An algorithm for replicating multi-threaded applications as done in replicated Popcorn. The application is made deterministic through the use of logical time. Any inter-thread synchronization operation must be protected by calls to EnterSync and ExitSync. Reads of the socket API are modeled by EnterRead. The scheduler processes (one per kernel) makes sure that the different copies of the application are consistent.

EXTENDS Naturals, Sequences, Integers, Library

CONSTANTS Pid, MaxTime, Kernel, SchedulerPID, Requests

Assume $SchedulerPID \notin Pid$

 $InitLogTime \stackrel{\Delta}{=} 1$

 $LogTime \stackrel{\triangle}{=} InitLogTime ... MaxTime$ The set of logical time values

Processes are of the form $\langle k, pid \rangle$, where k is the kernel the process is running on.

$$P \triangleq Kernel \times Pid$$

 $Primary \stackrel{\Delta}{=} CHOOSE \ k \in Kernel : TRUE$

 $Ker(p) \stackrel{\cdot}{=} p[1]$

 $PID(p) \triangleq p[2]$

 $OnKernel(kernel) \stackrel{\Delta}{=} \{kernel\} \times Pid$

Logical time comparison, using PIDs to break ties.

$$Less(p, tp, q, tq) \stackrel{\triangle}{=} tp < tq \lor (tp = tq \land PID(p) \le PID(q))$$

The sequence of TCP packets that will be received. No duplicates allowed (therefore the set TcpData must be big enough) so that any misordering of the threads will lead to a different data read. For TCPMultiStream, each stream has different data.

```
StreamLength \triangleq 3
```

 $TcpData \stackrel{\triangle}{=} 1 .. StreamLength * Requests$

 $TcpStream \stackrel{\triangle}{=} [i \in 1 .. StreamLength \mapsto i]$

 $TcpMultiStream \triangleq [r \in 1 .. Requests \mapsto ([i \in 1 .. StreamLength \mapsto i + (StreamLength * (r - 1))])]$

Assume NoDup(TcpStream)

Assume Len(TcpStream) = StreamLength

Shifts a sequence by 1: $Shift(\langle 1, 2, 3 \rangle) = \langle 2, 3 \rangle$ and $Shift(\langle \rangle) = \langle \rangle$.

$$Shift(s) \stackrel{\Delta}{=}$$

If
$$Len(s) > 1$$

THEN
$$[i \in 1 ... (Len(s) - 1) \mapsto s[i + 1]]$$

ELSE $\langle \rangle$

$$Shiftn(s) \triangleq$$

IF
$$Len(s) > 1$$

THEN
$$[i \in 1 ... (Len(s) - 1) \mapsto s[i + 1]]$$

ELSE $\langle -1 \rangle$

The algorithm *ReadAppend* models a set of worker threads being scheduled by the deterministic scheduler and executing the following code.

```
Code of worker w: While(true){

x = read(socket);

append(\langle w, x \rangle, file);

}
```

Variables:

The variable bumps records all logical time bumps executed by the primary in order for the secondaries to do the same, *i.e.* the initial logical time, the new logical time, and the value read from the tcp buffer. $\langle t1, t2, d \rangle \in bumps[pid]$ means that the primary bumped process pid from logical time t1 to t2 and delivered the data d. Note that the scheduler set bumps[pid] to a value that depends on the logical time of the processes on all replicas, and this value is then immediately available to all replicas. A more detailed model would instead include a distributed implementation of the choice of the logical time to bump the process to.

reads[p] stores the last value read by p from the socket.

tcpBuff[k] represents the state of the tcp buffer on kernel k. Each time a process reads from the buffer, the buffer shrinks by 1.

Definitions:

Bumped(kernel) is the set of processes running on the kernel "kernel" which are waiting to execute a "bump" decided by the primary.

If $p \in Bumped(Ker(p))$ then BumpedTo(p) is the logical time to which p should be bumped to.

If $p \in WaitingSync(Ker(p))$ then IsNextProc(kernel, p) is true iff p is the process to be scheduled next, that is: (1) p has the lowest ltime among running and waiting-sync processes and (2) if q is on the same kernel and q is waiting for a read and the primary has already decided to which logical time tq to bump q, then ltime[p] must be less than tq.

BumpTo is the logical time to which to bump a process that needs bumping. It is some logical time greater than all the logical times reached by any process on any kernel.

