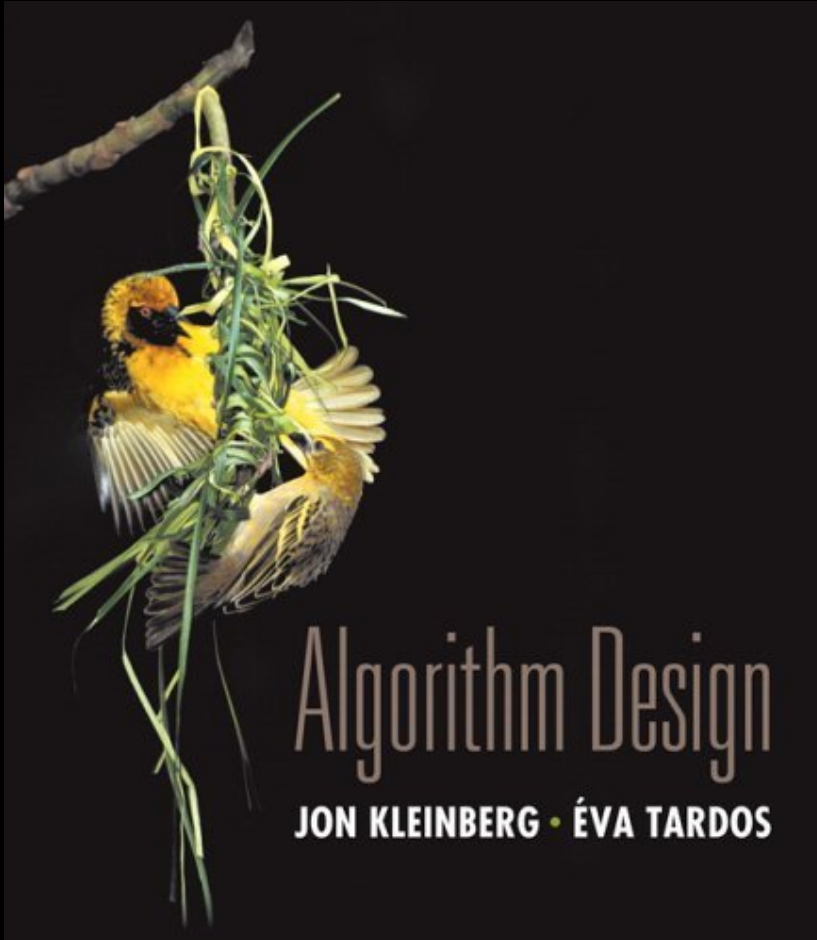


# Chapter 4

## Greedy Algorithms



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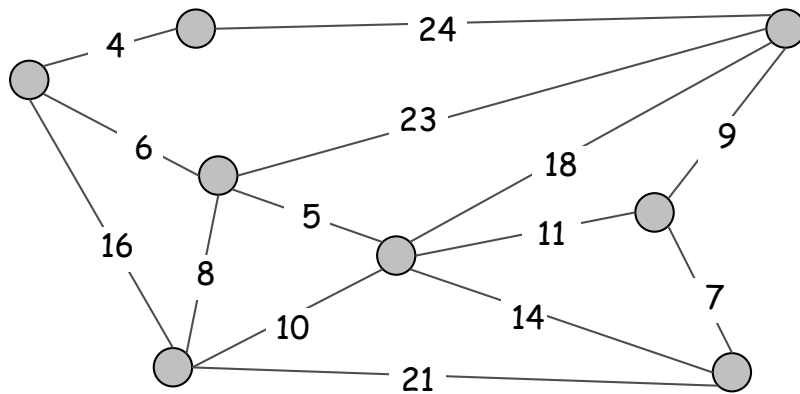
Acknowledgement: This lecture slide is revised and authorized from Prof. Kevin Wayne's Class  
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# Minimum Spanning Tree

