## 两对已匹配平面时的部分实验结果

目标函数为

$$J(\mathbf{\theta}) = \sum_{j=1}^{N^2} \frac{1}{n_j} \sum_{i=1}^{n_j} \frac{1}{(2\pi)^{d/2} |\mathbf{\Sigma}_i|^{1/2}} \exp\left[-\frac{1}{2} (\mathbf{p}_j^{'} - \mathbf{p}_i)^T \mathbf{\Sigma}_i^{-1} (\mathbf{p}_j^{'} - \mathbf{p}_i)\right]$$

其中,

$$\mathbf{p}_i = (x, y, z)$$

$$\mathbf{\theta} = \left(\alpha, \beta, \gamma, t_x, t_y, t_z\right)$$

$$^{2}\mathbf{p}_{j}^{'}=T\left( ^{2}\mathbf{p}_{j},\mathbf{\theta}\right)$$

 $n_i$ 为<sup>2</sup>**p**<sub>i</sub>邻域内点的个数。

对于两对已匹配平面

$$J(t_{2}) = \sum_{j=1}^{N^{2}} \frac{1}{n_{j}} \sum_{i=1}^{n_{j}} \frac{1}{(2\pi)^{d/2} |\Sigma_{i}|^{1/2}} \exp \left[ -\frac{1}{2} \mathbf{q} (i, j, t_{2})^{T} \mathbf{C}_{i}^{-1} \mathbf{q} (i, j, t_{2}) \right]$$

其中

$$\mathbf{q} = \mathbf{H} \cdot \left( {}^{2}\mathbf{p}_{j}^{'} - {}^{1}\mathbf{p}_{i} \right) = \mathbf{H}\mathbf{R} \cdot {}^{2}\mathbf{p}_{j} + \mathbf{H}\mathbf{t}_{1} \cdot {}^{2}\mathbf{p}_{j} + \mathbf{H}\mathbf{t}_{2} \cdot {}^{2}\mathbf{p}_{j} - \mathbf{H} \cdot {}^{1}\mathbf{p}_{i}$$

$$\mathbf{Ht}_2 = \begin{bmatrix} t_2 \\ 0 \\ 0 \end{bmatrix}$$

则其梯度向量与 Hessian 矩阵 (都为一维) 分别为

$$g = \frac{\partial J}{\partial t_{2}} = -\sum_{j=1}^{N^{2}} \frac{1}{n_{j}} \sum_{i=1}^{n_{j}} \frac{1}{(2\pi)^{d/2} |\mathbf{\Sigma}|^{1/2}} \mathbf{q}(i, j, t_{2})^{T} \mathbf{C}_{i}^{-1} \frac{\partial \mathbf{q}(i, j, t_{2})}{\partial t_{2}} \exp \left[ -\frac{1}{2} \mathbf{q}(i, j, t_{2})^{T} \mathbf{C}_{i}^{-1} \mathbf{q}(i, j, t_{2}) \right]$$

$$H = \frac{\partial^{2} J}{\partial t_{2}^{2}} = -\sum_{j=1}^{N^{2}} \frac{1}{n_{j}} \sum_{i=1}^{n_{j}} \frac{1}{\left(2\pi\right)^{d/2} \left|\mathbf{\Sigma}_{i}\right|^{1/2}} \exp \left[-\frac{1}{2} \mathbf{q}\left(i, j, t_{2}\right)^{T} \mathbf{C}_{i}^{-1} \mathbf{q}\left(i, j, t_{2}\right)^{T} \mathbf{C}_{i}^{-1} \frac{\partial^{2} \mathbf{q}\left(i, j, t_{2}\right)}{\partial t_{2}^{2}} - \left(\frac{\partial \mathbf{q}\left(i, j, t_{2}\right)}{\partial t_{2}}\right)^{T} \mathbf{C}_{i}^{-1} \frac{\partial \mathbf{q}\left(i, j, t_{2}\right)}{\partial t_{2}} + \left(\mathbf{q}\left(i, j, t_{2}\right)^{T} \mathbf{C}_{i}^{-1} \frac{\partial \mathbf{q}\left(i, j, t_{2}\right)}{\partial t_{2}}\right)^{2} \right]$$

其中

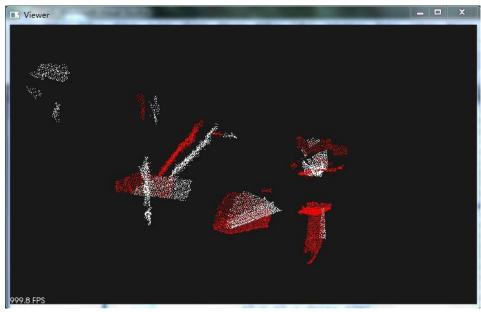
$$\frac{\partial \mathbf{q}(i, j, t_2)}{\partial t_2} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

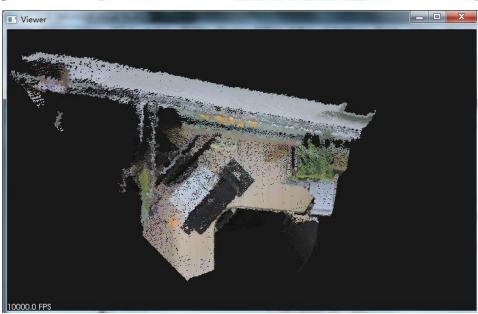
优化用 Newton-Raphson 算法。 初值为 0,迭代 5 次后收敛:

t2	0	0.0145813	0.0328292	0.0622077	0.101979
J	1.0172	1.01822	1.01861	1.0172	1.01574
Gradient	7.33636	9.64707	17.1325	27.7926	-1.86055
Hessian	-2515.67	-2643.34	-2915.82	-3494.09	-3556.76
Delta_t2	0.00291626	0.00364958	0.00587569	0.00795418	-0.0005231

选择匹配平面附近一定区域(0.1m~0.3m)内的点集。

优化前(已经过平面匹配):





## 优化后:

