

UAT: From Shallow to Deep

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- \LaTeX source of homework posted in Canvas (Thanks to Logan Stapleton!)

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Mind \LaTeX ! Mind your math!

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Math: Sophisticated mathematical expressions make a paper look technical and make the authors appear knowledgeable and "smart".

Plots: ROC, PR, and other performance plots convey a sense of thoroughness. Standard deviation bars are particularly pleasing to a scientific eye.

Figures/Screenshots: Illustrative figures that express complex algorithms in terms of 3rd grade visuals are always a must. Screenshots of anecdotal results are also very effective.

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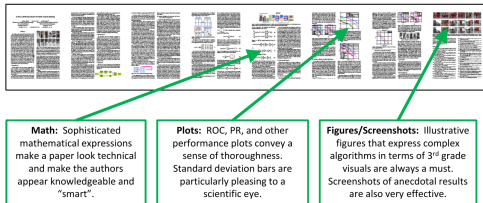
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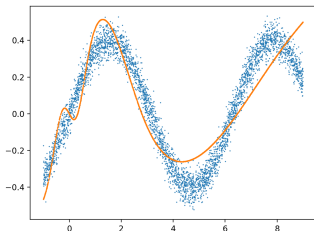


- Matrix Cookbook? Yes and No

Recap and more thoughts

From shallow to deep NNs

Supervised learning as function approximation



- Underlying true function: f_0
- Training data: $\mathbf{y}_i \approx f_0(\mathbf{x}_i)$
- Choose a family of functions \mathcal{H} , so that $\exists f \in \mathcal{H}$ and

f and f_0 are close

- **Approximation capacity:** \mathcal{H} matters (e.g., linear? quadratic? sinusoids? etc)
- **Optimization & Generalization:** how to find the best $f \in \mathcal{H}$ matters

We focus on approximation capacity now.

Approximation capacities of NNs

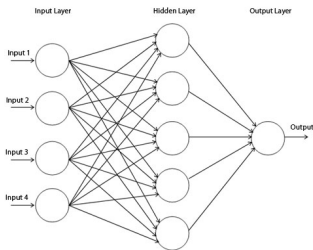
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Approximation capacities of NNs

- A single neuron has limited capacity
- Deep NNs with linear activation is no better
- Add in both depth and nonlinearity activation



two-layer network, linear
activation at output

universal approximation theorem

The 2-layer network can approximate **arbitrary continuous** functions **arbitrarily** well, provided that the hidden layer is **sufficiently wide**.

[A] universal approximation theorem (UAT)

Theorem (UAT, [Cybenko, 1989, Hornik, 1991])

Let $\sigma : \mathbb{R} \rightarrow \mathbb{R}$ be a *nonconstant, bounded, and continuous* function. Let I_m denote the m -dimensional *unit hypercube* $[0, 1]^m$. The space of *real-valued continuous functions on I_m* is denoted by $C(I_m)$. Then, given any $\varepsilon > 0$ and any function $f \in C(I_m)$, *there exist an integer N , real constants $v_i, b_i \in \mathbb{R}$ and real vectors $w_i \in \mathbb{R}^m$ for $i = 1, \dots, N$, such that we may define:*

$$F(x) = \sum_{i=1}^N v_i \sigma(w_i^T x + b_i)$$

as an approximate realization of the function f ; that is,

$$|F(x) - f(x)| < \varepsilon$$

for all $x \in I_m$.

Thoughts

- Approximate continuous functions with vector outputs, i.e.,
 $I_m \rightarrow \mathbb{R}^n$?

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... universality holds in modified form

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$$F(x) = \mathbf{w}^T \sigma(W_2 \sigma(W_1 \mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2) \quad \text{as} \quad \sum_k w_k g_k(\mathbf{x})$$

use w_k 's to linearly combine the same function

- **For geeks:** approximate both f and f' ?

