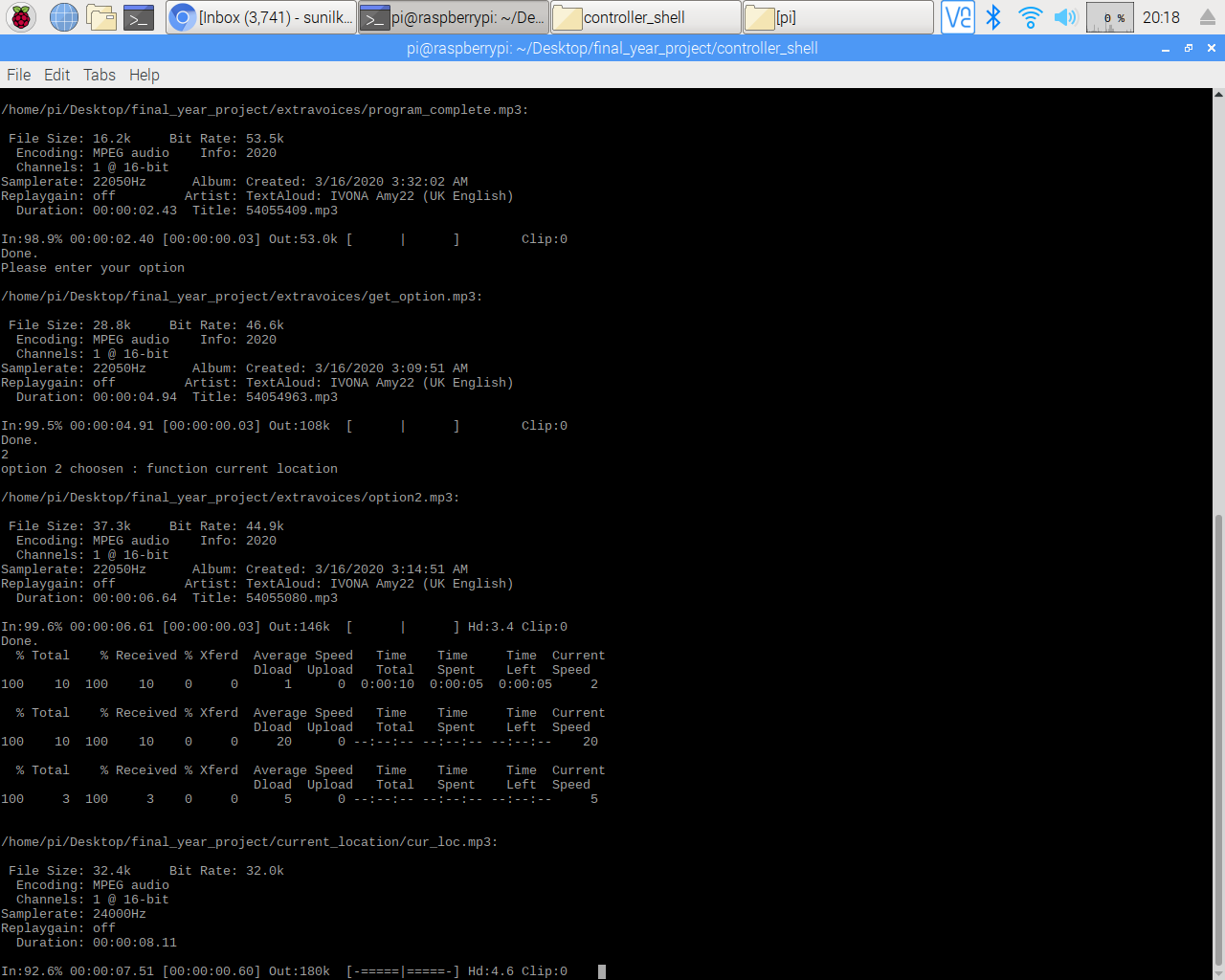


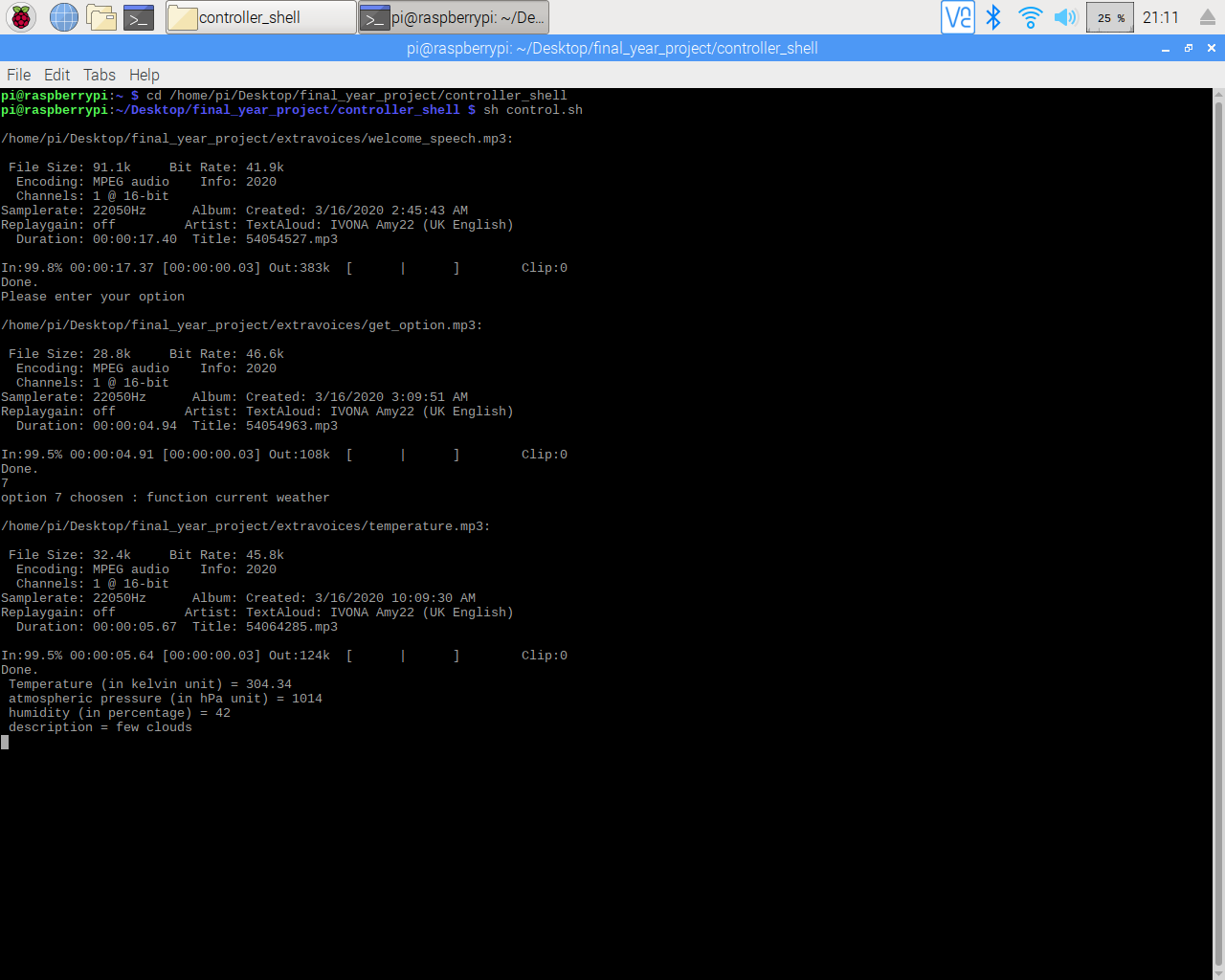
**Chapter 6**

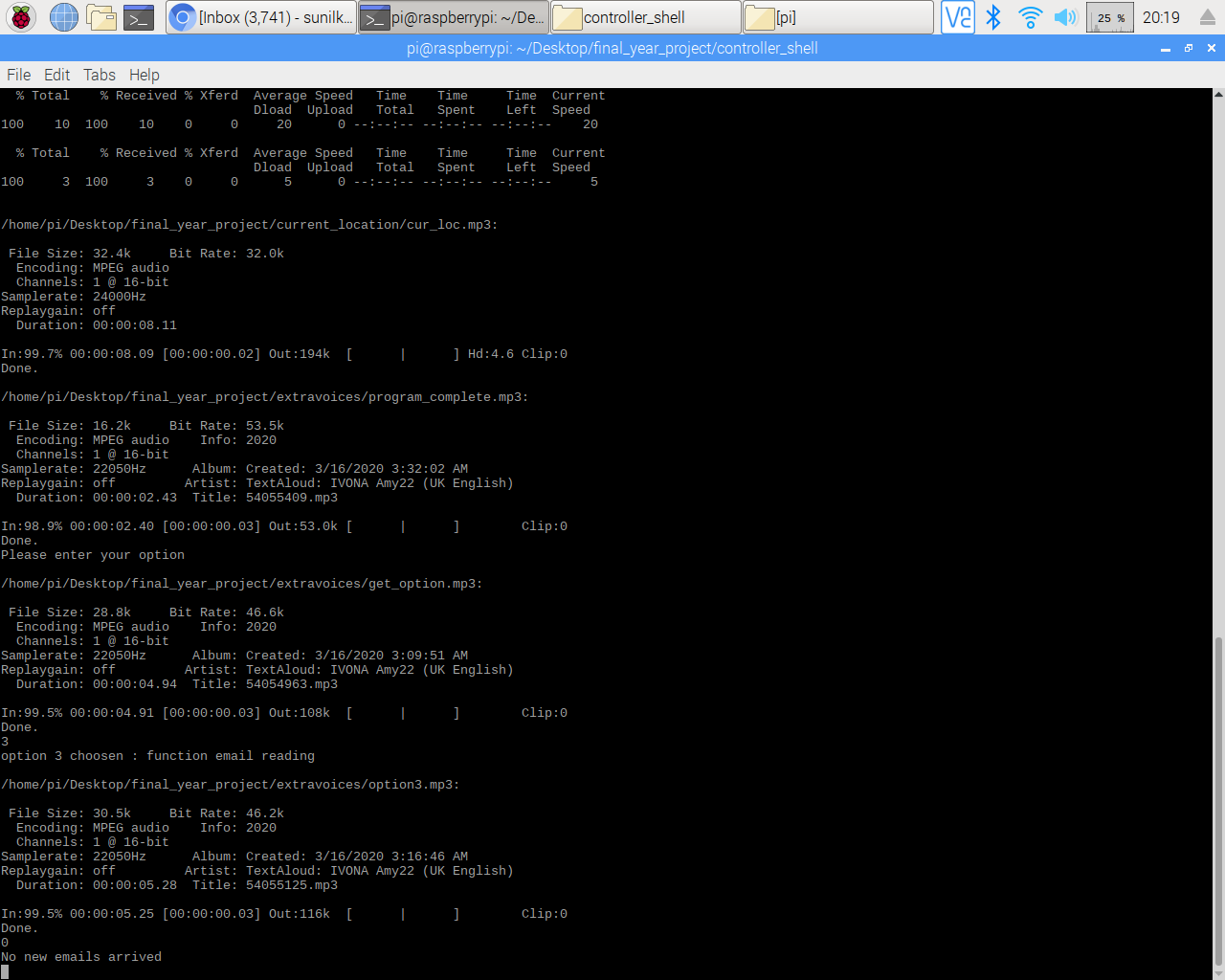
**Experimental Results**

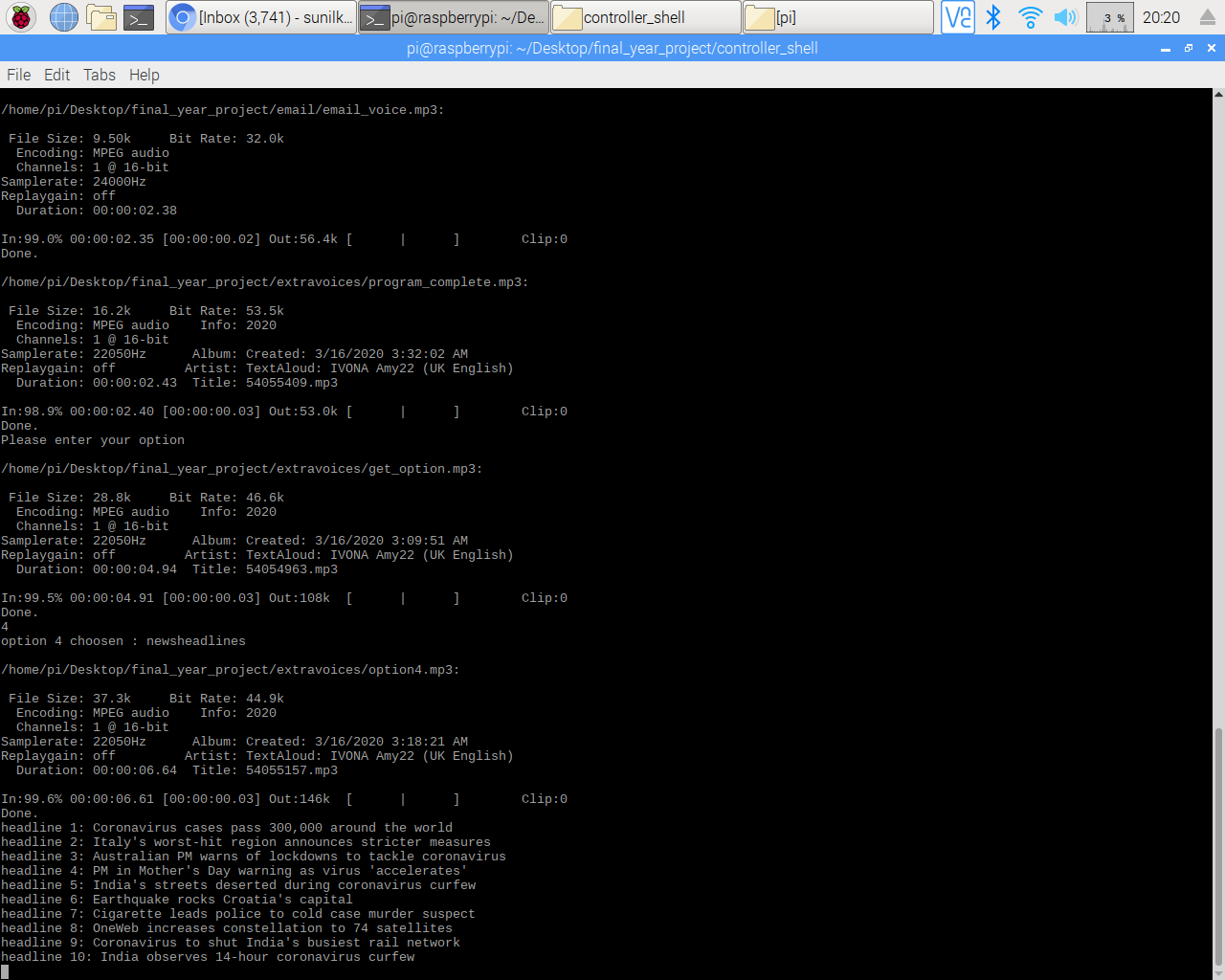
