

# Fundamental Belief: Universal Approximation Theorems

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# Outline

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## Recap

Why should we trust NNs?

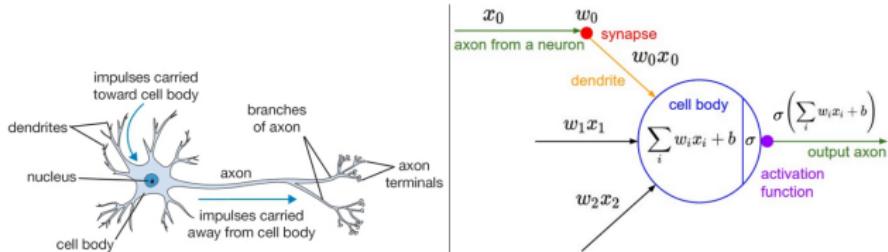
Visual proof of UAT

UAT in rigorous form

From shallow to deep NNs

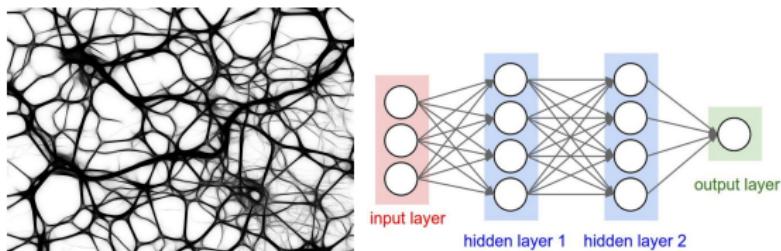
Suggested reading

# Recap I



A cartoon drawing of a biological neuron (left) and its mathematical model (right).

## biological neuron vs. artificial neuron

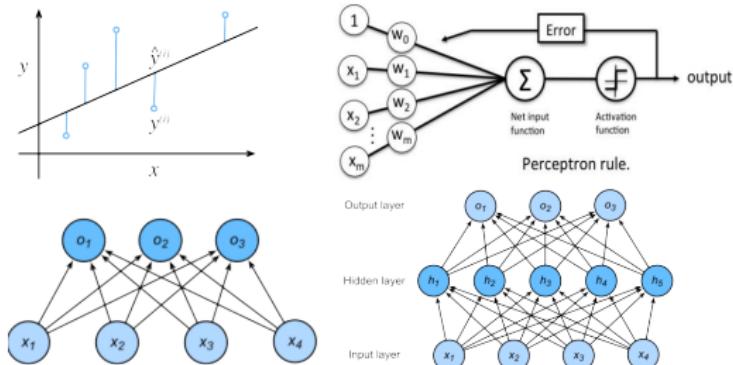


## biological NN vs. artificial NN

Artificial NN: (over)-simplification on **neuron & connection** levels

## Recap II

### Zoo of NN models in ML

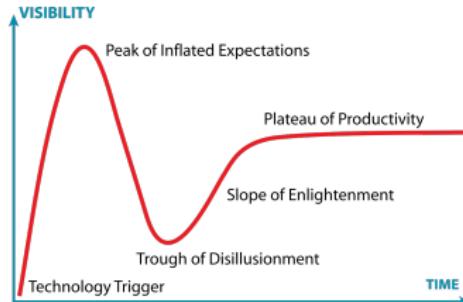
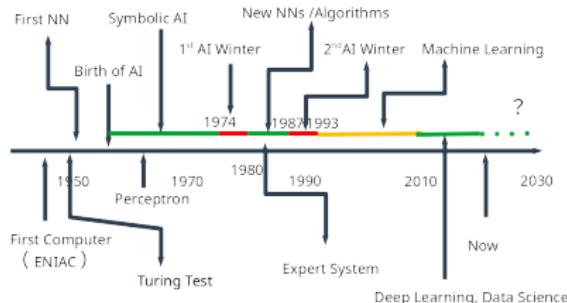


- Linear regression
- Perception and Logistic regression
- Softmax regression
- Multilayer perceptron (feedforward NNs)

Also:

- Support vector machines (SVM)
- PCA (autoencoder)
- Matrix factorization

## Recap III



### Brief history of NNs:

- 1943: first NNs invented (McCulloch and Pitts)
- 1958–1969: perceptron (Rosenblatt)
- 1969: *Perceptrons* (Minsky and Papert)—end of perceptron
- 1980's–1990's: Neocognitron, CNN, back-prop, SGD—we use today
- 1990's–2010's: SVMs, Adaboosting, decision trees and random forests
- 2010's–now: DNNs and deep learning
- Next transition?