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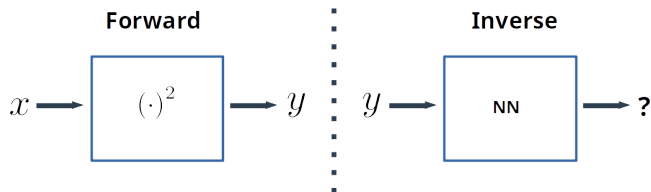
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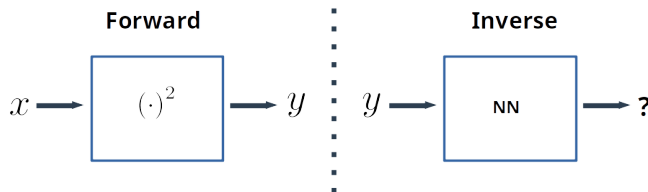
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- **For geeks:** approximate both f and f' ? check out [Hornik et al., 1990]

Learn to take square-root



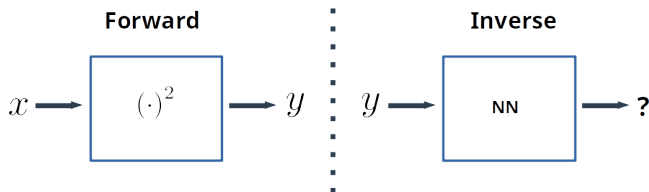
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Suppose we lived in a time square-root is not defined ...

- Training data: $\{x_i, x_i^2\}_i$, where $x_i \in \mathbb{R}$

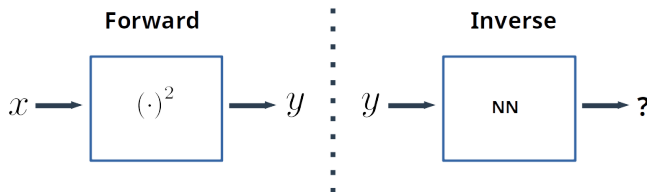
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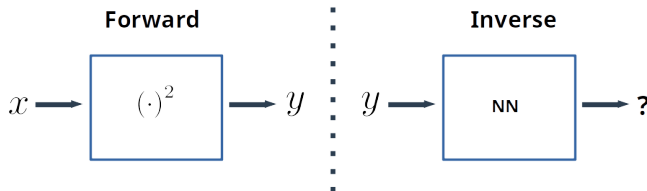
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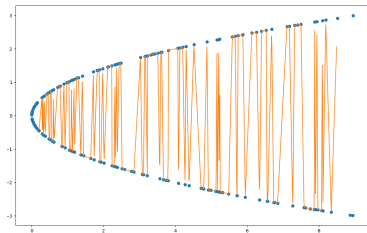
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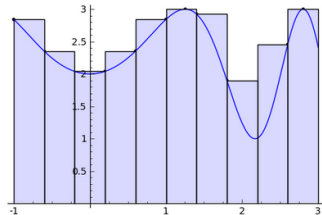
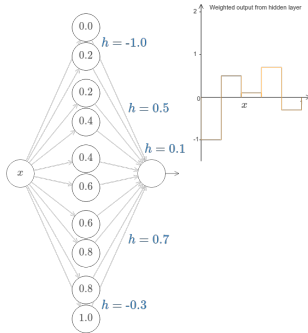
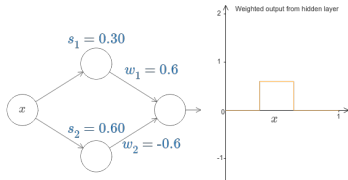
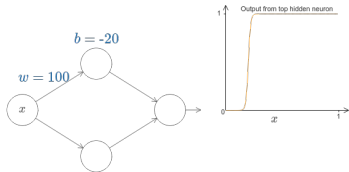


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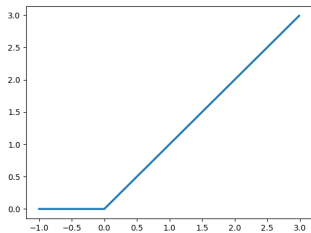
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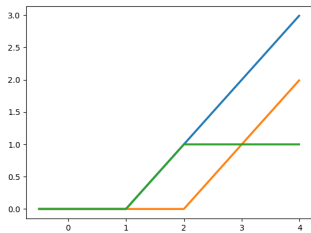
Visual “proof” of UAT



What about ReLU?

