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     1
             import os
             #import tensorflow as tf
             from tensorflow.core.protobuf import saver_pb2
             import driving_data
             import model
    6
    7
             #https://stackoverflow.com/questions/37383812/tensorflow-module-object-has-no-attribute-placeholder
    8
             import tensorflow.compat.v1 as tf
    9
             tf.disable_v2_behavior()
   10
             LOGDIR = './save'
             sess = tf.InteractiveSession()
   14
             L2NormConst = 0.001
             train_vars = tf.trainable_variables()
   18
   20
             loss = tf.reduce\_mean(tf.square(tf.subtract(model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y)) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y)) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y)) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y))) + tf.add\_n([tf.nn.l2\_loss(v) \ for \ v \ in \ train\_vars]) * L2NormConstant (model.y\_, model.y\_, model
             train_step = tf.train.AdamOptimizer(1e-4).minimize(loss)
             sess.run(tf.initialize_all_variables())
   23
   24
             # create a summary to monitor cost tensor
             tf.summary.scalar("loss", loss)
   26
             # merge all summaries into a single op
   27
             merged_summary_op = tf.summary.merge_all()
   28
             saver = tf.train.Saver(write_version = saver_pb2.SaverDef.V1)
   30
             # op to write logs to Tensorboard
             logs_path = './logs'
             summary_writer = tf.summary.FileWriter(logs_path, graph=tf.get_default_graph())
   34
             epochs = 30
   36
             batch_size = 100
   38
             # train over the dataset about 30 times
   39
             for epoch in range(epochs):
   40
                for i in range(int(driving_data.num_images/batch_size)):
   41
                     xs, ys = driving_data.LoadTrainBatch(batch_size)
   42
                     train_step.run(feed_dict={model.x: xs, model.y_: ys, model.keep_prob: 0.5})
   43
                     if i % 10 == 0:
                          xs, ys = driving_data.LoadValBatch(batch_size)
   45
                          loss_value = loss.eval(feed_dict={model.x:xs, model.y_: ys, model.keep_prob: 0.5})
                         print("Epoch: %d, Step: %d, Loss: %g" % (epoch, epoch * batch_size + i, loss_value))
   47
                     # write logs at every iteration
   49
                      summary = merged\_summary\_op.eval(feed\_dict=\{model.x:xs, model.y\_: ys, model.keep\_prob: 1.0\})
                      summary_writer.add_summary(summary, epoch * driving_data.num_images/batch_size + i)
```

```
if i % batch_size == 0:
          if not os.path.exists(LOGDIR):
54
            os.makedirs(LOGDIR)
55
           checkpoint_path = os.path.join(LOGDIR, "model.ckpt")
56
           filename = saver.save(sess, checkpoint_path)
57
      print("Model saved in file: %s" % filename)
58
59
     print("Run the command line:\n" \
60
               "--> tensorboard --logdir=./logs " \setminus
               "\nThen open http://0.0.0.0:6006/ into your web browser")
61
```