
























Initial Bill of Materials - Software

1. Estimated number of lines of code ~ 4000
2. Estimated number of source files: ~ 23
3. List of envisaged source files:

	actions.cc
	actions.h
	actuators.cc
	actuators.h
	colour_sensor.cc
	colour_sensor.h
	distance_sensor.cc
	distance_sensor.h
	ir_receiver.cc
	ir_receiver.h
	ir_transmitter.cc
	ir_transmitter.h
	line_sensors.cc
	line_sensors.h
	main.cc
	motors.cc
	motors.h
	navigation.cc
	navigation.h
	robot.cc
	robot.h
	sorting_motor.cc
	sorting_motor.h