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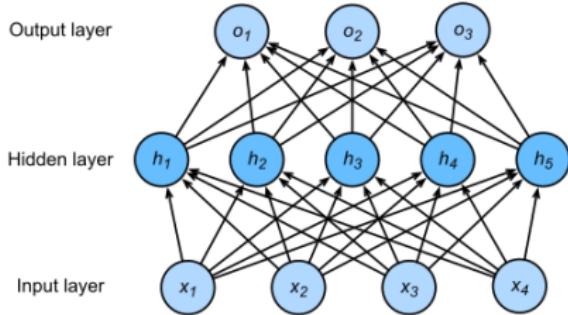
Suggested reading

# Supervised learning

Step	General view	NN view
1	Gather training set $(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_n, \mathbf{y}_n)$	Gather training set $(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_n, \mathbf{y}_n)$
2	Choose a family of functions, e.g., $\mathcal{H}$ , so that there is an $f \in \mathcal{H}$ to ensure $\mathbf{y}_i \approx f(\mathbf{x}_i), \forall i$	Choose a NN with $k$ neurons, so that there is a group of weights $(\mathbf{w}_1, \dots, \mathbf{w}_k, b_1, \dots, b_k)$ ensuring $\mathbf{y}_i \approx \{\text{NN}(\mathbf{w}_1, \dots, \mathbf{w}_k, b_1, \dots, b_k)\}(\mathbf{x}_i), \forall i$
3	Set up a loss function $\ell$	Set up a loss function $\ell$
4	Find an $f \in \mathcal{H}$ to minimize the average loss $\frac{1}{n} \sum_{i=1}^n \ell(\mathbf{y}_i, f(\mathbf{x}_i))$	Find weights $(\mathbf{w}_1, \dots, \mathbf{w}_k, b_1, \dots, b_k)$ to minimize the average loss $\frac{1}{n} \sum_{i=1}^n \ell[\mathbf{y}_i, \{\text{NN}(\mathbf{w}_1, \dots, \mathbf{w}_k, b_1, \dots, b_k)\}(\mathbf{x}_i)]$

Why we trust NNs? They're “powerful”—encoding “large”  $\mathcal{H}$

# Three fundamental questions in DL



- **$k$ -layer NNs:** with  $k$  layers of weights (along the deepest path)
- **$k$ -hidden-layer NNs:** with  $k$  hidden layers of nodes (i.e.,  $(k + 1)$ -layer NNs)

- **Approximation:** is it powerful, i.e., the  $\mathcal{H}$  large enough for all possible weights? (now)
- **Optimization:** how to solve

$$\min_{\mathbf{w}'_i s, \mathbf{b}'_i s} \frac{1}{n} \sum_{i=1}^n \ell [\mathbf{y}_i, \{\text{NN}(\mathbf{w}_1, \dots, \mathbf{w}_k, b_1, \dots, b_k)\}(\mathbf{x}_i)]$$

(later this course)

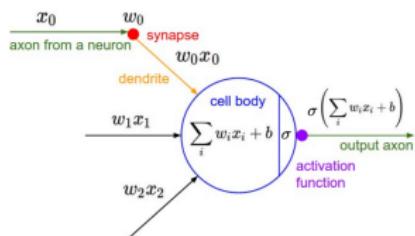
- **Generalization:** does the learned NN work well on “similar” data?  
(CSCI5525, and Deep Learning Theory)

# Is NN powerful? first trial

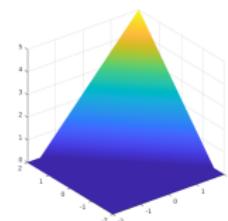
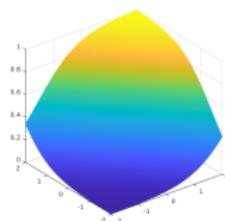
Think of single-output (i.e.,  $\mathbb{R}^n \mapsto \mathbb{R}$ ) problems first

- $\sigma$  identity or linear: **linear functions**
- $\sigma$  sign function  $\text{sign}(w^\top x + b)$   
(perceptron): **0/1 function with hyperplane threshold**
- $\sigma = \frac{1}{1+e^{-z}}$ :  $\left\{ \mathbf{x} \mapsto \frac{1}{1+e^{-(w^\top \mathbf{x} + b)}} \right\}$
- $\sigma = \max(0, z)$  (ReLU):  
 $\left\{ \mathbf{x} \mapsto \max(0, w^\top \mathbf{x} + b) \right\}$

## A single neuron



$$\mathcal{H} : \{\mathbf{x} \mapsto \sigma(w^\top \mathbf{x} + b)\}$$

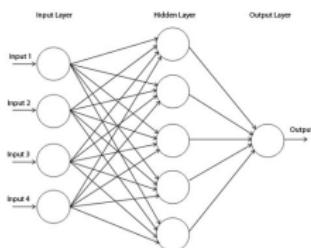


Question: What cannot be done?

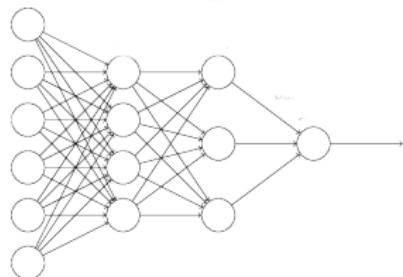
# Is NN powerful? second trial

Think of single-output (i.e.,  $\mathbb{R}^n \mapsto \mathbb{R}$ ) problems first

**Add depth!**



But make all hidden-nodes activations  
identity or linear



$$\sigma(\mathbf{w}_L^\top (\mathbf{W}_{L-1} (\dots (\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1) + \dots) \mathbf{b}_{L-1}) + b_L)$$

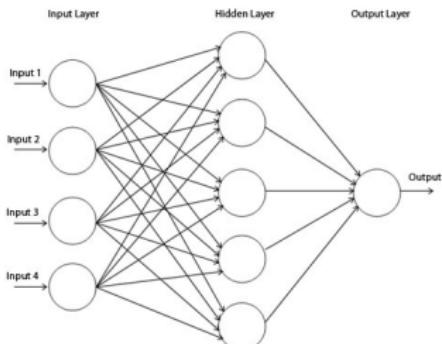
No better than a single neuron! Why?

