

ReLViT: Concept-guided Vision Transformer for Visual Relational Reasoning

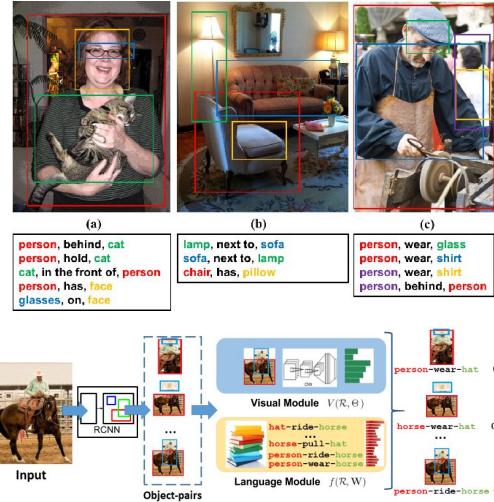
Xiaojian Ma¹, Weili Nie², Zhiding Yu², Huaizu Jiang³, Chaowei Xiao^{2,4},
Yuke Zhu^{2,5}, Song-Chun Zhu¹, Anima Anandkumar^{2,6}

¹UCLA ²NVIDIA ³Northeastern University ⁴ASU ⁵UT Austin ⁶Caltech

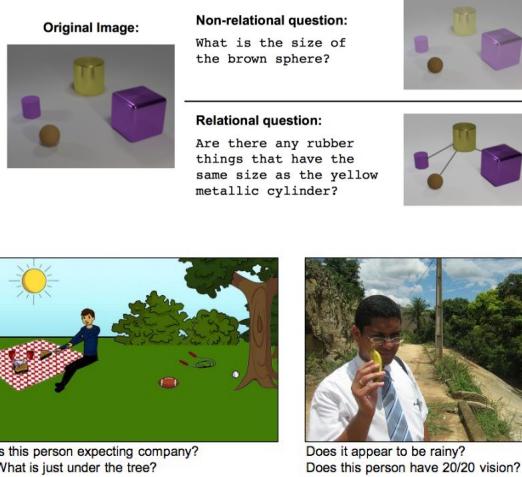


Motivation

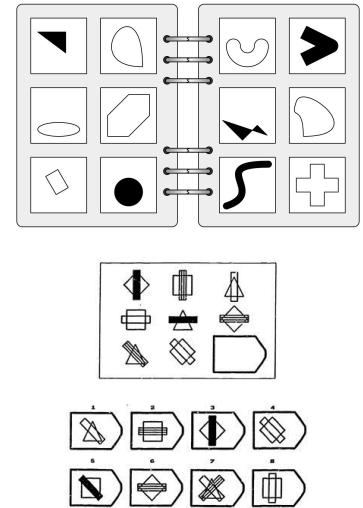
Visual Relational Reasoning: the niche of visual intelligence!



