

Palm movement

Mode 0: spider mode. Call hexapod robot action group

Extend your middle finger and crook your ring finger	Tilt the palm 35 to 90 degrees to the right	Turn right
Extend your middle finger and crook your ring finger	Tilt the palm 35 to 90 degrees to the left	Turn left
Crook your middle finger	Palm faces down	Stop
Straighten your middle finger and ring finger	Palm faces down	Move forward
Straighten your middle finger and little finger	Palm faces up	Move backward
Straighten your middle finger	Palm faces up	Stop

Mode 1: hand mode. Use finger to control the corresponding servo

thumb	NO.1 servo
index finger	NO.2 servo
middle finger	NO.3 servo
ring finger	NO.4 servo
little finger	NO.5 servo
rotate the palm with palm facing up	NO.6 servo

Mode 2: robotic car mode. Control car motor

Crook middle finger	Tilt the palm 35 to 90 degrees to the left	Turn left
---------------------	--	-----------

Crook middle finger	Tilt the palm 35 to 90 degrees to the right	Turn right
Crook middle finger	Tilt the palm 0 to 30 degrees	Move forward
Rest	Rest	Stop

Mode 3: robotic arm mode. Control the servo individually and rotate the pan-tilt

Crook index finger, middle finger and ring finger	Rotate to control the moving direction	NO.6 servo
Straighten index finger, middle finger and ring finger	Rotate to control the moving direction	NO.5 servo
Crook the thumb. Straighten index finger, middle finger and ring finger.	Rotate to control the moving direction	NO.4 servo
Crook the index finger. Straighten middle finger and ring finger.	Rotate to control the moving direction	NO.3 servo
Straighten index finger and middle finger. Crook the ring finger	Rotate to control the moving direction	NO.2 servo
Straighten index finger Crook middle finger and ring finger	Rotate to control the moving direction	NO.1 servo