...

# Is NN powerful? third trial

Think of single-output (i.e.,  $\mathbb{R}^n \mapsto \mathbb{R}$ ) problems first

Add both depth & nonlinearity!



two-layer network, linear activation  
at output

Surprising news: **universal approximation theorem (UAT)**

The 2-layer network can approximate **arbitrary continuous** functions **arbitrarily well**, provided that the hidden layer is **sufficiently wide**.

— so we don't worry about limitation in the capacity

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Visual proof of UAT

UAT in rigorous form

From shallow to deep NNs

Suggested reading

# Why could UAT hold?

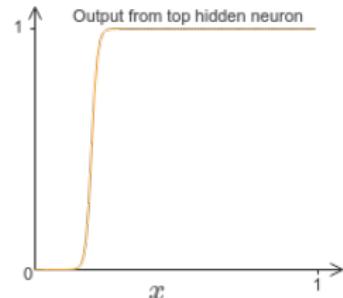
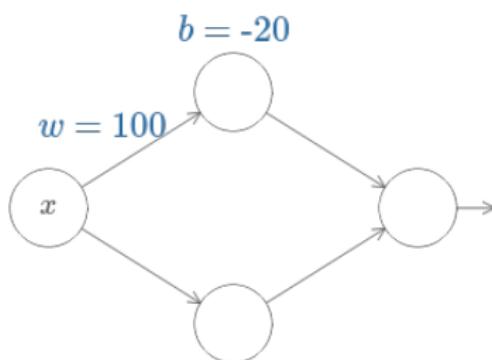
## Visual “proof”

(<http://neuralnetworksanddeeplearning.com/chap4.html>)

Think of  $\mathbb{R} \rightarrow \mathbb{R}$  functions first,  $\sigma = \frac{1}{1+e^{-z}}$

- Step 1: Build “step” functions
- Step 2: Build “bump” functions
- Step 3: Sum up bumps to approximate

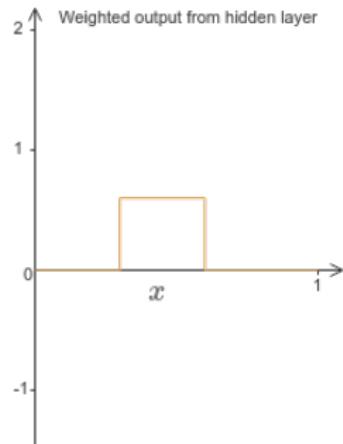
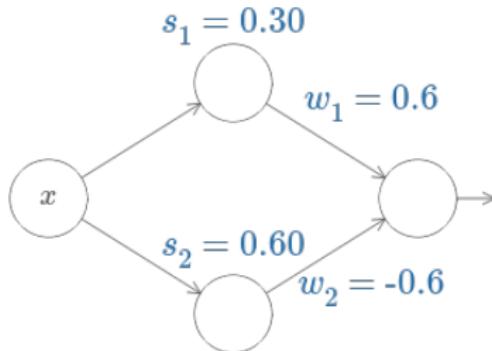
## Step 1: build step functions



$$y = \frac{1}{1 + e^{-(wx+b)}} = \frac{1}{1 + e^{-w(x-b/w)}}$$

- Larger  $w$ , sharper transition
- Transition around  $-b/w$ , written as  $s$

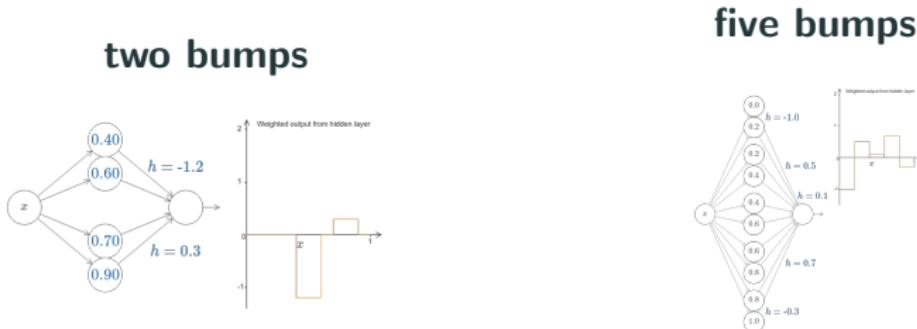
## Step 2: build bump functions



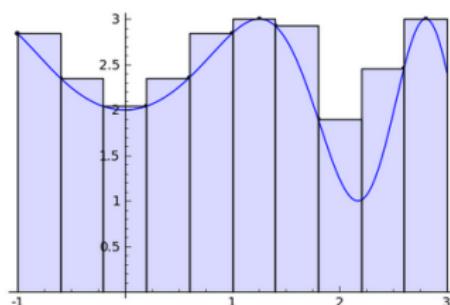
$$0.6 * \text{step}(0.3) - 0.6 * \text{step}(0.6)$$

Write  $h$  as the bump height

## Step 3: sum up bumps to approximate



ultimate idea ... familiar?



