
Self-supervising Fine-grained Region Similarities for Large-scale Image Localization



Yixiao Ge¹, Haibo Wang³, Feng Zhu², Rui Zhao², Hongsheng Li¹

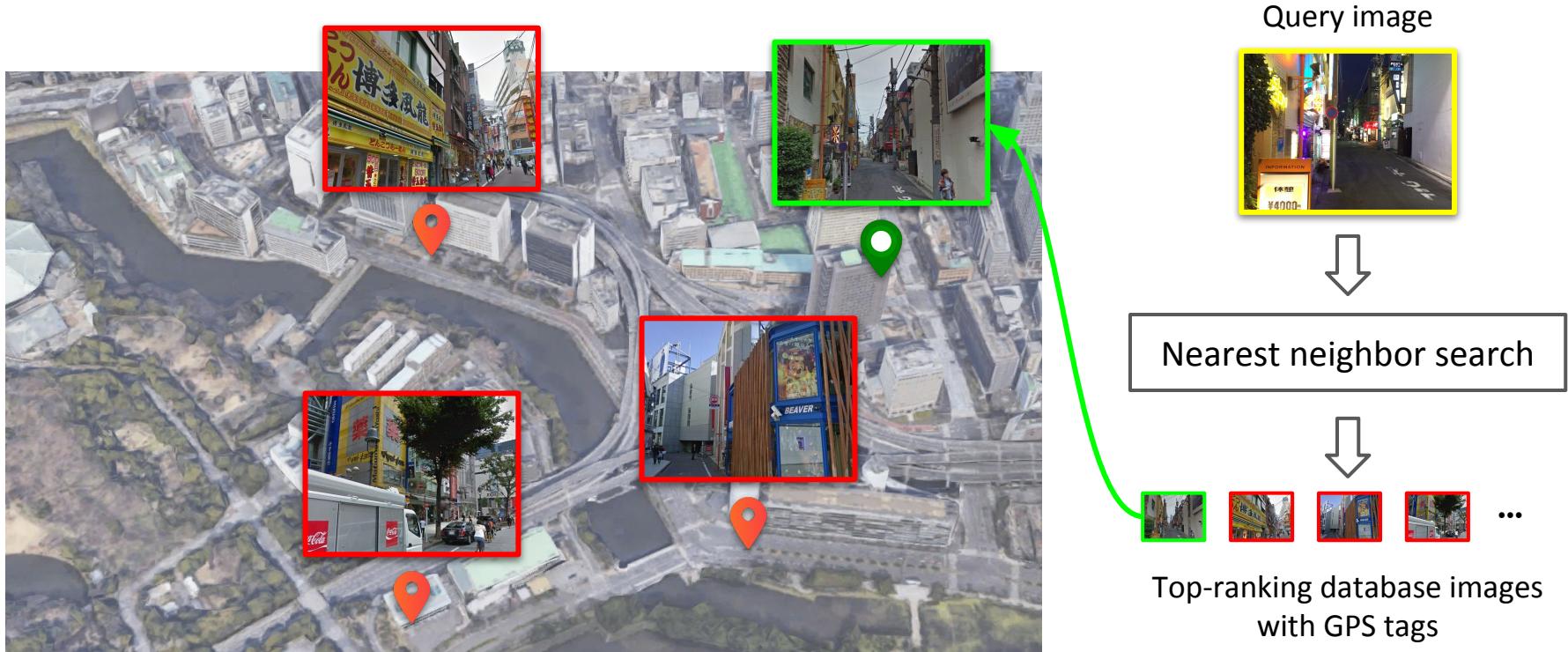
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²SenseTime Research,