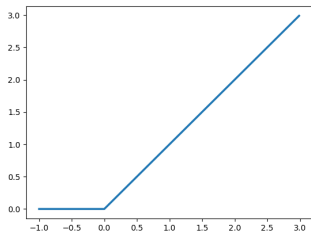


ReLU

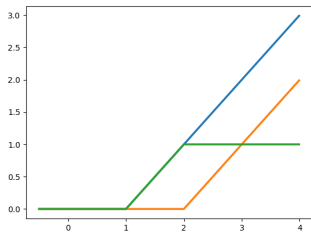


difference of ReLU's

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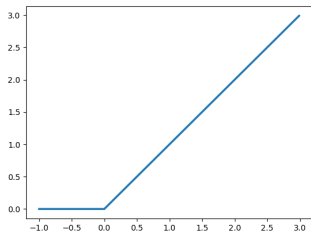
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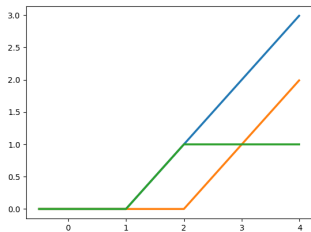
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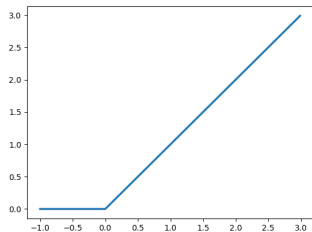


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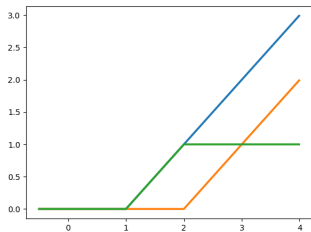
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How general σ can be?

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ReLU



difference of ReLU's

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How general σ can be? ... enough when σ not a polynomial
[Leshno et al., 1993]

Recap and more thoughts

From shallow to deep NNs

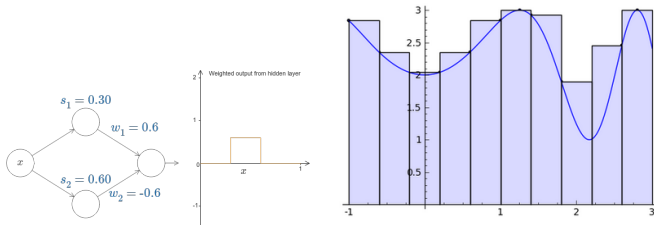
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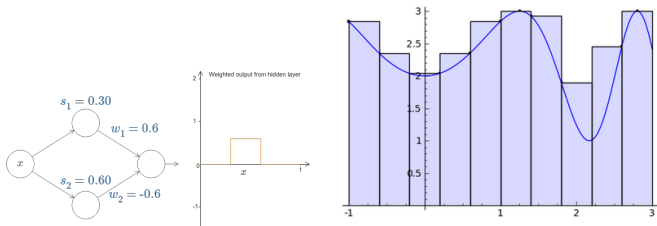
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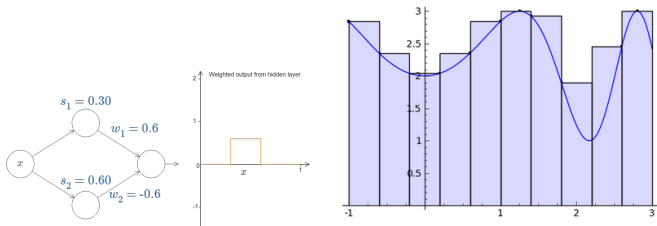


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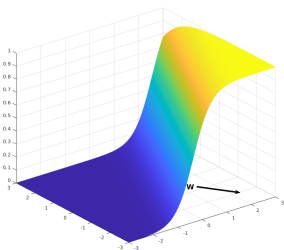
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What happens in $2D$? Visual proof in 2D first

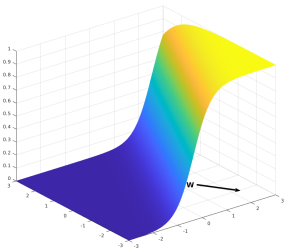


$\sigma(w^T x + b)$, σ sigmod

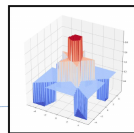
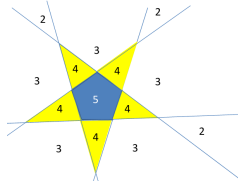
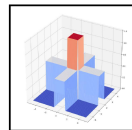
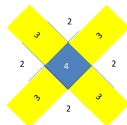
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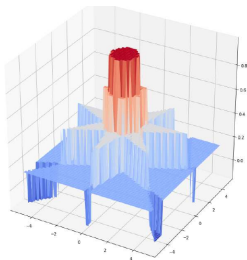
$\sigma(w^T x + b)$, σ sigmod
approach 2D step function when
making w large



Credit: CMU 11-785

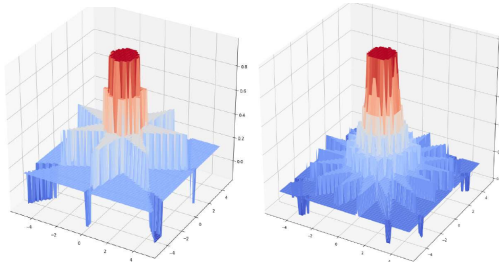
Visual proof for 2D functions

Keep increasing the number of step functions that are distributed evenly ...



