

SUNIN BAEK

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EDUCATION

Korea University, Seoul M.S. in Mechanical Engineering	2025 - Present
Korea University, Seoul B.S. in Mechanical Engineering B.S. in Medical Convergence Engineering	2018 - 2025

EXPERIENCE

Movement Intelligence Laboratory <i>Graduate Researcher (Advisor: Prof. Daekyum Kim)</i>	March 2025 - Present
<ul style="list-style-type: none">Developing an adaptive ankle exoskeleton control system using real-time physiological data and preference-based learning to adjust torque for personalized mobility assistance.	
Movement Intelligence Laboratory <i>Undergraduate Researcher (Advisor: Prof. Daekyum Kim)</i>	November 2023 - February 2025
<ul style="list-style-type: none">Implemented a multimodal sensor fusion system using IMU, ECG, EMG, PPG, FSR, RGB Camera, and etc.Developed a deep learning framework using open-source IMU data for lower-limb joint kinematic estimation.Designed a compact, torque-controllable ankle exoskeleton for walking assistance with modular sensor integration.	
ROKAF Air Defense Control Command, Osan AB <i>Staff Sergeant (Aviation Control)</i>	October 2020 - July 2022
<ul style="list-style-type: none">Managed confidential intelligence reports, identified potential tactical threats, and analyzed the findings for high-level command decisions.	

PUBLICATIONS

[J1] B. Hur, S. Baek , I. Kang, and D. Kim, "Learning-Based Lower Limb Joint Kinematic Estimation Using Open Source IMU Data," <i>Scientific Reports</i> , 15(1), 2025, 5287.
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HONORS & AWARDS

KU Veritas Scholarship <i>Creative Challenger Program Research Grant</i>	2024
Excellence Award, KAP Future Automotive Industry Idea Contest <i>Project: 3D Driver Pose Estimation Using Pressure Sheets</i>	2024
SW · AI Award(2nd Place), KU AI Forum <i>Title: Vision-Language Model based Walking Environment Recognition</i>	2024
Finalist, KU Capstone Design Fair <i>Project: Robotic Self-Navigating Solar-Powered Cube Vessel</i>	2023
Certificate of Academic Excellence(1st Place) <i>ROKAF Information & Communication School</i>	2020

TEACHING

(MOBI104) *How things work*
Teaching Assistant

Fall 2024

(MOBI203) *Data Structures and Algorithms*
Teaching Assistant

Spring 2025

TECHNICAL SKILLS

Programming Languages

Python, C, C++, MATLAB

Software Experiences

Fusion 360, ROS, OpenCV, TensorFlow, Pytorch, imufusion
LabStreamingLayer, Upper Computer(CubeMars), Arduino IDE,
OpenPose, DeepLabCut, OpenSim, OpenCap, RealSense SDK,
YOLO, CLIP, LaTeX

Languages

Korean(Native), English(Fluent), Spanish(Elementary)

EXTRACURRICULAR ACTIVITIES

LINC 3.0 KU Entrepreneurial Club, A_BOUT
Project Leader

April 2023 - October 2023

- Funded by the *Crimson Startup Institute* and the *KU Pioneer Village π -Ville 99 Studio*.
- Developed a full-scale vessel that successfully crossed the Han River.
- Optimized the Han River's waterway infrastructure using public data for demand forecasting and terminal selection; presented at the KUBS CDTB Data Analysis Contest.

KU School of Mechanical Engineering, Student Council
32nd & 33rd

May 2018 - December 2019

- Organized and led student welfare initiatives while also planning, promoting, and managing school and departmental events.

KU Rotaract Club(Community Service & Leadership)
External Affairs Executive

March 2018 - November 2019

- Orchestrated volunteer engagements at local facilities like 한국생명의전화종합사회복지관 (Social Welfare Center) and 승가원 (Disability Welfare Center), bolstering community relations and support.