



1. Wear the glove in standard way to ensure the above potentiometer can operate to the greatest extent, which can avoid the control problem due to insensitive operation.
2. Bluetooth connection: switch on the robot and press DEL key on the glove to clear the previous connection record. When the STA light lights up, it means the connection works.
3. Initialize the glove: straighten your arm and make a fist with the palm facing down. Put the power on, then LED lights in the middle will quick flash for several times. After the LEDs finish flashing, stretch your hand. When the LED lights complete the second flashing, it means that the initialization is completed.
4. Switch working mode by pressing K3 button:
  - When all the LED lights are off, the spider robot control mode is on.
  - When only one LED light is on, the hand control mode is on.
  - When 2 LED lights are on, the Tankbot control mode is on.
  - When 3 LED lights are on, the robotic arm control mode is on.
5. Please refer to gesture instruction of the glove to control the robot.