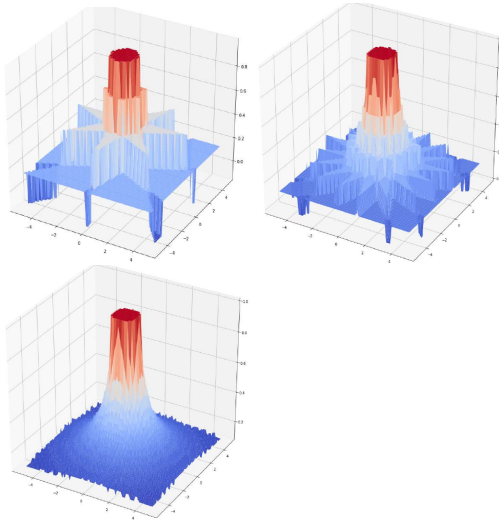
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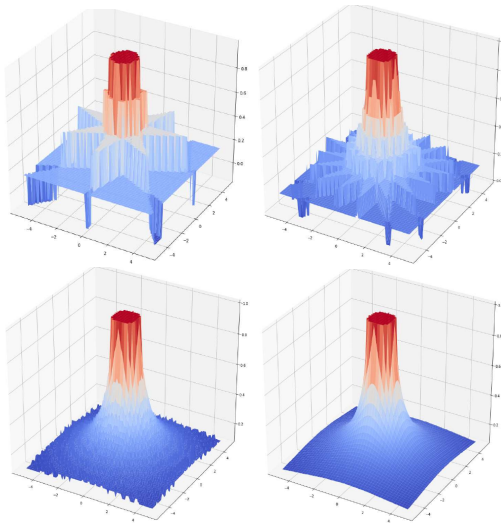


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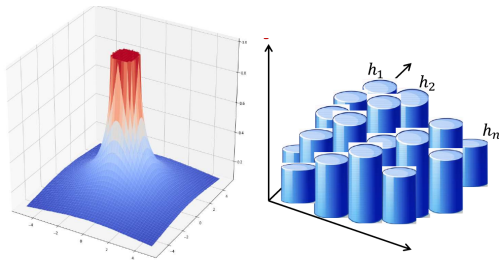


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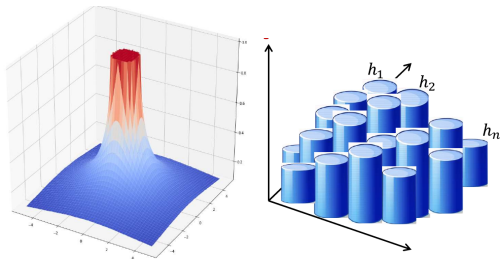


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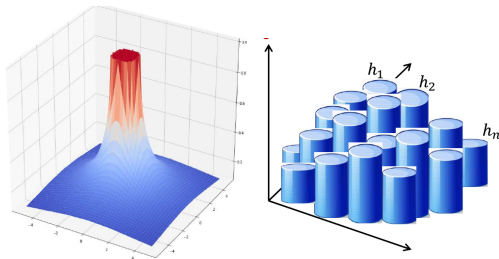


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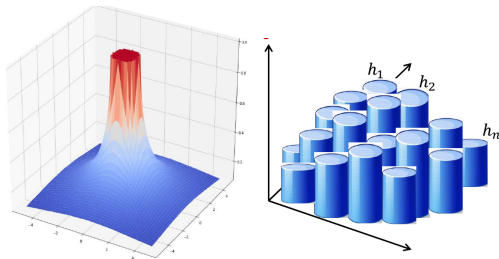


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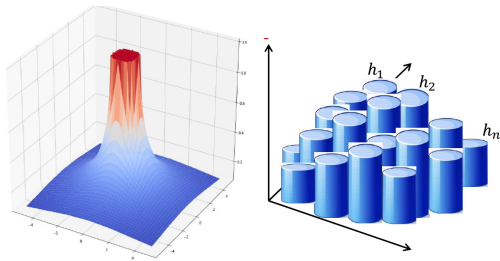


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For ε accuracy, need $O(\varepsilon^{-2})$ bumps. What about the n -D case? $O(\varepsilon^{-n})$.