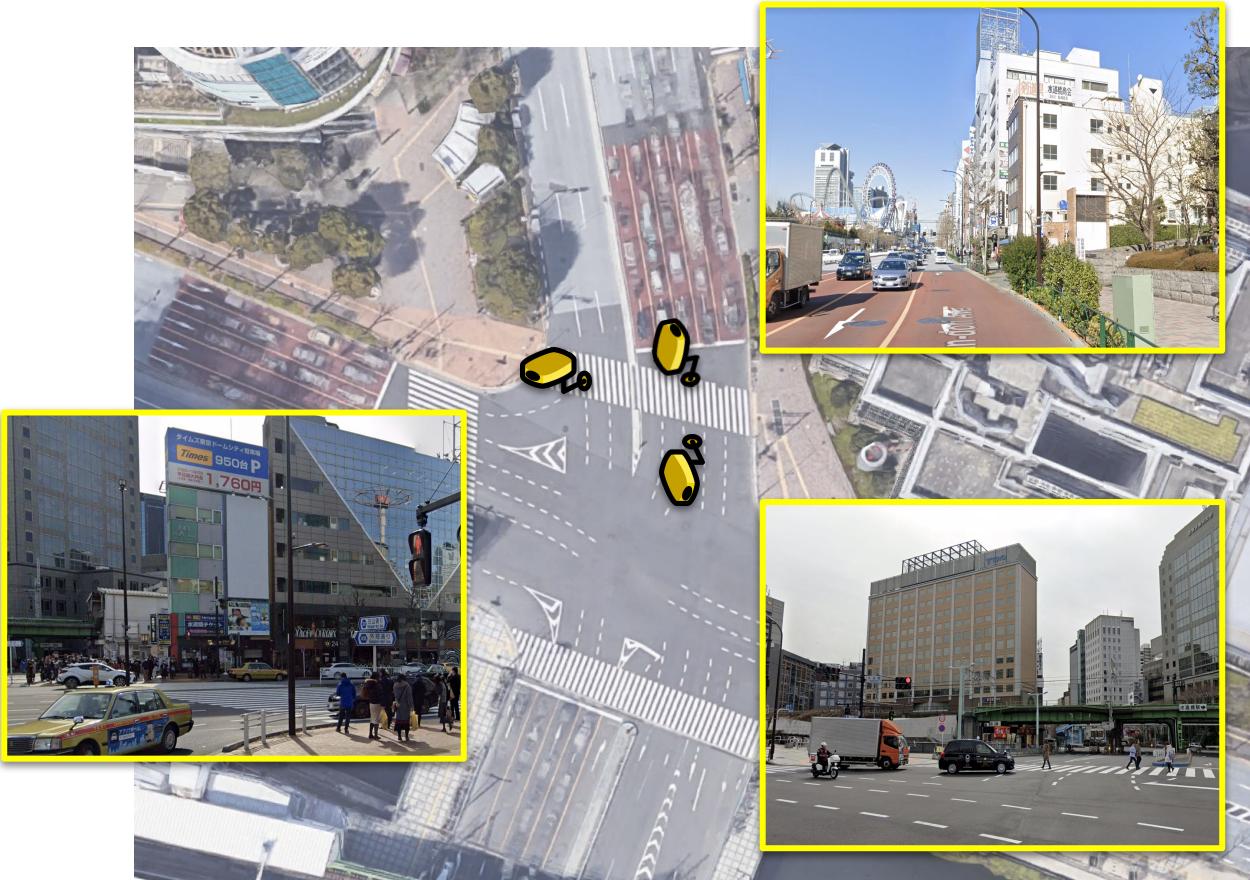
³China University of Mining and Technology



Image Localization via Image Retrieval



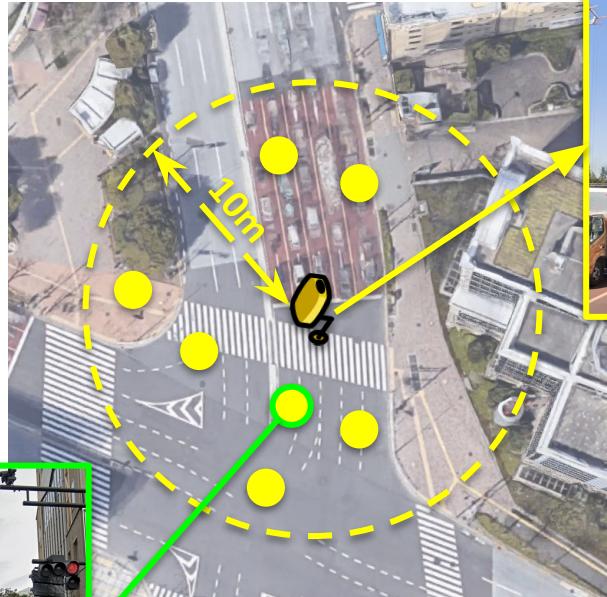
Challenge #1: Noisy Positives by Weak GPS Labels



Geographically close-by images may not depict the same scene when facing different directions.