**6.1 Outcome of Proposed System**



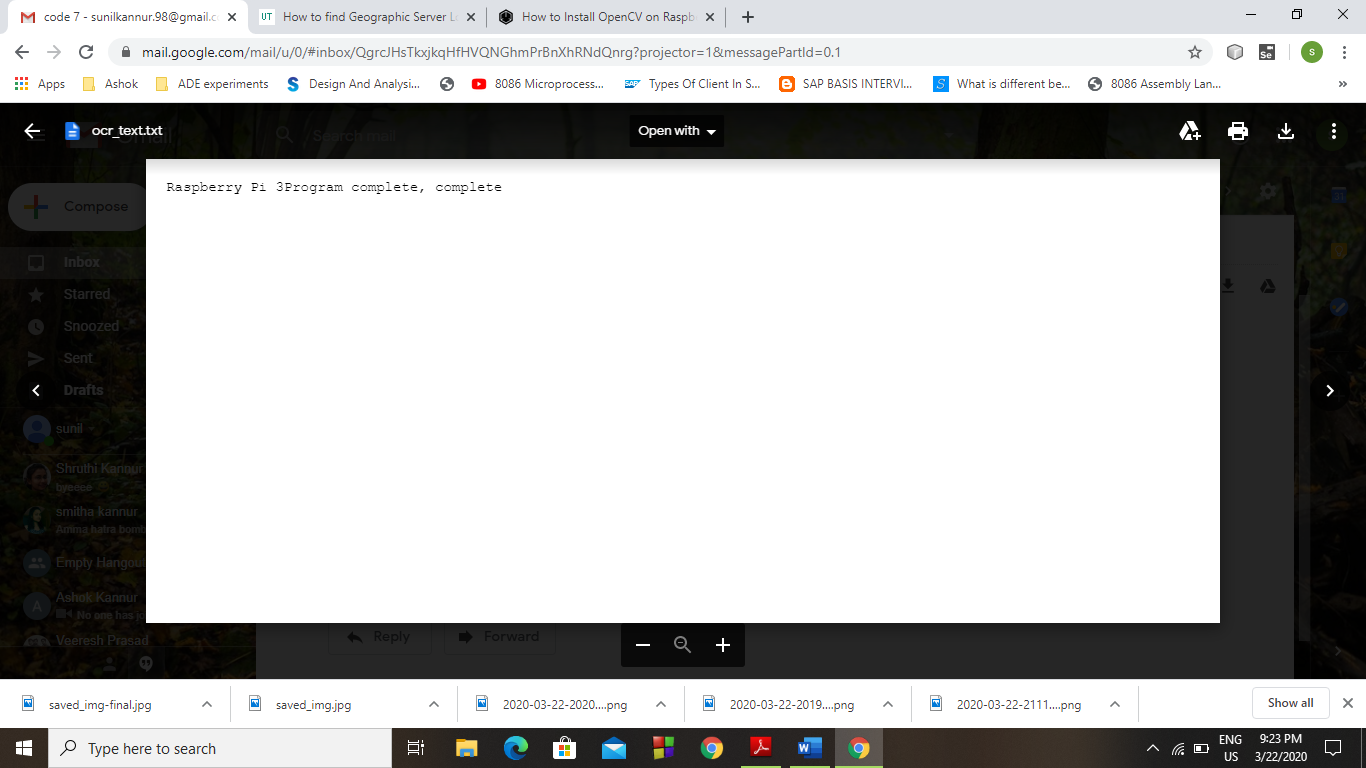




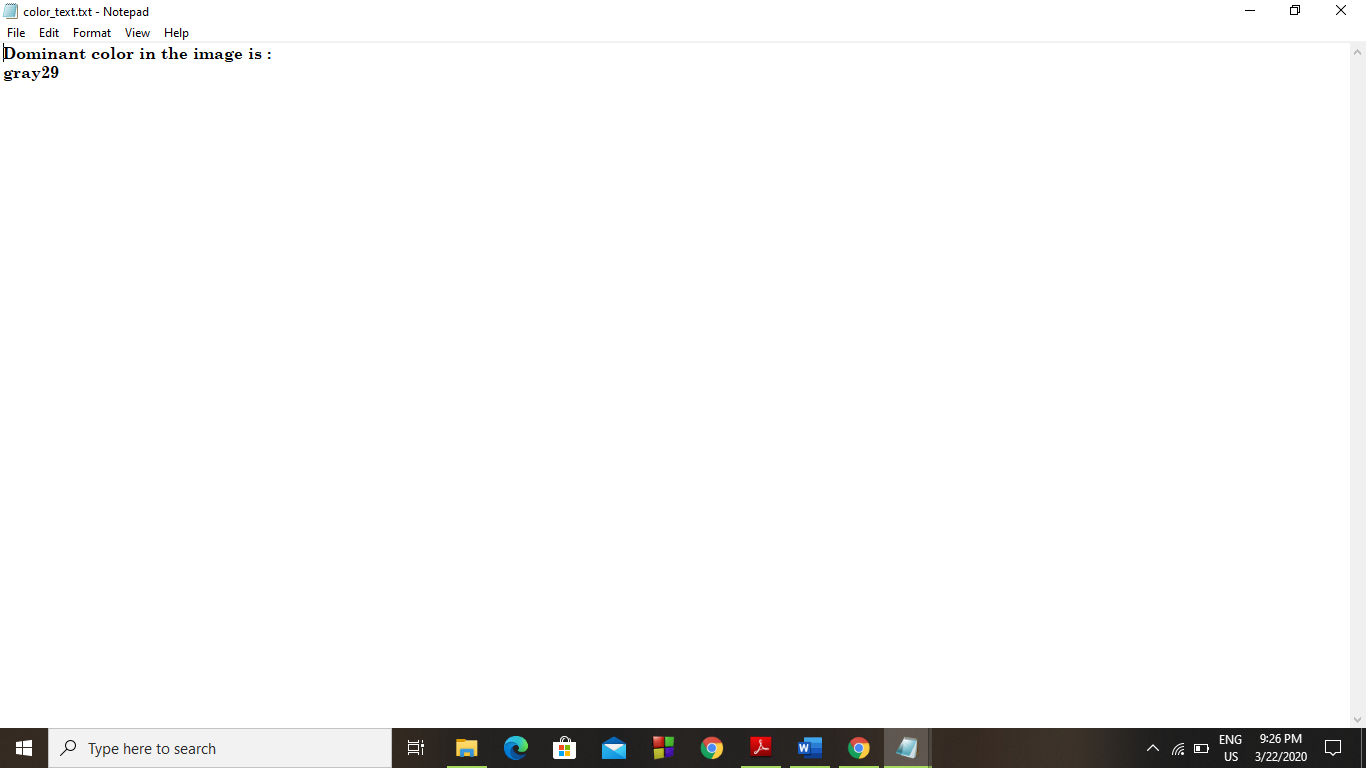




**OCR feature**



**Color detection feature**

**Chapter 7**

**Testing**

**7.1 Testing and Validations**

Software testing is the process used to evaluate the functionality of a software application with an intent to find whether the developed software met the specified requirements or not and to identify the defects to ensure that the product is defect free in order to produce the quality product. Validation Testing ensures that the product actually meets the client's needs. It can also be defined as to demonstrate that the product fulfills its intended use when deployed on appropriate environment.

In general, the following properties indicate the extent to which the component or system under test:

* Meets the requirements that guided its design and development,
* Responds correctly to all kinds of inputs,
* Performs its functions within an acceptable time,
* Is sufficiently usable,
* Can be installed and run in its intended environments, and
* Achieves the general result its stakeholders desire.

