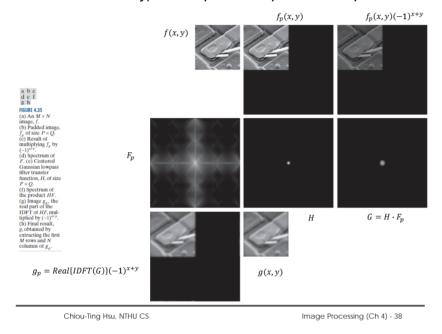
DIP Lab 3

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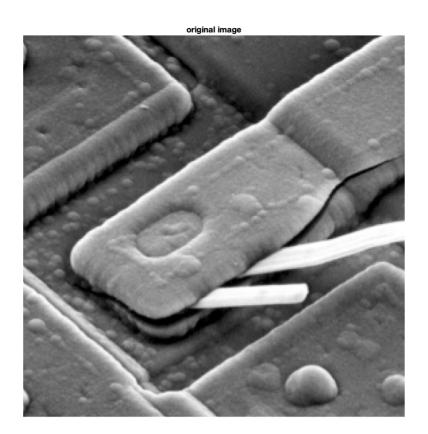
1. Proj.04-01 Two-Dimensional Fast Fourier Transform (40%)

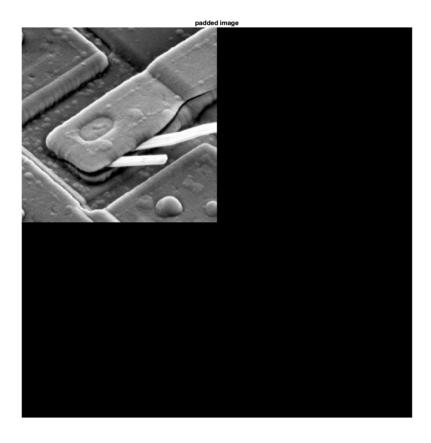
• Explanation:

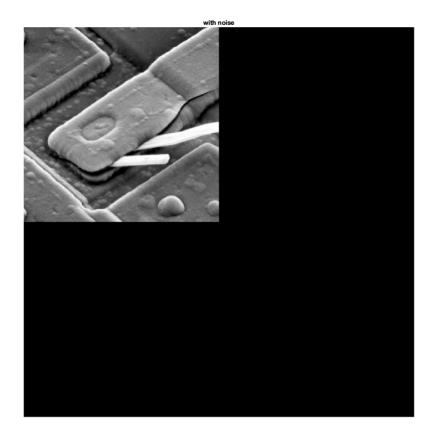
Do 2D-FFT manually, and repeat the process in p.38 of handout.

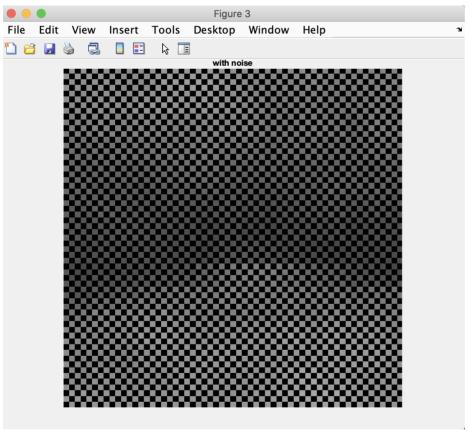


• Result:

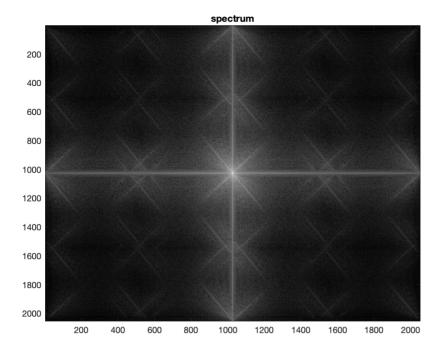


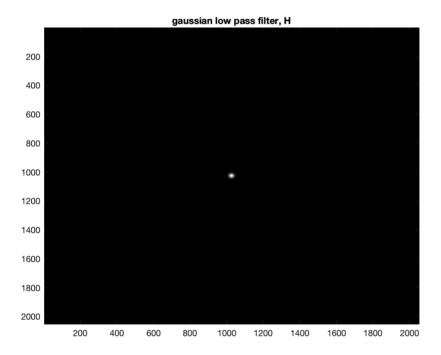


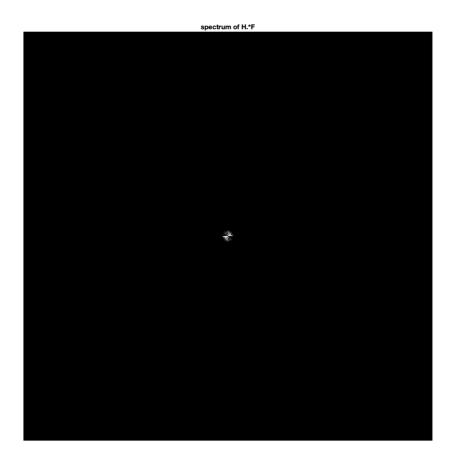


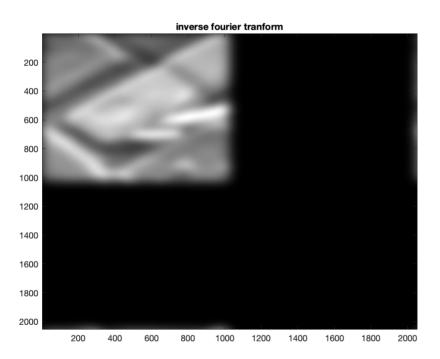


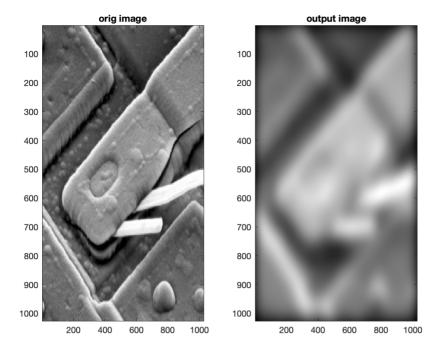
(Above: zoom in of noised image)











• Discussion:

First, implement 1D-FFT:

- Split the input vector into two, one contains odd elements of the input vector, and the other contains even elements of the input vector.
- Do DFT according to given equation to the two vectors:
 - 1-D DFT pair

-
$$F(u) = \sum_{x=0}^{M-1} f(x)e^{-\frac{j2\pi ux}{M}}, u = 0, 1, ..., M-1$$

Bind the two vectors. First half of the result(i): even_vector(i) + odd_vector(i) *
exp(-(1j2pi)/N); Second half of the result: even_vector(i-N/2) + odd_vector(i-N/2) *
exp(-(1j2pi)/N)

Then, implement 2D-FFT:

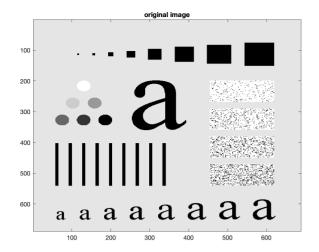
Split the 2D input image into two 1D-FFT.

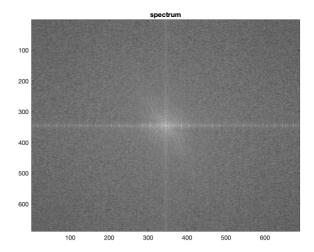
2. Proj.04-02 - Fourier Spectrum and Average Value (20%)

• Explanation:

Compute a given image's centered fourier spectrum, and calculate its average value. Compare it with the average value of the original image in spatial domain.

Result:





• Comparison:

Center frequency component is 207.3147, and the mean of spatial domain is also 207.3147.

One of the properties of 2D-DFT includes:

DC component

•
$$F(0,0) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) = \frac{1}{MN} \bar{f}(x,y)$$
 | $F(0,0)$ | is proportional to the average of $f(x,y)$

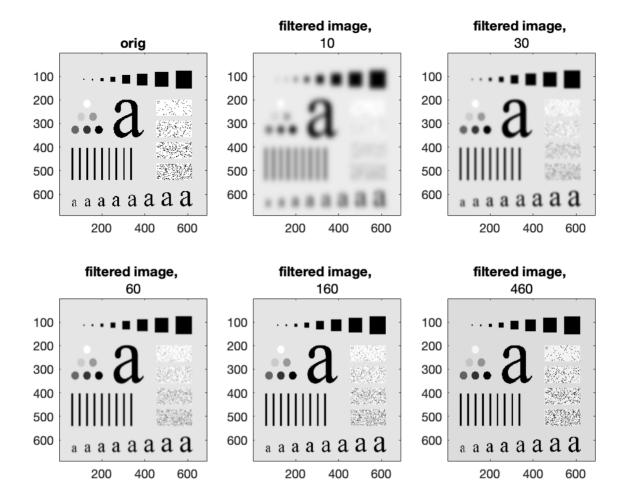
Since the center point of spectrum indicates the lowest frequency, which will be the average of the pixels in spatial domain. Higher frequency means above or below average.

3. Proj.04-03 Lowpass Filtering (20%)

• Explanation:

Implement the Gaussian lowpass filter, I/O as H = LowPassFilter(M, N, D0). M and N indicates the size of the filter, D0 as cut off frequency.

· Result:



Comparison:

Image becomes more blurred as the cut off frequency becomes lower, because the highter frequencies are filtered out.

4. Proj.04-04 Highpass Filtering (20%)

• Explanation:

Implement the Gaussian highpass filter. Basically it is the same program as Gaussian lowpass filter mentioned above.

Highpass filter

$$- H_{HP}(u, v) = 1 - H_{LP}(u, v)$$

Result:

