

ID	Task Mode	Task Name	Duration	Start	Finish
1	🚀	Project Introduction	14 days	Fri 3/7/14	Tue 3/25/14
2	🚀	Collaborated Ideas for Approach	4 days	Fri 3/7/14	Wed 3/12/14
3	🚀	Modified SimpleRobotProgram.as	10 days	Wed 3/12/14	Mon 3/24/14
4	🚀	Implemented Sonar and made Robot Spin 180 degrees	0 days	Mon 3/24/14	Mon 3/24/14
5	🚀	Compiled Efficient Approaches	10 days	Thu 3/13/14	Tue 3/25/14
6	🚀	Finalized Algorithm for Robot Tasks	0 days	Tue 3/25/14	Tue 3/25/14
7	🚀	UART Implementation	11 days	Wed 3/26/14	Sat 4/5/14
8	🚀	Researched UART Communication	1 day	Wed 3/26/14	Wed 3/26/14
9	🚀	Drafted UART Communication Code	5 days	Wed 3/26/14	Sun 3/30/14
10	🚀	Debugging UART Code	6 days	Sun 3/30/14	Fri 4/4/14
11	🚀	UART Communication with Base Station	0 days	Sat 4/5/14	Sat 4/5/14
12	🚀	Odometry Implementatio	12 days	Sun 4/6/14	Sat 4/19/14
13	🚀	Analyzed Odometry Controls	1 day	Sun 4/6/14	Sun 4/6/14
14	🚀	Developed Odometry Co	2 days	Mon 4/7/14	Tue 4/8/14
15	🚀	Proposal Due	0 days	Wed 4/9/14	Wed 4/9/14
16	🚀	Debugging Odometry Co	8 days	Wed 4/9/14	Fri 4/18/14
17	🚀	Odometry Movement Successful	0 days	Sat 4/19/14	Sat 4/19/14
18	🚀	Testing and Executing	3 days	Sun 4/20/14	Wed 4/23/14
19	🚀	Testing Full Functionali	2 days	Sun 4/20/14	Mon 4/21/14
20	🚀	Final Demo	0 days	Wed 4/23/14	Wed 4/23/14