Previous Solution: Train with Only the Easiest Positive

Potential positives
filtered by GPS labels



Top-1 database image



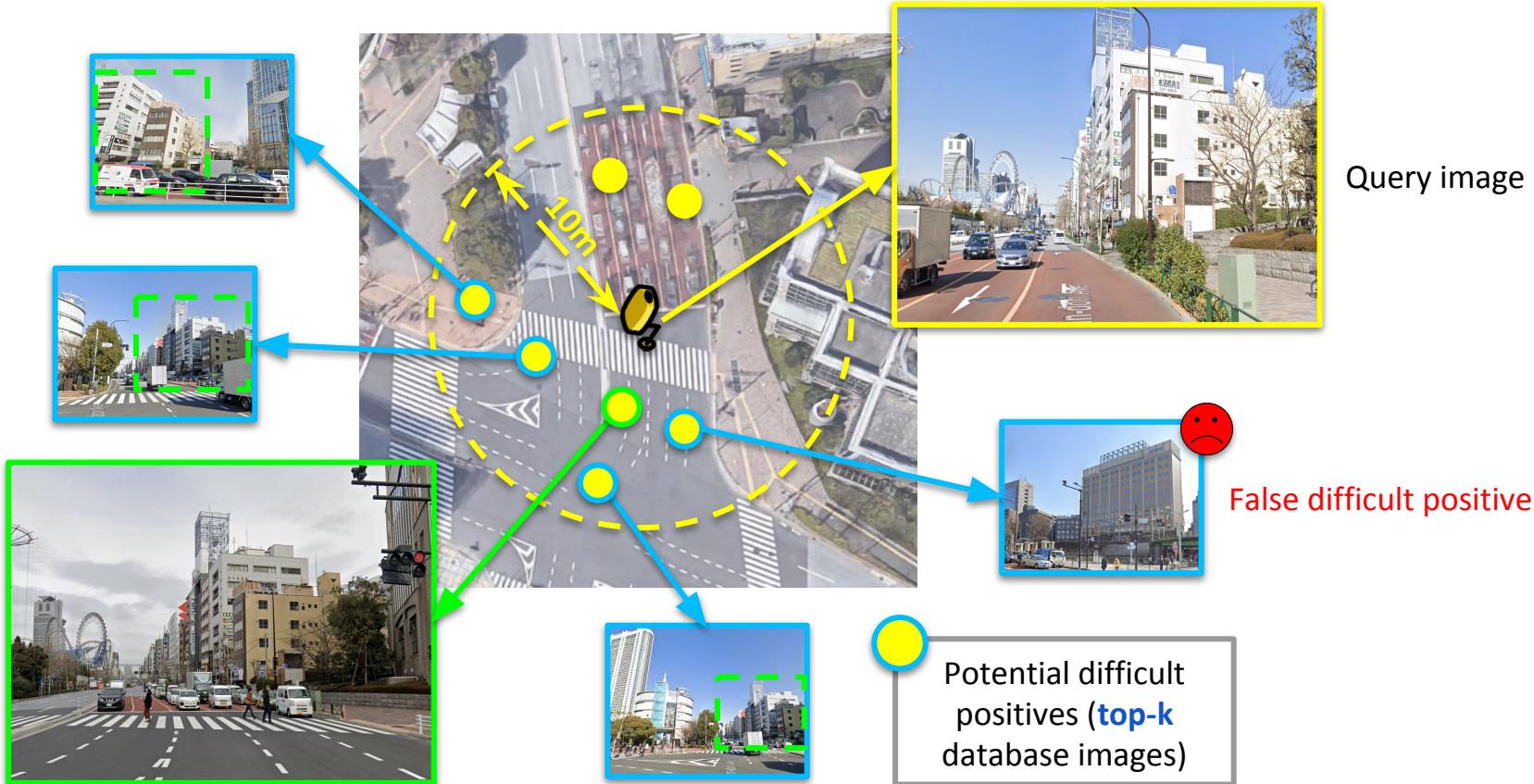
Query image



Forcing the queries to be closer to their already nearest neighbors results in a lack of robustness to varying conditions.