Visual Relationship Recognition



Visual Question Answering

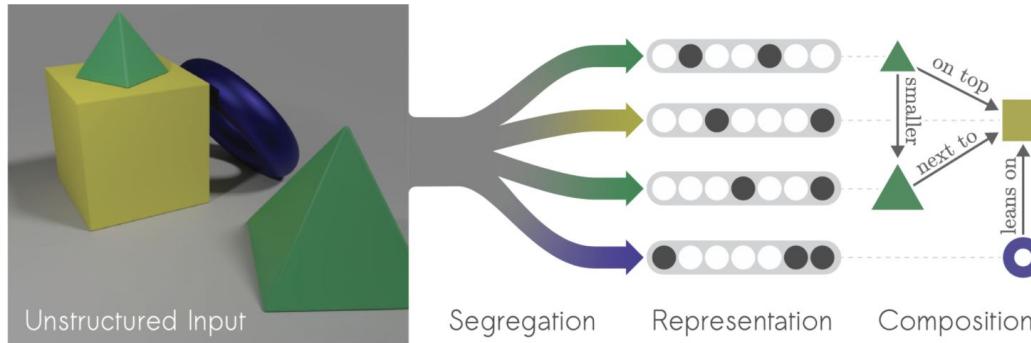


Abstract Visual Reasoning

Motivation

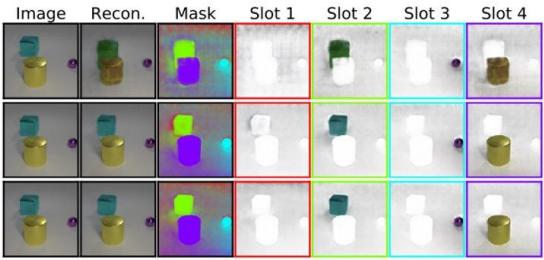
What makes Visual Relational Reasoning so challenging?

-> How do our humans perform visual reasoning?

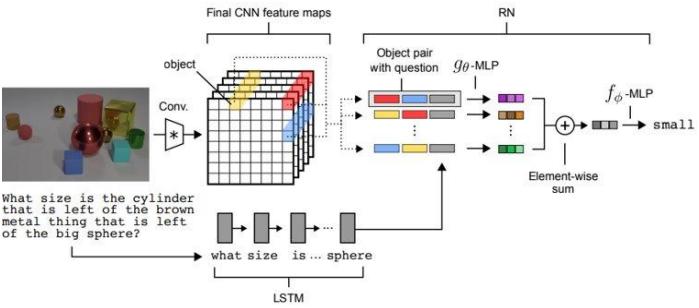


Motivation

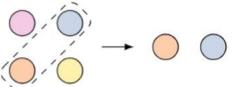
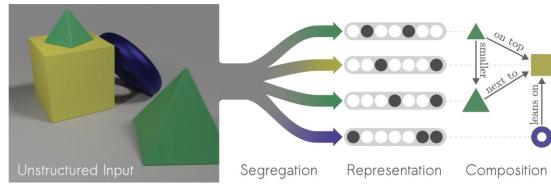
- What makes Visual Relational Reasoning so challenging?



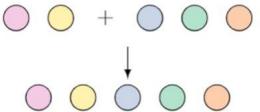
Object-centric
(disentangled)
representations



Relational inductive bias



(a) Systematicity

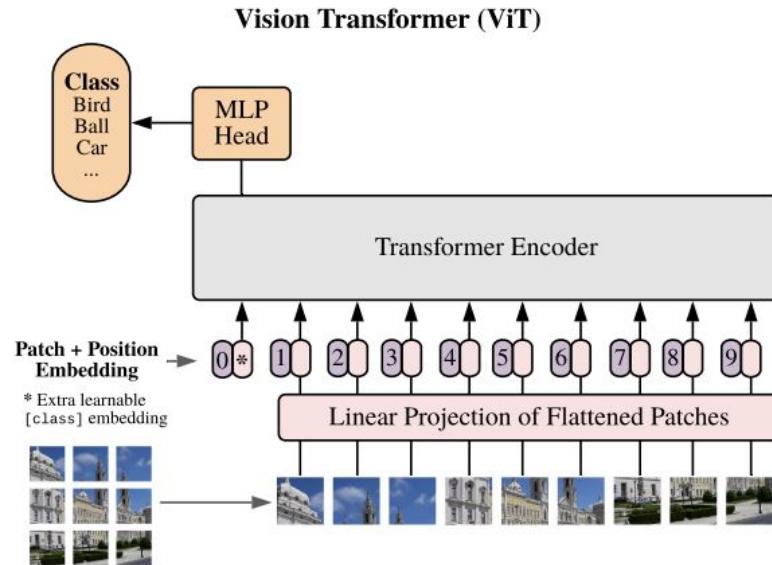
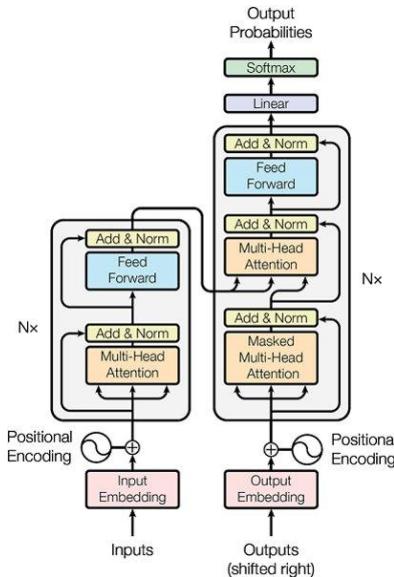


