

ELEC207 - Instrumentation & Control

Part-A: Instrumentation

Problem Class 4

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Lecture schedule:

Monday 1700-1800 (CHAD-CHAD) Thursday 1400-1500 (CTH-LTA)

Office Location: Room 513, Electrical Engineering





- Exam questions:
 - Transient analysis
 - Accelerometer
 - Interference and Noise



Sketch and briefly describe the step response of a second order system when:

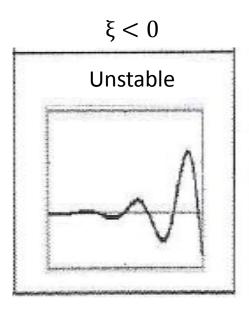
- 1. $\xi = 0$
- 2. $\xi < 0$,

where ξ is the damping ratio of the second order system.

Step Response $\begin{bmatrix} 2 \\ 1.8 \\ - \\ 1.6 \\ - \\ 1.4 \\ - \\ 1.2 \\ - \\ 0.8 \\ - \\ 0.6 \\ - \\ 0.4 \\ - \\ 0.2 \\ - \end{bmatrix}$

Time (sec.)

(4 marks)



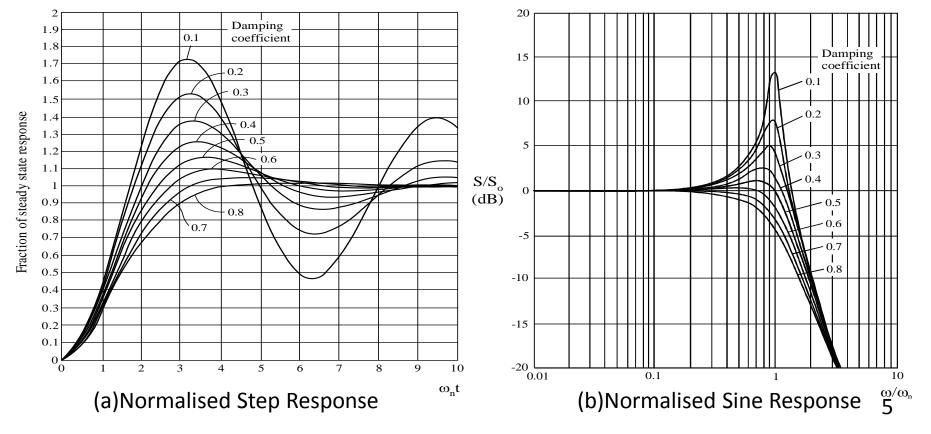


- a) Sketch a diagram to show the main internal components of a servo accelerometer. With reference to this diagram, explain how the servo accelerometer is able to produce an electrical output in response to an applied acceleration. (10 marks)
- b) What are the advantages of the servo accelerometer. (5 marks)

See slides 17-19, Lecture 11



Q) A servo accelerometer with natural resonant angular frequency ω_n = 100rad/s, damping coefficient ξ = 0.4 and low frequency sensitivity 3V/g is subject to both sinusoidal and step accelerations. With reference to the normalised dynamic response curves shown in figures (a) and (b), determine:





- (i) the *peak-to-peak* output voltage corresponding to an applied sinusoidal acceleration of amplitude 2g and angular frequency 80 rad/s. (5 marks)
- (ii) the magnitude of the peak output voltage produced during the transient for an applied step acceleration of 5g. (4 marks)
- (iii) the time taken for the output voltage to reach its first maximum for an applied step acceleration. (4 marks)
- (iv) the time for the output to settle within 5% of its final value for an applied step acceleration. (4 marks)





(i) the *peak-to-peak* output voltage corresponding to an **applied sinusoidal acceleration** of amplitude 2g and angular frequency 80 rad/s. **(5 marks)**

Given:
$$\omega_n = 100 \text{ rad/s}, \ \xi = 0.4 \text{ and } S_0 = 3 \text{ V/g}$$
 $\omega = 80 \text{ rad/s},$