→ **Difficult positives are needed!**

Motivation: Use Noisy Difficult Positives Properly

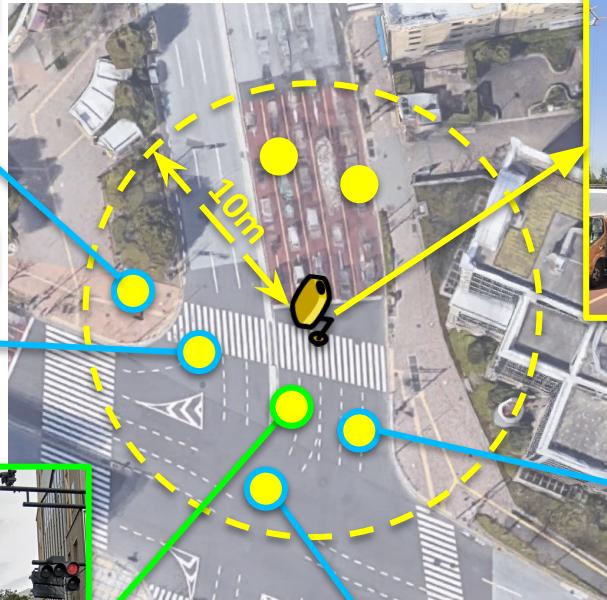


Our Solution: Image Similarities as Soft Supervisions

Similarity label = 0.6



Similarity label = 0.5



Query image

Small similarity label
for *false* difficult positive

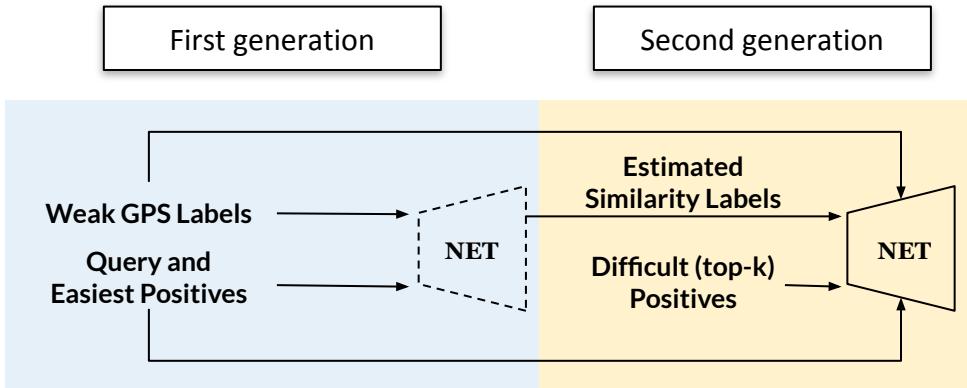
Similarity label = 0.1

Small similarity label for *true* difficult
positive with *small overlapping regions*

Similarity label = 1.0

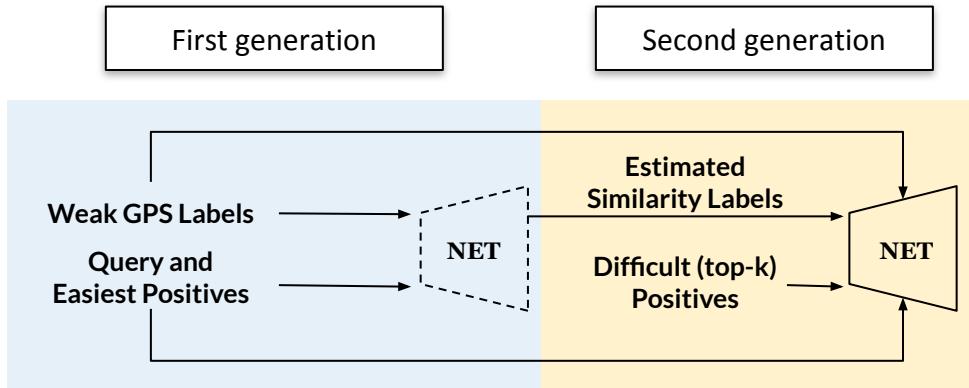
Similarity label = 0.3

Our Solution: Similarity Labels



The first generation's query-gallery similarities serve as the soft supervision for training the network in the second generation.