**Message:** all  $\mathbb{R} \mapsto \mathbb{R}$  functions can be “well” approximated using

2-layer NN's

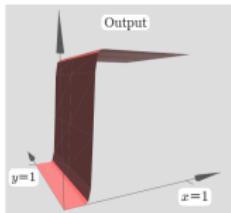
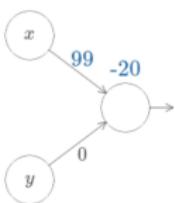
## What about high-dimensional?

Similar story

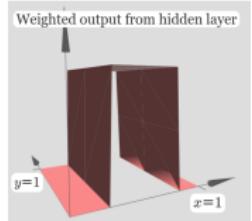
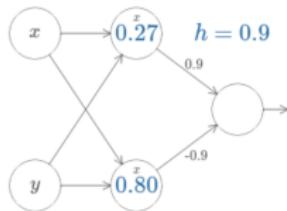
- Step 1: Build “step” functions
- Step 2: Build “bump” functions
- Step 3: Build “tower” functions
- Step 4: Sum up bumps to approximate

<http://neuralnetworksanddeeplearning.com/chap4.html>

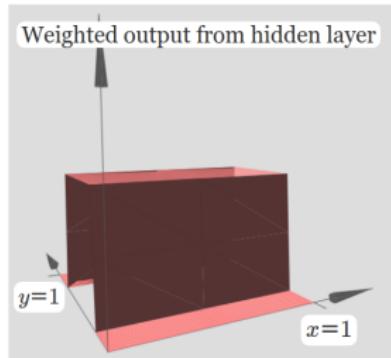
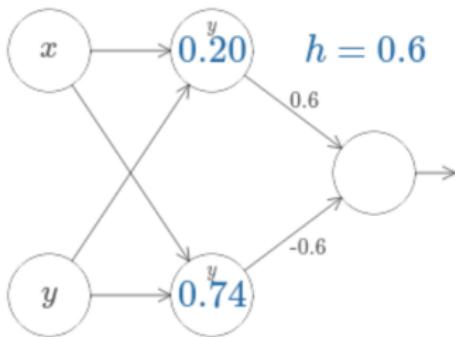
## Steps 1 & 2: build step and bump functions



step in  $x$  by setting large weight for  $x$

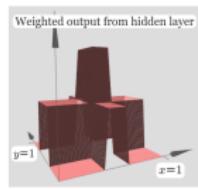
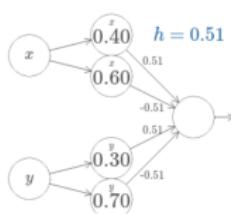


bump in  $x$  by diff of two steps in  $x$

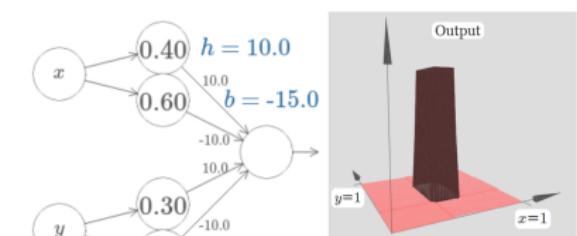
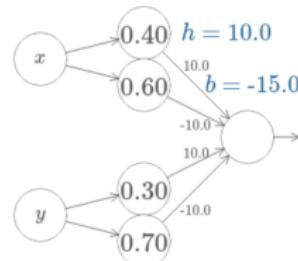