--algorithm ReadAppend{

variables

```
status = [p \in P \mapsto \text{"running"}], ltime = [p \in P \mapsto InitLogTime], file = [k \in Kernel \mapsto \langle \rangle], bumps = [p \in Pid \mapsto \{\}], reads = [p \in P \mapsto -1], tcpBuff = [k \in Kernel \mapsto TcpMultiStream], Queue for accepted connections socketQueue = [k \in Kernel \mapsto \langle \rangle], Queue for unhandled connections
```

```
requestQueue = [k \in Kernel \mapsto [r \in 1 .. Requests \mapsto r]],
      The socket that is handled by a process
    handledSocket = [p \in P \mapsto -1],
    connections = [k \in Kernel \mapsto \langle \rangle]
define {
    Run(p) \stackrel{\Delta}{=} status[p] = "running"
    Running(kernel) \stackrel{\Delta}{=} \{ p \in OnKernel(kernel) : Run(p) \}
     WaitingSync(kernel) \stackrel{\Delta}{=}
         \{p \in OnKernel(kernel) : status[p] = "waiting sync"\}
     WaitingRead(kernel) \triangleq
         \{p \in OnKernel(kernel) : status[p] = "waiting read"\}
    Bumped(kernel) \stackrel{\Delta}{=} \{ p \in OnKernel(kernel) : 
          \land status[p] = "waiting read"
          \land \exists t \in LogTime : \exists d \in TcpData : \langle ltime[p], t, d \rangle \in bumps[PID(p)] \}
    BumpedTo(p) \triangleq
         CHOOSE t \in LogTime : \exists d \in TcpData : \langle ltime[p], t, d \rangle \in bumps[PID(p)]
    BumpData(p) \triangleq
         CHOOSE d \in TcpData : \exists t \in LogTime : \langle ltime[p], t, d \rangle \in bumps[PID(p)]
    IsNextProc(kernel, p) \stackrel{\Delta}{=}
          \land \forall q \in Running(kernel) \cup WaitingSync(kernel) :
                 q \neq p \Rightarrow Less(p, ltime[p], q, ltime[q])
          \land \forall q \in Bumped(kernel) : Less(p, ltime[p], q, BumpedTo(q))
    BumpTo \stackrel{\Delta}{=} CHOOSE \ i \in LogTime : \forall \ p \in P : ltime[p] < i
}
macro EnterRead(p){
    status[p] := "waiting read";
macro EnterSync(p){
    status[p] := "waiting sync";
macro ExitSync(p){
    ltime[p] := ltime[p] + 1;
}
 Processes consume a connection
process (worker \in P){
           ww1: while (TRUE){
                      EnterSync(self);
                      await Run(self);
           ww2:
```

```
if (Len(requestQueue[Ker(self)]) > 0){
         ww3:
                       handledSocket[self] := requestQueue[Ker(self)][1];
                       requestQueue[Ker(self)] := Shift(requestQueue[Ker(self)]);
                   };
         ww4:
                   ExitSync(self);
         ww5:
                   if (handledSocket[self] \neq -1){
                   ww9:
                            while (Len(tcpBuff[Ker(self)][handledSocket[self]]) > 0){
                                EnterRead(self);
                       ww10:
                                await Run(self);
                                EnterSync(self);
                       ww11:
                                await Run(self);
                                file[Ker(self)] :=
                                   Append(file[Ker(self)], \langle PID(self), reads[self] \rangle);
                                ExitSync(self);
                       ww12:
         ww13: handledSocket[self] := -1;
         };
    }
process (scheduler \in \{\langle k, SchedulerPID \rangle : k \in Kernel\}) \{
         while (TRUE){
             either { Schedule a process waiting for synchronization:
                 with (p \in \{p \in WaitingSync(Ker(self)) : \}
                          IsNextProc(Ker(self), p))
                     status[p] := "running" \} 
             or { Bump a process waiting for a read:
                  with (p \in WaitingRead(Ker(self))){
                      if (Ker(self) = Primary) On the primary.
                       Record the bump for the secondaries.
                          bumps[PID(p)] :=
                              bumps[PID(p)] \cup \{\langle ltime[p],
                                  Bump To, tcpBuff[Ker(self)][handledSocket[p]][1]\rangle\};
                          ltime[p] := BumpTo;
                      }else { On a replica:
     Wait until the primary has bumped p and the data to be
   delivered to p in at the head of the tcp buffer
                       await p \in Bumped(Ker(self)) \land BumpData(p) =
                            tcpBuff[Ker(self)][handledSocket[p]][1];
                       ltime[p] := BumpedTo(p); Bump the process
```

```
\label{eq:continuous_problem} \left. \begin{array}{l} \mbox{$:$} \\ \mbox{$reads[p] := tcpBuff[Ker(self)][handledSocket[p]][1];} \\ \mbox{$tcpBuff[Ker(self)][handledSocket[p]]);} \\ \mbox{$Shift(tcpBuff[Ker(self)][handledSocket[p]]);} \\ \mbox{$status[p] := "running"; Let $p$ run.} \\ \mbox{$\}$} \\ \mbox{$\}$}
```