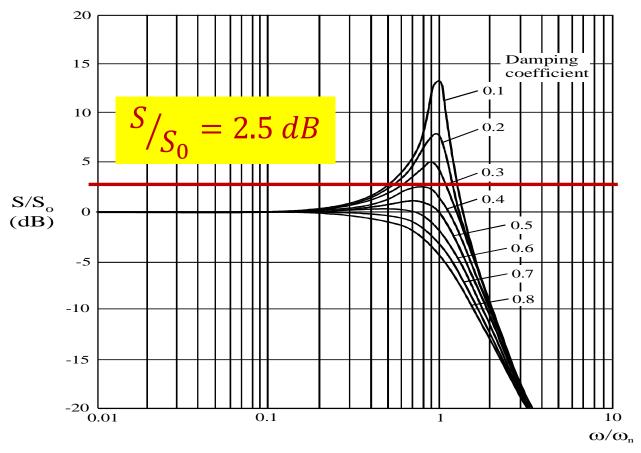
Required: $V_{p-p} = ?$

(Three step solution)

Solution



I. Find the value of S/S_0 (dB) from the curve corresponding to ξ =0.4.



 $20 \times \log_{10}(S/S_0) = 2.5 \text{ dB}$ (reading from the graph)

Solution



II. Find the value of S (Do not forget to convert the decibels!)

 $20 \times \log_{10} (S/S_0) = 2.5 \text{ dB}$ (reading from the graph)

$$S/S_0 = 10^{2.5/20} = 1.33$$

$$S_0 = 3 \text{ V/g (given)}$$

$$S = 3 * 1.33$$

$$S = 3.99 \, V/g$$

Solution



III. Find V_{p-p}

$$S = 3.99 \, V/g$$

Output voltage = S * input accelration

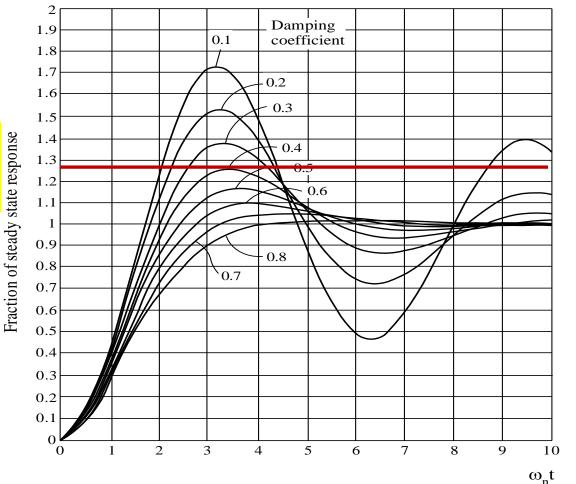
input accelration = 2g (given)

Output voltage = 3.99 * 2 = 7.98 V

$$V_{p-p} = 7.98 * 2 = 15.96 \text{ V}$$



(ii) the magnitude of the peak output voltage produced during the transient for an applied step acceleration of 5g. (4 marks)







(ii) the magnitude of the peak output voltage produced during the transient for an applied step acceleration of 5g. (4 marks)

$$\frac{s}{s_0} = 1.25$$
 (from graph)

$$S_0 = 3 \text{ V/g (given)}$$

$$S = 3 * 1.25$$

$$S = 3.75 \text{ V/g}$$

Output voltage = S * input acceleration

Output voltage = 3.75 * 5 = 18.75 V





(iii) the time taken for the output voltage to reach its first maximum for an applied step acceleration. (4 marks)

$$T_p = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}}$$

Slides 17-19, Lecture 10

 $T_p = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}}$ $T_p \text{ is the time at which the first accillation neak occurs.}$ oscillation peak occurs.