Our Solution: Similarity Labels

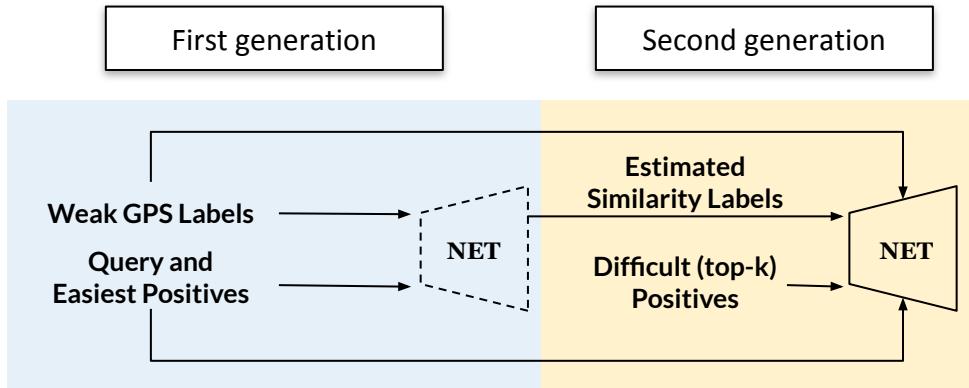


Similarity labels: $S_{\theta_1}(q, p_1, \dots, p_k; \tau_1) = \text{softmax} \left(\left[\frac{\langle f_{\theta_1}^q, f_{\theta_1}^{p_1} \rangle}{\tau_1}, \dots, \frac{\langle f_{\theta_1}^q, f_{\theta_1}^{p_k} \rangle}{\tau_1} \right]^T \right)$

Annotations below the equation:

- Query (Yellow dashed box)
- Positive #1 (Blue dashed box)
- Temperature for generation #1 (Orange dashed box)
- Image similarity between query and positive #1 (Red dashed box)
- Parameters of the network in generation #1 (Green dashed box)

Our Solution: Similarity Labels



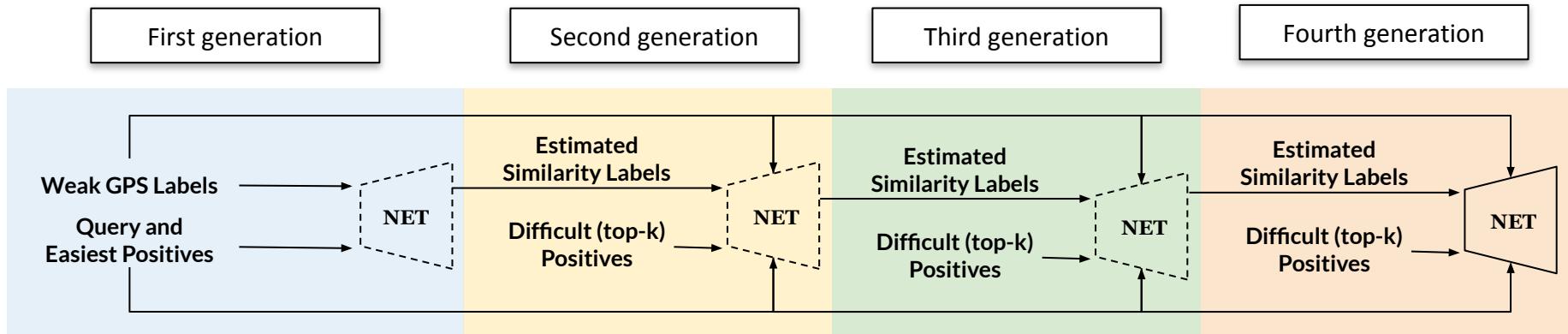
Similarity labels: $\mathcal{S}_{\theta_1}(q, p_1, \dots, p_k; \tau_1) = \text{softmax} \left(\left[\langle f_{\theta_1}^q, f_{\theta_1}^{p_1} \rangle / \tau_1, \dots, \langle f_{\theta_1}^q, f_{\theta_1}^{p_k} \rangle / \tau_1 \right]^\top \right)$

Soft-label loss: $\mathcal{L}_{\text{soft}}(\theta_2) = \ell_{ce}(\mathcal{S}_{\theta_2}(q, p_1, \dots, p_k; 1), \mathcal{S}_{\theta_1}(q, p_1, \dots, p_k; \tau_1))$

cross-entropy loss

similarity labels (learning targets)
estimated by the network in generation #1

Our Solution: Self-enhanced Similarity Labels



The generated soft supervisions are gradually refined as the network generation progresses.