(b) Productivity

Systematic
generalization

Background

Transformers and Vision transformers



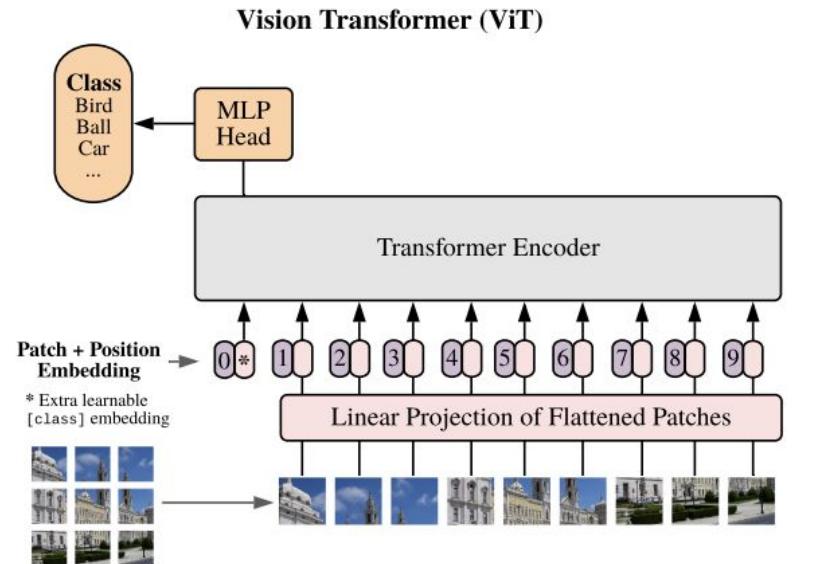
Transformer: explicitly capture the **pairwise relations** among input entities.

Vision transformers: **image patches (object candidates)** as input entities.

Background

Given the appealing nature of Vision transformers (ViTs) on **object-centric learning** and **relational inductive bias**, we choose to start with this model and see if we can make it better.

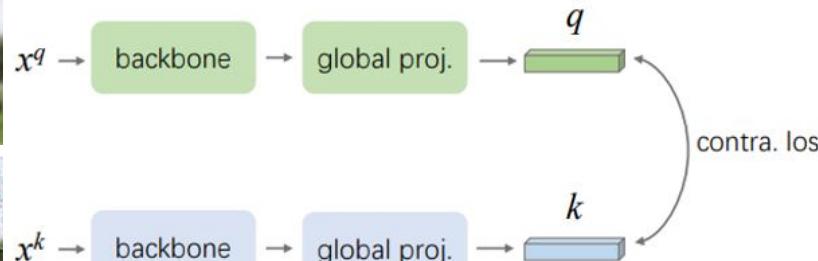
We propose to use **self-supervised contrastive learning** to achieve this goal.