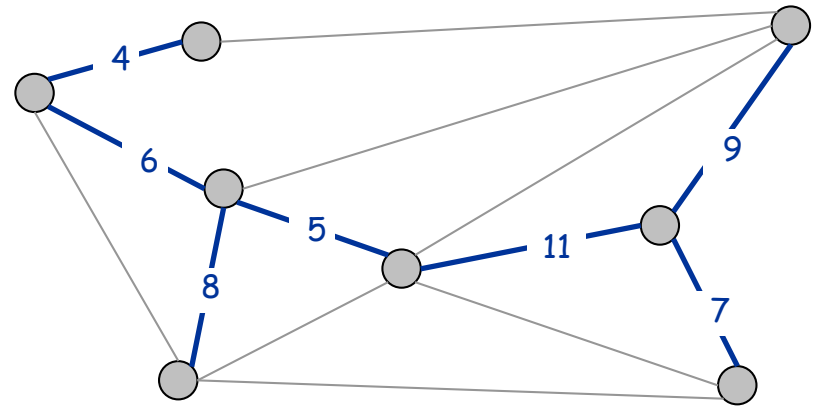
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# Minimum Spanning Tree

**Minimum spanning tree.** Given a connected graph  $G = (V, E)$  with real-valued edge weights  $c_e$ , an MST is a subset of the edges  $T \subseteq E$  such that  $T$  is a spanning tree whose sum of edge weights is minimized.



$G = (V, E)$



$T, \sum_{e \in T} c_e = 50$

**Cayley's Theorem.** There are  $n^{n-2}$  spanning trees of  $K_n$ .

↑  
can't solve by brute force

# Applications

MST is fundamental problem with diverse applications.

- Network design.
  - telephone, electrical, hydraulic, TV cable, computer, road
- Approximation algorithms for NP-hard problems.
  - traveling salesperson problem, Steiner tree
- Indirect applications.
  - max bottleneck paths
  - LDPC codes for error correction
  - image registration with Renyi entropy
  - learning salient features for real-time face verification
  - reducing data storage in sequencing amino acids in a protein
  - model locality of particle interactions in turbulent fluid flows
  - autoconfig protocol for Ethernet bridging to avoid cycles in a network
- Cluster analysis.

# Greedy Algorithms

**Kruskal's algorithm.** Start with  $T = \emptyset$ . Consider edges in ascending order of cost. Insert edge  $e$  in  $T$  unless doing so would create a cycle.

**Reverse-Delete algorithm.** Start with  $T = E$ . Consider edges in descending order of cost. Delete edge  $e$  from  $T$  unless doing so would disconnect  $T$ .

**Prim's algorithm.** Start with some root node  $s$  and greedily grow a tree  $T$  from  $s$  outward. At each step, add the cheapest edge  $e$  to  $T$  that has exactly one endpoint in  $T$ .

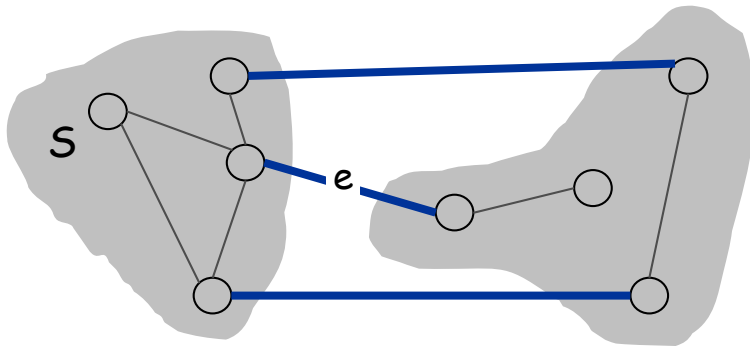
**Remark.** All three algorithms produce an MST.

