

Posterior Predictive Distribution

To make *predictions* using θ in our coin tossing example, we can use

$$P(\text{heads} \mid D) = \int_{\theta} P(\text{heads}, \theta \mid D) d\theta = \int_{\theta} P(\text{heads} \mid \theta, D) P(\theta \mid D) d\theta = \int_{\theta} \theta P(\theta \mid D) d\theta$$

Here, we used the fact that we defined $P(\text{heads}) = \theta$ and that $P(\text{heads}) = P(\text{heads} \mid D, \theta)$ (this is only the case for coin flipping - not in general).

In general, the posterior predictive distribution is

$$P(Y \mid D, X) = \int_{\theta} P(Y, \theta \mid D, X) d\theta = \int_{\theta} P(Y \mid \theta, D, X) P(\theta \mid D) d\theta$$

Unfortunately, the above is generally *intractable* in closed form and sampling techniques, such as Monte Carlo approximations, are used to approximate the distribution.

Machine Learning and estimation

In supervised Machine learning you are provided with training data D . You use this data to train a model, represented by its parameters θ . With this model you want to make predictions on a test point x_t .

- **MLE** Prediction: $P(y|x_t; \theta)$ Learning: $\theta = \operatorname{argmax}_{\theta} P(D; \theta)$. Here θ is purely a model parameter.
- **MAP** Prediction: $P(y|x_t, \theta)$ Learning: $\theta = \operatorname{argmax}_{\theta} P(\theta \mid D) \propto P(D \mid \theta) P(\theta)$. Here θ is a random variable.
- **"True Bayesian"** Prediction: $P(y|x_t, D) = \int_{\theta} P(y|\theta) P(\theta \mid D) d\theta$. Here θ is integrated out - our prediction takes all possible models into account.