Software testing can be conducted as soon as executable software (even if partially complete) exists. The overall approach to software development often determines when and how testing is conducted.

**7.2 Testing Levels**

A level of software testing is a process where every unit or component of a software/system is tested. The main goal of system testing is to evaluate the system's compliance with the specified needs.

There are many different testing levels which help to check behavior and performance for software testing. These testing levels are designed to recognize missing areas and reconciliation between the development lifecycle states. In SDLC models there are characterized phases such as requirement gathering, analysis, design, coding or execution, testing, and deployment. All these phases go through the process of software testing levels.

**7.2.1 Functional Testing**

FUNCTIONAL TESTING is a type of software testing whereby the system is tested against the functional requirements/specifications. Functions (or features) are tested by feeding them input and examining the output. Functional testing ensures that the requirements are properly satisfied by the application.

**Functional testing types include:**

* Unit testing.
* Integration testing.
* System testing.
* Sanity testing.
* Smoke testing.
* Interface testing.
* Regression testing.
* Beta/Acceptance testing.

**7.2.2 Non-Functional Testing**

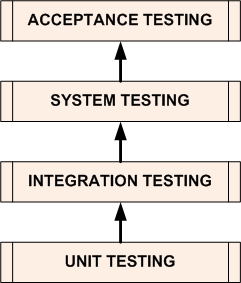
Non-functional testing is defined as a type of Software testing to check non-functional aspects (performance, usability, reliability, etc.) of a software application. It is designed to test the readiness of a system as per nonfunctional parameters which are never addressed by functional testing.

**Examples of non-functional tests include:**

* Load/Performance testing.
* Compatibility testing.
* Localization testing.
* Security testing.
* Reliability testing.
* Stress testing.
* Usability testing.
* Compliance testing.

**7.3 Whitebox Testing**

White Box Testing (also known as Clear Box Testing, Open Box Testing, Glass Box Testing, Transparent Box Testing, Code-Based Testing or Structural Testing) is a software testing method in which the internal structure/design of the item being tested is known to the tester.



**Stage – 1: Unit Testing**

This is the stage where the developers dissect the software and scrutinize its smallest units to find out any grass root level problems. Here the focus is on analyzing and testing each and every unit of every module to see whether it’s working properly.

**Stage – 2: Integration Testing**

Moving on from the units, the next stage involves testing how well the various modules and components are integrated within the developed software. The integration is checked both ways that is top-down as well as bottom-up, so as to bring out the design, construction and architectural defects in the software. It’s at this stage that most of the basic design flaws of the software will become obvious. The various interfaces will also be tested for defects at this stage.

**Stage – 3: Sub-System and System Testing**

This stage focuses on validating and analyzing that the software and all its sub-systems comply with the requirements as specified by the client. It’s at this stage the software is tested as a whole.

**Stage – 4: Testing Systems Engineering**

The objective of this fourth stage of software testing is to see whether the software works well when integrated with external components like computer systems and other software, as specified in the software requirements provided by the end user or client. It’s important to note here that the software will not be used on the developer’s computer system, so testing must be made keeping in mind the computer system on which the software will ultimately be used.

**Stage – 5: User Testing**

This final stage is also known as acceptance testing stage, wherein the end user or some representative tests the final software to see if its complete and it actually performs the functions it is supposed to perform.

**7.4.1 Unit Testing**

Unit testing, a testing technique using which individual modules are tested to determine if there are any issues by the developer himself. It is concerned with functional correctness of the standalone modules. The main aim is to isolate each unit of the system to identify, analyze and fix the defects. Unit Testing has its advantages, some of them are:

* Reduces Defects in the newly developed features or reduces bugs when changing

the existing functionality.

* Reduces Cost of Testing as defects are captured in very early phase.
* Improves design and allows better refactoring of code.
* Unit Tests, when integrated with build gives the quality of the build as well.