Challenge #2: Lack of Region-level Supervisions

Only image-level labels

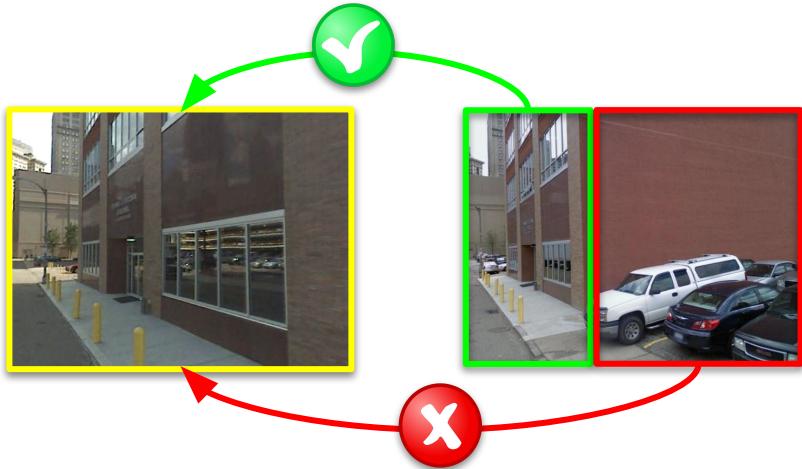


Query image



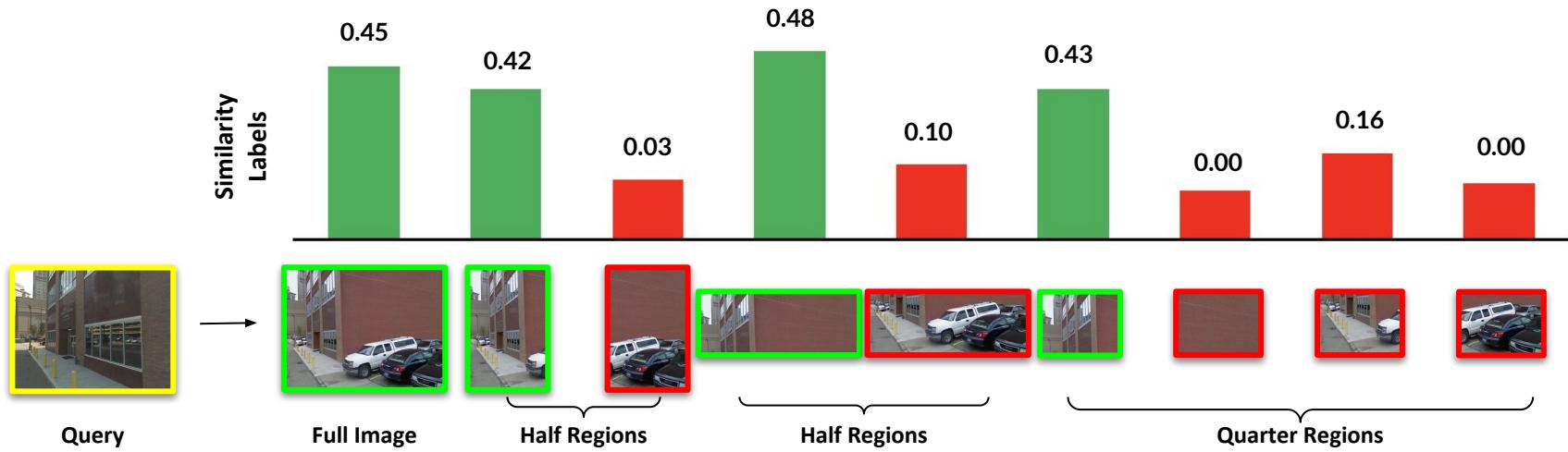
Positive sample

Ideal image-to-region labels



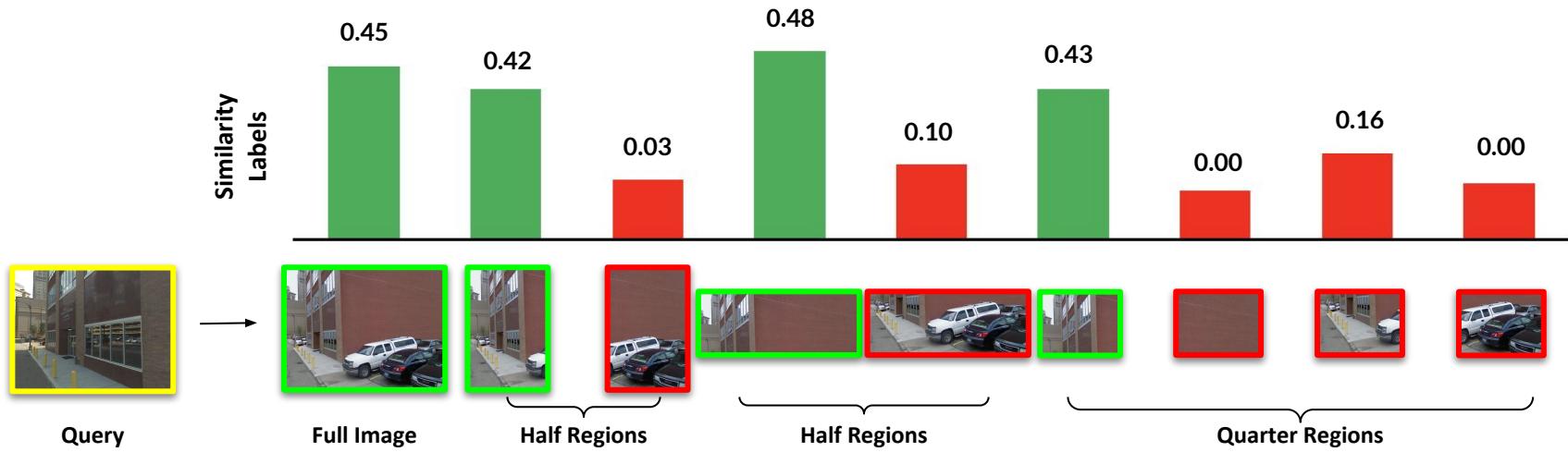
The correct image-level labels might not necessarily be the correct region-level labels.

