

Sistema

B) Modelos del sistema

hoja 1

$$G = \left(-\frac{1}{sR_2C_1} \right) \left(-1 \right) \left(-\frac{1}{sR_5C_2} \right) \left(-1 \right)$$

$$G = \frac{1}{R_2 R_5 C_1 C_2} \cdot \frac{1}{s^2} \Rightarrow \boxed{G = K \cdot \frac{1}{s^2}, K = \frac{1}{R_2 R_5 C_1 C_2}}$$

$K = \frac{1}{10^{-4}} = 10^4$

Compensación (Modelo)

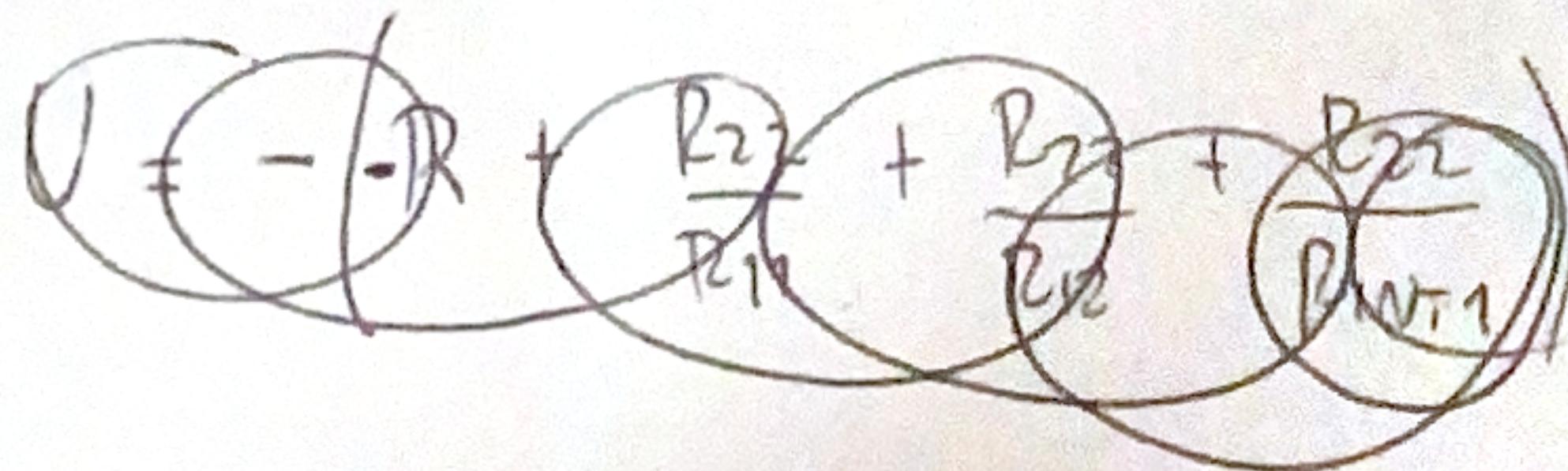
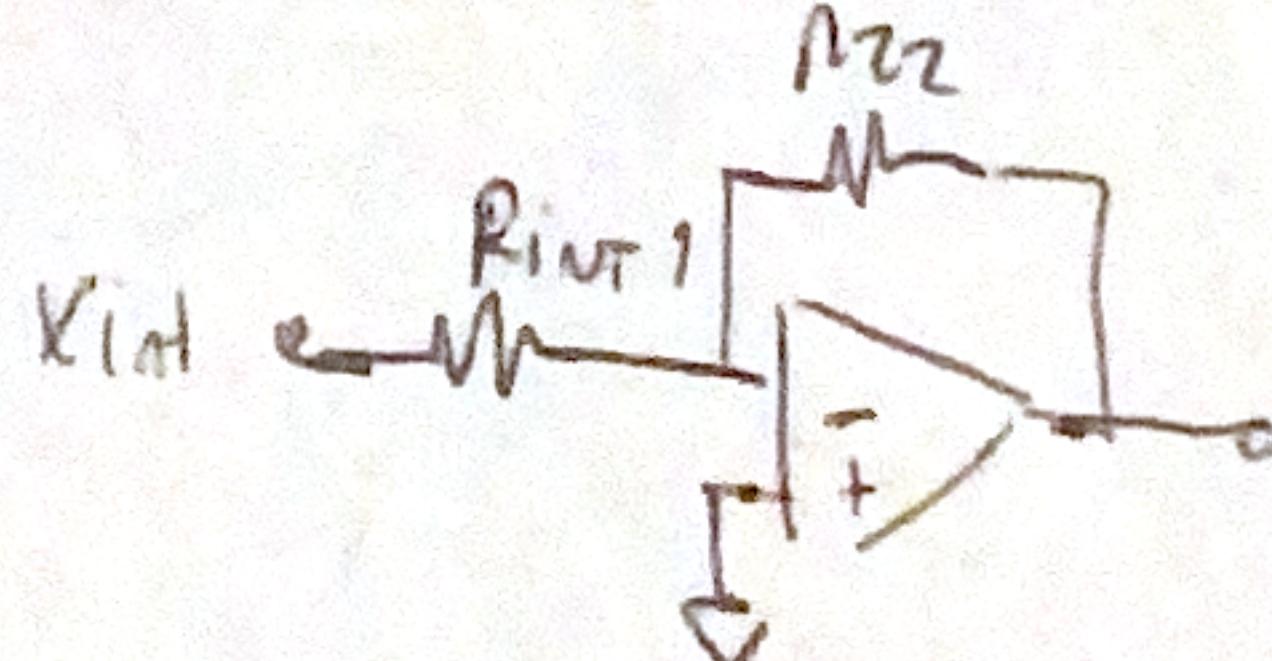