$$T_p = \frac{\pi}{100\sqrt{(1-(0.4)^2)}}$$
 $\omega_n = 100 \text{ rad/s}$

$$T_p = 34.3 \, \text{ms}$$





(iv) the time for the output to settle within 5% of its final value for an applied step acceleration. (4 marks)

$$e^{-\zeta.\omega_n t} = 0.05$$

Slides 17-19, Lecture 10

$$e^{-(0.4)(100)t} = 0.05$$

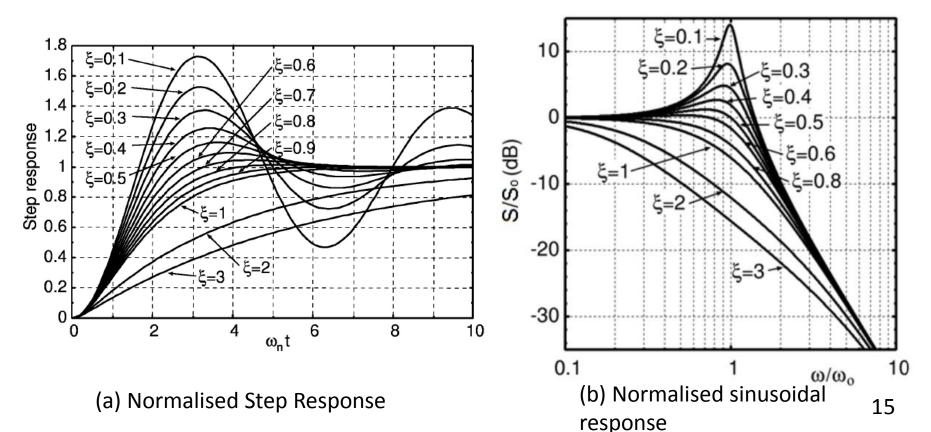
$$-(0.4)(100)t = -2.9957$$

$$t = \frac{2.9957}{40}$$

$$t = 74.9 \, \text{ms}$$



Q) A servo accelerometer with natural resonant angular frequency ω_n = 120 rad/s, damping coefficient ξ = 0.2 and low frequency sensitivity 3 V/g is subject to both sinusoidal and step accelerations. With reference to the normalised dynamic response curves shown in figures (a) and (b), determine:





- (i) the *peak-to-peak* output voltage corresponding to an applied **sinusoidal acceleration** of amplitude 2 g and angular frequency 108 rad/s. **(3 marks)**
- (ii) the magnitude of the peak output voltage produced during the transient for an applied **step acceleration** of 7g. **(3 marks)**
- (iii) the time taken for the output voltage to reach its first maximum for an applied **step acceleration**. **(3 marks)**

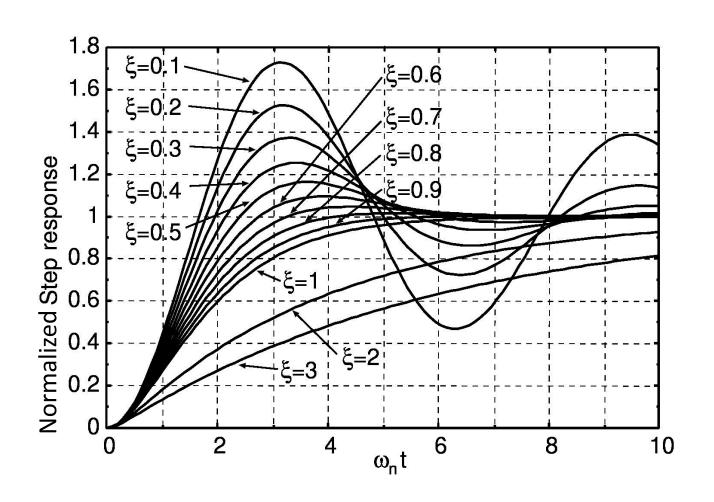




Q. During a test measurement, a **step acceleration** of 10 g was applied to a servo accelerometer. A damped oscillatory output was observed during which the output voltage of the accelerometer reached a peak voltage of 19 V at the first overshoot, occurring 8 ms after the application of the step. The output voltage eventually settled to 15 V.