Our Solution: Image-to-region Similarities as Soft Supervisions



Provide fine-grained image-to-region similarities to enhance the learning of local features.

Our Solution: Image-to-region Similarities as Soft Supervisions

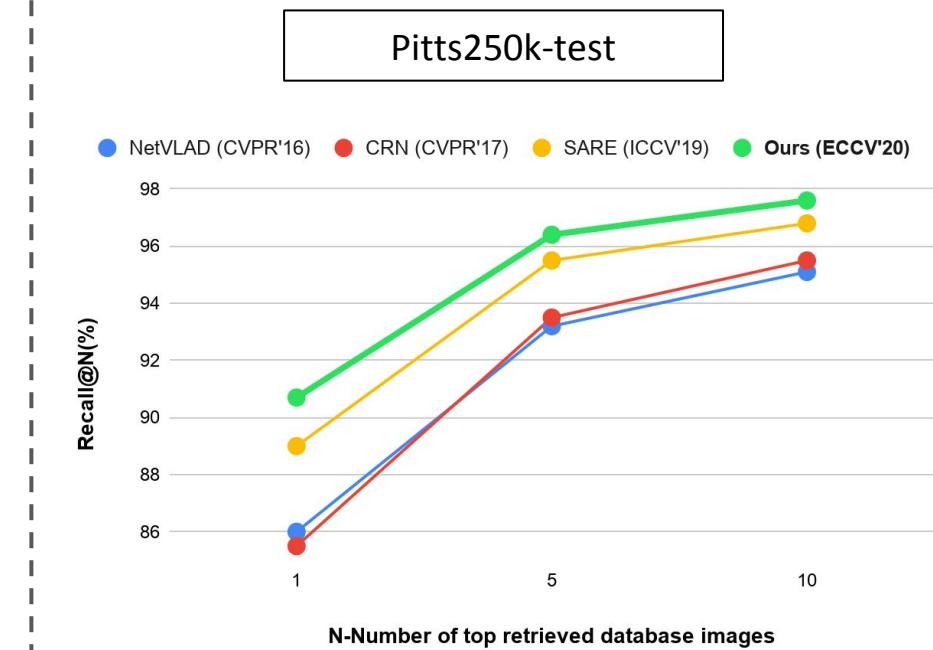
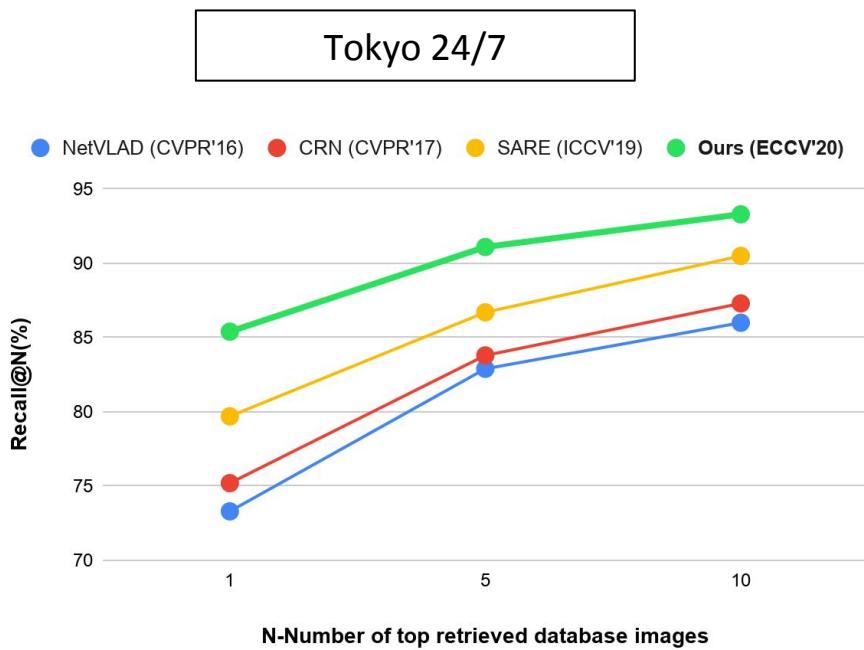


