

# SUNIN BAEK

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## EDUCATION

<b>Korea University, Seoul</b> M.S. in Mechanical Engineering	2025 - Present
<b>Korea University, Seoul</b> B.S. in Mechanical Engineering B.S. in Medical Convergence Engineering	2018 - 2025

## EXPERIENCE

<b>Movement Intelligence Laboratory</b> <i>Graduate Researcher (Advisor: Prof. Daekyum Kim)</i>	March 2025 - Present
<ul style="list-style-type: none"><li>Developing an adaptive ankle exoskeleton control system using real-time physiological data and preference-based learning to adjust torque for personalized mobility assistance.</li></ul>	
<b>Movement Intelligence Laboratory</b> <i>Undergraduate Researcher (Advisor: Prof. Daekyum Kim)</i>	November 2023 - February 2025
<ul style="list-style-type: none"><li>Implemented a multimodal sensor fusion system using IMU, ECG, EMG, PPG, FSR, RGB Camera, and etc.</li><li>Developed a deep learning framework using open-source IMU data for lower-limb joint kinematic estimation.</li><li>Designed a compact, torque-controllable ankle exoskeleton for walking assistance with modular sensor integration.</li></ul>	
<b>ROKAF Air Defense Control Command, Osan AB</b> <i>Staff Sergeant (Aviation Control)</i>	October 2020 - July 2022
<ul style="list-style-type: none"><li>Managed confidential intelligence reports, identified potential tactical threats, and analyzed the findings for high-level command decisions.</li></ul>	

## PUBLICATIONS

[J1] B. Hur, <b>S. Baek</b> , I. Kang, and D. Kim, “Learning Based Lower Limb Joint Kinematic Estimation Using Open Source IMU Data”, (in review), 2025.	
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## HONORS & AWARDS

<b>KU Veritas Scholarship</b> <i>Creative Challenger Program Research Grant</i>	2024
<b>Excellence Award, KAP Future Automotive Industry Idea Contest</b> <i>Project: 3D Driver Pose Estimation Using Pressure Sheets</i>	2024
<b>KU AI Forum, 2nd Place</b> <i>Title: Vision-Language Model based Walking Environment Recognition</i>	2024
<b>Finalist, KU Capstone Design Fair</b> <i>Project: Robotic Self-Navigating Solar-Powered Cube Vessel</i>	2023
<b>Certificate of Academic Excellence(1st Place)</b> <i>ROKAF Information &amp; Communication School</i>	2020

## TEACHING

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**(MOBI104) *How things work***  
*Teaching Assistant*

Fall 2024

## TECHNICAL SKILLS

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<b>Programming Languages</b>	Python, C, C++, MATLAB
<b>Software Experiences</b>	Fusion 360, ROS, OpenCV, TensorFlow, Pytorch, imufusion LabStreamingLayer, Upper Computer(CubeMars), Arduino IDE, OpenPose, DeepLabCut, OpenSim, OpenCap, RealSense SDK, YOLO, CLIP, LaTeX
<b>Languages</b>	Korean(Native), English(Fluent), Spanish(Elementary)

## EXTRACURRICULAR ACTIVITIES

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<b>LINC 3.0 KU Entrepreneurial Club, A_BOUT</b> <i>Project Leader</i>	April 2023 - October 2023
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- Funded by the *Crimson Startup Institute* and the *KU Pioneer Village  $\pi$ -Ville 99 Studio*.
- Developed a full-scale vessel that successfully crossed the Han River.
- Optimized the Han River's waterway infrastructure using public data for demand forecasting and terminal selection; presented at the KUBS CDTB Data Analysis Contest.

<b>KU School of Mechanical Engineering, Student Council</b> <i>32nd &amp; 33rd</i>	May 2018 - December 2019
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- Organized and led student welfare initiatives while also planning, promoting, and managing school and departmental events.

<b>KU Rotaract Club(Community Service &amp; Leadership)</b> <i>External Affairs Executive</i>	March 2018 - November 2019
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- Orchestrated volunteer engagements at local facilities like 한국생명의전화종합사회복지관 (Social Welfare Center) and 승가원 (Disability Welfare Center), bolstering community relations and support.