# Greedy Algorithms

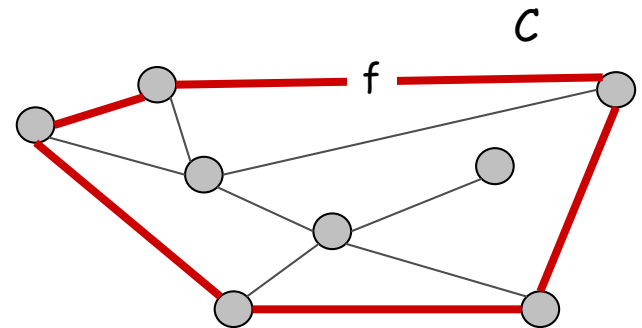
**Simplifying assumption.** All edge costs  $c_e$  are distinct.

**Cut property.** Let  $S$  be any subset of nodes, and let  $e$  be the min cost edge with exactly one endpoint in  $S$ . Then the MST contains  $e$ .

**Cycle property.** Let  $C$  be any cycle, and let  $f$  be the max cost edge belonging to  $C$ . Then the MST does not contain  $f$ .



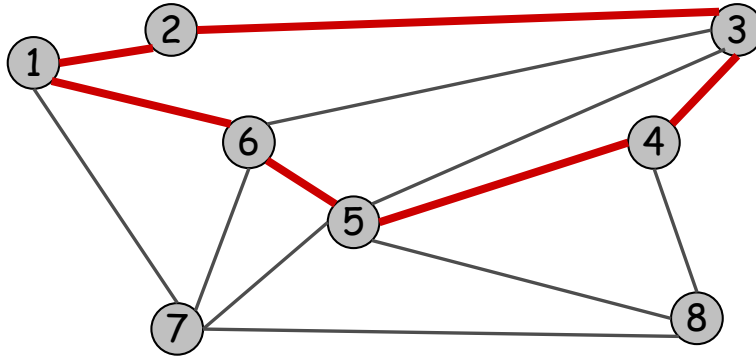
$e$  is in the MST



$f$  is not in the MST

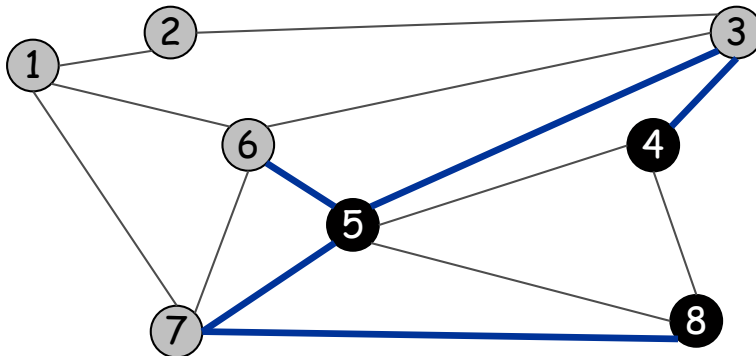
# Cycles and Cuts

**Cycle.** Set of edges the form  $a-b, b-c, c-d, \dots, y-z, z-a$ .



Cycle  $C = 1-2, 2-3, 3-4, 4-5, 5-6, 6-1$

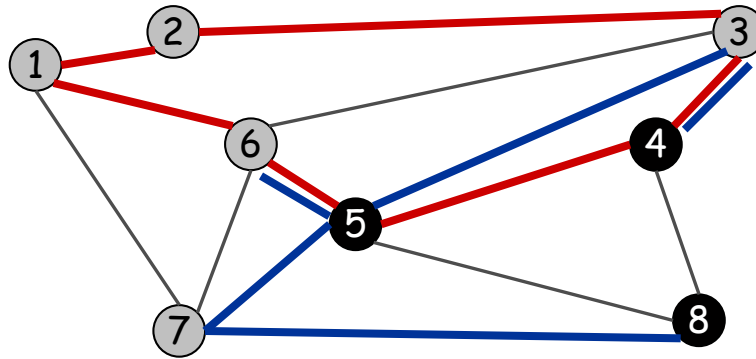
**Cutset.** A cut is a subset of nodes  $S$ . The corresponding cutset  $D$  is the subset of edges with exactly one endpoint in  $S$ .



