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Rui JIN

EDUCATION BACKGROUND

Zhejiang University, Hangzhou

Sep 2021-Mar 2024

- FAST Lab, College of Control Science and Engineering.
- MEng of Control Science and Engineering.
- GPA: 3.68/4, Postgraduate Recommendation (Ranking: 1/81).

Northwestern Polytechnical University, Xi'an

Sep 2017-Jun 2021

- School of Mechanical Engineering.
- BEng of Mechanical Design & Manufacturing and Their Automation.
- Comprehensive Ranking: 1/94 (1.1%), Average Score: 86.37 (13.4%).

PUBLICATIONS

GS-Planner: A Gaussian-Splatting-based Planning Framework for Active High-Fidelity Reconstruction

Rui Jin^{}, Yuman Gao^{*}, Haojian Lu, Fei Gao.*

∞ Accepted by *IROS 2024*

- Proposed the first active 3D reconstruction system using 3DGS with online evaluation.
- Designed a feedback strategy of online model-consistent completeness and quality evaluation.
- Devised a planning framework for active reconstruction and safe navigation in the 3DGS map.

Unmanned Aerial Vehicle Mediated Drug Delivery for First Aid ∞

Advanced Materials 2023

Sheng Tao^{}, Rui Jin^{*} (co-first author), et al, Fei Gao, Haojian Lu, Jichen Yu, Zhen Gu.*

(Frontispiece, IF: 29.4)

- Proposed a UAV-mediated first-aid system achieving autonomous administration of emergency medication without the involvement of bystander or the conscious patient.
- Designed a contact-triggered microneedle applicator capable of providing adequate force to insert microneedles upon contact with the skin, enabling fully autonomous first aid administration.

Canfly: A Can-sized Autonomous Mini Coaxial Helicopter ∞

IROS 2023

Neng Pan, Rui Jin, Chao Xu, Fei Gao.

- Presented hardware design and control strategy for a mini coaxial helicopter, which occupies 62% less collision area compared to the state-of-the-art autonomous mini quadrotor.

Adaptive Tracking and Perching for Quadrotor in Dynamic Scenarios ∞

T-RO 2024

Yuman Gao, Jialin Ji, Qianhao Wang, Rui Jin, Chao Xu, Fei Gao.

- UAV dynamic tracking and perching on 30 km/h high-speed SUV.
- UAV dynamic perching on high-speed 60-degree tilt plain.
- T-RO popular articles highest **Ranking No.5**, video with 35,000 views.

Other Publications

- Modeling and Force Control of a Variable-Length Continuum Robot with Variable Stiffness for Minimally Invasive Surgery, T-ASE 2024 (4th author)
- Soft Lightweight Small-Scale Parallel Robot With High-Precision Positioning, T-MECH 2023 (5th author)
- A Survey on Design, Actuation, Modeling, and Control of Continuum Robot, Cyborg and Bionic Systems 2022 (6th author, IF: 10.5)

INTERNSHIP EXPERIENCE

Skysys Intelligent Technology (SKYSYS)

- Research and Development Department

• Photovoltaic Cleaning Robot (Project Leader)

Aug 2023-Jan 2024

Proposed a UAV-based autonomous delivery system for deploying and retrieving cleaning robots on photovoltaic panels.

RESEARCH EXPERIENCES

Design, Modeling and Control of Miniature Coaxial Helicopter

Dec 2020-Nov 2023

- Proposed the hardware design and flight control algorithm for an autonomous coaxial dual-rotor UAV weighing 1.5 kg with a 33-minute endurance.
- Developed the flight control algorithm with a differential-flatness-based cascading controller and an actuator allocation algorithm based on quadratic programming to prevent actuator saturation.

Neural Collision Field for Efficient Trajectory Optimization for Mobile Robots

Jan 2023-Present

- Compressed a swept-volume-based continuous-time SDF into the neural network to enable efficient and accurate representation, and applied it to optimize quadrotor trajectories.
- Designed a progressive guidance training strategy, and a Level-of-Details sampling strategy to enhance network performance and training efficiency.

Nuclear Power Plant Autonomous Inspection Tracked Robot

Aug 2023-Dec 2023

- Engineered software algorithms enabling autonomous inspection, obstacle avoidance, and cross-platform capability for a nuclear power plant inspection tracked vehicle.

COMPETITION EXPERIENCES

China Robot Competition, Championship Prize (Top 1%)

2019

- Designed and built a transformer robot capable of transforming between vehicular and humanoid forms.

National 3D Innovative Design Competition, Top-tier Award of Shanxi Province (Top 3%)

2019

HONORS AND AWARDS

Outstanding Graduate of Northwestern Polytechnical University

2021

Interdisciplinary Contest In Modeling, Honorable Mention

2020

Fastgear Scholarship, Top-tier Prize (Top 1%)

2019

National Training Program of Innovation for Undergraduates, Outstanding Conclusion Award

2018&2019

Huawei Scholarship, First Prize (Top 1%)

2018

Northwestern Polytechnical University Scholarship, First Prize (Top 10%)

2017&2018&2019

SKILLS

Programming Skills

- C++, Python, MATLAB, ROS

Design Skills

- Solidworks, Altium Designer, Keyshot, Premiere

English proficiency

- IELTS: 7.0, GRE: 327, CET 6: 581

FAST Lab Video Account Management

- Produced video edits with over a million views