bump in  $y$  by diff of two steps in  $y$

## Step 3: build tower functions

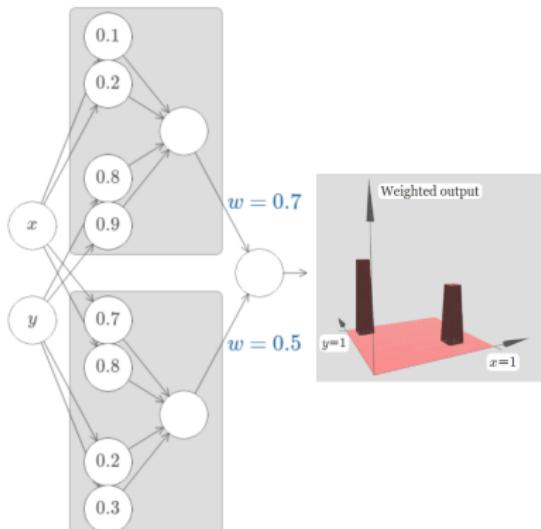


sum up  $x, y$  bumps to obtain a  
stair tower

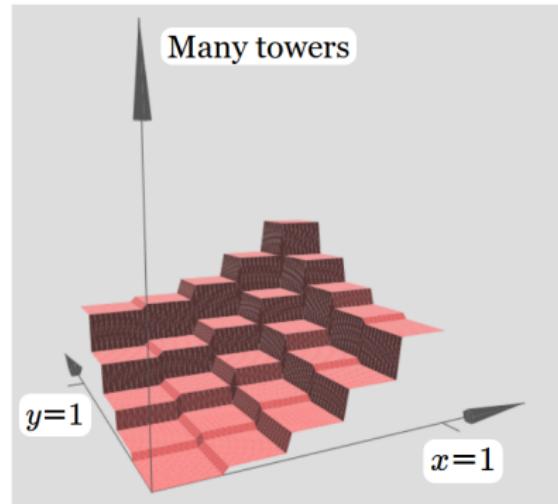


threshold to obtain a sharp tower

## Step 4: sum up towers for approximation



sum up two towers



sum up many towers

**Message:** all  $\mathbb{R}^2 \mapsto \mathbb{R}$  functions can be “well” approximated using  
**3-layer NN’s** **Question:** Possible using 2-layer NNs only?

## General cases?

- What about  $\mathbb{R}^n \mapsto \mathbb{R}$  functions?  
The “step → (bump) → tower → tower array” construction carries over
- What about  $\mathbb{R}^n \mapsto \mathbb{R}^m$  functions?  
Approximate each  $\mathbb{R}^n \mapsto \mathbb{R}$  separately and then glue them together

**Message:** All  $\mathbb{R}^n \mapsto \mathbb{R}^m$  functions can be “well” approximated using 2-layer NN’s

# Outline

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Why should we trust NNs?

Visual proof of UAT

UAT in rigorous form

From shallow to deep NNs

Suggested reading

## [A] universal approximation theorem (UAT)

### Theorem (UAT, [Cybenko, 1989, Hornik, 1991])

Let  $\sigma : \mathbb{R} \rightarrow \mathbb{R}$  be a *nonconstant, bounded, and continuous* function. Let  $I_m$  denote the  $m$ -dimensional *unit hypercube*  $[0, 1]^m$ . The space of *real-valued continuous functions on  $I_m$*  is denoted by  $C(I_m)$ . Then, given any  $\varepsilon > 0$  and any function  $f \in C(I_m)$ , there exist an integer  $N$ , real constants  $v_i, b_i \in \mathbb{R}$  and real vectors  $w_i \in \mathbb{R}^m$  for  $i = 1, \dots, N$ , such that we may define:

$$F(\mathbf{x}) = \sum_{i=1}^N v_i \sigma \left( \mathbf{w}_i^T \mathbf{x} + b_i \right) = \mathbf{v}^\top \sigma (\mathbf{W}^\top \mathbf{x} + \mathbf{b})$$

as an approximate realization of the function  $f$ ; that is,

$$|F(\mathbf{x}) - f(\mathbf{x})| < \varepsilon$$

for all  $\mathbf{x} \in I_m$ .

## Rigorous proof?

The proof is very technical ... functional analysis

- ① Riesz Representation: Every linear functional on  $C^0([0, 1]^k)$  is given by

$$f \mapsto \int_{[0,1]^k} f(x) d\mu(x), \quad \mu \in \mathcal{M}$$

where  $\mathcal{M} = \{\text{finite signed regular Borel measures on } [0, 1]^k\}.$

- ② **Lemma.** Suppose for each  $\mu \in \mathcal{M}$ , we have

$$\int_{[0,1]^k} \phi(w \cdot x + b) d\mu(x) = 0 \quad \forall w, b \quad \Rightarrow \quad \mu = 0. \quad (0.1)$$

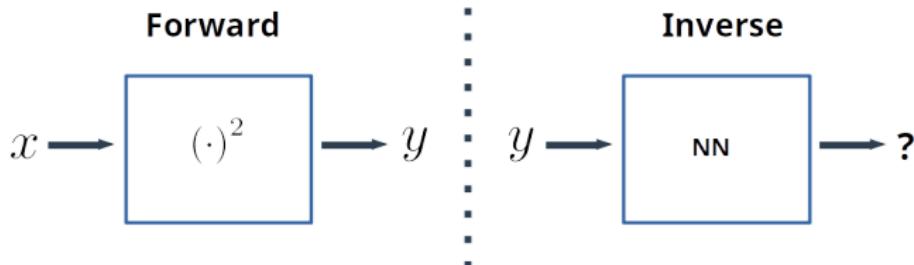
Then  $\text{Nets}_1(\phi)$  is dense in  $C^0([0, 1]^k)$ .

- ③ **Lemma.**  $\phi$  continuous, sigmoidal  $\Rightarrow$  satisfies (0.1).