Cut  $S = \{4, 5, 8\}$   
Cutset  $D = 5-6, 5-7, 3-4, 3-5, 7-8$

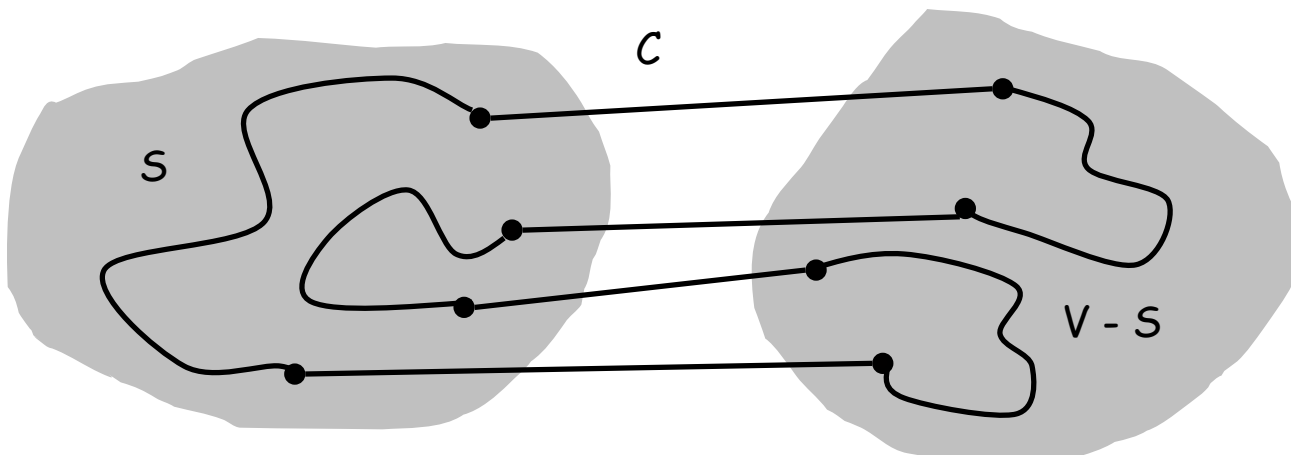
# Cycle-Cut Intersection

**Claim.** A cycle and a cutset intersect in an even number of edges.



Cycle  $C = 1-2, 2-3, 3-4, 4-5, 5-6, 6-1$   
Cutset  $D = 3-4, 3-5, 5-6, 5-7, 7-8$   
Intersection =  $3-4, 5-6$

**Pf.** (by picture)





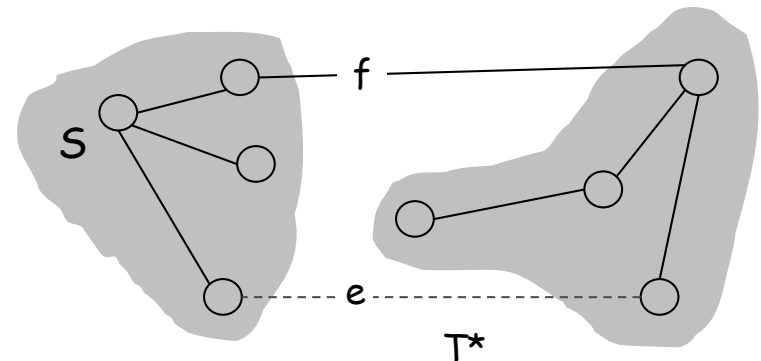
# Greedy Algorithms

**Simplifying assumption.** All edge costs  $c_e$  are distinct.

**Cut property.** Let  $S$  be any subset of nodes, and let  $e$  be the min cost edge with exactly one endpoint in  $S$ . Then the MST  $T^*$  contains  $e$ .

