Computer Vision Module - Session 5



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Online Training & Certification Course on Artificial Intelligence & Machine Learning
Defence Institute of Advanced Technology (DU), Pune.



Computer Vision





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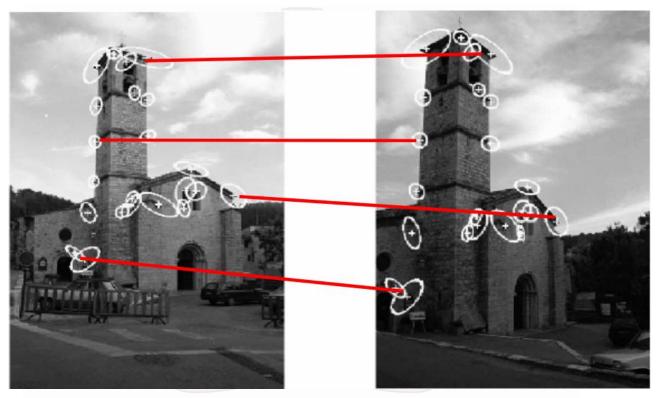


Outline of Presentation

- Introduction
- Basic Idea
- Harris Corner Detector



Introduction



Properties of good features

Local: features are local, robust to occlusion and clutter

Accurate: precise localization.

Invariant(or **covariant**)

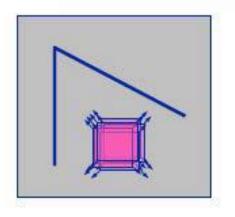
Robust: noise, blur, compression, etc.

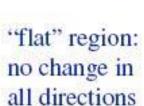
Distinctive: individual features can be matched to a large database

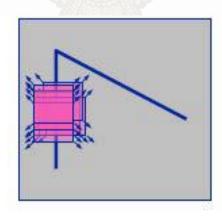
of objects.

Efficient: close to real-time performance.

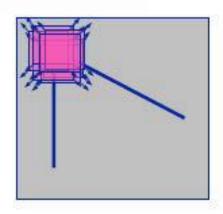
Basic Concept







"edge": no change along the edge direction

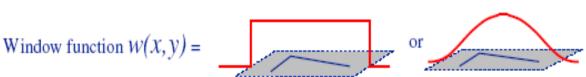


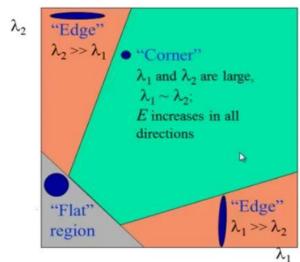
"corner": significant change in all directions

Harris Corner Detector

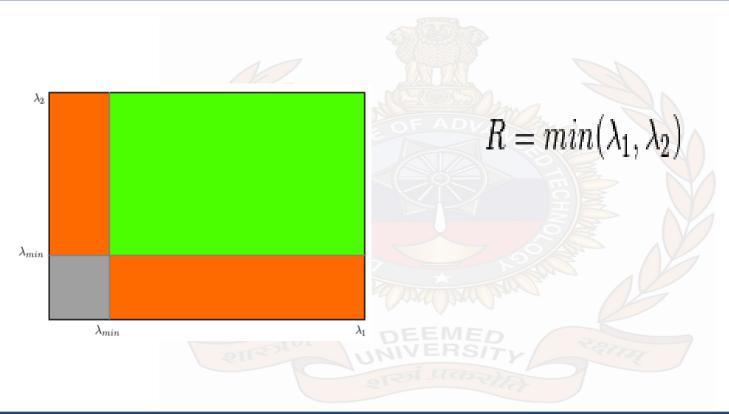
Change of intensity for the shift [u, v]:

$$E(u,v) = \sum_{x,y} w(x,y) [I(x+u,y+v) - I(x,y)]^{2}$$
Window function Shifted intensity Intensity





Shi-Tomasi Corner Detector



Reference Material

- 1. E. R. Davies, "Computer & Machine Vision", Fourth Edition, Academic Press, 2012.
- 2. R. Szeliski, "Computer Vision: Algorithms and Applications", Springer 2011.
- 3. Simon J. D. Prince, "Computer Vision: Models, Learning, and Inference", Cambridge University Press, 2012.
- 4. Mark Nixon and Alberto S. Aquado, "Feature Extraction & Image Processing for Computer Vision", Third Edition, Academic Press, 2012.
- 5. Sunita Dhavale, "Advanced Image-Based Spam Detection and Filtering Techniques", Book Published by CyberTech: An Imprint of MKP Technologies, Hershey, PA, USA IGI Global, March 2017, ISBN13: 9781683180135|ISBN10: 1683180135|EISBN13: 9781683180142|DOI: 10.4018/978-1-68318-013-5.

<<Epilogue>>

- We will meet in next scheduled lecture.
- Try to implement the algorithms in python.
- Feel free to ask your questions.
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