## Thoughts on UAT

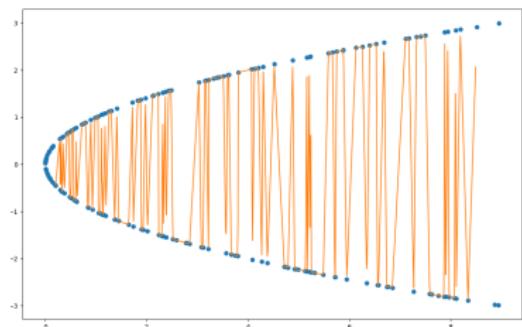
- $\sigma : \mathbb{R} \rightarrow \mathbb{R}$  be a nonconstant, bounded, and continuous:  
what about ReLU (leaky ReLU) or sign function (as in perceptron)? We have many UAT theorem(s)
- $I_m$  denote the m-dimensional unit hypercube  $[0, 1]^m$ : this can be replaced by any compact subset of  $\mathbb{R}^m$
- there exist an integer  $N$ : but how large  $N$  needs to be?  
(later)
- The space of real-valued continuous functions on  $I_m$ : two examples to ponder on
  - binary classification
  - learn to solve square root

# Learn to take square-root



Suppose we lived in a time square-root is not defined ...

- Training data:  $\{x_i, x_i^2\}_i$ , where  $x_i \in \mathbb{R}$
- Forward: if  $x \mapsto y, -x \mapsto y$   
also
- To invert, what to output?  
What if just throw in the training data?



# Thoughts

- Approximate continuous functions with vector outputs, i.e.,  
 $I_m \rightarrow \mathbb{R}^n$ ? think of the component functions
- Map to  $[0, 1]$ ,  $\{-1, +1\}$ ,  $[0, \infty)$ ? choose appropriate activation  $\sigma$  at the output

$$F(x) = \sigma \left( \sum_{i=1}^N v_i \sigma(\mathbf{w}_i^T \mathbf{x} + b_i) \right)$$

... universality holds in modified form

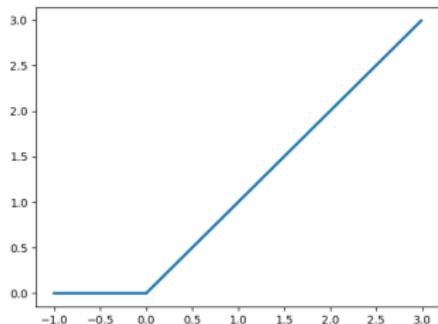
- Get deeper? three-layer NN? change to matrix-vector notation for convenience

$$F(x) = \mathbf{w}^T \sigma(\mathbf{W}_2 \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2) \quad \text{as } \sum_k w_k g_k(x)$$

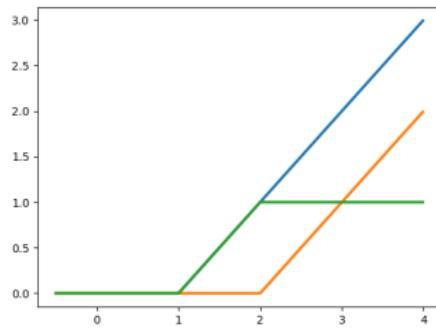
use  $w_k$ 's to linearly combine the same function

- For geeks: approximate both  $f$  and  $f'$ ? check out  
[Hornik et al., 1990]

# What about ReLU?



ReLU



difference of ReLU's

what happens when the slopes of the ReLU's are changed?

**How general  $\sigma$  can be?** ... enough when  $\sigma$  not a polynomial  
[Leshno et al., 1993, Gühring et al., 2020, DeVore et al., 2021]

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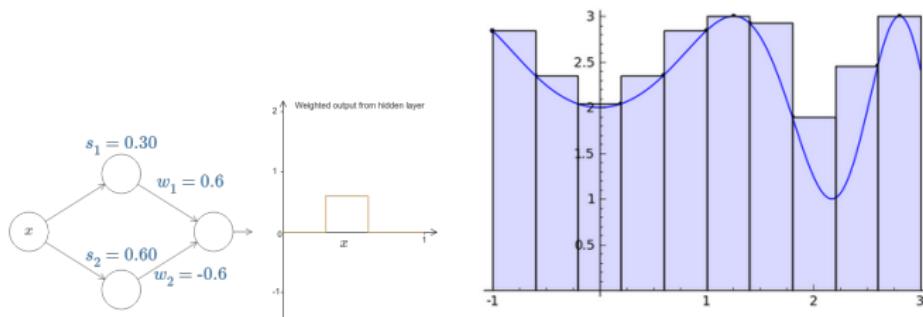
From shallow to deep NNs

Suggested reading

# What's bad about shallow NNs?

From UAT, "... there exist an integer N, ...", but how large?

What happens in 1D?



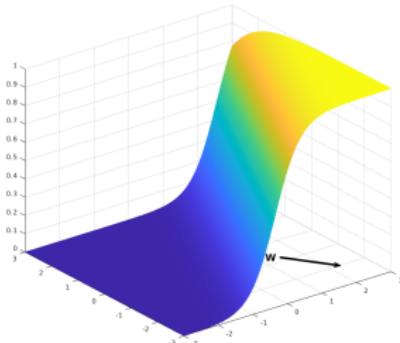
Assume the target  $f$  is 1-Lipschitz, i.e.,  $|f(x) - f(y)| \leq |x - y|, \forall x, y \in \mathbb{R}$

For  $\varepsilon$  accuracy, need  $\frac{1}{\varepsilon}$  bumps

# What's bad about shallow NNs?

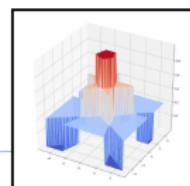
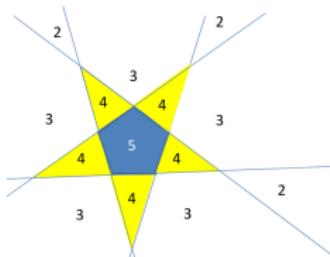
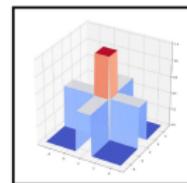
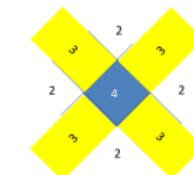
From UAT, "... there exist an integer N, ...", but how large?