Fine-grained Similarity labels:

$$\mathcal{S}_{\theta_\omega}^r(q, p_1, \dots, p_k; \tau_\omega) = \text{softmax} \left([\langle f_{\theta_\omega}^q, f_{\theta_\omega}^{p_1} \rangle / \tau_\omega, \langle f_{\theta_\omega}^q, f_{\theta_\omega}^{r_1^1} \rangle / \tau_\omega, \dots, \langle f_{\theta_\omega}^q, f_{\theta_\omega}^{r_1^8} \rangle / \tau_\omega, \dots, \langle f_{\theta_\omega}^q, f_{\theta_\omega}^{p_k} \rangle / \tau_\omega, \langle f_{\theta_\omega}^q, f_{\theta_\omega}^{r_k^1} \rangle / \tau_\omega, \dots, \langle f_{\theta_\omega}^q, f_{\theta_\omega}^{r_k^8} \rangle / \tau_\omega] \right)$$

Image similarities between query and regions of positive #1

Performances on Image Localization Benchmarks

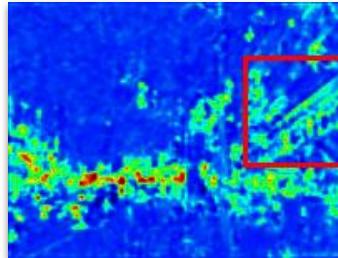


Comparison with State-of-the-art (#1)



SARE
(ICCV'19)

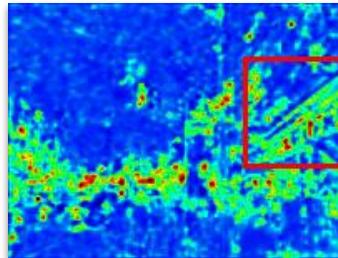
Query's heatmap



Retrieved top-1 image



Ours
(ECCV'20)



Our method pays more attention on the discriminative shop signs than SARE.

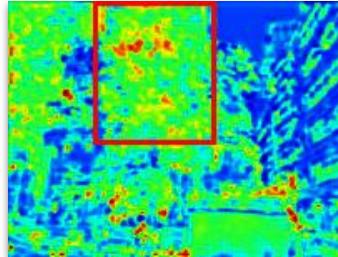
Comparison with State-of-the-art (#2)

Query image



SARE
(ICCV'19)

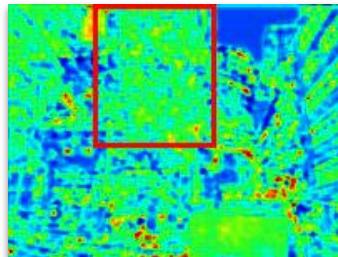
Query's heatmap



Retrieved top-1 image



Ours
(ECCV'20)



SARE incorrectly focuses on the trees,
while our method learns to ignore such misleading regions.

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Code available at



<https://github.com/yxgeee/SFRS>