Pf. (exchange argument)

- Suppose  $e$  does not belong to  $T^*$ , and let's see what happens.
- Adding  $e$  to  $T^*$  creates a cycle  $C$  in  $T^*$ .
- Edge  $e$  is both in the cycle  $C$  and in the cutset  $D$  corresponding to  $S$   
 $\Rightarrow$  there exists another edge, say  $f$ , that is in both  $C$  and  $D$ .
- $T' = T^* \cup \{e\} - \{f\}$  is also a spanning tree.
- Since  $c_e < c_f$ ,  $\text{cost}(T') < \text{cost}(T^*)$ .
- This is a contradiction. ▀



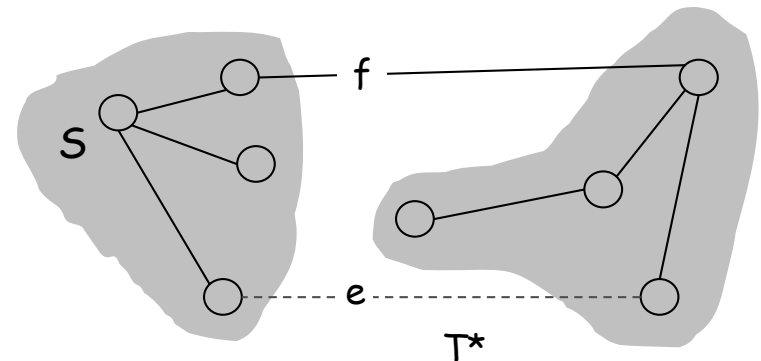
# Greedy Algorithms

**Simplifying assumption.** All edge costs  $c_e$  are distinct.

**Cycle property.** Let  $C$  be any cycle in  $G$ , and let  $f$  be the max cost edge belonging to  $C$ . Then the MST  $T^*$  does not contain  $f$ .

**Pf.** (exchange argument)

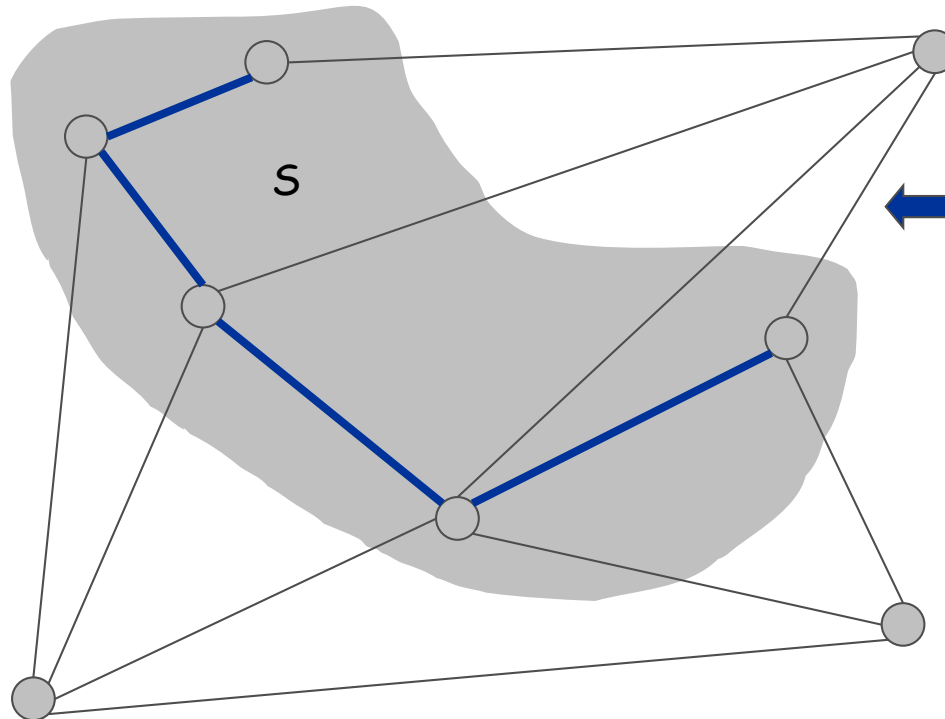
- Suppose  $f$  belongs to  $T^*$ , and let's see what happens.
- Deleting  $f$  from  $T^*$  creates a cut  $S$  in  $T^*$ .
- Edge  $f$  is both in the cycle  $C$  and in the cutset  $D$  corresponding to  $S$   
 $\Rightarrow$  there exists another edge, say  $e$ , that is in both  $C$  and  $D$ .
- $T' = T^* \cup \{e\} - \{f\}$  is also a spanning tree.
- Since  $c_e < c_f$ ,  $\text{cost}(T') < \text{cost}(T^*)$ .
- This is a contradiction. ▀