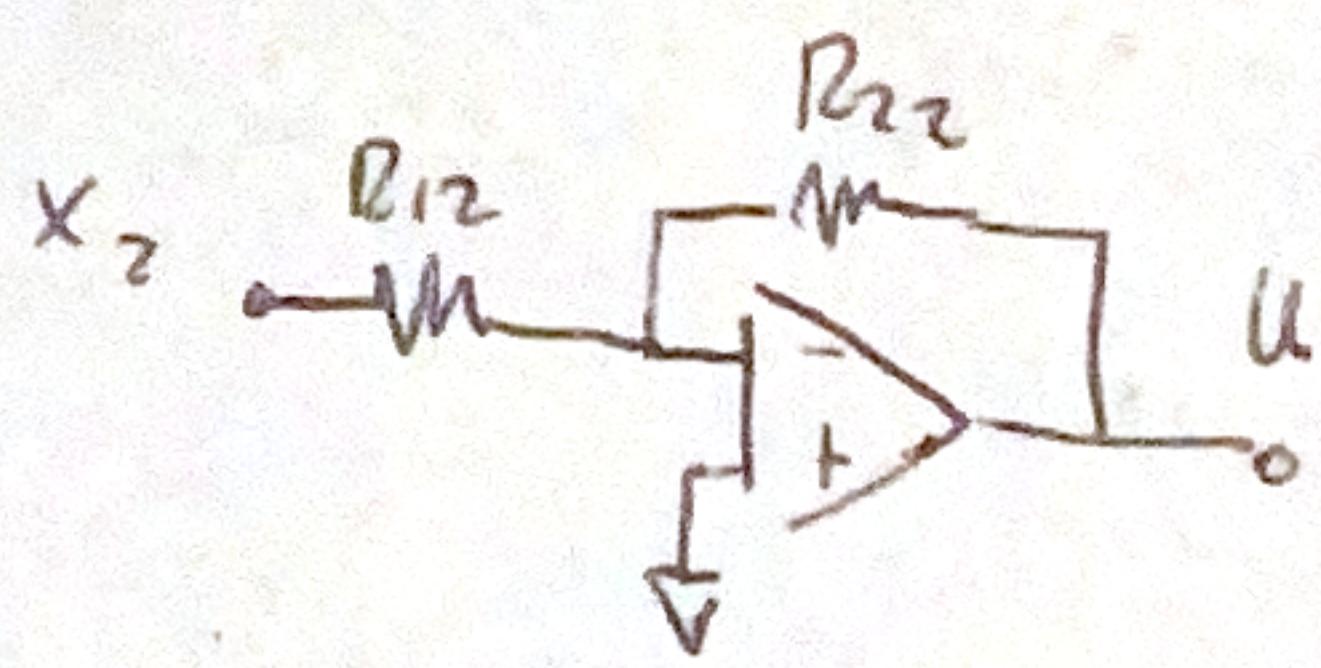
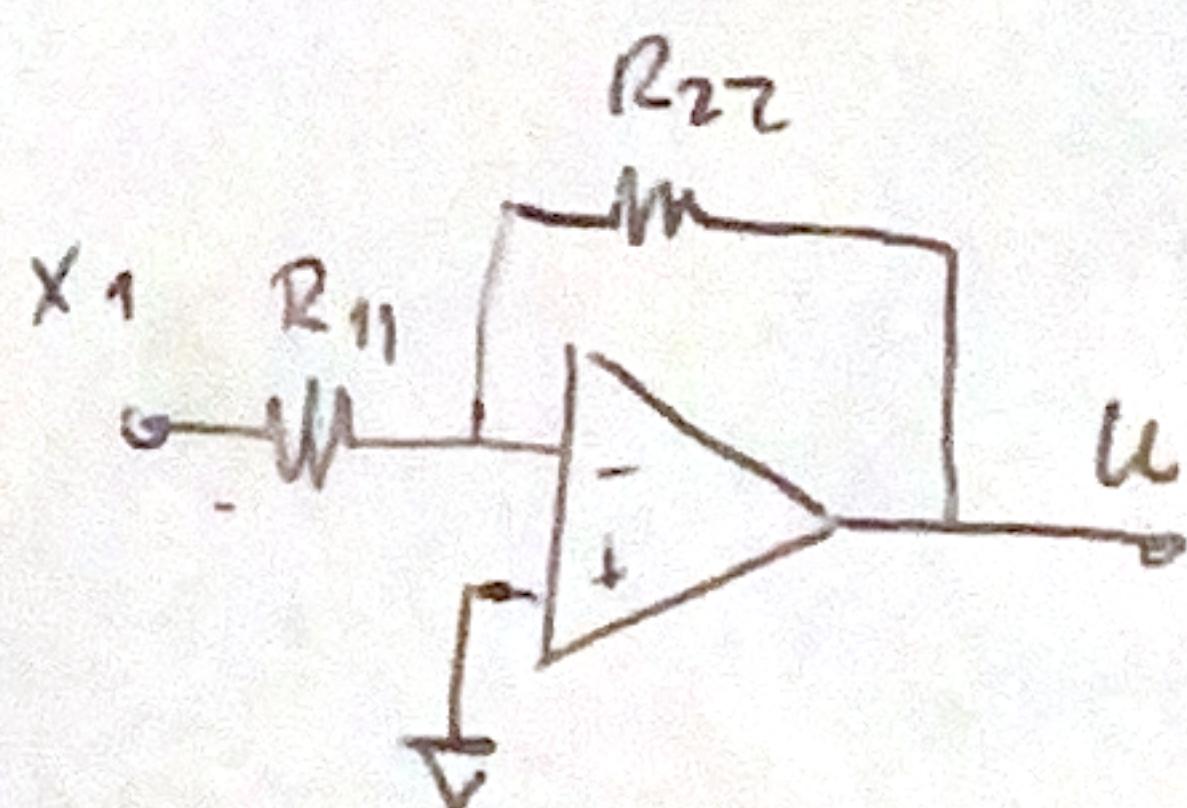
$$C = (-1) \left(\frac{-1}{sR_{10}C_3} \right) = \frac{1}{R_{10}C_3} \cdot \frac{1}{s} \Rightarrow \boxed{C = K \cdot \frac{1}{s}}$$