With reference to the normalised step response curves shown in Figure (next slide), <u>determine the low frequency sensitivity</u> (in V/g), <u>the natural resonance frequency (in Hz) and the damping coefficient of the accelerometer.</u>







Given:

- Step acceleration = 10 g
- Steady state voltage (V_S) = 15 V
- Peak output voltage (V_P) = 19 V
- Time of first oscillation peak (T_P) = 8 ms

Find:

- Steady state sensitivity (S_0) (Low frequency sensitivity)
- Natural resonance frequency (f_n)
- Damping coefficient (ξ)





• Steady state sensitivity (S_0) (Low frequency sensitivity)

$$S_0 = \frac{steady\ state\ voltage\ (V_s)}{acceleration}$$

$$S_0 = \frac{15}{10} = 1.5 \frac{V}{g}$$

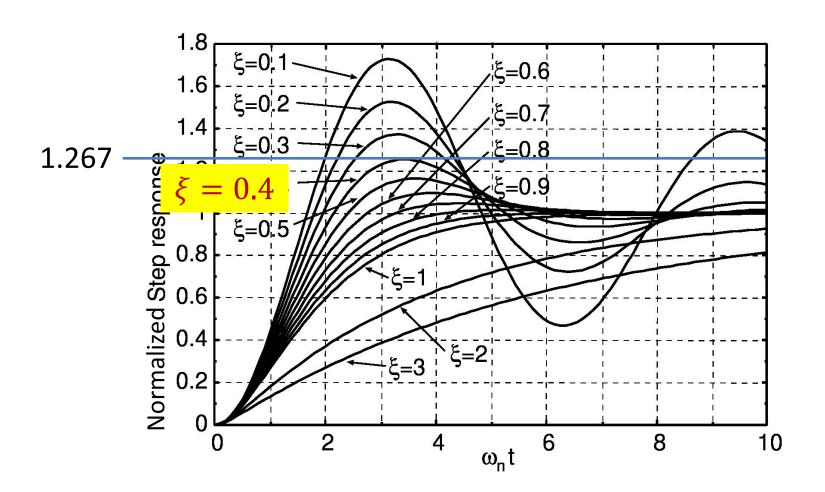
• Damping ratio (ξ)

$$-\frac{S}{S_0} = \frac{V_P}{V_S} = \frac{19}{15} = 1.267$$

From graph, find a curve with first peak at "1.267"



From graph, find a curve with first peak at "1.267"





• Natural resonance frequency $(f_n) = ?$

$$T_p = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}}$$

 $T_p = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}}$ T_p is the time at which the first oscillation peak occurs.

$$T_p = \frac{\pi}{2\pi f_n \sqrt{1-\zeta^2}}$$

$$T_{p} = \frac{\pi}{2\pi f_{n}\sqrt{(1-\zeta^{2})}} \qquad f_{n} = \frac{\pi}{2\pi T_{p}\sqrt{(1-\zeta^{2})}}$$

$$f_n = \frac{1}{2(0.008)\sqrt{(1-0.4^2)}}$$

$$f_n = 68.19Hz$$

Interference and Noise



- a) Briefly describe the following two sources of noise in instrumentation systems: electrostatic and electromagnetic coupling. Use diagrams for illustration.
- b) Describe noise prevention methods to minimize the influence of noise due to electromagnetic (electrostatic) coupling. Use diagrams for illustration.

Electrostatic coupling: Slides 5-8 of Lecture 12

Electromagnetic coupling: Slides 11-13 of Lecture 12



Summary

Topics covered:

- ✓ Exam questions:
 - ✓ Transient analysis
 - ✓ Accelerometer
 - ✓ Interference and Noise

Next Lecture:

Revision class in semester 2 (TBA by Prof S. Maskell)