# Prim's Algorithm: Proof of Correctness

**Prim's algorithm.** [Jarník 1930, Dijkstra 1957, Prim 1959]

- Initialize  $S$  = any node.
- Apply cut property to  $S$ .
- Add min cost edge in cutset corresponding to  $S$  to  $T$ , and add one new explored node  $u$  to  $S$ .



# Implementation: Prim's Algorithm

**Implementation.** Use a priority queue.

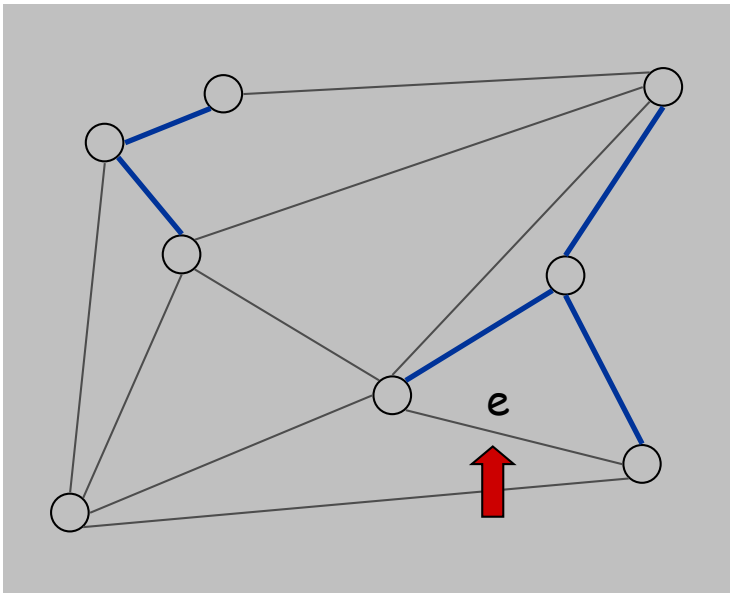
- Maintain set of explored nodes  $S$ .
- For each unexplored node  $v$ , maintain attachment cost  $a[v]$  = cost of cheapest edge  $v$  to a node in  $S$ .
- $O(n^2)$  with an array;  $O(m \log n)$  with a binary heap.

```
Prim(G, c) {  
    foreach ( $v \in V$ )  $a[v] \leftarrow \infty$   
    Initialize an empty priority queue  $Q$   
    foreach ( $v \in V$ ) insert  $v$  onto  $Q$   
    Initialize set of explored nodes  $S \leftarrow \phi$   
  
    while ( $Q$  is not empty) {  
         $u \leftarrow$  delete min element from  $Q$   
         $S \leftarrow S \cup \{u\}$   
        foreach (edge  $e = (u, v)$  incident to  $u$ )  
            if ( $(v \notin S)$  and ( $c_e < a[v]$ ))  
                decrease priority  $a[v]$  to  $c_e$   
    }  
}
```

