

# MA3238 (Stochastic Processes 1)

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Reference: Introduction to Probability Models (9th edition)

## 1 Revision

*Limit of the binomial distribution is the poisson distribution* Let  $X_n \sim (n, p = \frac{\lambda}{n})$  and consider the distribution of  $X_n$  as  $n \rightarrow \infty$ . **Note** that as we increase  $n$ , we also shrink  $p$  since that  $p = \frac{\lambda}{n}$ .

Observe that

$$\begin{aligned}\binom{n}{k} p^k (1-p)^{n-k} &= \frac{n^k}{k!} \left(\frac{\lambda}{n}\right)^k \left(1 - \frac{\lambda}{n}\right)^{n-k} \\ &= \frac{\lambda^k}{k!} \cdot \frac{n^k}{n^k} \left(1 - \frac{\lambda}{n}\right)^{n-k}\end{aligned}$$

Since  $\frac{\lambda^k}{k!}$  is independent of  $n$ , it suffices to take the limit of the latter expression. We have

$$\begin{aligned}\lim_{n \rightarrow \infty} \frac{n^k}{n^k} \left(1 - \frac{\lambda}{n}\right)^{n-k} &= \lim_{n \rightarrow \infty} \frac{n^k}{n^k} \left(1 - \frac{\lambda}{n}\right)^n \left(1 - \frac{\lambda}{n}\right)^{-k} \\ &= \lim_{n \rightarrow \infty} \frac{n^k}{n^k} \lim_{n \rightarrow \infty} \left(1 - \frac{\lambda}{n}\right)^n \lim_{n \rightarrow \infty} \left(1 - \frac{\lambda}{n}\right)^{-k} \\ &= 1 \cdot e^{-\lambda} \cdot 1 = e^{-\lambda}\end{aligned}$$

*A r.v. cannot be both continuous (not necessarily absolutely continuous) and discrete.*

- A discrete r.v. takes probability 1 on a countable set  $C$ . Equivalently, there is a countable set  $C$  such that  $\sum_{c \in C} p(c) = 1$  for some function  $p$ , such that  $P(X = c) := p(c)$ .
- A continuous r.v. has a continuous cdf.

Suppose  $X$  is discrete. Let  $C$  be a countable set for which  $P(X \in C) = \sum_{c \in C} p(c) = 1$ . Clearly, it is not possible for all  $p(c) = 0$ , so  $\exists c \in C, p(c) > 0$ . Let  $F$  be the cdf of  $X$ . Then we claim that  $F$  is left-discontinuous at  $c$ . Because  $\forall \epsilon, F(c - \epsilon) < P(X < c) = F(c) - p(c)$ . ■

*Non-independent but covariance 0.* Consider  $Y = 1, -1$  with probability  $1/2$  each. Then,

- Given  $Y = 1$ ,  $X = 1$  with probability  $1/2$  and 0 otherwise
- Given  $Y = -1$ ,  $X = 2$  with probability  $1/4$  and 0 otherwise

The idea of  $Y$  is clear, the positive half and negative half cancel out. The idea of  $X$  is to vary its behavior given differing value of  $Y$ , but not too much, so that the positive part of  $XY$  cancels out the negative parts, with their respective probability weights.

Note: The paragraphs in this document correspond to subsections in the textbook. For e.g. **4.2** corresponds to Chapman-Kolmogorov Equations.

#### 4.1

We have  $P_{i,j} = P(X_{n+1} = j | X_n = i, X_{n-1} = i_{n-1}, \dots, X_0 = i_0)$  for all  $i_0, \dots, i_{n-1}$  in the state space. Hence,  $P(X_{n+1} = j | X_n = i) = \sum P(X_{n+1} = j | X_n = i, X_{n-1} = i_{n-1}, \dots, X_0 = i_0) P(X_{n-1} = i_{n-1}, \dots, X_0 = i_0) = P_{i,j}$ .

Hence, conditioning on  $X_n = i$ , the events  $\{X_{n+1} = j\}$  and  $\{X_{n-1} = i_{n-1}, \dots, X_0 = i_0\}$  are independent.

#### 4.2

Claim: Consider the case of a state space with absorbing states  $A$ . Suppose states  $i, j \notin A, k \in A$ . Then  $P(X_{n+m} = j \cap X_n = k | X_0 = i) = 0$ . i.e. once state  $k$  is reached, the probability of reaching any other state distinct from  $k$  is 0.

Since  $P(X_{n+m} = j \cap X_n = k | X_0 = i) = P(X_{n+m} = j | X_n = k \wedge X_0 = i) P(X_n = k | X_0 = i) = P(X_m = j | X_0 = k) P(X_n = k | X_0 = i)$ , it suffices to show that  $P_{k,j}^m = 0$ .

This can be verified inductively. We shall only show the inductive step. Suppose  $P_{k,j}^\lambda = 0$  (in fact we need to assume the same for all  $j$  distinct from  $k$ ). Then  $P_{k,j}^{\lambda+1} = \sum_l P_{k,l}^\lambda \cdot P_{l,j} = P_{k,k}^\lambda \cdot P_{k,j} = 1 \cdot 0 = 0$ .

#### 4.3

Another way to interpret  $P_{i,j}^n$  is the following.  $P_{i,j}^n > 0$  iff there is a sequence  $l_1, \dots, l_{n-1}$  such that  $P_{i,l_1}, P_{l_1,l_2}, \dots, P_{l_{n-1},j} \neq 0$ . This is equivalent to saying  $i \rightarrow l_1 \rightarrow l_2 \rightarrow \dots \rightarrow l_{n-1} \rightarrow j$ . We can also let  $l_0 := i, l_n := j$  and obtain a sequence  $l_0, \dots, l_n$ .

To take example 4.12 in this section as an example: Suppose we want to show that states 0, 1 cannot access state 2. One possible argument to make is to consider the candidates for states  $l := l_{n-1}$  (for any  $n$ ) such that  $l_{n-1} \rightarrow 2$ , or equivalently,  $P_{l,2} > 0$ . But looking at the 3rd column of the Markov matrix, we see that the only candidate for  $l$  is 2 itself. So it is impossible to have a series of state transition from 0 or 1 that ends up in 2. (A formal proof can involve induction on the number of state transitions.)

*Characterization of recurrent and transient states* For a state  $i$ , let  $f_i$  be the probability that state  $i$  is revisited, given that the current state is  $i$ .

Let  $Y_i \sim \text{Geom}(p = (1 - f_i))$  be a r.v. counting the number of times state  $i$  was entered, given that the starting state is  $i$ . Transient states:

- Have a  $f_i$  value  $< 1$
- Have a finite expectation  $E[Y_i]$

Recurrent states:

- Have  $f_i = 1$
- Have an infinite expectation  $E[Y_i]$

Hence to argue that in a finite state space, there must be at least 1 recurrent state, we argue that the sum of expectation of all  $Y_i$  must be infinite, so there must be some  $i$  for which  $E[Y_i] > 0$ .

*Corollary 4.2* We provide a more succinct derivation of this result.

- State  $i$  recurrent implies  $\sum_n p_{i,i}^n = \infty$
- $i \leftrightarrow j$  implies  $\exists m_1, m_2, p_{i,j}^{m_1} > 0 \wedge p_{j,i}^{m_2} > 0$

Hence,

$$\sum_n p_{j,j}^n \geq \sum_{n \geq m_1 + m_2} p_{j,j}^n \geq \sum_{n \geq m_1 + m_2} p_{j,i}^{m_2} p_{i,i}^{n-m_1-m_2} p_{i,j}^{m_1} = p_{j,i}^{m_2} p_{i,j}^{m_1} \sum_n p_{i,i}^n$$

The last sum is unbounded and we are done.