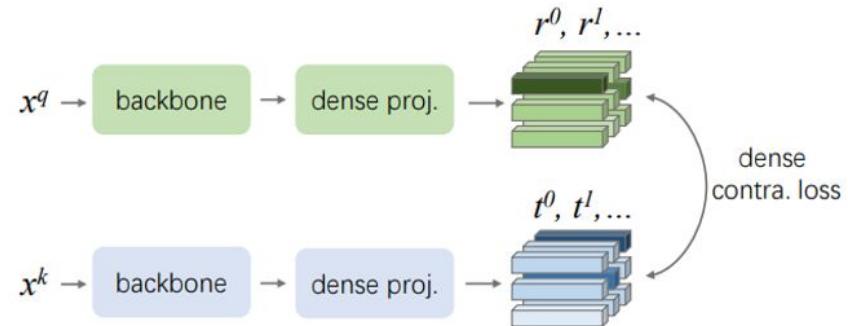
Vision transformers: **image patches (object candidates)** as input entities.

Background

Contrastive learning (CL) tasks for ViT



Global CL: Contrasting the **global features** of input images.



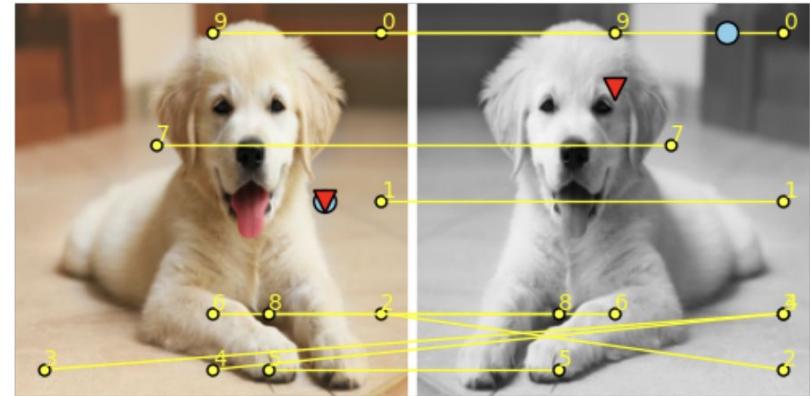
Local CL: Contrasting the **(spatially) local image features** of the input images.

Background

How can vision transformer benefit from contrastive learning?



Global CL: Contrasting the **global descriptions** of input images.
-> boosting **relational meaning and reasoning** via instance contrasting

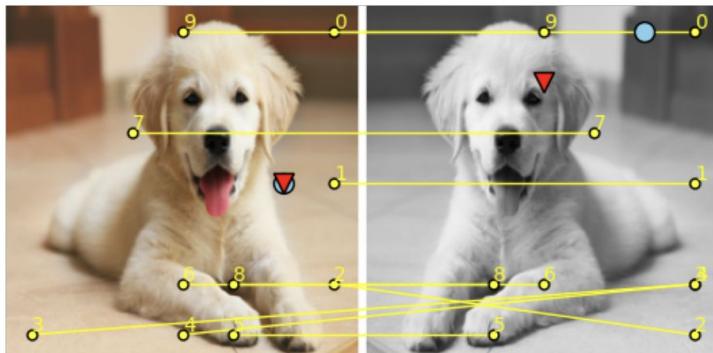


Local CL: Contrasting the **(spatially) local descriptions** of the input images.
-> boosting **object-centric representation** via unsupervised **correspondence learning**

Background

An issue: the original global and local CL are *concepts/semantics-free* -- image are treated as **isolated samples**. Therefore, these CL methods will promote:

- representations that **fail** to capture the **semantic similarity** of different objects
- relational deduction that **fails** to exploit these **semantics** for more efficient / lifted reasoning.