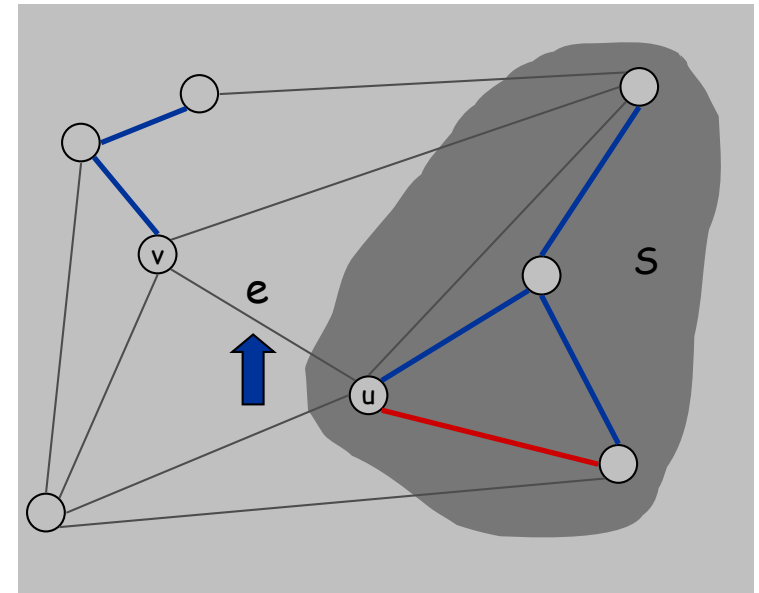
# Kruskal's Algorithm: Proof of Correctness

Kruskal's algorithm. [Kruskal, 1956]

- Consider edges in ascending order of weight.
- Case 1: If adding  $e$  to  $T$  creates a cycle, discard  $e$  according to cycle property.
- Case 2: Otherwise, insert  $e = (u, v)$  into  $T$  according to cut property where  $S$  = set of nodes in  $u$ 's connected component.



Case 1



Case 2

# Implementation: Kruskal's Algorithm

**Implementation.** Use the **union-find** data structure.

- Build set  $T$  of edges in the MST.
- Maintain set for each connected component.
- $O(m \log n)$  for sorting and  $O(m \underbrace{\alpha(m, n)}_{\text{essentially a constant}})$  for union-find.

$\swarrow$   $m \leq n^2 \Rightarrow \log m$  is  $O(\log n)$        $\underbrace{\hspace{1.5cm}}$  essentially a constant

```
Kruskal(G, c) {  
    Sort edges weights so that  $c_1 \leq c_2 \leq \dots \leq c_m$ .  
     $T \leftarrow \phi$   
  
    foreach ( $u \in V$ ) make a set containing singleton  $u$   
  
    for  $i = 1$  to  $m$       are  $u$  and  $v$  in different connected components?  
         $(u, v) = e_i$        $\swarrow$   
        if ( $u$  and  $v$  are in different sets) {  
             $T \leftarrow T \cup \{e_i\}$   
            merge the sets containing  $u$  and  $v$   
        }  
         $\swarrow$  merge two components  
    return  $T$   
}
```

# MST Algorithms: Theory

## Deterministic comparison based algorithms.

- $O(m \log n)$  [Jarník, Prim, Dijkstra, Kruskal, Boruvka]
- $O(m \log \log n)$ . [Cheriton-Tarjan 1976, Yao 1975]
- $O(m \beta(m, n))$ . [Fredman-Tarjan 1987]
- $O(m \log \beta(m, n))$ . [Gabow-Galil-Spencer-Tarjan 1986]
- $O(m \alpha(m, n))$ . [Chazelle 2000]

## Holy grail. $O(m)$ .

### Notable.

- $O(m)$  randomized. [Karger-Klein-Tarjan 1995]
- $O(m)$  verification. [Dixon-Rauch-Tarjan 1992]

### Euclidean.

- 2-d:  $O(n \log n)$ . compute MST of edges in Delaunay
- k-d:  $O(k n^2)$ . dense Prim