What happens in 2D? Visual proof in 2D first



$$\sigma(w^T x + b), \sigma \text{ sigmod}$$

approach 2D step function when  
making  $w$  large



Credit: CMU 11-785

# Visual proof for 2D functions

Keep increasing the number of step functions that are distributed evenly ...

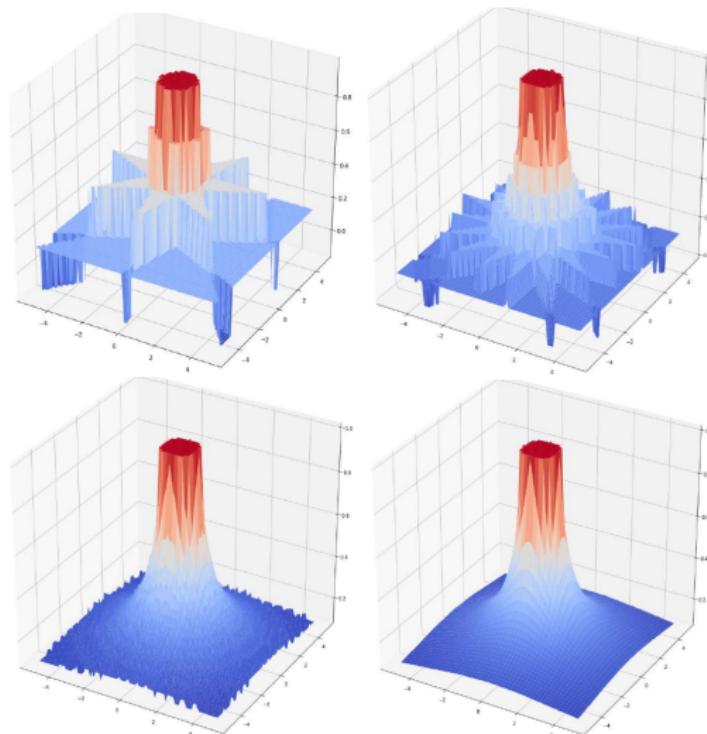


Image Credit: CMU 11-785

# What's bad about shallow NNs?

From UAT, "... there exist an integer N, ...", but how large?

What happens in 2D?

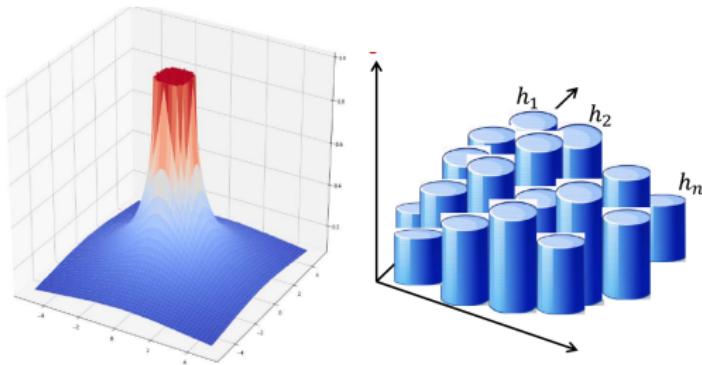


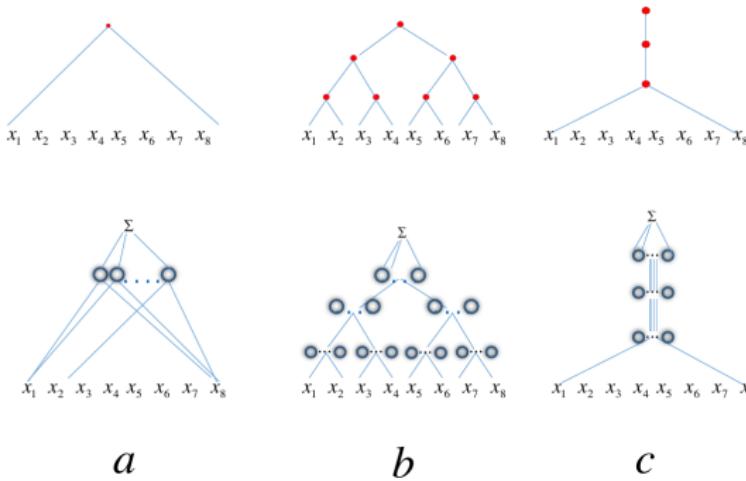
Image Credit: CMU 11-785

Assume the target  $f$  is 1-Lipschitz, i.e.,  $|f(\mathbf{x}) - f(\mathbf{y})| \leq \|\mathbf{x} - \mathbf{y}\|_2, \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^2$

For  $\varepsilon$  accuracy, need  $O(\varepsilon^{-2})$  bumps. What about the  $n$ -D case?  $O(\varepsilon^{-n})$ .