ReViT

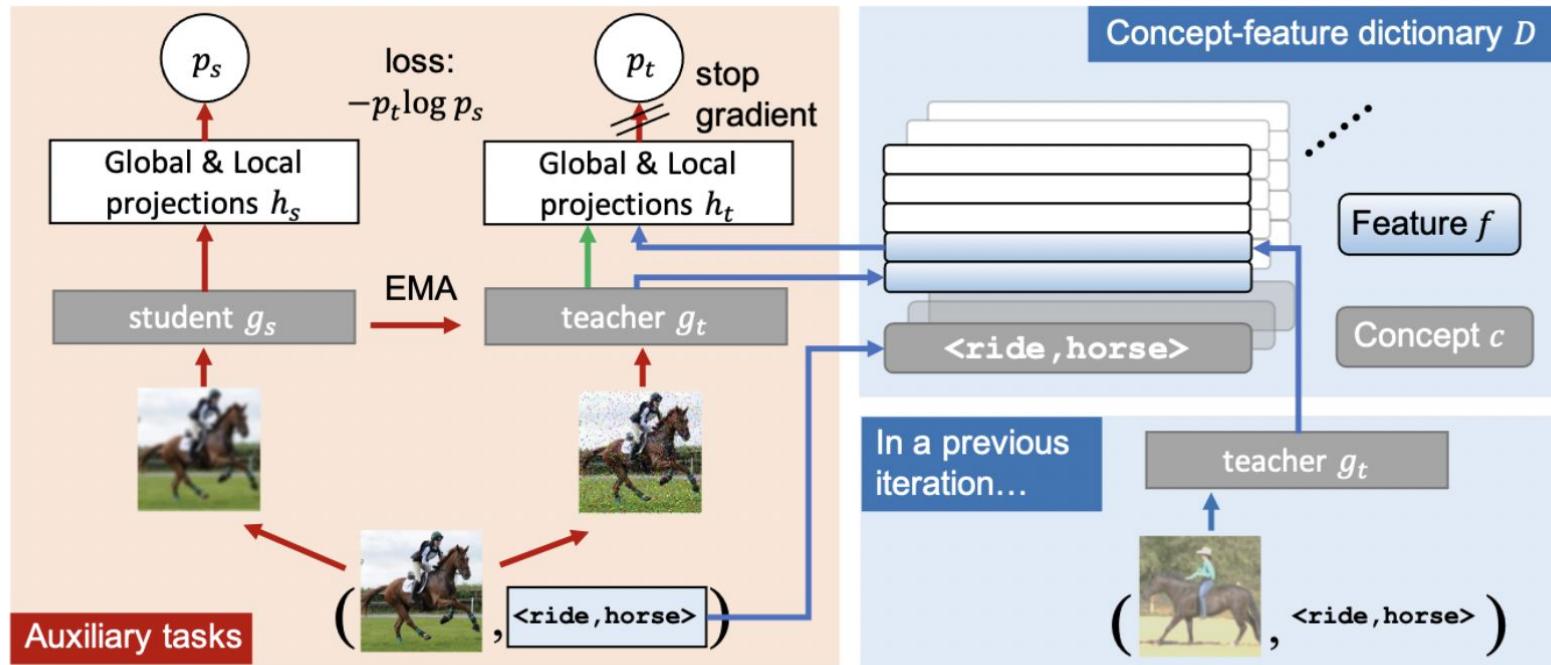


Figure 1: An overview of our method. **Red+Green**: the learning pipeline of DINO (Caron et al., 2021) and EsViT (Li et al., 2021); **Red+Blue**: our pipeline.

ReViT

- Concept-guided Vision Transformer

// Pseudo code

Input: image x, concept c

```
1 x1, x2 = aug1(x), aug2(x)
2 f1, f2 = backbone(x1), backbone(x2)
3 fn2 = dequeue_n_enqueue(f2, c)
4 loss_global = DINO_GLOBAL(f1[0], fn2[0]) // f*[0] is [CLS]
5 loss_local = DINO_LOCAL(f1[1:], fn2[1:])
6 (loss_local + loss_global).backward()
```

Experiments

We evaluate RelViT on two datasets:

-**HICO**: Human-object-interaction recognition

Formula: $I \Rightarrow \langle \text{object}, \text{ interaction} \rangle$

-**GQA**: Relational visual question answering

Formula: $\langle Q, I \rangle \Rightarrow \text{answer category}$



hold	✓
walk	✓
sit on	✗
straddle	✗
jump	✗
repair	✗

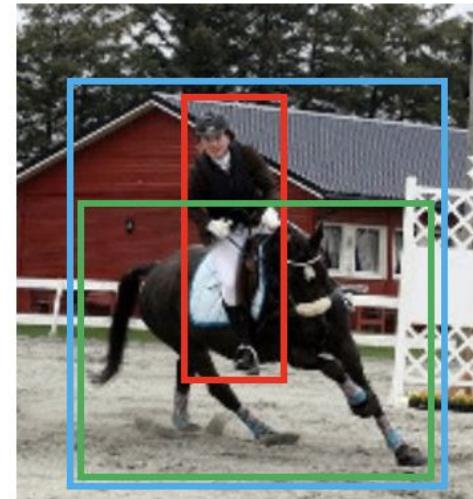


- A1. Is the **tray** on top of the **table** black or light brown? light brown
A2. Are the **napkin** and the **cup** the same color? yes

Experiments

Concept in HICO

- > HOI category (#concepts=600)
- > Interaction category (#concepts=117)
- > Object category (#concepts=80)



<**Ride**, **Horse**>

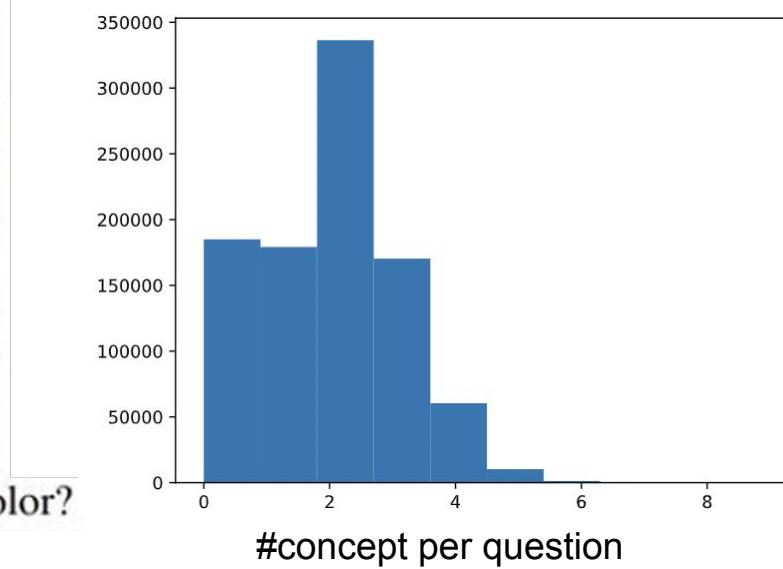
Experiments

Concept in GQA

We propose to parse the question into concept tokens.



Are the **napkin** and the **cup** the same color?

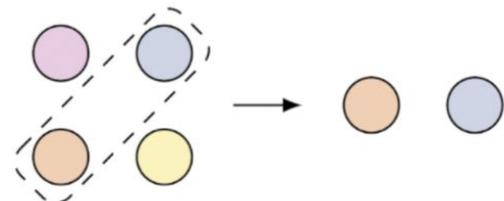


Top 10 concepts
man 39540
animal 34279
furniture 29982
white 22728
woman 19550
vehicle 19487
black 16639
person 15906
shirt 15418
table 12999

Experiments

Systematic generalization test for HICO:

- We make several HOI category **unseen** during training, e.g <TV, sit> only appears in testing data.
- We ensure the training data includes all the objects and interactions (e.g. TV and sit).
- Testing **systematicity** of systematic generalization.