What's good about deep NNs?

Learn Boolean functions ($f : \{+1, -1\}^n \mapsto \{+1, -1\}$): DNNs can have #nodes linear in n , whereas 2-layer NN needs exponential nodes (more in HW1)

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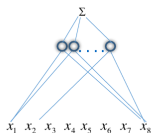
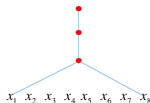
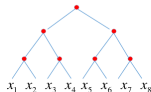
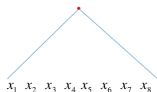
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What general functions set deep and shallow NNs apart?

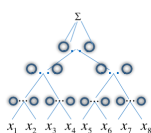
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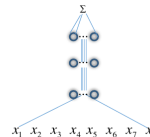
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a



b



c

A family: compositional function [Poggio et al., 2017]

Compositional functions

$$f(x_1, \dots, x_8) = h_3(h_{21}(h_{11}(x_1, x_2), h_{12}(x_3, x_4)), \\ h_{22}(h_{13}(x_5, x_6), h_{14}(x_7, x_8))) \quad (4)$$

W_m^n : class of n -variable functions with partial derivatives up to m -th order,
 $W_m^{n,2} \subset W_m^n$ is the compositional subclass following binary tree structures

Theorem 1. *Let $\sigma : \mathbb{R} \rightarrow \mathbb{R}$ be infinitely differentiable, and not a polynomial. For $f \in W_m^n$ the complexity of shallow networks that provide accuracy at least ϵ is*

$$N = \mathcal{O}(\epsilon^{-n/m}) \text{ and is the best possible.} \quad (5)$$

Theorem 2. *For $f \in W_m^{n,2}$ consider a deep network with the same compositional architecture and with an activation function $\sigma : \mathbb{R} \rightarrow \mathbb{R}$ which is infinitely differentiable, and not a polynomial. The complexity of the network to provide approximation with accuracy at least ϵ is*

$$N = \mathcal{O}((n-1)\epsilon^{-2/m}). \quad (6)$$

from [Poggio et al., 2017] ; see Sec 4.2 of [Poggio et al., 2017] for lower bound

Nonsmooth activation

A terse version of UAT

Proposition 2. *Let $\sigma =: \mathbb{R} \rightarrow \mathbb{R}$ be in C^0 , and not a polynomial. Then shallow networks are dense in C^0 .*

Nonsmooth activation

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Shallow vs. deep

Theorem 4. *Let f be a L -Lipshitz continuous function of n variables. Then, the complexity of a network which is a linear combination of ReLU providing an approximation with accuracy at least ϵ is*

$$N_s = \mathcal{O} \left(\left(\frac{\epsilon}{L} \right)^{-n} \right),$$

wheres that of a deep compositional architecture is

$$N_d = \mathcal{O} \left((n-1) \left(\frac{\epsilon}{L} \right)^{-2} \right).$$

Width-bounded DNNs

Narrower than $n + 4$ is fine

Theorem 1 (Universal Approximation Theorem for Width-Bounded ReLU Networks). *For any Lebesgue-integrable function $f: \mathbb{R}^n \rightarrow \mathbb{R}$ and any $\epsilon > 0$, there exists a fully-connected ReLU network \mathcal{A} with width $d_m \leq n + 4$, such that the function $F_{\mathcal{A}}$ represented by this network satisfies*

$$\int_{\mathbb{R}^n} |f(x) - F_{\mathcal{A}}(x)| dx < \epsilon. \quad (3)$$

But no narrower than $n - 1$

Theorem 3. *For any continuous function $f: [-1, 1]^n \rightarrow \mathbb{R}$ which is not constant along any direction, there exists a universal $\epsilon^* > 0$ such that for any function F_A represented by a fully-connected ReLU network with width $d_m \leq n - 1$, the L^1 distance between f and F_A is at least ϵ^* :*

$$\int_{[-1, 1]^n} |f(x) - F_A(x)| dx \geq \epsilon^*. \quad (5)$$

from [Lu et al., 2017]; see also [Kidger and Lyons, 2019]

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Deep vs. shallow still active area of research

Fundamental theorem of DNNs

Universal approximation theorems

Number one principle of DL

Fundamental theorem of DNNs

Universal approximation theorems

Fundamental slogan of DL

Where there is a mapping, there is a NN... and fit it!

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