$K = 10^2$

Recomendación (Modelo)

$$\boxed{\begin{aligned} \frac{U}{X_1} &= -\frac{R_{22}}{R_{11}} \\ \frac{U}{X_2} &= -\frac{R_{22}}{R_{12}} \\ \frac{U}{K_{INT1}} &= -\frac{R_{22}}{R_{INT1}} \end{aligned}}$$

$$\frac{U}{R} = +\frac{R_{22}}{R_8}$$



$$U = R - R_{22} \left(\frac{X_1}{R_{11}} + \frac{X_2}{R_{12}} + \frac{K_{int1}}{R_{int1}} \right)$$

$$C) \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} \alpha_{11} & \alpha_{12} \\ \alpha_{21} & \alpha_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} u \quad y = \begin{bmatrix} c_1 & c_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

hoj 2

Planteo:

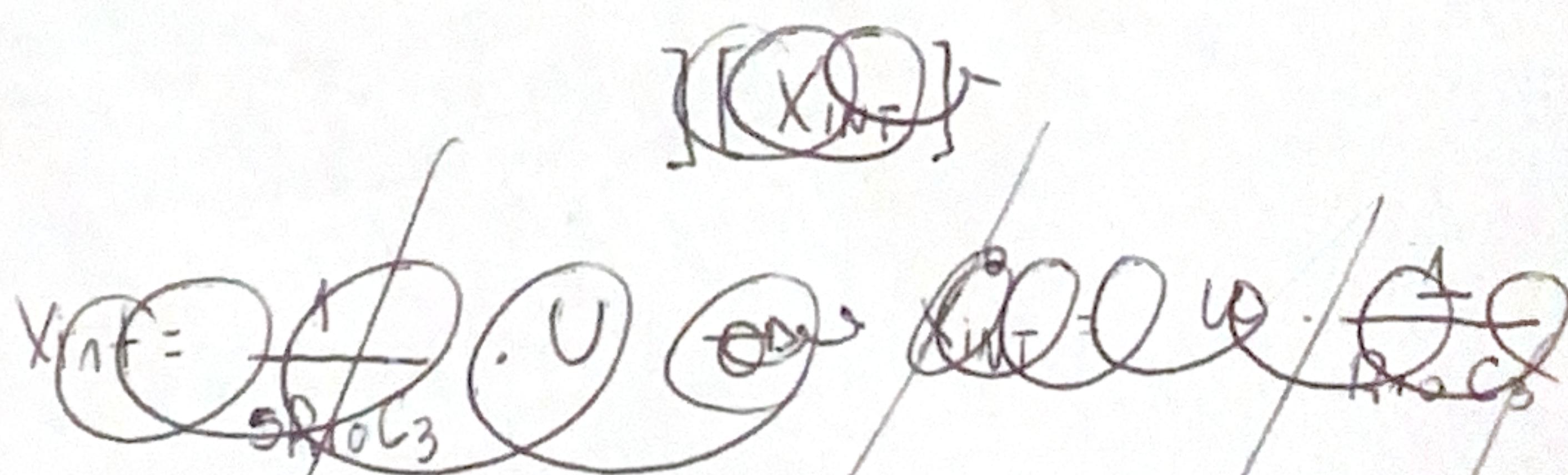
$$x_2 = \text{Res. } U \cdot \frac{1}{5R_2C_1} \rightarrow s\dot{x}_2 = U \cdot \frac{1}{R_2C_1} \rightarrow \dot{x}_2 = U \cdot \frac{1}{R_2C_1}$$

$$x_1 = x_2 \cdot \frac{1}{5R_5C_2} \rightarrow s\dot{x}_1 = x_2 \cdot \frac{1}{R_5C_2} \rightarrow \dot{x}_1 = x_2 \cdot \frac{1}{R_5C_2}$$

$$\Rightarrow \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{R_5C_2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{1}{R_2C_1} \end{bmatrix} u$$

Bloque I

$$\Rightarrow y = [1 \ 0] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$



$$x_{int} = x_1$$



$$\begin{bmatrix} \dot{x}_{int} \end{bmatrix} = \begin{bmatrix} -1 \end{bmatrix} \begin{bmatrix} x_{int} \end{bmatrix} + \begin{bmatrix} \frac{1}{R_5C_2} \end{bmatrix} u$$

$$[y] = [1] [x_{int}]$$

$$X_{INT} = -R \cdot \frac{1}{R_{10}C_{3,5}} + X_1 \cdot \frac{1}{5R_{10}C_3} \cdot \frac{\cancel{R_{13}}^1}{\cancel{R_{13}}} \quad (1) \quad \text{Bloque II}$$

$$Y = X_{INT}$$

$$\text{de (1): } \overset{\circ}{X_{INT}} = \left(\frac{1}{R_{10}C_3} \right) X_1 - \left(\frac{1}{R_{10}C_3} \right) R = \frac{1}{R_{10}C_3} (X_1 - R)$$

$$Y = X_{INT}$$

\Rightarrow Matriz expandida

$$\begin{bmatrix} \overset{\circ}{X_1} \\ \overset{\circ}{X_2} \\ \overset{\circ}{X_{INT}} \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{R_5C_2} & 0 \\ 0 & 0 & 0 \\ \frac{1}{R_{10}C_3} & 0 & 0 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_{INT} \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ \frac{1}{R_2C_1} & 0 \\ 0 & \frac{-1}{R_{10}C_3} \end{bmatrix} \begin{bmatrix} u \\ r \end{bmatrix}$$

2.2 Diseño de realimentación G)

$$\text{An } [A - BK] = \begin{bmatrix} 0 & \frac{1}{R_s C_2} \\ 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 \\ \frac{1}{R_2 C_1} \end{bmatrix} \cdot \begin{bmatrix} K_1 & K_2 \end{bmatrix}$$

$$\Rightarrow [A - BK] = \begin{bmatrix} 0 & \frac{1}{R_s C_2} \\ 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 \\ \frac{K_1}{R_2 C_1} & \frac{K_2}{R_2 C_1} \end{bmatrix}$$

$$[A - BK] = \begin{bmatrix} 0 & \frac{1}{R_s C_2} \\ -\frac{K_1}{R_2 C_1} & -\frac{K_2}{R_2 C_1} \end{bmatrix} = A_{LC}$$