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Test**  **ID** | **Test Case Description** | **Input data** | **Expected Output** | **Actual Output** | **Status** |
| 1 | Date and time | Date and time option selected | Current date and time | Current date and time | Pass |
| 2 | Current location | Current location option selected | Current city, region and country | Current city, region and country | Pass |
| 3 | Current weather | Current weather option selected | Current weather info | Current weather info | Pass |
| 4 | Email | Email option selected | Unread emails | Unread emails | Pass |
| 5 | News headlines | News headlines option selected | Top 10 news headlines | Top 10 news headlines | Pass |
| 6 | OCR | OCR option selected | Image to text to speech | Image to text to speech | Pass |
| 7 | Color detection | Color detection option selected | Identify dominant color in image | Identify dominant color in image | Pass |

**Table 7.1 Unit Testing**

**7.4.2 Integration Testing**

In Integration Testing, individual software modules are integrated logically and tested as a group. A typical software project consists of multiple software modules, coded by different programmers. Integration testing focuses on checking data communication amongst these modules. Although each software module is unit tested, defects still exists for various reasons like:

* A Module in general is designed by an individual software developer whose understanding and programming logic may differ from other programmers.
* At the time of module development, there are wide chances of change in requirements by the clients. These new requirements may not be unit tested.
* Interfaces of the software modules with the database could be erroneous.

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Test**  **ID** | **Test Case Description** | **Input data** | **Expected Output** | **Actual Output** | **Status** |
| 1 | Controller shell | Particular option | Execute corresponding  program | Execute corresponding  program | Pass |
| 2 | Date and time | Date and time option selected | Current date and time | Current date and time | Pass |
| 3 | Current location | Current location option selected | Current city, region and country | Current city, region and country | Pass |
| 4 | Current weather | Current weather option selected | Current weather info | Current weather info | Pass |
| 5 | Email | Email option selected | Unread emails | Unread emails | Pass |

**Table 7.2 Integration Testing**

**7.4.1 System Testing**

System testing is performed on a completely integrated system which would meet the specified requirements. The main purpose of system testing is to check the problems between any of the software components. It takes all the components which have passed the integration testing. It not only checks the functionalities along with the behavior of the system. Some of the tests included in system testing are graphical user interface testing and usability testing.

Finally The system is tested altogether and all the subsystems that were tested are put together and tested as a whole system. The various components of the system work well together and it passes the test cases. This ensures that the user can easily and efficiently use the system.

**Chapter 8**

**Conclusion and Future Enhancement**

**8.1 Conclusion**

Technology today has grown to an extent where a machine is able to perform complex tasks by using machine learning. Machine learning and computer vision helps the machine to even retrieve meaningful data and information. Machine learning provides solution to complex problems and it is set to be pillar of our future civilization.

Smart glasses for visually impaired people is a project that uses such machine learning models to provide a assistive device for the visually impaired user. The developed product helps the visually impaired user to know the current date and time, current weather information, current location, get unread emails, get the text in an image, get the dominant color in an image, get the top 10 news headlines and also provide obstacle avoidance capacity. All the features have voice-based output to the visually impaired user. These features are accessible to the visually impaired user through the push of single particular button on the hand held remote. The processing is done by the Raspberry pi processor. The final product developed is easy to use and provides efficient results.

This project can be enhanced in the future to add more features and tide over the gap between the visually impaired people with rest of the society.

**8.2 Future Enhancement**

The processing of all the features here in the developed product is performed by the raspberry pi processor. For further enhancements of the project we can send the data form the webcam and remote to the cloud where the processing is made and the results are sent out to the audio output devices. This enhancement would eradicate the use of raspberry pi in the product and thus would make the product much lighter and easier to use for the visually impaired user. Even advancements of the project we may integrate real time object detection feature which would voice out all the objects surrounding the visually impaired user. Various other features like blind navigation can also be added to the product.