# What's good about deep NNs?

- Learn Boolean functions ( $f : \{+1, -1\}^n \mapsto \{+1, -1\}$ ): DNNs can have #nodes linear in  $n$ , whereas 2-layer NN needs exponential nodes
- What general functions set deep and shallow NNs apart?



A family: compositional function [Poggio et al., 2017]

## Compositional functions

$$f(x_1, \dots, x_8) = h_3(h_{21}(h_{11}(x_1, x_2), h_{12}(x_3, x_4)), \\ h_{22}(h_{13}(x_5, x_6), h_{14}(x_7, x_8))) \quad (4)$$

$W_m^n$ : class of  $n$ -variable functions with partial derivatives up to  $m$ -th order,  
 $W_m^{n,2} \subset W_m^n$  is the compositional subclass following binary tree structures

**Theorem 1.** Let  $\sigma : \mathbb{R} \rightarrow \mathbb{R}$  be infinitely differentiable, and not a polynomial. For  $f \in W_m^n$  the complexity of shallow networks that provide accuracy at least  $\epsilon$  is

$$N = \mathcal{O}(\epsilon^{-n/m}) \text{ and is the best possible.} \quad (5)$$

**Theorem 2.** For  $f \in W_m^{n,2}$  consider a deep network with the same compositional architecture and with an activation function  $\sigma : \mathbb{R} \rightarrow \mathbb{R}$  which is infinitely differentiable, and not a polynomial. The complexity of the network to provide approximation with accuracy at least  $\epsilon$  is

$$N = \mathcal{O}((n-1)\epsilon^{-2/m}). \quad (6)$$

from [Poggio et al., 2017] ; see Sec 4.2 of [Poggio et al., 2017] for lower bound

## Nonsmooth activation

A terse version of UAT

**Proposition 2.** *Let  $\sigma =: \mathbb{R} \rightarrow \mathbb{R}$  be in  $\mathcal{C}^0$ , and not a polynomial. Then shallow networks are dense in  $\mathcal{C}^0$ .*

Shallow vs. deep with ReLU activation

**Theorem 4.** *Let  $f$  be a  $L$ -Lipshitz continuous function of  $n$  variables. Then, the complexity of a network which is a linear combination of ReLU providing an approximation with accuracy at least  $\epsilon$  is*

$$N_s = \mathcal{O}\left(\left(\frac{\epsilon}{L}\right)^{-n}\right),$$

whereas that of a deep compositional architecture is

$$N_d = \mathcal{O}\left((n-1)\left(\frac{\epsilon}{L}\right)^{-2}\right).$$

# Width-bounded DNNs

Narrower than  $n + 4$  is fine

**Theorem 1** (Universal Approximation Theorem for Width-Bounded ReLU Networks). *For any Lebesgue-integrable function  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  and any  $\epsilon > 0$ , there exists a fully-connected ReLU network  $\mathcal{A}$  with width  $d_m \leq n + 4$ , such that the function  $F_{\mathcal{A}}$  represented by this network satisfies*

$$\int_{\mathbb{R}^n} |f(x) - F_{\mathcal{A}}(x)| dx < \epsilon. \quad (3)$$

But no narrower than  $n - 1$

**Theorem 3.** *For any continuous function  $f: [-1, 1]^n \rightarrow \mathbb{R}$  which is not constant along any direction, there exists a universal  $\epsilon^* > 0$  such that for any function  $F_A$  represented by a fully-connected ReLU network with width  $d_m \leq n - 1$ , the  $L^1$  distance between  $f$  and  $F_A$  is at least  $\epsilon^*$ :*

$$\int_{[-1,1]^n} |f(x) - F_A(x)| dx \geq \epsilon^*. \quad (5)$$

from [Lu et al., 2017]; see also [Kidger and Lyons, 2019]

Deep vs. shallow still active area of research

# Number one principle of DL

## Fundamental theorem of DNNs

Universal approximation theorems (UATs)

## Fundamental slogan of DL

Where there is a function, there is a NN...  
and go ahead fitting it!

# Outline

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Recap

Why should we trust NNs?

Visual proof of UAT

UAT in rigorous form

From shallow to deep NNs

Suggested reading

## Suggested reading

- Chap 4, Neural Networks and Deep Learning (online book)  
<http://neuralnetworksanddeeplearning.com/chap4.html>
- Why and when can deep-but not shallow-networks avoid the curse of dimensionality: A review. (by Poggio et al)  
<https://arxiv.org/abs/1611.00740> [Poggio et al., 2017]
- Expressivity of Deep Neural Networks (by Ingo Gühring, Mones Raslan, Gitta Kutyniok) <https://arxiv.org/abs/2007.04759> [Gühring et al., 2020]
- The Modern Mathematics of Deep Learning (by Julius Berner, Philipp Grohs, Gitta Kutyniok, Philipp Petersen)  
<https://arxiv.org/abs/2105.04026> [Berner et al., 2021]

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