~~det[A - BK]~~ = ~~$\frac{1}{R_2 R_s C_1 C_2}$~~

$$\begin{bmatrix} -\lambda & \frac{1}{R_s C_2} \\ -\frac{K_1}{R_2 C_1} & -\frac{K_2}{R_2 C_1} - \lambda \end{bmatrix} = \lambda II - A$$

~~$\det[\lambda II - A] = \det[A - \lambda II]$~~

$$\lambda \left(\lambda + \frac{K_2}{R_2 C_1} \right) - \left(\lambda + \frac{K_1}{R_2 C_1} \right) \left(\lambda - \frac{1}{R_s C_2} \right)$$

$$\lambda^2 + \frac{K_2}{R_2 C_1} \lambda - \left[\lambda^2 + \lambda \left[\frac{K_1}{R_2 C_1} - \frac{1}{R_s C_2} \right] - \frac{K_1}{R_2 R_s C_1 C_2} \right]$$

$$\lambda \left(\lambda + \frac{k_2}{R_2 C_1} \right) + \frac{k_1}{R_2 C_1 C_2 R_5} = \lambda^2 + \frac{\lambda k_2}{R_2 C_1} + \frac{k_1}{R_2 C_1 C_2 R_5}$$

Poles conjugados ($s = 100 \pm j300$)

$$\lambda^2 + \frac{\lambda k_2}{R_2 C_1} + \frac{k_1}{R_2 R_5 C_1 C_2} = (\lambda + 100 - j300)(\lambda + 100 + j300)$$

$$= \lambda^2 + \lambda[200] + (100 + j300)(100 - j300)$$

$$= \lambda^2 + \lambda(200) + (100^2 + 300^2)$$

$$\lambda^2 + \lambda \frac{k_2}{R_2 C_1} + \frac{k_1}{R_2 R_5 C_1 C_2} = \lambda^2 + \lambda(200) + \frac{10000}{40.00}$$

$$\Rightarrow \frac{k_2}{R_2 C_1} = 200 \rightarrow k_2 = 200 \cdot \underbrace{R_2 C_1}_{1/100} = 2$$

$$\Rightarrow k_1 = \underbrace{10000 \cdot R_2 R_5 C_1 C_2}_{1/10^4} = 10$$

$$\therefore \text{ si } \frac{U}{X_1} = -\frac{R_{22}}{R_{11}} \quad , \quad \frac{U}{X_2} = \frac{R_{22}}{R_{12}}$$

$$\Rightarrow k_1 = \frac{R_{22}}{R_{11}} \rightarrow R_{11} = \frac{R_{22}}{k_1} = 400 \Omega$$

$$k_2 = \frac{R_{22}}{R_{12}} \rightarrow R_{12} = \frac{R_{22}}{k_2} = 23,5 \Omega$$

Poles $\lambda_1 = -100, \lambda_2 = -500$

$$\lambda^2 + \frac{\lambda K_2}{R_2 C_1} + \frac{K_1}{R_2 C_1 R_s C_2} = (\lambda + 100)(\lambda + 500)$$

$$= \lambda^2 + 600\lambda + 50.000$$

$$\Rightarrow \frac{K_2}{R_2 C_1} = 600 \rightarrow K_2 = 600 \cdot R_2 C_1 = 6, \quad \left. \begin{array}{l} \\ \end{array} \right\} R_{11} = 9 k4$$

$$\Rightarrow K_1 = R_2 R_s C_1 C_2 \cdot (50.000) = 5, \quad \left. \begin{array}{l} \\ \end{array} \right\} R_{12} = 7 k8$$

Poles en $\lambda = -100 \pm j100$

 100^2

$$= (\lambda + 100 + j100)(\lambda + 100 - j100)$$

$$= \lambda^2 + \lambda(200) + 20.000$$

$$\Rightarrow \frac{K_2}{R_2 C_1} = 200 \rightarrow K_2 = 2$$

$$\left. \begin{array}{l} \\ \end{array} \right\} R_{12}, R_{11} = 23 k5$$

$$\frac{K_1}{R_2 C_1 R_s C_2} = 20.000 \rightarrow K_1 = 2$$