```
#include <Servo.h>

#define threshold  350
#define threshold2 350
#define threshold3 270
#define unpress_angle 25

#define press_angle 0
Servo myservo;

void setup() {
  myservo.attach(9);
  myservo.write(unpress_angle);
  Serial.begin(9600);
}

void loop() {
int x=analogRead(A0);
int y=analogRead(A1);
int Z=analogRead(A2);
myservo.write(unpress_angle);
delay(1);
Serial.println(x);
// Serial.println(y);
//Serial.println(Z);
if(analogRead(A2)< threshold3){
  if(analogRead(A1)< 150 &&  analogRead(A0)< 150)
    {
        myservo.write(unpress_angle);
        delay(50 );
    }
    else if(analogRead(A1)> 150 || analogRead(A0)> 150)
    {
        myservo.write(press_angle);
        delay(50 );
}
 }
 else{
    if(analogRead(A0)< threshold || analogRead(A1)< threshold2)
    {
        myservo.write(press_angle);
        delay(50 );
    }
 }
}
```