(a) Systematicity

Experiments

Systematic generalization test for GQA:

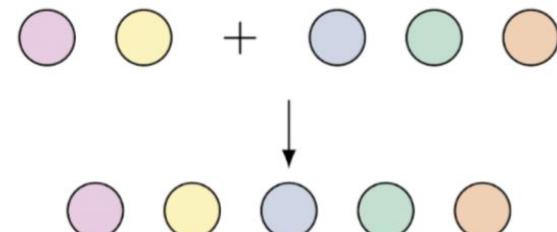
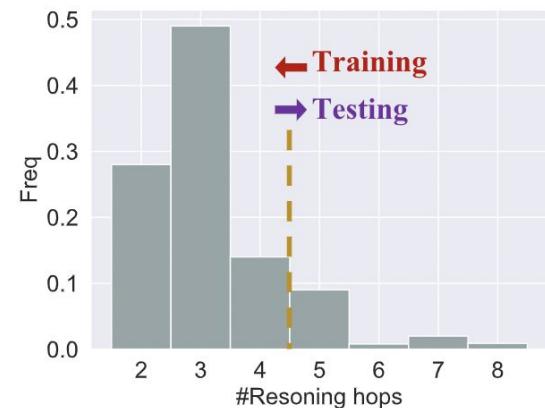
- Each GQA question is also labelled with a reasoning program.
- We make training data only contain questions with shorter reasoning programs -- testing **productivity** of systematic generalization.

What color is the food on the red object left of the small girl that is holding a hamburger, yellow or brown?

Question

Select: hamburger → Relate: girl, holding → Filter size: small → Relate: object, left → Filter color: red → Relate: food, on → Choose color: yellow | brown

#reasoning hops: 7



(b) Productivity

Experiments (HICO)

- We largely improve the current learners on both **standard test** and **systematic generalization test**, without any oracle object-centric representations (bboxes).
- Our model makes significant progress on **unseen categories**.

Method	Ext. superv.	Backbone	Orig.	Systematic-easy		Systematic-hard	
				Full cls.	Unseen cls.	Full cls.	Unseen cls.
Mallya & Lazebnik (2016)*		ResNet-101	33.8	-	-	-	-
Girdhar & Ramanan (2017)*	bbox	ResNet-101	34.6	-	-	-	-
Fang et al. (2018)*	pose	ResNet-101	39.9	-	-	-	-
Hou et al. (2020) [†]		ResNet-101	28.57	26.65	11.94	21.76	10.58
ViT-only		PVTv2-b2	35.48	31.06	11.14	19.03	18.85
EsViT (2021)		PVTv2-b2	38.23	35.15	11.53	22.55	21.84
RelViT (Ours)		PVTv2-b2	39.4	36.99	12.26	22.75	22.66
RelViT + EsViT (Ours)		PVTv2-b2	40.12	37.21	12.51	23.06	22.89

Experiments (GQA)

- We largely improve the current learners on both **standard test** and **systematic generalization test**, without any oracle object-centric representations (bboxes).
- This can be way impressive for VQA tasks -- object-detection play crucial role in almost all state-of-the-art VQA learners **but not with our method**.

Method	Bbox feat.*	Backbone	Orig.	Sys.
BottomUp (2018)	✓	ResNet-101	53.21	-
MAC (2018b)	✓	ResNet-101	54.06	-
MCAN-Small (2019)	✓	ResNet-101	58.35	36.21
MCAN-Small (2019)		ResNet-101	51.1	30.12
ViT-only		PVTv2-b2	56.62	31.39
EsViT (2021)		PVTv2-b2	56.95	31.76
RelViT (Ours)		PVTv2-b2	57.87	35.48

GQA overall accuracy	MCAN-Small (w/ bbox)	RelViT (PVTv2-b2)	RelViT (PVTv2-b3)	RelViT (Swin-base)
original	58.35	57.87	61.41	65.54
systematic	36.21	35.48	36.25	37.51

Takeaway

ViT is a promising architecture that offers **object-centric representations** and **relational inductive bias**.

Using **concept-guided contrastive learning** as an **auxiliary task** to further exploit the visual relational reasoning data could significantly boost the performance of ViTs on these tasks, especially on **systematic generalization**.

RelViT: Concept-guided Vision Transformer
for Visual Relational Reasoning

